

# On splitting complete manifolds via infinity harmonic functions

Damião J. Araújo      Marco Magliaro      Luciano Mari  
Leandro F. Pessoa

Departamento de Matemática, Universidade Federal da Paraíba  
58059-900, João Pessoa - Paraíba (Brazil)  
E-mail: araujo@mat.ufpb.br

Departamento de Matemática, Universidade Federal do Ceará  
60455-760, Fortaleza, (Brazil)  
E-mail: marco.magliaro@mat.ufc.br

Dipartimento di Matematica, Università degli studi di Torino,  
Via Carlo Alberto 10, 10123 Torino (Italy)  
E-mail: luciano.mari@unito.it

Departamento de Matemática, Universidade Federal do Piauí,  
64049-550, Teresina (Brazil)  
E-mail: leandropessoa@ufpi.edu.br

## Abstract

In this paper, we prove some splitting results for manifolds supporting a non-constant infinity harmonic function which has at most linear growth on one side. Manifolds with non-negative Ricci or sectional curvature are considered. In dimension 2, we extend Savin's theorem on Lipschitz infinity harmonic functions in the plane to every surface with non-negative sectional curvature.

## 1 Introduction

The present paper regards the interplay between the geometry of a Riemannian manifold and the qualitative properties of  $\infty$ -harmonic functions, i.e., solutions to

$$\Delta_{\infty} u \doteq \nabla^2 u(\nabla u, \nabla u) = 0 \quad \text{on } M$$

in the viscosity sense. The  $\infty$ -Laplace operator and its normalized counterpart

$$\Delta_{\infty}^N u \doteq \nabla^2 u \left( \frac{\nabla u}{|\nabla u|}, \frac{\nabla u}{|\nabla u|} \right)$$

gained increasing importance in the field of fully-nonlinear PDEs over the past 60 years, see [6, 15] for a thorough account of the theory, with historical insights and a detailed set of references. The investigation herein is a natural continuation of [3, 34, 35], where the geodesic completeness of a boundaryless Riemannian (or Finsler) manifold was characterized in terms of suitable Liouville properties of viscosity solutions to

$$\Delta_{\infty}^N u \geq g(u).$$

It is known that  $u$  solves  $\Delta_\infty u \geq 0$  ( $= 0, \leq 0$ ) if and only if it solves  $\Delta_\infty^N u \geq 0$  ( $= 0, \leq 0$ ). Therefore, for the purpose of the present paper we will only consider  $\Delta_\infty$ . Among the various equivalent conditions, by [3, Theorem 1.1] (cf. also [34, Theorem 8.1]) a connected Riemannian manifold  $M$  without boundary is shown to be complete *if and only if* all solutions to  $\Delta_\infty u \leq 0$  whose negative part  $u_-$  satisfies

$$u_-(x) = o(r(x)) \quad \text{as } x \rightarrow \infty \quad (1)$$

are constant<sup>1</sup>. Here,  $r(x)$  denotes the distance to a fixed origin. The result extends the known Liouville theorem for positive  $\infty$ -superharmonic functions on  $\mathbb{R}^m$  proved by Lindqvist and Manfredi in [31, 32], see also [15, p.113], and we stress that the *if* part is its main novelty. The lack of curvature or volume growth requirements on  $M$  in order for the aforementioned Liouville property to hold makes the theory of slowly growing  $\infty$ -harmonic functions considerably different from that developed for other operators  $\mathcal{F}$  like the Laplacian [12, 43], the  $p$ -Laplacian [42] and in recent years the minimal hypersurface operator [14, 17, 39]. In these latter cases,  $\text{Ric} \geq 0$  is the weakest known condition to guarantee that positive solutions to  $\mathcal{F}[u] = 0$  are constant. For solutions satisfying the more general (1), in the minimal hypersurface case further technical conditions on  $M$  are needed as of yet, see [13, 18].

Hereafter,  $M$  will always denote a complete, connected Riemannian manifold without boundary. A natural problem is then to see what happens to  $\infty$ -harmonic functions that grow at most linearly on one side, namely, that satisfy

$$\limsup_{r(q) \rightarrow \infty} \frac{u(q)}{r(q)} < \infty. \quad (2)$$

Especially, we shall look for geometric conditions to force a rigidity of  $M$  or  $u$ , in the sense that  $M$  splits as a (possibly warped) product and  $u$  only depends on split-off variables. The next example shows that a constraint on the geometry of  $M$  is necessary in this case.

**Example 1.1.** On a Cartan-Hadamard manifold, that is, a simply connected manifold with non-positive sectional curvature  $\text{Sec}$ , given a ray  $\gamma : [0, \infty) \rightarrow M$  one can consider the Busemann function

$$b_\gamma : M \rightarrow \mathbb{R}, \quad b_\gamma(x) = \lim_{t \rightarrow \infty} \left( d(x, \gamma(t)) - t \right).$$

It is known by [26] that  $b_\gamma \in C^2(M)$  and  $|\nabla b_\gamma| = 1$  on  $M$ , so differentiating we get that  $b_\gamma$  is a globally Lipschitz solution to  $\Delta_\infty b_\gamma = 0$  on  $M$ . However, in general  $M$  does not split off any line.

**Remark 1.2.** It is known, see Lemma 2.2 below, that for solutions to  $\Delta_\infty u \geq 0$  the following identity holds (possibly with infinite values):

$$\limsup_{r(q) \rightarrow \infty} \frac{u(q)}{r(q)} = \text{Lip}(u, M),$$

with  $\text{Lip}(u, M)$  the Lipschitz constant of  $u$  on  $M$ . Therefore, non-constant globally Lipschitz solutions to  $\Delta_\infty u = 0$  are precisely those for which the limsup in (2) is a positive real number. By scaling  $u$ , in our main results we shall assume this number to be one.

Based on the theory of harmonic functions with linear growth developed in [10, 28, 33] and the corresponding results for minimal graphs which appeared in recent years [13, 18, 19], the assumptions

$$\text{Ric} \geq 0 \quad \text{or} \quad \text{Sec} \geq 0$$

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<sup>1</sup>The implication is (1)  $\Leftrightarrow$  (2) in [3, Theorem 1.1], once we observe that  $v = -u$  solves  $\Delta_\infty v \geq 0$  (hence  $\Delta_\infty^N v \geq 0$ ) with  $v_+ = o(r)$ .

seem to be appropriate. For Euclidean space, Aronsson in [5, Section 7] proved that any solution of class  $C^2$  on  $\mathbb{R}^2$  is affine, see also [20] for the case of dimension  $m \geq 3$ . Examples therein show that this fails for viscosity solutions which are not  $C^2$ , unless one assumes a priori growth of  $u$ . On the other hand, Savin's remarkable theorem [40] states that

$$\Delta_\infty u = 0 \text{ on } \mathbb{R}^2, \quad u \text{ Lipschitz} \implies u \text{ is affine.}$$

As of today, its extension to  $\mathbb{R}^m$  for  $m \geq 3$  has not been established. In higher dimensions, we are only aware of the next half-space theorem showed by Crandall, Evans and Gariepy [16]:

$$\Delta_\infty u \leq 0, \quad u(x) \geq a + \langle p, x \rangle \text{ on } \mathbb{R}^m \implies u = u(0) + \langle p, x \rangle,$$

and the recent work of Hong and Zhao [25], who proved that  $u$  is affine by assuming (2) and

$$\lim_{r(p) \rightarrow \infty} |Du(p)| = \text{Lip}(u, \mathbb{R}^m).$$

The methods herein are much inspired by those in [16, 25]. As a matter of fact, we show that elaborating on their arguments in a manifold setting, and employing some basic facts of metric geometry, we are able to obtain results with nontrivial geometric content. Let  $M$  be complete, connected and without boundary, and assume that  $u$  is a nonconstant  $\infty$ -harmonic function satisfying (2), so by Remark 1.2 we can assume

$$\limsup_{r(q) \rightarrow \infty} \frac{u(q)}{r(q)} = 1.$$

We prove:

- (i) Theorem 3.1. If  $\text{Ric} \geq 0$ , then any blowdown  $M_\infty$  of  $M$  splits as  $\mathbb{R} \times N_\infty$ . Moreover, the blowdown of  $u$  only depends on the arclength  $t$  of the  $\mathbb{R}$  factor, and it is affine in  $t$ .
- (ii) Proposition 3.4. In the assumptions of (i),  $M$  itself may not split off lines: there exists a manifold  $M$  with  $\text{Ric} > 0$  carrying a linearly growing  $\infty$ -harmonic function. However, by the tangency principle in Proposition 3.5, if the graph of  $u$  touches that of a (possibly translated and dilated) Busemann function from above or below, then  $M$  splits and  $u$  is an affine function of the split direction only.
- (iii) If  $\text{Sec} \geq 0$ , general theory gives a way to split  $M$  itself as  $\mathbb{R} \times N$ . We prove in Theorem 4.3. that the blowdown of  $u$  is unique and that, writing  $(x, y) \in \mathbb{R} \times N$  and orienting  $\mathbb{R}$  appropriately, it holds

$$\lim_{x \rightarrow +\infty} \frac{u(x, y) - u(-x, y)}{2x} = 1 \quad \text{for each fixed } y \in N.$$

In the assumptions of (iii), whether the function  $u$  only depends on  $x$  is an open problem even in  $\mathbb{R}^m$ , whose solution would allow to extend Savin's result to higher dimensions. As pointed out in [15, 16], a positive answer is likely to give new insights on the  $C^{1,\alpha}$  regularity property of  $\infty$ -harmonic functions. In dimension  $m \geq 3$ , we have the following sufficient condition:

- (iv) Assume  $\text{Sec} \geq 0$ , and that there exist a ray  $\gamma$  and a constant  $C$  for which either

$$u(\gamma(t)) \geq t - C \quad \text{or} \quad u(\gamma(t)) \leq -t + C$$

holds for all  $t \in \mathbb{R}^+$ . Then, referring to the splitting in (iii), we have  $u(x, y) = x + C_2$  for some constant  $C_2$ .

On the other hand, (iii) strengthens in dimension 2 and gives rise to a full extension of Savin's theorem to any complete surface with non-negative sectional curvature. We get

**Theorem 1.3.** *Let  $M$  be a complete connected surface with  $\text{Sec} \geq 0$ , and let  $u \in C(M)$  be a non-constant  $\infty$ -harmonic function such that*

$$\limsup_{r(q) \rightarrow \infty} \frac{u(q)}{r(q)} < \infty, \quad (3)$$

where  $r$  is the distance from a fixed origin. Then,  $M = \mathbb{R}^2$  or  $M = \mathbb{R} \times \mathbb{S}^1$ . Furthermore,  $u$  only depends on the arclength  $x$  of a split  $\mathbb{R}$  factor, and it is affine in  $x$ .

Most of the arguments in the present paper extend, almost directly, to RCD spaces, for which we refer to the survey [1] and the references therein. An exception might be the approximation procedure we carried over to prove Theorem 4.3, see Section 5. As a side remark, to approximate we have chosen to use the  $p$ -Laplacian instead of the inhomogeneous operator proposed in [22]. In another direction, Finsler manifolds proved to be a quite natural setting for the techniques developed to investigate the  $\infty$ -Laplacian, see [3]. However, in such a generality the topological/geometric conclusions that can be achieved from splitting theorems are weaker, apart from the subclass of Berwald metrics, [37]. For these reasons, we decided to stick to the smooth, Riemannian setting to avoid technicalities.

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## 2 Preliminaries

### Busemann functions and convergence

We here collect some basic facts on metric geometry, mostly to fix notation. We refer to [38] for more details. Hereafter, a segment  $\gamma : [0, T] \rightarrow M$  will be a unit speed geodesic which is minimizing between its endpoints. A unit speed geodesic  $\gamma$  will be called:

- a ray if  $\gamma$  is defined on  $[0, \infty)$  and is a segment between any pair of its points;
- a line if  $\gamma$  is defined on  $\mathbb{R}$  and is a segment between any pair of its points.

