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Concept design of low frequency telescope for CMB B-mode polarization satellite LiteBIRD

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Concept Design of Low Frequency Telescope for CMB B-mode Polarization satellite LiteBIRD

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ABSTRACT

LiteBIRD has been selected as JAXA's strategic large mission in the 2020s, to observe the cosmic microwave background (CMB) B-mode polarization over the full sky at large angular scales. The challenges of LiteBIRD are the wide field-of-view (FoV) and broadband capabilities of millimeter-wave polarization measurements, which are derived from the system requirements. The possible paths of stray light increase with a wider FoV and the far sidelobe knowledge of -56 dB is a challenging optical requirement. A crossed-Dragone configuration was chosen for the low frequency telescope (LFT: 34–161 GHz), one of LiteBIRD's onboard telescopes. It has a wide field-of-view $(18^{\circ} \times 9^{\circ})$ with an aperture of 400 mm in diameter, corresponding to an angular resolution of about 30 arcminutes around 100 GHz. The focal ratio f/3.0 and the crossing angle of the optical axes of 90° are chosen after an extensive study of the stray light. The primary and secondary reflectors have rectangular shapes with servations to reduce the diffraction pattern from the edges of the mirrors. The reflectors and structure are made of aluminum to proportionally contract from warm down to the operating temperature at 5 K. A 1/4 scaled model of the LFT has been developed to validate the wide field-of-view design and to demonstrate the reduced far sidelobes. A polarization modulation unit (PMU), realized with a half-wave plate (HWP) is placed in front of the aperture stop, the entrance pupil of this system. A large focal plane with approximately 1000 AlMn TES detectors and frequency multiplexing SQUID amplifiers is cooled to 100 mK. The lens and sinuous antennas have broadband capability. Performance specifications of the LFT and an outline of the proposed verification plan are presented.

Keywords: Cosmic microwave background, space program, millimeter-wave polarization, cryogenic telescope

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1. INTRODUCTION

LiteBIRD, the Lite (Light) satellite for the study of *B*-mode polarization and Inflation from cosmic background Radiation Detection, observes the cosmic microwave background (CMB) polarization over the full sky at large angular scales.^{1–3} Cosmological inflation predicts primordial gravitational waves, which imprinted large-scale curl (*B*-mode) patterns on the CMB polarization map.^{4–7} Measurements of the CMB *B*-mode signals are known as the best probe to detect the primordial gravitational waves and to measure the inflation energy. The scientific objective of LiteBIRD is to test major inflationary models.⁸ The power of the *B*-modes is proportional to the tensor-to-scalar ratio, *r*. The current upper limit on *r* is r < 0.044.⁹ The mission goal of LiteBIRD is to measure *r* with a precision of $\delta r < 0.001$, which provides a crucial test of cosmic inflation. The required angular coverage is $2 < \ell < 200$, where ℓ is the multipole moment.

LiteBIRD has been selected as JAXA's strategic large mission in the late 2020s. It will be launched with an H3 vehicle for three years of observations at the Lagrangian point (L2) of the Earth-Sun system. It is a spinning satellite with a precession angle (α) of 45° and spin angle (β) of 50° with spin rate of 0.05 rpm and precession period of 180 minutes, which are optimized from crossing angles and revisits of previously scanned regions. The concept design has been studied by researchers from Japan, U.S., Canada, and Europe since September 2016.

LiteBIRD observes millimeter waves from 34 GHz to 448 GHz with two instruments, LFT and MHFT.^{10,11} Both instruments have the same relative bandwidth of min: max frequencies = 1:5. LFT will explore synchrotron and CMB emission, while MHFT covers CMB emission and will also extend to higher frequencies to explore the dust contribution. The bands in common between the two telescopes, i.e. 89–161 GHz, allow reduction of systematics associated with the telescopes, and add redundancy. A transmissive half-wave plate (HWP) for polarization modulation has a limited bandwidth, and so LiteBIRD has two instruments to cover the frequency bands. Both instruments are operated at cryogenic temperature of 5 K to reduce the photon noise. The focal plane design is based on multi-chroic TES detectors at 100 mK operation.^{12,13} Cryogenic chain of LiteBIRD is described by Hasebe et al.¹⁴ and Duval et al.¹⁵

Challenges for LiteBIRD are wide field-of-view (FoV) and broadband capabilities of millimeter-wave polarization measurements, which are derived from the sensitivity specifications. The wide FoV corresponds to a large focal plane area; a detector pixel has different spill-over or edge-taper depending on the pixel position on the focal plane. The possible paths of stray light increase with a wider FoV. A stable system is also required to perform the all sky survey.

LiteBIRD is currently under the conceptual study phase. It is important to define preliminary design specifications in order to make progress on the system design. The derivation of the detailed requirements and the detailed design study are moving in parallel, and affect each other iteratively. In this paper we introduce a list of design specifications in this phase. Based on further simulation-based studies of the error budget allocation over the entire system, the numbers we list for the design specifications may change.

2. OVERVIEW OF LFT

LFT has been designed to meet specifications described in the next section. This section describes a brief overview of LFT before describing design details. LFT is a wide field-of-view telescope designed to observe the CMB and synchrotron radiation in the frequencies of 34-161 GHz, as shown in Figure 1. The aperture diameter is 400 mm. The angular resolution is 24-71 arcminutes. LFT is operated at cryogenic temperature of 5 K to reduce the optical loading and is surrounded by radiators called V-grooves. The thermal design of LiteBIRD is described in Hasebe et al.¹⁴ LFT has a crossed Dragone antenna made of aluminum. A frame structure at 5 K supports all components: the PMU (polarization modulation unit); focal plane; primary and secondary reflectors; and absorbers. An earlier design² has been updated.

A PMU with a transmissive HWP (half-wave plate)¹⁶ is mounted in front of the aperture stop. LFT focal plane is based on multi-chroic TES detectors at 100 mK operation.^{12,13} There are interfaces with the LFT PMU and the LFT focal plane.

3. LFT DESIGN SPECIFICATIONS

The performance specifications for LFT are as follows.

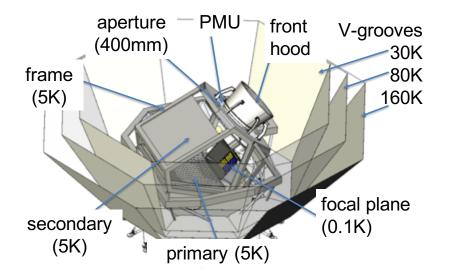


Figure 1. Overview of low frequency telescope (LFT). MHFT and side panels are not shown for clarity.

3.1 Frequency bands and noise

Frequency coverage 34–161 GHz

Band sensitivities LFT shall have the array sensitivities as tabulated in Table 1, which shall satisfy the maplevel sensitivity specifications. The sensitivity is limited by the number of pixels, which is closely related with the field of view of the telescope. The noise of the detector in a pixel is limited by the optical loading.

CUL.	Since 1. 1 chormance specifications of Eff. The bandwidth (DW) is (fight - Low)/ Center inequely								
	Center freq.	BW	Beam fwhm	pixel dia.	No. det	NET _{array}	Pol. sensitivity		
	GHz		[arcmin]	[mm]		$[\mu \text{Krts}]$	$[\mu K \text{ arcmin}]$		
	40	0.30	70.5	32	48	18.5	37.4		
	50	0.30	58.5	32	24	16.5	33.5		
	60	0.23	51.1	32	48	10.5	21.3		
	68	0.23	41.6	16	144	9.8	16.9		
	68	0.23	47.1	32	24	15.7	10.3		
	78	0.23	36.9	16	144	7.7	12.1		
	78	0.23	43.8	32	48	9.5	12.1		
	89	0.23	33.0	16	144	6.1	11.3		
	89	0.23	41.5	32	24	14.2	11.0		
	100	0.23	30.2	16	144	5.1	6.6		
	119	0.30	26.3	16	144	3.8	4.6		
	140	0.30	23.7	16	144	3.6	4.8		

Table 1. Performance specifications of LFT. The bandwidth (BW) is (High – Low)/Center frequency.