Therefore, a line is characterized by the identity

$$d(\gamma(t), \gamma(s)) = |t - s| \quad \forall s, t \in \mathbb{R}.$$

Given a ray  $\gamma$ , the Busemann function  $b_\gamma : M \rightarrow \mathbb{R}$  is defined as the limit

$$b_\gamma(x) = \lim_{t \rightarrow \infty} \left( d(x, \gamma(t)) - t \right).$$

Such a limit exists since the family of functions  $b_{\gamma,t}(x) = d(x, \gamma(t)) - t$  is monotone decreasing and bounded as  $t \uparrow \infty$ , see [38, Sec. 7.3.2]. Given a point  $p \in M$ , an asymptote of  $\gamma$  issuing

from  $x$  is a sequential limit  $\tilde{\gamma}$  of a sequence of segments  $\tilde{\gamma}_j$  joining  $x$  to  $\gamma(t_j)$  for some  $t_j \rightarrow \infty$ . Notice that  $\tilde{\gamma}$  is a ray from  $x$ . By [38, Prop. 7.3.8], it holds

$$b_\gamma(x) \leq b_\gamma(p) + b_{\tilde{\gamma}}(x)$$

with equality at  $p$ , namely,  $b_\gamma(p) + b_{\tilde{\gamma}}$  is a support function from above for  $b_\gamma$  at  $p$ .

Next, we denote with  $\lambda = \{\lambda_j\}$  a sequence with  $\lambda_j \rightarrow \infty$ . For each  $j$ , we let  $M_j^\lambda$  be the manifold  $M$  with metric  $g_j = \lambda_j^{-2}g$ , distance  $d_j = \lambda_j^{-1}d$  and induced volume form  $dV_j = \lambda_j^{-m}dV$ . Also, let  $B_R^j$  be geodesic balls in  $M_j^\lambda$  centered at a fixed origin  $o$ . A pointed measured Gromov-Hausdorff limit

$$(M, d_j, dV_j, o) \longrightarrow (M_\infty^\lambda, d_\infty, \mathbf{m}_\infty, o_\infty), \quad (4)$$

see [1, Section 6] for its definition, will be written as  $M_j^\lambda \rightarrow M_\infty^\lambda$  and named a tangent cone at infinity (or a blowdown) of  $M$  at  $o$ . Henceforth, given  $u : M \rightarrow \mathbb{R}$ ,  $\text{Lip}(u, U)$  will denote the Lipschitz constant of  $u$  on a subset  $U \subset M$ . Assume that  $u$  is globally Lipschitz. Defining

$$u_j^\lambda : M_j^\lambda \rightarrow \mathbb{R}, \quad u_j^\lambda(x) = \frac{u(x) - u(o)}{\lambda_j},$$

we have  $\text{Lip}(u_j^\lambda, M_j^\lambda) = \text{Lip}(u, M)$  for each  $j$  and therefore, up to a subsequence,  $u_j^\lambda$  converges pointwise in the Gromov-Hausdorff sense (see [38, Lem. 11.1.9]) to a function  $v^\lambda : M_\infty^\lambda \rightarrow \mathbb{R}$ , meaning that, for each  $x_j \in M_j^\lambda$ ,  $x_\infty \in M_\infty^\lambda$ ,

$$x_j \rightarrow x_\infty \quad \implies \quad u_j^\lambda(x_j) \rightarrow v^\lambda(x_\infty).$$

## Comparison with cones and its consequences

We recall some well-known properties of  $\infty$ -subharmonic functions, which can be found in the surveys [6, 15, 41]. Despite the references being set in Euclidean space, the proof of the lemmata below carry over verbatim to any complete Riemannian manifold. For more general metric spaces, we refer to [9].

Let  $\Omega$  be an open domain of  $M$  and let  $u \in C(\Omega)$ . It is known that  $\Delta_\infty u \geq 0$  is equivalent to  $u$  enjoying comparison with cones

$$C_x(y) = a + b d(x, y), \quad a, b \in \mathbb{R}$$

from above, meaning that if  $u \leq C_x$  in  $\partial\Omega \cup \{x\}$ , then  $u \leq C_x$  in  $\Omega$ , see [16, Section 3] and [9, 15]. As a consequence, if  $\Delta_\infty u \geq 0$  then

$$u(y) \leq u(x) + \left( \max_{\partial B_R(x)} \frac{u(y) - u(x)}{R} \right) d(x, y) \quad \forall x \in \Omega, y \in B_R(x) \Subset \Omega.$$

Even more, by [16, Lem. 2.4] the function

$$R \mapsto S_{u,R}^+(x) = \max_{z \in \partial B_R(x)} \frac{u(z) - u(x)}{R} \quad (5)$$

is non-decreasing for  $R < d(x, \partial\Omega)$ , and therefore the limits

$$S_u^+(x) = \lim_{R \rightarrow 0} S_{u,R}^+(x) \quad \text{and} \quad S_{u,\infty}^+(x) = \lim_{R \rightarrow \infty} S_{u,R}^+(x)$$

(the latter, if  $\Omega = M$ ) are well defined. As a direct consequence,  $u \in \text{Lip}_{\text{loc}}(\Omega)$ , see [16, Lem. 2.5]. The following proposition collects some of the properties in [15, Lemm. 4.2 and 4.3].

**Proposition 2.1.** *Let  $\Omega \subset M$  be an open subset and  $u \in C(\Omega)$  satisfy  $\Delta_\infty u \geq 0$ . Then, for each  $x \in \Omega$*

$$S_u^+(x) = \lim_{r \rightarrow 0} \text{Lip}(u, B_r(x)) = \lim_{r \rightarrow 0} \|\nabla u\|_{L^\infty(B_r(x))}.$$

*Moreover, if  $u$  is differentiable at  $x$ , the three quantities equal  $|\nabla u(x)|$ .*

We next state a simple yet very useful consequence of comparison with cones, essentially contained in [15, Prop. 7.1] [25, Prop. 1.1]. We include a proof for the sake of completeness.

**Lemma 2.2.** *If  $u \in C(M)$  satisfies  $\Delta_\infty u \geq 0$ , and let  $r$  be the distance from a fixed origin  $o$ . Then,*

$$\text{Lip}(u, M) = S_{u,\infty}^+(x) = \limsup_{r(q) \rightarrow \infty} \frac{u(q)}{r(q)},$$

*for any  $x \in M$ , possibly with infinite values.*

*Proof.* We prove the first equality. From the monotonicity of  $S_{u,R}^+(x)$  we deduce that  $S_{u,R}^+(x) = \max_{z \in \bar{B}_R(x)} \frac{u(z) - u(x)}{R}$ . Therefore, for each  $w \in M$  we get

$$\begin{aligned} S_{u,R}^+(x) &\leq \max_{\bar{B}_{R+d(w,x)}(w)} \frac{u(z) - u(x)}{R} \\ &= \max_{\partial B_{R+d(w,x)}(w)} \left( \frac{u(z) - u(w)}{R + d(w,x)} \right) \frac{R + d(w,x)}{R} + \frac{u(w) - u(x)}{R} \\ &\leq \frac{R + d(w,x)}{R} S_{u,R}^+(w) + \frac{u(w) - u(x)}{R}. \end{aligned}$$

Letting  $R \rightarrow \infty$  we may conclude  $S_{u,\infty}^+(x) \leq S_{u,\infty}^+(w)$ . Since  $x$  and  $w$  are arbitrary, equality holds and the limit  $\ell = S_{u,\infty}^+(x)$  (possibly infinite) does not depend on the point  $x$ . We now show that  $\ell = \text{Lip}(u, M)$ . It is clear that  $S_{u,R}^+(x) \leq \text{Lip}(u, M)$ , thus  $\ell \leq \text{Lip}(u, M)$ . Assume by contradiction that there exists  $C \in (\ell, \text{Lip}(u, M))$  and pick  $z, w \in M$  such that  $u(z) \geq u(w) + Cd(w, z)$ . Then,

$$\ell = S_{u,\infty}^+(w) \geq \frac{u(z) - u(w)}{d(w, z)} \geq C,$$

contradiction. The second equality follows from  $S_{u,\infty}^+(x) = S_{u,\infty}^+(o)$  and the definition of  $S_{u,\infty}^+(o)$ .  $\square$

As we shall see, Lemma 2.2 guarantees the non-constancy of any blowdown of  $u$ . Thus, it plays the same important role as that of the relation

$$\lim_{R \rightarrow \infty} \int_{B_R} |\nabla u|^2 = \sup_M |\nabla u|^2 \quad (6)$$

in the theory of harmonic functions [10, 33] and minimal graphs [13]. However, we emphasize that the proof of (6) in the above references is considerably subtler than that of Lemma 2.2.

## Tightness and the anti-peeling Lemma

We next present two key lemmata which will be often used in the arguments below. The first one adapts [16, Lem. 4.2].

**Lemma 2.3.** *Let  $(N, d_N)$  be a metric space and let  $v$  be a 1-Lipschitz function on the product space  $\mathbb{R} \times N$  such that, for some  $y_0 \in N$ ,*

$$v(x, y_0) = x \quad \forall x \in \mathbb{R}.$$

*Then,*

$$v(x, y) = x \quad \forall (x, y) \in \mathbb{R} \times N.$$

*Proof.* Let us fix  $\lambda \in \mathbb{R}$ . Since  $v$  is 1-Lipschitz

$$|v(x, y) - \lambda|^2 = |v(x, y) - v(\lambda, y_0)|^2 \leq |x - \lambda|^2 + d_N(y, y_0)^2. \quad (7)$$

Expanding the squares on both sides and simplifying we get

$$v(x, y)^2 - 2\lambda v(x, y) \leq x^2 - 2\lambda x + d_N(y, y_0)^2. \quad (8)$$

Dividing by  $\lambda > 0$  and letting  $\lambda \rightarrow +\infty$  we obtain  $v(x, y) \geq x$ . Likewise, dividing by  $\lambda < 0$  and letting  $\lambda \rightarrow -\infty$  we conclude that  $v(x, y) \leq x$ , whence  $v(x, y) = x$ .  $\square$

The second Lemma follows from [15, Prop. 6.2]. We borrowed the name ‘‘anti-peeling Lemma’’ because of its analogy with [7, Thm. 3.2], which is a key result in the theory of the prescribed Lorentzian mean curvature equation.