- **Band shape** The frequency bandpasses are defined by a combination of superconducting band-pass filters on the wafer,¹² and the use of quasi-optical metal-mesh filters¹⁷ in front of the focal plane to reject higher frequencies. Lower frequencies than the defined band (red-leak) might contribute to sidelobes due to the distorted beam pattern. The red-leak is rejected only by a superconducting band-pass filter on the wafer.¹² Higher frequencies than the defined band (blue-leak) might contribute to noise due to far-infrared radiation. The blue leak is rejected by both the on-chip filter and the quasi-optical metal mesh filter in front of the focal plane.
- 1/f noise The knee frequency of the post-demodulation 1/f noise should be below 0.1 mHz (assuming a 0.05 rpm

spin rate, precession angle $\alpha = 45^{\circ}$ and spin angle $\beta = 50^{\circ}$). The knee frequency of the raw 1/f noise should be well below 3.1 Hz (46 rpm×4). The 46 rpm value is the LFT HWP rotation rate. In the HWP failure mode, the pair-differenced $f_{\rm knee}$ is 20 mHz for individual detectors and 100,mHz for the common mode.

Data loss and operational duty cycle The operating life of the instruments should be long enough to perform observations for 3 years. The system shall have an operational duty cycle of 85% for science observations, including all downtime for cryogenic cycling, detector operation preparation, and data transfer. Data loss due to cosmic ray glitches should be less than 5%.

3.2 Beam

- Angular resolution The angular resolution of each detector response should be sufficient to cover the required angular scales of $2 < \ell < 200$, where ℓ is the spherical harmonic index. It shall have a FWHM of 80' or better. Angular resolution should be better than 30' at 100 GHz, for measuring the recombination bump, which is the prominent structure at degree scales in the *B*-mode power spectrum coming from the primordial gravitational waves. It shall also be better than 80' at 40 GHz, for dealing with point sources.
- Pointing offset knowledge The pointing offset knowledge should be less than 2.1'.^{18,19}
- Far sidelobe knowledge The extended component of the far sidelobe should be known at a precision level of $-56 \text{ dB}.^{20,21}$ Radiation from the Galactic plane through the far sidelobes contaminates the signal and therefore the inferred power spectrum. The far sidelobe is currently defined as the domain located above 0.2 rad.
- **Small scale feature of sidelobe** The small-scale features of the far sidelobes should be known at a precision level of -33 dB, more specifically defined by the following equation: (intensity/0.05%)× (diameter/30')², where the diameter is the FWHM of the small-scale features due to possible optical ghosts or optical multiple reflections.
- Near sidelobe knowledge The beam pattern of near sidelobes (out to 10° from the co-polar beam peak) should be known at a precision level of -30 dB. Also, it should be confirmed to be consistent with its designed pattern at a precision level of 10% or better.
- Beam stability knowledge The beam-shape stability over time, should be better than 0.46% (synchronous) / 2%(random) for beam width, and better than 1.7'' (synchronous) / 16'' (random) for pointing, better than 0.086% (synchronous) / 2.7% (random) at the third flattening (often called ellipticity), better than -46 dB at sidelobes around several to 30 degrees.¹⁹ The time scale of the synchronous beam fluctuation is 163 msec for LFT in which HWP rotates by 45° , while "random" is a component that fluctuates randomly over time. They correspond to "differential beam shape" and are also related to optical qualities of the instrument in the broad sense. Note that in the case of a perfect polarization modulator, differential beam effects are negligibly small. Therefore beam stability specifications are tied to imperfections of the polarization modulation system.

3.3 Polarization

Knowledge of polarization efficiency The polarization efficiency knowledge should be better than 0.2%.

- Absolute polarization angle knowledge (monopole) The absolute polarization angle knowledge on the stable monopole component should be better than 2.7'.^{18,19}
- **Polarization modulation** The modulation frequency should be $> 4 \times 0.76$ Hz, which assures 4 modulation (at least) during beam-size excursions of 30'. The modulation frequency should be $< 4 \times 4.5$ Hz, given by an argument about the bolometer time constant.
- Modulation synchronous instrumental polarization knowledge The 4f synchronous instrumental polarization knowledge should be better than 0.0063%.