**Lemma 2.4. [Anti-peeling Lemma]** *Let  $M$  be a complete Riemannian manifold,  $\Omega \subset M$  an open subset, and let  $u : \Omega \rightarrow \mathbb{R}$  satisfy, for some  $x \in \Omega$ ,*

$$\Delta_\infty u \geq 0 \quad \text{on } \Omega, \quad S_u^+(x) = \|\nabla u\|_{L^\infty(\Omega)} = 1.$$

*Then, there exists a segment  $\gamma : [0, b) \rightarrow \Omega$  issuing from  $x$  such that*

$$u(\gamma(t)) - u(\gamma(s)) = t - s \quad (9)$$

*for each  $0 < s < t < b$ . Moreover,  $u$  is differentiable at each point of  $\gamma((0, b))$  with gradient  $\nabla u(\gamma(t)) = \gamma'(t)$ , and if  $b < \infty$  it holds*

$$\lim_{t \rightarrow b} \gamma(t) \in \partial\Omega.$$

*In particular, the existence of such  $\gamma$  occurs if  $\|\nabla u\|_{L^\infty(\Omega)} = 1$  and there exists a geodesic  $\bar{\gamma} : [0, b') \rightarrow M$  issuing from  $x$  where (9) holds for  $0 < s < t < b'$ , and in this case  $\gamma$  extends  $\bar{\gamma}$ .*

*Proof.* By Proposition 2.1,  $S_u^+(x)$  coincides with  $\lim_{r \rightarrow 0} \text{Lip}(u, B_r(x))$ . It was proved in [15, Prop. 6.2] that there exists a Lipschitz curve  $\gamma : [0, b) \rightarrow \Omega$  of velocity  $|\gamma'| \leq 1$  issuing from  $x$  and satisfying, among other properties,

$$u(\gamma(t)) \geq u(x) + t S_u^+(x) = u(x) + t, \quad \lim_{t \rightarrow b} \gamma(t) \in \partial\Omega \quad \text{if } b \text{ is finite.}$$

Since  $u$  is 1-Lipschitz,  $u(\gamma(t)) = u(x) + t$  on  $[0, b)$  and therefore

$$|t - s| = |u(\bar{\gamma}(t)) - u(\bar{\gamma}(s))| \leq d(\gamma(t), \gamma(s)) \leq |t - s|,$$

whence  $\gamma$  is a segment. By [41, Lem. 3.5], if the domain of a 1-Lipschitz function  $u$  contains a segment  $\gamma$  where  $u$  has slope 1, then  $u$  is differentiable at any interior point of  $\gamma$ . Moreover, its gradient is  $\pm\gamma'(t)$  according to whether  $u$  grows or decreases along  $\gamma$ . This concludes the first part of the proof. Next, let  $\bar{\gamma} : [0, b') \rightarrow \Omega$  be a geodesic from  $x$  satisfying (9). Using again [41, Lem. 3.5] and Proposition 2.1 we get  $S_u^+(y) = 1$  and  $\nabla u(y) = \bar{\gamma}'(t)$  at every interior point  $y = \bar{\gamma}(t)$  of  $\bar{\gamma}$ . Applying the first part of the proof, there exists a curve  $\gamma$  issuing from  $y$  where  $u$  has slope 1. Since  $u$  is differentiable at  $y$ ,  $1 = (u \circ \gamma)'(0) = \langle \nabla u(y), \gamma'(0) \rangle \leq 1$ , whence  $\bar{\gamma}' = \gamma'$  at  $y$  and  $\gamma$  extends  $\bar{\gamma}$ .  $\square$

### 3 Manifolds with $\text{Ric} \geq 0$

We begin by investigating manifolds with  $\text{Ric} \geq 0$ . First, we analyse their blowdowns by adapting an argument in [15, Prop. 7.1], see also Lemma 7.1 therein and [25, Prop. 1].

**Theorem 3.1.** *Let  $M^m$  be a complete manifold with  $\text{Ric} \geq 0$ , and let  $u \in C(M)$  be an  $\infty$ -harmonic function such that*

$$\limsup_{r(q) \rightarrow \infty} \frac{u(q)}{r(q)} = 1, \quad (10)$$

where  $r$  is the distance from a fixed origin. Then, every tangent cone at infinity of  $M$  splits as  $\mathbb{R} \times N_\infty$  for some  $N_\infty \in \text{RCD}(0, m-1)$ . Furthermore, the blowdown of  $u$  only depends on the arclength  $\tau$  of the  $\mathbb{R}$ -factor, and it is affine in  $\tau$ .

*Proof.* By Lemma 2.2,  $\text{Lip}(u, M) = 1$ . Let  $M_j^\lambda \rightarrow M_\infty^\lambda$  be a tangent cone at infinity centered at  $o \in M$ , and let  $u_j^\lambda \rightarrow v^\lambda$  be the associated blowdown of  $u$ . We hereafter omit the superscript  $\lambda$ . Fix  $R > 0$ , and for each  $j$  consider a point  $z_j^+ \in \partial B_{\lambda_j R}(o) \subset M$  which realizes  $S_{\lambda_j R}^+(o)$ . By Lemma 2.2,

$$\frac{u_j(z_j^+)}{R} = \frac{u(z_j^+) - u(o)}{\lambda_j R} \rightarrow 1 \quad \text{as } j \rightarrow \infty. \quad (11)$$

Likewise, we can consider  $z_j^- \in \partial B_{\lambda_j R}(o) \subset M$  which realizes  $S_{\lambda_j R}^-(o)$  and obtain

$$\frac{u_j(z_j^-)}{R} = \frac{u(z_j^-) - u(o)}{\lambda_j R} \rightarrow -1 \quad \text{as } j \rightarrow \infty.$$

From  $z_j^\pm \in \partial B_{\lambda_j R}^j(o)$  passing to limits as  $j \rightarrow \infty$  and using the local uniform convergence of  $u_j$ , up to subsequences

$$z_j^\pm \rightarrow z_R^\pm \in \partial B_R^\infty(o_\infty), \quad v(z_R^+) = R = -v(z_R^-). \quad (12)$$

Having set  $\gamma_R^+ : [0, R] \rightarrow M_\infty$  (respectively  $\gamma_R^- : [0, R] \rightarrow M_\infty$ ) a segment from  $o$  to  $z_R^+$  (resp. from  $o$  to  $z_R^-$ ), we can define  $\gamma_R : [-R, R] \rightarrow M_\infty$  as

$$\gamma_R(t) = \begin{cases} \gamma_R^-(-t) & \text{for } t \in [-R, 0], \\ \gamma_R^+(t) & \text{for } t \in [0, R]. \end{cases} \quad (13)$$

From (12) we deduce  $d_\infty(z_R^+, z_R^-) \geq u(z_R^+) - u(z_R^-) = 2R$ , so by the triangle inequality  $d_\infty(z_R^+, z_R^-) = 2R$ . It follows that  $\gamma_R$  is a segment from  $z_R^-$  to  $z_R^+$ , and by (12) and  $\text{Lip}(v, M_\infty) \leq 1$  we deduce

$$v(\gamma_R(t)) = t \quad \text{for each } t \in [-R, R]. \quad (14)$$

Letting  $R \rightarrow \infty$ ,  $\gamma_R$  converges to a line  $\gamma_\infty$  in  $M_\infty$ . Cheeger-Colding's splitting Theorem in [11, Thm. 6.64] guarantees that  $M_\infty$  splits as  $\mathbb{R} \times N_\infty$ . Moreover, as shown by Gigli's nonsmooth splitting Theorem [23],  $(N_\infty, d')$  is in  $\text{RCD}(0, m-1)$ . Let  $(\tau, y) \in \mathbb{R} \times N_\infty$ , with  $o = (0, o')$ . Since  $v(\tau, o') = \tau$  for each  $\tau \in \mathbb{R}$ , the conclusion  $v(\tau, y) = \tau$  on  $\mathbb{R} \times N_\infty$  then follows from Lemma 2.3.  $\square$

**Remark 3.2.** Notice that the identity  $v(x, y) = x$  for  $(x, y) \in \mathbb{R} \times N_\infty$ , together with (14), imply that each  $\gamma_R$  is the curve  $(t, o')$  for  $t \in [-R, R]$ . Hence,  $\gamma_\infty$  is indeed the extension of each  $\gamma_R$  to the entire real line.

As mentioned above, Theorem 3.1 is not enough to guarantee that  $M$  itself splits off a line. The following counterexample describes a manifold with  $\text{Ric} > 0$  (hence, not splitting off lines) and carrying a linearly growing  $\infty$ -harmonic function. Even more, the example points out that assumption  $\text{Sec} \geq 0$  cannot be weakened to the non-negativity of any of the following partial Ricci curvature functions  $\text{Ric}^{(\ell)}$  for  $\ell \geq 2$ :

**Definition 3.3.** Let  $M$  be a manifold of dimension  $m \geq 2$ . For  $\ell \in \{1, \dots, m-1\}$ , the  $\ell$ -th (normalized) Ricci curvature is the function

$$v \in T_x M \quad \mapsto \quad \text{Ric}^{(\ell)}(v) \doteq \inf_{\substack{\mathcal{W} \leq v^\perp \\ \dim \mathcal{W} = \ell}} \left( \frac{1}{\ell} \sum_{j=1}^{\ell} \text{Sec}(v \wedge e_j) \right),$$

where  $\{e_j\}$  is an orthonormal basis of  $\mathcal{W}$ .

We recall that  $\text{Ric}^{(\ell)}$  interpolates between the sectional and Ricci curvatures, obtained respectively for  $\ell = 1$  and (up to a normalization constant) for  $\ell = m-1$ . In particular, with our chosen normalization the following implications are immediate:

$$\text{Sec} \geq \kappa \implies \text{Ric}^{(\ell-1)} \geq \kappa \implies \text{Ric}^{(\ell)} \geq \kappa \implies \text{Ric} \geq (m-1)\kappa.$$

**Proposition 3.4.** For  $m \geq 4$ , there exists a complete manifold  $M$  with

$$\text{Ric}^{(2)} \geq 0, \quad \text{Ric} > 0, \quad \text{and} \quad |\text{Sec}| \leq \bar{\kappa}^2$$

for some constant  $\bar{\kappa} > 0$ , which carries a non-constant linearly growing  $\infty$ -harmonic function.

*Proof.* We consider the example in [29, p. 913], along with the observations made in [13]. Fix  $\alpha, \beta \in (0, 1)$  such that  $m-1-\beta > 2+\alpha$ , and let  $0 < \zeta_1, \zeta_2 \in C^\infty(\mathbb{R}^+)$  satisfy

$$\zeta_1(t) = \begin{cases} t & \text{if } t \in (0, 1] \\ t^{-1-\alpha} & \text{if } t \in [2, \infty), \end{cases} \quad \zeta_2(t) = \int_t^\infty \zeta_1(s) ds.$$

Then, for  $b, c \in \mathbb{R}^+$ , define

$$\eta(r) = \frac{1}{2}r + \frac{1}{2\zeta_2(0)} \int_0^r \zeta_2(s) ds, \quad f(r) = (b+r^2)^{\frac{\beta+3-m}{2}} + c.$$

We consider  $M \doteq \mathbb{R} \times \mathbb{R}^+ \times \mathbb{S}^{m-2}$  with coordinates  $(t, r, \theta)$  and metric

$$g = f(r)^2 dt^2 + dr^2 + \eta(r)^2 d\theta^2,$$

where  $d\theta^2$  is the round metric on  $\mathbb{S}^{m-2}$ . Notice that the choice of  $\eta$  implies that  $g$  extends smoothly at  $r = 0$  and that  $M$  is complete. It was shown in [13, Section 9] that  $|\text{Sec}|$  is bounded on  $M$ , and that  $\text{Ric}^{(2)} \geq 0$ ,  $\text{Ric} > 0$  on  $M$  if  $b, c$  are chosen large enough. Given a function  $u : M \rightarrow \mathbb{R}$  of the coordinate  $t$  alone, it holds

$$|\nabla u| = \frac{\partial_t u}{f}, \quad \Delta_\infty u = \frac{(\partial_t^2 u)(\partial_t u)^2}{f^4}.$$

Hence, any affine function  $u(t) = at + k$  gives rise to an  $\infty$ -harmonic function. Also,  $|\nabla u| = a/f$  is bounded on  $M$  since  $f$  is bounded below by a positive constant, thus  $u$  has at most linear growth.  $\square$

Despite, in general,  $\text{Ric} \geq 0$  does not guarantee the splitting of  $M$  when the latter supports a non-constant, linearly growing  $\infty$ -harmonic function, this happens in some special cases. The next result is a tangency principle between  $\infty$ -harmonic functions and (rescaled, translated) Busemann functions.

**Proposition 3.5. [tangency principle]** *Let  $M$  be a complete manifold with  $\text{Ric} \geq 0$ , and let  $u \in C(M)$  satisfy  $\Delta_\infty u \geq 0$  on  $M$ . Let  $c > 0$  and assume that there exists a ray  $\gamma$  such that  $u - cb_\gamma$  has a global maximum point. Then,*

- (i)  $M$  splits as  $\mathbb{R} \times N$ , for some complete manifold  $N$  with  $\text{Ric}_N \geq 0$ ;
- (ii) choosing a suitable arclength parameter  $x$  of the  $\mathbb{R}$ -factor, it holds  $u(x, y) = cx$  for each  $(x, y) \in \mathbb{R} \times N$ ;
- (iii)  $\gamma$  is a half-line of the type  $(-\infty, a] \times \{y_0\}$ . In particular,  $u - cb_\gamma$  is constant on  $M$ .

*Proof.* First, observe that for any fixed  $o \in M$

$$u(x) \leq cb_\gamma(x) + \max_M(u - cb_\gamma) \leq c(b_\gamma(x_0) + d(x, o)) + \max_M(u - cb_\gamma),$$

whence by Lemma 2.2  $u$  is  $c$ -Lipschitz. Let  $p$  be a global maximum point of  $u - cb_\gamma$ . Defining

$$\bar{u} = \frac{1}{c}(u - u(p) + cb_\gamma(p))$$

then  $\bar{u}$  is 1-Lipschitz and  $\bar{u} \leq b_\gamma$  on  $M$ , with equality in  $p$ . We consider an asymptote  $\tilde{\gamma}$  for  $\gamma$  at  $p$ . Then,  $b_\gamma(p) + b_{\tilde{\gamma}}$  is a support function for  $b_\gamma$  from above at  $p$ , which gives

$$\bar{u}(\tilde{\gamma}(t)) \leq b_\gamma(p) + b_{\tilde{\gamma}}(\tilde{\gamma}(t)) = b_\gamma(p) - t$$

for  $t \geq 0$ , with equality at  $t = 0$ . Since  $\bar{u}$  is 1-Lipschitz, necessarily

$$\bar{u}(\tilde{\gamma}(t)) = b_\gamma(p) - t$$

whence  $\bar{u}$  is linear with slope 1 on  $\tilde{\gamma}$ . Since  $\Delta \bar{u} \geq 0$ , by the anti-peeling Lemma 2.4  $\tilde{\gamma}$  can be continued to a line  $\tilde{\gamma} : \mathbb{R} \rightarrow M$  where  $\bar{u}$  has slope 1. The splitting theorem guarantees that  $M$  splits as  $\mathbb{R} \times N$  with the product metric  $d\tau^2 + g_N$ ,  $p = (0, y_0) \in \mathbb{R} \times N$  and  $\mathbb{R} \times \{y_0\}$  is the line  $\tilde{\gamma}$ . This shows (i). Then,

$$\bar{u}(\tau, y_0) = b_\gamma(p) + \tau,$$

thus by Lemma 2.3 we infer  $\bar{u}(\tau, y) = b_\gamma(p) + \tau$  on  $M$ . Up to choosing  $x = \tau + h$  for suitable constant  $h$  and recalling the definition of  $\bar{u}$ , we get  $u(x, y) = cx$  on  $M$ , which proves (ii). To conclude, observe that since  $\tilde{\gamma}$  is an asymptote of  $\gamma$ , then necessarily  $\gamma$  is of the type  $(-\infty, a] \times \{y_1\}$  for some  $y_1$ . Direct computation of  $b_\gamma$  shows that  $b_\gamma(\tau, y) = \tau - a$  and thus  $\bar{u} - b_\gamma$ , hence  $u - cb_\gamma$ , is constant.  $\square$

**Remark 3.6.** Note that the completeness assumption on  $M$  is crucial. Indeed, on  $\mathbb{R}^m \setminus \{0\}$  the function  $-|x|$  is  $\infty$ -harmonic and  $-|x| + x_1$  attains infinitely many maximum points (see also [15, Exercise 2.9]).

## 4 Manifolds with $\text{Sec} \geq 0$

Let  $u \in C(M)$  satisfy  $\Delta_\infty u = 0$  and

$$\limsup_{r(q) \rightarrow \infty} \frac{u(q)}{r(q)} = 1. \quad (15)$$

By general theory, if  $\text{Sec} \geq 0$  then blowdowns at any fixed point  $o$  are unique (see [24, Lemma 3.4]), so we denote by  $M_\infty$  the blowdown and write  $M_j^\lambda \rightarrow M_\infty$ . By Theorem 3.1,  $\lambda$  induces a splitting  $M_\infty = \mathbb{R} \times N_\infty$  along a line  $\gamma_\infty^\lambda$  for which the blowdown  $v^\lambda$  of  $u$  writes as  $v^\lambda(x, y) = x$ ,  $o_\infty = (0, o'_\infty)$  and  $\gamma_\infty^\lambda(t) = (t, o'_\infty)$ . It is well-known that a splitting of  $M_\infty$  induces, if  $\text{Sec} \geq 0$ , a splitting of  $M$  itself (see [2, Thm. 4.6] for a proof). For our purposes, it is convenient to include the proof in the following lemma, which regards the behaviour of  $u$  along the split off line of  $M$ .

**Lemma 4.1.** *If  $\text{Sec} \geq 0$ , the line  $\gamma_\infty^\lambda(t) = (t, o'_\infty) \in M_\infty = \mathbb{R} \times N_\infty$  induces a unique line  $\gamma^\lambda : \mathbb{R} \rightarrow M$  passing through an origin  $o \in M$  whose blowdown is  $\gamma_\infty^\lambda$ . Moreover,*

$$\frac{u(\gamma^\lambda(\lambda_j R)) - u(\gamma^\lambda(-\lambda_j R))}{2\lambda_j R} \rightarrow 1 \quad \text{as } j \rightarrow \infty. \quad (16)$$

*Proof.* As we work for fixed  $\lambda$ , we omit its writing. Fix  $R > 0$ . We refer to the proof of Theorem 3.1 for the construction of  $\gamma_\infty$  and for notation, so let  $z_j^\pm \in M_j$  realize  $S_{\lambda_j R}^\pm(o)$ , let  $z_R^\pm \in M_\infty$  be their limits on  $M_\infty$  and let  $\gamma_R : [-R, R] \rightarrow M_\infty$  be the segment built therein to join  $z_R^-$  to  $z_R^+$ . By Remark 3.2,  $z_R^\pm = \gamma_R(\pm R) = \gamma_\infty(\pm R)$ . It follows that

$$M_j \ni z_j^\pm \longrightarrow \gamma_\infty(\pm R) \quad \text{as } j \rightarrow \infty, \quad (17)$$

We select segments  $\gamma_j^\pm : [0, \lambda_j R] \rightarrow M$  joining  $o$  to  $z_j^\pm$ . Up to subsequence,  $\gamma_j^\pm \rightarrow \gamma^\pm$  for some rays  $\gamma^\pm : [0, \infty) \rightarrow M$ . The concatenation

$$\gamma_j := -\gamma_j^- * \gamma_j^+ = \begin{cases} \gamma_j^-(t) & \text{for } t \in [-\lambda_j R, 0), \\ \gamma_j^+(t) & \text{for } t \in [0, \lambda_j R], \end{cases}$$

locally uniformly converges to  $\gamma = -\gamma^- * \gamma^+ : \mathbb{R} \rightarrow M$ . We prove that  $\gamma$  is a line, so fix  $S > 0$  and  $s \leq S$ . Then, by Toponogov's Theorem,

$$d(\gamma_j(-s), \gamma_j(s)) \geq d(z_j^-, z_j^+) \frac{s}{\lambda_j R}.$$

However,  $d(z_j^-, z_j^+) = \lambda_j d_j(z_j^-, z_j^+) = 2\lambda_j R(1 + o_j(1))$ , whence

$$d(\gamma_j(-s), \gamma_j(s)) \geq 2s(1 + o_j(1)).$$

Therefore, the excess

$$0 \leq d(\gamma_j(-s), o) + d(\gamma_j(s), o) - d(\gamma_j(-s), \gamma_j(s)) \leq 2s o_j(1) \leq 2S o_j(1)$$

converges to zero uniformly for  $s \in [0, S]$ , which proves that  $\gamma$  is a line. We next point out that the blowdown of  $\gamma$  is exactly  $\gamma_\infty$ . Applying the cosine law to the hinge  $(o, \gamma, \gamma_j)$  and using that the angle

$$\angle(\dot{\gamma}_j^\pm(0), \dot{\gamma}^\pm(0)) \rightarrow 0 \quad \text{as } j \rightarrow \infty,$$

we deduce

$$d(\gamma(\pm\lambda_j R), z_j^\pm)^2 \leq 2(\lambda_j R)^2 - 2(\lambda_j R)^2 \cos \angle(\dot{\gamma}_j^\pm(0), \dot{\gamma}^\pm(0)) = o_j(\lambda_j^2 R^2). \quad (18)$$

Rescaling, we get

$$d_j(\gamma(\pm\lambda_j R), z_j^\pm) \rightarrow 0 \quad \text{as } j \rightarrow \infty,$$

and by the triangle inequality and (17) we deduce

$$\gamma(\pm\lambda_j R) \subset M_j^\lambda \rightarrow \gamma_\infty(\pm R).$$

Therefore, the blowdown of  $\gamma$  (which is clearly a line in  $M_\infty^\lambda$ ) restricted to  $[-R, R]$  is a segment joining  $\gamma_\infty(-R)$  to  $\gamma_\infty(R)$ . Since  $\gamma_\infty$  is the only such segment, we conclude from the arbitrariness of  $R$  that  $\gamma$  blows down to  $\gamma_\infty$ . If there were a line  $\sigma \neq \gamma$  with  $\sigma(0) = o$  whose blowdown is  $\gamma_\infty$ , writing

$$\sigma(s) = (b_1 s, \bar{\sigma}(s)) \in \mathbb{R} \times N \quad \text{with } |b_1| < 1,$$

the curve  $\bar{\sigma} : \mathbb{R} \rightarrow N$  would be a line in  $N$ . Since  $N$  has non-negative sectional curvature, the splitting theorem would guarantee that

$$M = \mathbb{R} \times \mathbb{R} \times N', \quad \text{with } \begin{cases} \gamma(t) = (t, 0, o''), \\ \sigma(s) = (b_1 s, b_2 s, \hat{\sigma}(s)) \end{cases}$$

for some  $o'' \in N'$ ,  $b_2 \in (0, 1)$  and line  $\hat{\sigma}$  in  $N'$ , which is incompatible with the assumption that  $\sigma$  blows down to  $\gamma_\infty$ .

To prove (16), observe that by definition of  $z_j^\pm$ ,

$$\frac{u_j(z_j^\pm)}{R} = \frac{u(z_j^\pm) - u(o)}{\lambda_j R} \rightarrow \pm 1 \quad \text{as } j \rightarrow +\infty. \quad (19)$$

We consider

$$0 \leq 1 - \frac{u(\gamma(\lambda_j R)) - u(\gamma(-\lambda_j R))}{2\lambda_j R} = 1 - \frac{u(z_j^+) - u(z_j^-)}{2\lambda_j R} + A_+ - A_- \quad (20)$$

where

$$A_\pm = \frac{u(\gamma(\pm\lambda_j R)) - u(z_j^\pm)}{2\lambda_j R}.$$

Using  $\text{Lip}(u, M) = 1$  and (18) we get

$$|A_\pm| \leq \frac{d(\gamma(\pm\lambda_j R), z_j^\pm)}{2\lambda_j R} \rightarrow 0 \quad \text{as } j \rightarrow \infty,$$

whence letting  $j \rightarrow \infty$  in (20) and using (19) we conclude (16).  $\square$

We first study the 2-dimensional case, where Theorem 3.1 and Savin's result [40] are enough to give a full classification.