Table 2. Optical specifications of LFT antenna					
Aperture diameter	400 mm				
Field of view	$18^{\circ} \times 9^{\circ}$				
Strehl ratio	> 0.95 at $161{\rm GHz}$				
Focal plane telecentricity	$< 1.0^{\circ}$				
Focal ratio	2.9 < F/# < 3.1				
PSF flattening	< 5 %				
Cross polarization	< -30 dB				
Rotation of polarization angle across FoV	$<\pm1.5^{\circ}$				

3.4 Gain

Gain variation in time The gain variation in time for a single detector should be better than 10% assuming that the gain parameter is updated every 1200 sec (which corresponds to a 0.05 rpm rotation period). The effective differential gain should be smaller than 0.0069% (synchronous, i.e., 163 msec for LFT, in which the HWP rotates by 45°) / 0.3% (random).

3.5 Other specifications

There are other specifications. According to the system design,² heat dissipation of LFT is limited to 4 mW, which includes the PMU and temperature control of the LFT optical components. The minumum eigen-frequency for LFT is assumed to be 100 Hz and 50 Hz for axial and lateral axes, respectively; however, this might be optimized by a combined design with the cryo-structure of the payload module (PLM). LFT is designed to withstand quasi-static loads of 20 g for the axial and lateral axes. EMC/EMI specifications have been studied with simulations.²²

4. OPTICAL DESIGN

4.1 Antenna design

After trade-off studies of various optical configurations among crossed-Dragone, offset-Gregorian,²³ and open-Dragone,^{24,25} we concluded that the crossed-Dragone antenna is the best option for LFT because of the wide-field of view and the low cross polarization. Multiple reflections of crossed-Dragone antennas have been described earlier.²⁶

A crossed-Dragone antenna of LFT has been designed with an amorphic aspherical surfaces²⁷ to achieve the specifications listed in Table 2. The anamorphic aspherical surface is described with the following equation for both the primary mirror (PM) and the secondary mirror (SM):²⁷

$$z_m = \frac{C_{m,x}x_m^2 + C_{m,y}y_m^2}{1 + \sqrt{1 - (1 + k_{m,x})C_{m,x}^2 x_m^2 - (1 + k_{m,y})C_{m,y}^2 y_m^2}} + \sum_{i=2}^5 A_{m,i} \left[(1 - B_{m,i}) x_m^2 + (1 + B_{m,i}) y_m^2 \right]^i, \quad (1)$$

where m = PM, SM, $C_{m,x}$ and $C_{m,y}$ are curvatures for the x and y directions, $k_{m,x}$ and $k_{m,y}$ are conic constants in the x and y directions, and $A_{m,i}$ and $B_{m,i}$ are aspherical coefficients.

	$C_{m,x}/\mathrm{mm}^{-1}$	$C_{m,y}/\mathrm{mm}^{-1}$	$k_{m,x}$	$k_{m,y}$	$y_{m,0}/\text{mm}$	$z_{m,0}/\mathrm{mm}$	$\theta_m/\text{deg.}$	
\mathbf{PM}	-1.60053×10^{-4}	-4.71355×10^{-4}	15.857906	-5.174224	0	696.344	0	
SM	4.05234×10^{-4}	5.04062×10^{-4}	-4.162644	-1.282787	-163.771	346.223	42.45664	
FP					550.924	343.223	90	
	$A_{m,2}$	$B_{m,2}$	$A_{m,3}$	$B_{m,3}$	$A_{m,4}$	$B_{m,4}$	$A_{m,5}$	$B_{m,5}$
\mathbf{PS}	-5.28×10^{-12}	-3.31×10^{-1}	1.63×10^{-18}	-0.716	-2.50×10^{-24}		-2.17×10^{-34}	0.0929
SM	-3.10×10^{-16}	59.834	7.42×10^{-18}	-0.375	-3.45×10^{-23}	-1.157	-3.89×10^{-31}	-0.349

Table 3. Optical parameters of anamorphic aspherical surfaces.²⁷

A ray diagram of LFT is shown in Figure 2, which has an aperture diameter of 400 mm and an FoV of $18^{\circ} \times 9^{\circ}$. The aperture diameter is derived from the requirement of the angular resolution of 80' at 40 GHz. The FoV

corresponds to the focal plane area of $420 \,\mathrm{mm} \times 210 \,\mathrm{mm}$, which is roughly proportional to the sensitivity. This meets the sensitivity requirement in Table 1.