*Proof of Theorem 1.3.* By Theorem 3.1 and Lemma 4.1,  $M = \mathbb{R} \times N$  for some 1-dimensional complete manifold  $N$ , which is therefore either  $\mathbb{R}$  or  $\mathbb{S}^1$ . If  $M = \mathbb{R}^2$ , since  $u \in \text{Lip}(M)$  we can apply Savin's result to deduce that  $u$  is affine. If  $M = \mathbb{R} \times \mathbb{S}^1$ , we consider the universal covering  $\pi : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R} \times \mathbb{S}^1$  and the preimage  $\bar{u} = u \circ \pi$ , which is  $\infty$ -harmonic. Savin's result guarantees that  $\bar{u}$  is affine on  $\mathbb{R}^2$ , so  $\bar{u}(x, y) = ax + by + c$ . By construction,  $\bar{u}$  is bounded in the  $y$ -coordinate for any fixed  $x$ , thus  $b = 0$  and  $\bar{u}(x, y) = ax + c$  only depends on the first factor.  $\square$

In dimension  $m \geq 3$ , we are going to show uniqueness of the blowdown of  $u$ . This depends on refined one-sided gradient estimates for solutions to approximate problems which were obtained, in Euclidean setting, by Evans and Smart [22]. We closely follow the approach therein but with a different approximation, as we use solutions  $u_p$  to the  $p$ -Laplace equation

$$\begin{cases} \Delta_p u_p = 0 & \text{on } \Omega \Subset M, \\ u_p = u & \text{on } \partial\Omega \end{cases}$$

in the limit  $p \rightarrow \infty$ . The main properties of  $u_p$  are put off to the next section as not to interrupt the flow of the discourse. We begin with the following

**Lemma 4.2.** *Let  $M = \mathbb{R} \times \mathbb{R} \times N'$  be a complete manifold and let  $x^1, x^2, \pi : M \rightarrow \mathbb{R}$  be the natural projections onto the three factors. Consider a smooth function  $u : M \rightarrow \mathbb{R}$  satisfying*

$$\max_{B_T} |u - b_1 x^1 - b_2 x^2| < \eta T,$$

for some  $\eta, T > 0$ , where  $B_T$  is a geodesic ball centered at  $o = (0, 0, \delta)$ . Then, there exists an interior point  $q_0 \in B_T$  such that

$$|\partial_{x^i} u(q_0) - b_i| \leq 4\eta, \quad \text{for } i = 1, 2, \quad (21)$$

$$|\nabla^{N'} u(q_0)| \leq 4\eta. \quad (22)$$

*Proof.* Consider the auxiliary function

$$w = b_1 x^1 + b_2 x^2 - 2\frac{\eta}{T}\rho^2, \quad \rho(q) \doteq d_M(q, o).$$

We observe that  $(u - w)(o) < \eta T$  and  $(u - w)(q) \geq \eta T$  for any  $q \in \partial B_T$ . Therefore there exists an interior minimum point  $q_0 \in B_T$ . If  $\rho$  is smooth around  $q_0$ , the desired conclusion follows from  $\nabla(u - w)(q_0) = 0$ . Otherwise, we use Calabi's trick by considering a unit speed minimizing geodesic  $\gamma$  from  $o$  to  $q_0$  and the function  $\rho_\varepsilon$  with  $\rho_\varepsilon(q) = \varepsilon + d_M(\gamma(\varepsilon), q)$ . From  $\rho_\varepsilon \geq \rho$  on  $M$  with equality at  $q_0$ , and since  $\rho_\varepsilon$  is smooth near  $q_0$  as shown in [38, end of Lemma 7.1.9], the conclusion follows as above by replacing  $\rho$  with  $\rho_\varepsilon$ .  $\square$

With the above preparation, we are ready to prove the main result of this section, which generalizes [25, Proposition 2].

**Theorem 4.3.** *Let  $M$  be a complete manifold with  $\text{Sec} \geq 0$ , and let  $u \in C(M)$  be an  $\infty$ -harmonic function such that*

$$\limsup_{r(q) \rightarrow \infty} \frac{u(q)}{r(q)} = 1, \quad (23)$$

where  $r$  is the distance from a fixed origin. Then, for each  $o \in M$  the blowdown  $v_\infty$  of  $u$  at  $o$  does not depend on the chosen sequence, and there exists a splitting  $M = (\mathbb{R} \times N, dx^2 + g_N)$  for some complete manifold  $(N, g_N)$  such that

$$\lim_{x \rightarrow +\infty} \frac{u(x, y) - u(-x, y)}{2x} \rightarrow 1 \quad \forall y \in N. \quad (24)$$

Moreover, in the splitting  $M_\infty = \mathbb{R} \times N_\infty$  induced by  $M = \mathbb{R} \times N$ , it holds  $v_\infty(x, y) = x$ .

*Proof.* We already know by Lemma 2.2 that  $\text{Lip}(u, M) = 1$ . We introduce some notation. Let  $M_j^\lambda \rightarrow M_\infty$  be a tangent cone with associated blowdown  $u_j^\lambda \rightarrow v^\lambda$ , and let  $\mathbb{R} \times N$  be the splitting of  $M$  induced by the line  $\gamma^\lambda$ . Write  $o = (0, o') \in \mathbb{R} \times N$ . Notice that, by Lemma 4.1,  $N_\infty$  is the tangent cone of  $N$  at  $o'$ . Also, (16) guarantees that (24) holds with  $y = o'$  provided that the blowdown  $v^\lambda$  does not depend on  $\lambda$ . Once (24) is shown for  $y = o'$ , its validity for any fixed  $y$  immediately follows from the triangle inequality, since

$$\left| u(x, y) - u(-x, y) - (u(x, o') - u(-x, o')) \right| \leq 2d_N(y, o').$$

To conclude the proof we assume, by contradiction, the existence of a sequence  $\mu = \{\mu_k\} \rightarrow \infty$  such that the blowdown  $u_k^\mu \rightarrow v^\mu$  associated to the tangent cone  $M_k^\mu \rightarrow M_\infty$  satisfies  $v^\mu \neq v^\lambda$ . Consider the line  $\gamma_\infty^\mu$  in  $M_\infty$  induced by  $\mu$ . From  $v^\mu(\gamma_\infty^\mu(s)) = s$  and  $v^\mu \neq v^\lambda$ , we deduce  $\gamma_\infty^\mu \neq \gamma_\infty^\lambda$  and therefore, in the splitting  $\mathbb{R} \times N_\infty$  induced by  $\gamma_\infty^\lambda$ , we can write

$$\gamma_\infty^\mu(s) = (b_1 s, \sigma_\infty^\mu(s)), \quad b_1^2 + |\dot{\sigma}_\infty^\mu|^2 = 1.$$

Since  $\sigma_\infty^\mu$  is a line as well, it induces a splitting  $N_\infty = \mathbb{R} \times \tilde{N}_\infty$  and, by Lemma 4.1, a corresponding splitting  $N = \mathbb{R} \times \tilde{N}$ . Summarizing, we can write

$$M_\infty = \mathbb{R} \times \mathbb{R} \times \tilde{N}_\infty, \quad o_\infty = (0, 0, \tilde{o}_\infty)$$

with induced projections  $(x_\infty^1, x_\infty^2, \pi_\infty) : M_\infty \rightarrow \mathbb{R} \times \mathbb{R} \times \tilde{N}_\infty$ , and in these coordinates

$$\gamma_\infty^\lambda(t) = (t, 0, \tilde{o}_\infty), \quad \gamma_\infty^\mu(s) = (b_1 s, b_2 s, \tilde{o}_\infty), \quad \text{with } b_1^2 + b_2^2 = 1, \quad b_2 \neq 0.$$

Accordingly,

$$M = \mathbb{R} \times \mathbb{R} \times \tilde{N}, \quad o = (0, 0, \tilde{o})$$

with projections  $(x^1, x^2, \pi)$ , and

$$\gamma^\lambda(t) = (t, 0, \tilde{o}), \quad \gamma^\mu(s) = (b_1 s, b_2 s, \tilde{o}), \quad \text{with } b_1^2 + b_2^2 = 1, \quad b_2 \neq 0.$$

In these coordinates

$$v^\lambda = x_\infty^1, \quad v^\mu = b_1 x_\infty^1 + b_2 x_\infty^2,$$

whence

$$u_j^\lambda \rightarrow x_\infty^1, \quad u_k^\mu \rightarrow b_1 x_\infty^1 + b_2 x_\infty^2$$

pointwise in the Gromov-Hausdorff sense. Also, associated to the tangent cone  $M_j^\lambda \rightarrow M_\infty$  we define coordinates

$$x_{\lambda,j}^1 = \frac{x^1}{\lambda_j}, \quad x_{\lambda,j}^2 = \frac{x^2}{\lambda_j},$$

which are 1-Lipschitz on  $M_j^\lambda$ . By construction,  $x_{\lambda,j}^i \rightarrow x_\infty^i$  pointwise in the Gromov-Hausdorff sense for each  $i \in \{1, 2\}$ . Likewise, the coordinates

$$x_{\mu,k}^1 = \frac{x^1}{\mu_k} \quad \text{and} \quad x_{\mu,k}^2 = \frac{x^2}{\mu_k} \quad \text{on } M_k^\mu$$

satisfy  $x_{\mu,k}^i \rightarrow x_\infty^i$ . It easily follows that, for each  $\ell > 0$ , there exists  $j_0(\ell)$  such that

$$\max_{q \in B_{\lambda_j}} |u(q) - x^1(q)| < \ell \lambda_j \quad \text{for } j \geq j_0(\ell). \quad (25)$$

Indeed, otherwise, there exist  $\ell > 0$  and points  $q_j \in B_{\lambda_j} \subset M$  such that

$$\ell \leq |u_j^\lambda(q_j) - x_{\lambda,j}^1(q_j)|.$$

Up to a subsequence,  $q_j \in B_1^j \subset M_j^\lambda$  converges to  $q_\infty \in B_1^\infty$  and therefore

$$\begin{aligned} \ell &\leq |u_j^\lambda(q_j) - x_{\lambda,j}^1(q_j)| \leq |u_j^\lambda(q_j) - x_\infty^1(q_\infty)| + |x_\infty^1(q_\infty) - x_{\lambda,j}^1(q_j)| \\ &\rightarrow 0 \quad \text{as } j \rightarrow \infty, \end{aligned}$$

contradiction. Similarly to (25), for the tangent cone  $M_k^\mu \rightarrow M_\infty$  and for  $\eta > 0$  we obtain

$$\max_{q \in B_{\mu_k}} |u(q) - b_1 x^1(q) - b_2 x^2(q)| < \eta \mu_k \quad \text{for } k \geq k_0(\eta). \quad (26)$$

Consider for each  $p > 2$  and  $j$  the solution  $u_{p,j}$  to

$$\begin{cases} \Delta_p u_{p,j} = 0 & \text{on } B_{2\lambda_j}, \\ u_{p,j} = u & \text{on } \partial B_{2\lambda_j}. \end{cases}$$

As recalled in Section 5,  $u_{p,j} \rightarrow u$  uniformly on  $\overline{B_{2\lambda_j}}$  as  $p \rightarrow \infty$ . Moreover, by (25) we get

$$\ell \geq \lambda_j^{-1} \|u_{p,j} - x^1\|_{L^\infty(B_{\lambda_j})} \quad \text{for } p \geq p_j \text{ large.} \quad (27)$$

Therefore, since  $\text{Sec} \geq 0$  and  $u$  is 1-Lipschitz, Theorems 5.1 and 5.3 with  $p \geq \ell^{-1}$  guarantee the existence of a constant  $C = C(m, u(o))$  such that

$$|\nabla u_{p,j}| \leq C, \quad |\nabla u_{p,j}|^2 \leq \partial_1 u_{p,j} + C \ell^{\frac{1}{8}} (1 + \ell)^{\frac{5}{4}} \quad \text{on } B_{\lambda_j/2}.$$

We now choose  $\ell, \eta$ . First, define

$$\theta = 1 - b_1 \in (0, 1),$$

and let  $\ell, \eta > 0$  small enough to satisfy

$$C \ell^{\frac{1}{8}} (1 + \ell)^{\frac{5}{4}} < \frac{\theta}{4}, \quad \eta < \frac{3\theta}{4 \cdot 28}.$$