Optical rays are designed to have 640 mm diameter at the aperture from the focal plane to keep enough edge tapers at both primary and secondary reflectors. The Strehl ratio at 161 GHz is larger than 0.95, as shown in Figure 3. Rotation of the polarization angle for the *y*-axis polarization across the field of view is shown in Figure 3. The rotation is estimated to $< \pm 1.5^{\circ}$ according to the ray tracing simulation with a finite resistivity. The derived optical parameters are tabulated in Table 3.

The allocated volumes of LFT and MHFT are shown in Figure 4. The field of view of LFT is maximized under the volume constraint. Crossed-Dragone antennae with f/2.5, 3.0, and 3.5 are compared. The volume is roughly proportional to the f-number. Under the volume constraint, the smaller values are preferable, but, the stray light is larger. We chose f/3.0 for LFT, considering focal-plane dimensions and feed parameters.

We updated the design of a crossed-Dragone antenna reported by.²⁷ The f/3.0 and the crossing angle of the optical axes of 90° have been chosen after an extensive study of stray light (on the right of Figure 2).

Figure 5 shows the stray light with the crossing angles; At the crossing angle of 110° , the direct path from the feed to the sky is small, but there are many triple reflection paths. At 82° , there are large direct paths. Then the 90° angle moderates for both the triple reflections and direct paths.

The detector hood and front hood whose height of 500 mm reduces stray light to far sidelobes as shown in Figure 2. The *y*-direction of the focal plane in the focal plane coordinate (Figure 6) is limited by multiple reflections or stray light. The *x*-direction is limited by the 5K allocated area of LiteBIRD, as shown in Figure 4.

Primary and secondary mirrors have rectangular shapes of 835×795 mm and 872×739 mm, respectively, with servations to reduce diffraction patterns from the edges of mirrors. The mirror sizes were reduced from the previous design² because the 2 K cold aperture stop was removed due to limitations of the cooling capacity and then the length between the aperture and the main reflector was reduced. The optical design is based on feed parameters as tabulated in Table 4.

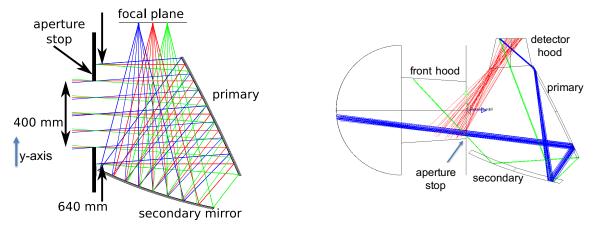


Figure 2. (Left) Ray tracing diagram of Low Frequency Telescope (LFT). Blue, Red, and Green lines show $\theta_y = +4.5^{\circ}$, $\theta_y = 0^{\circ}$, $\theta_y = -4.5^{\circ}$, respectively. (Right) Possible stray light paths of LFT. Red lines show direct paths. Blue and green lines show triple reflections.

4.2 Optical simulation

Physical optics simulations of LFT with $GRASP10^{28}$ have been studied in the same way by Imada et al.²⁹ Lower frequencies make it relatively difficult to meet the far sidelobe requirement due to diffraction effects. Figure 7 shows the impact of the feed sidelobes.

The LFT antenna pattern assuming a Gaussian feed is shown in the left panels of Figure 7, while the feed simulated with $HFSS^{30}$ is shown in the right ones. Upper panels show the antenna pattern of a pixel near the primary reflector, while lower ones show that of near the aperture. It is clear that the direct path from the feed

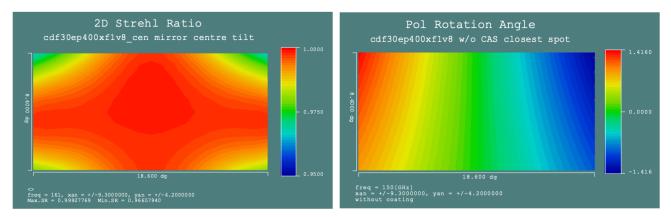


Figure 3. (Left) Map of Strehl ratio of LFT antenna at 161 GHz. (Right) Rotation of polarization angle of y-axis polarization across the field of view in units of degrees.