Therefore,

$$|\nabla u_{p,j}|^2 \leq \partial_1 u_{p,j} + \frac{\theta}{4} \quad \forall j \geq j_0(\ell). \quad (28)$$

For  $k_0 = k_0(\eta)$  as in (26), choose  $j_1 = j_1(\eta)$  such that  $\lambda_{j_1} \geq 2\mu_{k_0}$  and let

$$j_2(\ell, \eta) = \max\{j_0(\ell), j_1(\eta)\}.$$

We choose  $j = j_2$  and write  $u_p = u_{p,j_2}$  for ease of notation. From  $B_{\mu_{k_0}} \subset B_{\lambda_{j_2}/2}$  and the uniform convergence  $u_p \rightarrow u$  as  $p \rightarrow \infty$ , and from (25), (26), we infer the existence of  $p_1 = p_1(\ell, \eta)$  for which

$$\max_{q \in B_{\mu_{k_0}}} |u_p(q) - b_1 x^1(q) - b_2 x^2(q)| < \eta \mu_{k_0} \quad \text{for } p \geq p_1. \quad (29)$$

Using Lemma 4.1, we get the existence of  $q_0 \in B_{\mu_{k_0}}$  such that

$$|\partial_1 u_p(q_0)| \leq b_1 + 4\eta,$$

$$|\nabla u_p(q_0)| \geq 1 - |(b_1 - \partial_1 u_p)\partial_{x^1} + (b_2 - \partial_2 u_p)\partial_{x^2} - \nabla^{N'} u_p(q_0)| \geq 1 - 12\eta.$$

On the other hand, (28) and  $B_{\mu_{k_0}} \subset B_{\lambda_{j_2}/2}$  give  $|\nabla u_p(q_0)|^2 \leq \partial_1 u_p(q_0) + \theta/4$ . Putting together the estimates we conclude

$$1 - 24\eta \leq (1 - 12\eta)^2 \leq |\nabla u_p(q_0)|^2 \leq b_1 + 4\eta + \frac{\theta}{4} = 1 - \frac{3\theta}{4} + 4\eta,$$

contradicting our choice for  $\eta$ .  $\square$

We conclude this section with a sufficient condition for the function  $u$  in Theorem 4.3 to depend only on the variable  $x$ . The result below is inspired by the proof of the ‘‘Half-space theorem’’ in [16, Thm. 4.1], which guarantees that a solution to  $\Delta_\infty u \geq 0$  on  $\mathbb{R}^m$  is affine provided that it lies below an affine function. However, our statement is significantly different: on the one hand, it only applies to  $\infty$ -harmonic functions, while on the other hand the extra condition we require is only localised on a single ray.

**Theorem 4.4.** *Let  $M$  be a complete manifold with  $\text{Sec} \geq 0$ , and let  $u \in C(M)$  be an  $\infty$ -harmonic function such that*

$$\limsup_{r(q) \rightarrow \infty} \frac{u(q)}{r(q)} = 1, \quad (30)$$

where  $r$  is the distance from a fixed origin. Assume that there exist a ray  $\gamma$  and a constant  $C$  such that either

$$u(\gamma(t)) \geq t - C \quad \text{or} \quad u(\gamma(t)) \leq -t + C$$

for each  $t \in \mathbb{R}^+$ . Then, there exists a splitting  $M = (\mathbb{R} \times N, dx^2 + g_N)$  for some complete manifold  $(N, g_N)$  such that  $u(x, y) = x$  for each  $(x, y) \in \mathbb{R} \times N$ .

*Proof.* In our assumptions, we know that  $\text{Lip}(u, M) = 1$ . Define  $o = \gamma(0)$ . By Theorem 4.3,  $M$  splits as  $\mathbb{R} \times N$  with metric  $dx^2 + g_N$  in such a way that (24) is satisfied. In particular, (30) holds both for  $u$  and for  $-u$ . Up to changing the sign of  $u$ , we can therefore assume that

$$u(\gamma(t)) \leq -t + C \quad \forall t \in \mathbb{R}^+. \quad (31)$$

We first claim that in coordinates  $(x, y)$  we have  $\gamma(t) = (-t, o')$ . Indeed, let  $M_\infty = \mathbb{R} \times N_\infty$  be the blow-down of  $M$  at  $o$ ,  $o_\infty = (0, o'_\infty)$  its reference point and  $u_\infty, \gamma_\infty$  the associated blowdowns of  $u$  and  $\gamma$ . We know by Theorem 3.1 that  $u_\infty(x, y) = x$ , with  $x$  the arclength of the  $\mathbb{R}$ -factor properly oriented. Blowing down (31) and using that  $u$ , hence  $u_\infty$ , is 1-Lipschitz we deduce  $u_\infty(\gamma_\infty(t)) = -t$  for each  $t \in \mathbb{R}^+$ . Writing  $\gamma_\infty(t) = (b_1 t, \sigma_\infty(t)) \in \mathbb{R} \times N_\infty$  with  $b_1^2 + |\sigma'_\infty|^2 = 1$  we get  $\gamma_\infty(t) = (-t, o'_\infty)$ . Our claim follows by the uniqueness part in Lemma 4.1. We therefore proved that

$$u(x, o') - x \leq C \quad \forall x \in (-\infty, 0]. \quad (32)$$

Since  $\text{Lip}(u, M) = 1$ , the function  $x \mapsto \delta(x, y) \doteq u(x, y) - x$  is non-increasing on  $\mathbb{R}$  (thus, (32) holds for each  $x \in \mathbb{R}$ ). Let us call  $\delta(-\infty, y)$  its limit as  $x \rightarrow -\infty$ . By assumption,  $\delta(-\infty, y_0)$  is finite. We prove that  $\delta(-\infty, y)$  does not depend on  $y$ . First, since  $u$  is 1-Lipschitz we have

$$|\delta(x, y) - \delta(x, y_0)| = |u(x, y) - u(x, y_0)| \leq d_N(y, y_0) \quad \forall x \in \mathbb{R},$$

whence  $\delta(-\infty, y)$  is finite for each  $y$ . Again since  $u$  is 1-Lipschitz,

$$\begin{aligned} |x + \delta(x, y) - \lambda - \delta(\lambda, y_0)|^2 &= |u(x, y) - u(\lambda, y_0)|^2 \\ &\leq (x - \lambda)^2 + d_N(y, y_0)^2. \end{aligned}$$

Expanding the squares and rearranging,

$$[\delta(x, y) - \delta(\lambda, y_0)]^2 + 2(x - \lambda)(\delta(x, y) - \delta(\lambda, y_0)) \leq d_N(y, y_0)^2.$$

Discarding the first term on the left hand side, putting  $x = 2\lambda < 0$ , dividing by  $\lambda$  and letting  $\lambda \rightarrow -\infty$  gives  $\delta(-\infty, y) - \delta(-\infty, y_0) \geq 0$ . On the other hand, letting  $x = \lambda/2 < 0$ , dividing by  $\lambda$  and letting  $\lambda \rightarrow -\infty$  gives  $\delta(-\infty, y) - \delta(-\infty, y_0) \leq 0$ . Hence,  $\delta(-\infty, y) = \delta(-\infty, y_0)$ .

Up to translating  $u$ , we can therefore assume

$$\delta(-\infty, y) = 0 \quad \text{for each } y \in N$$

so that

$$u(x, y) \leq x \quad \forall (x, y) \in M, \quad \text{and} \quad \lim_{x \rightarrow -\infty} (x - u(x, y)) = 0.$$

By contradiction, we assume that  $u(x_0, y_0) < x_0$  for some  $(x_0, y_0) \in M$ . Defining  $v(x, y) \doteq u(x + x_0, y) - x_0$ , we observe that  $v$  is an  $\infty$ -harmonic function satisfying

$$\lim_{x \rightarrow -\infty} (x - v(x, y)) = 0 \quad \text{and} \quad v(x, y) \leq x, \quad \text{with} \quad v(0, y_0) < 0. \quad (33)$$

Fix  $\mu > 0$  such that  $v(0, y_0) \leq -\mu$ . Since  $|\nabla v| \leq 1$  a.e. in  $M$ , we get

$$v(x, y) \leq \sqrt{|x|^2 + d_N(y, y_0)^2} - \mu. \quad (34)$$

Next, for  $R > r$  we consider the sphere and ball of radius  $R$  in  $\mathbb{R} \times N$  centered at  $(-r, y_0)$ :

$$S_R = \left\{ (x, y) : \sqrt{|x + r|^2 + d_N(y, y_0)^2} = R \right\},$$

and

$$\bar{B}_R = \left\{ (x, y) : \sqrt{|x + r|^2 + d_N(y, y_0)^2} \leq R \right\}.$$

In order to obtain an upper bound for  $v(x, y)$  on  $S_R$ , on the one hand  $v(x, y) \leq x$ , while on the other hand, by (34),

$$\begin{aligned} v(x, y) &\leq -\mu + \sqrt{|x|^2 + d_N(y, y_0)^2} \\ &= -\mu + \sqrt{(x + r)^2 - 2rx - r^2 + d_N(y, y_0)^2} \\ &= -\mu + \sqrt{R^2 - 2rx - r^2} \quad \text{on } S_R. \end{aligned} \quad (35)$$

Whence, for each  $(x, y) \in S_R$  we have

$$v(x, y) \leq \max_{x \in [-R-r, R-r]} \min \left\{ x, -\mu + \sqrt{R^2 - 2rx - r^2} \right\}.$$

Since the function  $\sqrt{R^2 - 2rx - r^2}$  is decreasing in  $x$ , the maximum is attained when

$$x \in [-R - r, R - r] \quad \text{solves} \quad x = -\mu + \sqrt{R^2 - 2rx - r^2},$$

that is,  $x = -\mu - r + \sqrt{R^2 + 2\mu r}$ . Concluding,

$$v(x, y) \leq \sqrt{R^2 + 2\mu r} - \mu - r = -r + \frac{\sqrt{R^2 + 2\mu r} - \mu}{R} \sqrt{|x + r|^2 + d_N(y, y_0)^2} \quad \text{on } S_R.$$

The same inequality is also satisfied at the vertex  $(-r, y_0)$ . Therefore, by the comparison with cone property,

$$v(x, y) \leq -r + \frac{\sqrt{R^2 + 2\mu r} - \mu}{R} \sqrt{|x + r|^2 + d_N(y, y_0)^2} \quad \text{on } B_R.$$

To conclude the proof, for  $0 \leq s < r$  we choose  $x = -s$  and  $y = y_0$  to deduce

$$u(-s, y_0) - (-s) \leq \left( -1 + \frac{\sqrt{R^2 + 2\mu r} - \mu}{R} \right) (r - s).$$

Taking  $R = 2r$  and letting  $r \rightarrow \infty$ , we infer

$$u(-s, y_0) - (-s) \leq -\frac{\mu}{4} < 0,$$

which implies by letting  $s \rightarrow \infty$  that  $\delta(-\infty, y_0) \leq -\mu/4$ , a contradiction.  $\square$

## 5 On the approximation via $p$ -harmonic functions

Let  $u \in C(M)$  solve  $\Delta_\infty u = 0$  on  $M$ . In this section, we prove the relevant gradient and one-side gradient estimates for  $p$ -harmonic approximations of  $u$  that are used in the proof of Theorem 4.3. In Euclidean setting, the result is due to Evans and Smart [22], where it is used to infer the uniqueness of the blowup of  $u$  at a given point and, consequently, the everywhere differentiability of  $u$ . Therein, for  $\varepsilon > 0$  the authors choose to approximate  $\Delta_\infty$  with the operator

$$\Delta_{\infty, \varepsilon} \phi = \varepsilon e^{-\frac{|\nabla \phi|^2}{2\varepsilon}} \operatorname{div} \left( e^{\frac{|\nabla \phi|^2}{2\varepsilon}} \nabla \phi \right) = \Delta_\infty \phi + \varepsilon \Delta \phi$$

and, for each  $R > 0$ , the function  $u$  with the solution  $u_\varepsilon$  to the problem

$$\begin{cases} \Delta_{\infty, \varepsilon} u_\varepsilon = 0 & \text{on } B_R, \\ u_\varepsilon = u & \text{on } \partial B_R. \end{cases}$$

While their arguments can be adapted to the manifold setting, we prefer to approximate via the  $p$ -Laplace operator, in the hope that its peculiar features (notably its homogeneity) may be further exploited to get even sharper estimates in the direction of those required in [21].