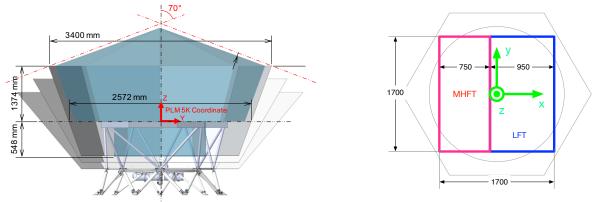


Figure 4. (Left) Usable volume of LFT and MHFT and the PLM coordinate. V-grooves are also shown. The most inner V-groove is at 30 K. The top of the truss is the 5 K structural interface for LFT and MHFT. (Right) Allocated area of LFT and MHFT and the PLM coordinate.

sidelobe contributes the far sidelobe of LFT at a level of -60 dB. The feed sidelobe of a pixel near the aperture contributes the point-like sidelobe due to triple reflections (feed \rightarrow primary \rightarrow secondary \rightarrow primary \rightarrow sky: shown in green). Note that there are discrepancies of the feed sidelobes at a level around -20 dB between the HFSS simulation and the room-temperature measurement of the sinuous/lens feed.³¹

We have simulated the antenna pattern at 30 GHz, as shown in Figure 8, since a bandpass filter cannot cut off sharply at a specific frequency, e.g., 34 GHz, which causes a red leak to the sidelobe. The feed here is polarized along the x axis, and located at (x, y) = (-88 mm, +44 mm) with a diameter of 24 mm, which is different from the current design, but the qualitative effects are the same. Several features, originating from the diffraction at the mirror edges, are shown within circles in both panels. These features are at a higher level than that of the

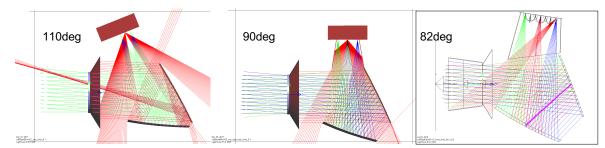


Figure 5. Stray light with the crossing angle of the optical axes of the crossed-Dragone configuration.

detectors is two times the number of pixels because of two orthogonal polarization detections.									
Ty	ype	Center freq.	BW	Low	High	Pixel dia.	Beam waist	No. pix	No. det.
		[GHz]		[GHz]	[GHz]	[mm]	radius [mm]		
	1	40	0.30	34	46	32	11.64	24	48
		60	0.23	53	67	32	11.64	24	48
		78	0.23	69	87	32	11.64	24	48
	2	50	0.30	43	58	32	11.64	12	24
		68	0.23	60	76	32	11.64	12	24
		89	0.23	79	99	32	11.64	12	24
	3	68	0.23	60	76	16	5.82	72	144
		89	0.23	79	99	16	5.82	72	144
		119	0.30	101	137	16	5.82	72	144
	4	78	0.23	69	87	16	5.82	72	144
		100	0.23	89	112	16	5.82	72	144
		140	0.30	119	161	16	5.82	72	144

Table 4. Frequency bands and feed parameters. The bandwidth (BW) is (High - Low)/Center frequency. The number (No.) of detectors is two times the number of pixels because of two orthogonal polarization detections.

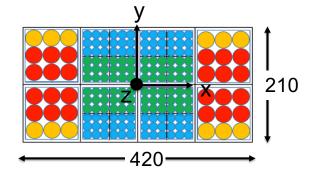


Figure 6. LFT focal plane pixel arrangement. There are eight square $(10 \text{ cm} \times 10 \text{ cm})$ tiles. Red, yellow, and green, blue pixels correspond Type 1, 2, 3, and 4 of Table 4, respectively. The LFT focal plane coordinate is shown in black arrows. The scales are shown in units of millimeters.

nominal diffracted point spread function (PSF).