Fix a smooth, relatively compact set  $\Omega$ , and for  $p \in (1, \infty)$  consider the solution  $u_p$  to

$$\begin{cases} \Delta_p u_p \doteq \operatorname{div} (|\nabla u_p|^{p-2} \nabla u_p) = 0 & \text{on } \Omega, \\ u_p = u & \text{on } \partial\Omega. \end{cases} \quad (36)$$

It is known by [8] and the uniqueness result in [4, 27] that  $u_p \rightarrow u$  uniformly on  $\overline{\Omega}$  as  $p \rightarrow \infty$ . Moreover,  $u_p \in C^{1, \alpha}(\Omega)$  and it is  $C^\infty$  on the open set  $\{|\nabla u_p| > 0\}$ . In a manifold setting, a sharp local gradient estimate for  $p$ -harmonic functions was obtained by Kotschwar and Ni in [30, Thm. 1.1], see also [42]. While they were interested in the limit  $p \rightarrow 1$ , in our setting their estimate implies the following simpler one, which is enough for our purposes.

**Theorem 5.1.** Assume that  $u_p$  is  $p$ -harmonic on a ball  $B_{2R}(o) \Subset M^m$ , and that  $\text{Sec} \geq -\kappa^2$  on  $B_{2R}(o)$ . Then,

$$\sup_{B_R(o)} |\nabla \log u_p|^2 \leq \frac{C_m}{(p-1)^2} \left( \frac{p^2}{R^2} + \frac{p\kappa}{R} + \kappa^2 \right),$$

where  $C_m$  only depends on  $m$ .

As a consequence, if  $R \geq 1$  and  $u_p$  solves (36) on  $\Omega = B_{2R}(o)$ , then for  $p \geq R$  we have

$$|\nabla u_p(x)| \leq C_m (1 + \kappa) \frac{u(x)}{R} \quad \forall x \in B_R(o).$$

Theorem 5.1 is obtained by a careful application of the improved version of Cheng-Yau's technique to a suitable Bochner formula for the  $p$ -Laplacian, which we now recall. Formally differentiating the  $p$ -Laplacian at  $u_p$  we get the linearized operator

$$\phi \mapsto \frac{d}{dt} \Big|_{t=0} \Delta_p(u_p + t\phi) = \text{div} (A(\nabla u_p) \nabla \phi)$$

where, for a nonzero vector  $X \in T_x M$ ,  $A(X) : T_x M \rightarrow T_x M$  is the endomorphism

$$A(X) = |X|^{p-2} \left( (p-2) \left\langle \frac{X}{|X|}, \cdot \right\rangle \frac{X}{|X|} + \text{id} \right).$$

Notice that  $A(X)$  has eigenvalues  $(p-1)|X|^{p-2}$  in direction  $X$  and  $|X|^{p-2}$  on  $X^\perp$ . For each  $x \in \{|\nabla u_p| > 0\}$  we consider a local orthonormal frame  $\{v, e_j\}$  with  $v = \nabla u_p / |\nabla u_p|$  and  $\{e_j\}$ ,  $2 \leq j \leq m$  tangent to the level sets of  $u_p$ . Then the following Bochner formula in [36, Prop. 2.14] holds:

$$\begin{aligned} \frac{1}{2} \text{div} (A(\nabla u_p) \nabla |\nabla u_p|^2) &= \\ &= |\nabla u_p|^{p-2} \left\{ (p-1)u_{vv}^2 + p \sum_j u_{vj}^2 + \sum_{i,j} u_{ij}^2 + \text{Ric}(\nabla u_p, \nabla u_p) \right\}, \end{aligned} \quad (37)$$

where  $u_{vv}, u_{vj}, u_{ij}$  are the components of  $\nabla^2 u_p$ . For convenience, we also consider the normalized linearization

$$\mathcal{L}_p \phi = \frac{d}{dt} \Big|_{t=0} \frac{\Delta_p(u_p + t\phi)}{|\nabla(u_p + t\phi)|^{p-2}} = |\nabla u_p|^{2-p} \text{div} (A(\nabla u_p) \nabla \phi).$$

So that the above Bochner formula simplifies to

$$\begin{aligned} \frac{1}{2} \mathcal{L}_p |\nabla u_p|^2 &= (p-1)u_{vv}^2 + p \sum_j u_{vj}^2 + \sum_{i,j} u_{ij}^2 + \text{Ric}(\nabla u_p, \nabla u_p) \\ &= (p-2)|\nabla^2 u_p(v)|^2 + |\nabla^2 u_p|^2 + \text{Ric}(\nabla u_p, \nabla u_p) \\ &\geq (p-1)|\nabla^2 u_p(v)|^2 + \text{Ric}(\nabla u_p, \nabla u_p). \end{aligned} \quad (38)$$

We shall rewrite  $\mathcal{L}_p$  in trace form. Let  $\{e^a\}$ ,  $1 \leq a, b \leq m$  be the dual coframe of  $\{e_a\}$ . The components of  $A(\nabla u_p)$  satisfy

$$A_b^a = |\nabla u|^{p-2} \left[ \delta_b^a + (p-2) \frac{u^a u_b}{|\nabla u|^2} \right],$$

and expanding  $\Delta_p u_p = 0$  we get

$$\Delta u = -(p-2)u_{vv}.$$

Therefore, a computation gives

$$[\operatorname{div} A(\nabla u_p)]_b e^b = A_{b,a}^a e^b = 2(p-2)|\nabla u|^{p-3} u_{vj} e^j.$$

It follows that in components

$$\begin{aligned} \mathcal{L}_p \phi &= |\nabla u|^{2-p} (A_b^a \phi^b)_a = |\nabla u|^{2-p} A_b^a \phi_a^b + 2(p-2)|\nabla u|^{-1} u_{vj} \phi^j \\ &= \left[ \delta_b^a + (p-2) \frac{u^a u_b}{|\nabla u|^2} \right] \phi_a^b + 2(p-2)|\nabla u|^{-1} u_{vj} \phi^j. \end{aligned} \quad (39)$$

Assume that  $M$  splits as  $\mathbb{R} \times N$  with coordinates  $(x, y)$  and metric  $dx^2 + g_N$ , and consider the function  $\partial_x u_p = \langle \nabla u_p, \partial_x \rangle$ . Since  $\partial_x$  is a Killing field,

$$\mathcal{L}_p(\partial_x u_p) = 0 \quad \text{on } \{|\nabla u_p| > 0\}. \quad (40)$$

Furthermore, by using (39) we get

$$|\mathcal{L}_p x| \leq 2|p-2||\nabla u|^{-1} |\nabla^2 u(v)|. \quad (41)$$

We next estimate  $\mathcal{L}_p \varphi^2$  when  $\varphi$  is a cut-off depending on the distance from a fixed point.

**Lemma 5.2.** *Assume that  $\operatorname{Sec} \geq -\kappa^2$  in a ball  $B_{2R} \Subset M$ , for some  $\kappa \in \mathbb{R}_0^+$ . Then, there exists a function  $\varphi \in \operatorname{Lip}_c(B_{2R})$  such that  $0 \leq \varphi \leq 1$ ,  $\varphi \equiv 1$  on  $B_R$  and, for  $p \geq m$ ,*

$$|\nabla \varphi| \leq \frac{C}{R}, \quad \mathcal{L}_p \varphi^2 \geq -Cp\varphi(C_R + R^{-1}|\nabla u|^{-1}|\nabla^2 u(v)|)$$

in the barrier sense, where  $C$  is an absolute constant and  $C_R \doteq R^{-2}(1 + \kappa R)$ .

*Proof.* Let  $\eta \in C_c^\infty([0, 2])$  satisfy

$$0 \leq \eta \leq 1, \quad \eta \equiv 1 \text{ on } [0, 1], \quad \eta' \leq 0, \quad |\eta'| + |\eta''| \leq C,$$

and let  $\varphi(x) = \eta(r(x)/R)$  where  $r$  is the distance from the center of the ball. Setting

$$\operatorname{tn}_\kappa(t) = \begin{cases} \kappa \coth(\kappa t) & \text{if } \kappa > 0, \\ 1/t & \text{if } \kappa = 0, \end{cases}$$

by the Hessian comparison theorem

$$\nabla^2 r \leq \operatorname{tn}_\kappa(r) \left( \langle \cdot, \cdot \rangle - dr^2 \right)$$

in the barrier (i.e. support) sense, see [38, Lem. 12.2.4]. Noting that  $\eta' = 0$  on  $[0, 1]$ , we have

$$\begin{aligned} \nabla^2 \varphi &= \eta'' R^{-2} dr^2 + \eta' R^{-1} \nabla^2 r \geq -C R^{-2} dr^2 + \eta' R^{-1} \operatorname{tn}_\kappa(R) \left( \langle \cdot, \cdot \rangle - dr^2 \right) \\ &\geq -C R^{-2} (1 + R \operatorname{tn}_\kappa(R)) \langle \cdot, \cdot \rangle \geq -C C_R \langle \cdot, \cdot \rangle \end{aligned} \quad (42)$$

for suitable  $C$ , where we used that  $\text{Rtn}_\kappa(R) \leq 1 + \kappa R$ . Whence, using (39) and for  $p \geq m$ ,

$$\begin{aligned}
\mathcal{L}_p \varphi &= \left[ \delta_b^a + (p-2) \frac{u^a u_b}{|\nabla u|^2} \right] \varphi_a^b + 2(p-2) |\nabla u|^{-1} u_{vj} \varphi^j \\
&= (p-1) \varphi_{vv} + \varphi_{jj} + 2(p-2) |\nabla u|^{-1} u_{vj} \varphi^j \\
&\geq -C C_R p - 2(p-2) |\nabla u|^{-1} |\nabla^2 u(v)| |\nabla \varphi| \\
&\geq -C p (C_R + R^{-1} |\nabla u|^{-1} |\nabla^2 u(v)|)
\end{aligned} \tag{43}$$

and

$$\mathcal{L}_p \varphi^2 \geq 2\varphi \mathcal{L}_p \varphi, \tag{44}$$

from which the thesis follows.  $\square$

We now prove the one-side gradient estimate.

**Theorem 5.3.** *Let  $M^m = \mathbb{R} \times N$  be a complete manifold with metric  $dx^2 + g_N$ , and assume that  $N$  has  $\text{Sec} \geq -\kappa^2$ . Let  $u_p \in C^1(\overline{B_{2R}})$  solve  $\Delta_p u_p = 0$  on  $B_{2R}$ . Then, for*

$$\ell \geq R^{-1} \|u - x\|_{L^\infty(B_{2R})}, \quad A \geq 1 + \|\nabla u_p\|_{L^\infty(B_{2R})},$$

and  $p \geq 2$  there exists an absolute constant  $C$  such that

$$|\nabla u_p|^2 \leq \partial_x u_p + C m A^2 \ell^{\frac{1}{8}} (\ell + 1)^{\frac{5}{4}} \left[ 1 + \kappa R + \frac{1}{\ell^p} \right] \quad \text{on } B_R.$$

*Proof.* Let  $\varphi$  be a cut-off function. For convenience, we suppress the subscript  $p$  and simply write  $u$ . We consider

$$\Phi = |\nabla u|^2 - \partial_x u.$$

Because of (38), (40) and our assumptions on the sectional curvature, on the set  $\{\Phi > 0\}$  and setting  $v = \nabla u / |\nabla u|$  it holds

$$\mathcal{L}_p \Phi^2 \geq 2\Phi \mathcal{L}_p \Phi \geq 4(p-1)\Phi |\nabla^2 u(v)|^2 - 4(m-1)\kappa^2 \Phi |\nabla u|^2.$$

We compute on  $\{\Phi > 0\}$  the following expression:

$$\begin{aligned}
\mathcal{L}_p(\varphi^2 \Phi^2) &\geq \varphi^2 \mathcal{L}_p \Phi^2 + \Phi^2 \mathcal{L}_p \varphi^2 + 2(p-2) \langle v, \nabla \varphi^2 \rangle \langle v, \nabla \Phi^2 \rangle + 2 \langle \nabla \varphi^2, \nabla \Phi^2 \rangle \\
&\geq 4(p-1) \varphi^2 \Phi |\nabla^2 u(v)|^2 - 4(m-1) \kappa^2 \varphi^2 \Phi |\nabla u|^2 + \Phi^2 \mathcal{L}_p \varphi^2 \\
&\quad - 8(p-1) \Phi \varphi |\nabla \varphi| |\langle v, \nabla \Phi \rangle| - 8 \Phi \varphi |\nabla \varphi| |\nabla \Phi|.
\end{aligned}$$

Notice that  $\nabla \Phi = 2\nabla^2 u(\nabla u) - \nabla^2 u(e_1)$ , whence

$$|\langle v, \nabla \Phi \rangle| \leq 2|\nabla^2 u(v)|(1 + |\nabla u|), \quad |\nabla \Phi| \leq 2|\nabla^2 u|(1 + |\nabla u|).$$

Inserting into the above we get

$$\begin{aligned}
\mathcal{L}_p(\varphi^2 \Phi^2) &\geq 4(p-1) \varphi^2 \Phi |\nabla^2 u(v)|^2 - 4(m-1) \kappa^2 \varphi^2 \Phi |\nabla u|^2 + \Phi^2 \mathcal{L}_p \varphi^2 \\
&\quad - 16(p-1) \Phi \varphi |\nabla \varphi| |\nabla^2 u(v)|(1 + |\nabla u|) - 16 \Phi \varphi |\nabla \varphi| |\nabla^2 u|(1 + |\nabla u|).
\end{aligned}$$

On the other hand, we compute

$$\begin{aligned}
\mathcal{L}_p(u-x)^2 &\geq 2(u-x)\mathcal{L}_p(u-x) + 2(p-1)\langle v, \nabla(u-x) \rangle^2 \\
&\geq -2|u-x|\mathcal{L}_p x + 2(p-1)|\nabla u|^{-2} (|\nabla u|^2 - \partial_x u)^2 \\
&\geq -4|p-2||u-x||\nabla u|^{-1}|\nabla^2 u(v)| + 2(p-1)|\nabla u|^{-2}\Phi^2.
\end{aligned}$$

Let us define

$$w \doteq \varphi^2\Phi^2 + \beta R^{-2}(u-x)^2 + \ell|\nabla u|^2,$$

for some  $\beta > 0$  to be determined later. Notice that  $\beta, \ell$  are invariant under the natural scaling  $\langle \cdot, \cdot \rangle' = R^{-2}\langle \cdot, \cdot \rangle$  and  $u' = u/R$ . Let us assume that  $w$  attains its maximum at an interior point  $p_0$ . If  $\Phi(p_0) > 0$ , then

$$\begin{aligned}
0 &\geq \mathcal{L}_p w = \mathcal{L}_p(\varphi^2\Phi^2) + \beta R^{-2}\mathcal{L}_p(u-x)^2 + \ell\mathcal{L}_p|\nabla u|^2 \\
&\geq 4(p-1)\varphi^2\Phi|\nabla^2 u(v)|^2 - 4(m-1)\kappa^2\varphi^2\Phi|\nabla u|^2 + \Phi^2\mathcal{L}_p\varphi^2 \\
&\quad - 16(p-1)\Phi\varphi|\nabla\varphi||\nabla^2 u(v)|(1+|\nabla u|) - 16\Phi\varphi|\nabla\varphi||\nabla^2 u|(1+|\nabla u|)^2 \\
&\quad - 4|p-2|\beta R^{-2}|u-x||\nabla u|^{-1}|\nabla^2 u(v)| + 2(p-1)\beta R^{-2}|\nabla u|^{-2}\Phi^2 \\
&\quad + 2(p-2)\ell|\nabla^2 u(v)|^2 + 2\ell|\nabla^2 u|^2 - 2(m-1)\kappa^2\ell|\nabla u|^2.
\end{aligned}$$

Using that

$$\begin{aligned}
16\Phi\varphi|\nabla\varphi||\nabla^2 u(v)|(1+|\nabla u|) &\leq 2\varphi^2\Phi|\nabla^2 u(v)|^2 + 32\Phi|\nabla\varphi|^2(1+|\nabla u|)^2, \\
16\Phi\varphi|\nabla\varphi||\nabla^2 u|(1+|\nabla u|) &\leq 2\ell|\nabla^2 u|^2 + 32\ell^{-1}\Phi^2\varphi^2|\nabla\varphi|^2(1+|\nabla u|)^2, \\
4\beta R^{-2}|u-x||\nabla u|^{-1}|\nabla^2 u(v)| &\leq 2\ell|\nabla^2 u(v)|^2 + 2\beta^2 R^{-4}\ell^{-1}(u-x)^2|\nabla u|^{-2},
\end{aligned}$$

and the definition of  $\Phi$  we get

$$\begin{aligned}
0 &\geq 2(p-1)\varphi^2\Phi|\nabla^2 u(v)|^2 - 4(m-1)\kappa^2\varphi^2\Phi|\nabla u|^2 + \Phi^2\mathcal{L}_p\varphi^2 \\
&\quad - 32(p-1)\Phi|\nabla\varphi|^2(1+|\nabla u|)^2 - 32\ell^{-1}\Phi^2\varphi^2|\nabla\varphi|^2(1+|\nabla u|)^2 \\
&\quad - 2\beta^2 R^{-4}\ell^{-1}(u-x)^2|\nabla u|^{-2} + 2(p-1)\beta R^{-2}|\nabla u|^{-2}\Phi^2 \\
&\quad - 2(m-1)\kappa^2\ell|\nabla u|^2.
\end{aligned}$$

We hereafter denote with  $C_1, C_2, \dots$  absolute constants. Define  $\varphi$  as in Lemma 5.2, so that  $|\nabla\varphi|^2 \leq CR^{-2}$  and, since  $p \geq 2$ ,

$$\begin{aligned}
\mathcal{L}_p\varphi^2 &\geq -C_p\varphi C_R - C_p\varphi R^{-1}|\nabla u|^{-1}|\nabla^2 u(v)| \\
&\geq -C_p\varphi C_R - 2(p-1)\varphi^2\Phi^{-1}|\nabla^2 u(v)|^2 - C_1 p\Phi R^{-2}|\nabla u|^{-2}.
\end{aligned}$$

Inserting into the above and multiplying by  $|\nabla u|^2$  we infer

$$\begin{aligned}
0 &\geq -4(m-1)\kappa^2\varphi^2\Phi|\nabla u|^4 - C_p\varphi\Phi^2 C_R|\nabla u|^2 - C_1 p\Phi^3 R^{-2} \\
&\quad - 32(p-1)\Phi|\nabla\varphi|^2(1+|\nabla u|)^2|\nabla u|^2 - 32\ell^{-1}\Phi^2\varphi^2|\nabla\varphi|^2(1+|\nabla u|)^2|\nabla u|^2 \\
&\quad - 2\beta^2 R^{-4}\ell^{-1}(u-x)^2 + 2(p-1)\beta R^{-2}\Phi^2 - 2(m-1)\kappa^2\ell|\nabla u|^4.
\end{aligned}$$

Using  $|\varphi| \leq 1$ ,  $|\nabla\varphi| \leq C_2/R$ ,  $|u - x| \leq \ell R$ ,  $|\nabla u| \leq A$  together with the inequality  $\Phi^3 \leq A^2\Phi^2$ , and rearranging, we obtain

$$\begin{aligned} 0 &\geq -4(m-1)\kappa^2\Phi A^4 - Cp\Phi^2 C_R A^2 - C_1 p A^2 \Phi^2 R^{-2} \\ &\quad - 32(p-1)\Phi C_2^2 R^{-2} A^4 - 32\ell^{-1}\Phi^2 C_2^2 R^{-2} A^4 \\ &\quad - 2\beta^2 R^{-2} \ell + 2(p-1)\beta R^{-2} \Phi^2 - 2(m-1)\kappa^2 \ell A^4 \\ &= (E\Phi^2 - B\Phi - F)R^{-2}, \end{aligned}$$

where we set

$$\begin{aligned} E &\doteq 2(p-1)\beta - CpR^2 C_R A^2 - C_1 p A^2 - 32\ell^{-1} C_2^2 A^4 \\ B &\doteq 4(m-1)\kappa^2 R^2 A^4 + 32(p-1)C_2^2 A^4, \\ F &\doteq 2\beta^2 \ell + 2(m-1)\kappa^2 \ell A^4 R^2. \end{aligned}$$

Whence,

$$E\Phi^2 \leq B\Phi + F \leq BA^2 + F \quad \text{at } p_0.$$

It follows that, at  $p_0$ ,

$$\begin{aligned} w &\leq \Phi^2 + \beta R^{-2}(u-x)^2 + \ell|\nabla u|^2 \\ &\leq E^{-1}(BA^2 + F) + \beta\ell^2 + \ell A^2. \end{aligned}$$

Therefore, for each  $x \in B_R$ ,

$$\Phi^2(x) \leq w(x) \leq w(p_0) \leq E^{-1}(BA^2 + F) + \ell(\beta\ell + A^2). \quad (45)$$

By the definition of  $C_R$

$$E \geq p\beta - C_3 p A^2 \left[ 1 + \kappa R + \frac{A^2}{\ell p} \right] \geq \frac{p\beta}{2},$$

where in the latter inequality we have chosen

$$\beta = 2C_3 \left( \frac{\ell+1}{\ell} \right)^{\frac{1}{4}} A^4 [1 + \kappa R + \ell^{-1} p^{-1}].$$

Estimating  $B, F$  for such a choice of  $\beta$  we obtain:

$$B \leq C_5 m p A^4 (1 + \kappa^2 R^2), \quad F \leq C_6 m \sqrt{\ell(\ell+1)} (1 + \kappa^2 R^2 + \ell^{-2} p^{-2}) A^8,$$

which gives

$$\begin{aligned} \Phi^2(x) &\leq C_7 m A^4 \ell^{\frac{1}{4}} (\ell+1)^{\frac{3}{4}} (1 + \kappa R + \ell^{-1} p^{-1}) \\ &\leq C_7 m A^4 \ell^{\frac{1}{4}} (\ell+1)^{\frac{5}{2}} (1 + \kappa R + \ell^{-1} p^{-1}) \end{aligned}$$

and the conclusion follows by taking square roots. If  $p_0 \in \partial B_{2R}$  we have for each  $x \in B_R$

$$\begin{aligned} \Phi^2(x) &\leq w(x) \leq w(p_0) = (\beta R^{-2}(u-x)^2 + \ell|\nabla u|^2)(p_0) \leq \beta\ell^2 + \ell A^2 \\ &\leq C_8 A^4 \ell^{\frac{7}{4}} (\ell+1)^{\frac{3}{4}} [1 + \kappa R + \ell^{-1} p^{-1}] \\ &\leq C_8 A^4 \ell^{\frac{1}{4}} (\ell+1)^{\frac{5}{2}} [1 + \kappa R + \ell^{-1} p^{-1}], \end{aligned}$$

from which the desired inequality follows as well.  $\square$

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