The current simulations take into account the reflectors, the aperture stop and the front baffle with perfect absorbers. The followings items will be considered for further studies, which might generate additional side-lobes.

- Actual absorbers have finite reflections on the aperture stop, front hood, detector hood, frame, and panels. The absorbers covering the optical cavity and the focal plane are not ideal and they have frequency dependence as well as angle dependence of reflectance.
- There are multiple reflections (i.e. ghost effects) or multiple scattering among the HWP, the focal plane, the aperture stop, quasi-optical LP Filters, and the absorbers.

4.3 Other optical components

The aperture stop at 4.8 K with an inner diameter of 400 mm is made of millimeter absorber, TK-RAM^{32,33} on an aluminum plate. This works to make good beam shape for a relatively low edge taper of about 3 dB configuration.

Millimeter absorbers to reduce reflections are attached on the inside surface of the 5 K frame, which plays a role of a cavity. Eccosorb AN72 and HR10 are candidates for such absorbers; however, they have large TML (total

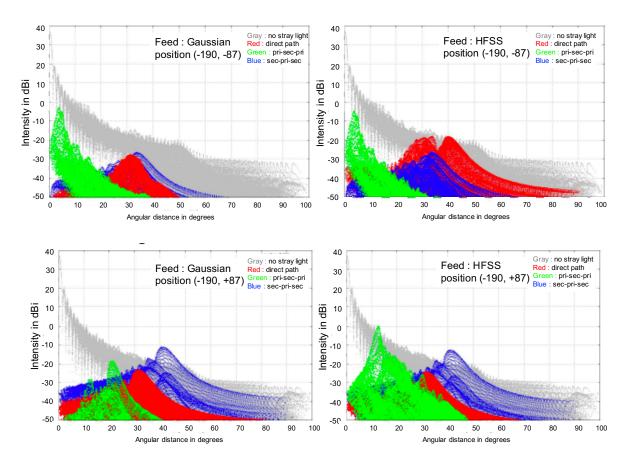


Figure 7. Optical simulation of far-field beam pattern of LFT at 34 GHz. Gray shows the nominal beam pattern without stray light, red shows the direct path from the focal plane to sky, green shows triple reflections (feed – primary – secondary – primary – sky), and blue shows triple reflections (feed – secondary – primary – secondary – sky). (Top, Left) A pixel near the primary reflector around (x, y) = (-190 mm, -87 mm) with a Gaussian feed. (Top, Right) A pixel near the primary reflector with HFSS simulation of sinuous antenna. The feed sidelobe contributes the far sidelobe of LFT due to direct path (Red). (Bottom, Left) A pixel near the aperture stop around (x, y) = (-190 mm, +87 mm) with a Gaussian feed. (Top, Right) A pixel near the aperture stop with HFSS simulation of sinuous antenna. The feed sidelobe contributes the far sidelobe contributes the far sidelobe of LFT due to triple reflections (feed – primary – secondary – primary – sky: Green).

mass loss) and CVCM (collected volatile condensable materials). According to the NASA outgass database,³⁴ AN72 washed with ethanol shows reasonable TML and CVCM.

The front-hood, as shown in Figure 9, is made of millimeter absorber Eccosorb AN72 and aluminum plate.

4.4 Thermal control

Temperature stability of the optical components of LFT is required to meet the specification of the single detector $f_{\rm knee} = 20 \,\mathrm{mHz}$, which corresponds to 50 seconds. The noise equivalent temperature (NET) of each detector is around $50 \mu \mathrm{K}/\sqrt{\mathrm{Hz}}$, so the noise is integrated to $\Delta T = 7 \,\mu \mathrm{K}$ in the 50 seconds. It is necessary to meet the following constraint:

$$(\Delta T)^2 \gg \sum_{o=1}^{N_o} \left(\delta T_o \times \eta_o \times \epsilon_o \times (\text{optical efficiency}) \right)^2, \tag{2}$$

where N_o is the number of optical components, δT_o is the temperature stability of the optical components, η_o is the optical load fraction and, ϵ_o is the emissivity of the optical components. The optical efficiency of the feed is assumed to be 0.69. The noise contribution of each optical component is assumed less than $2 \mu K$. The derived

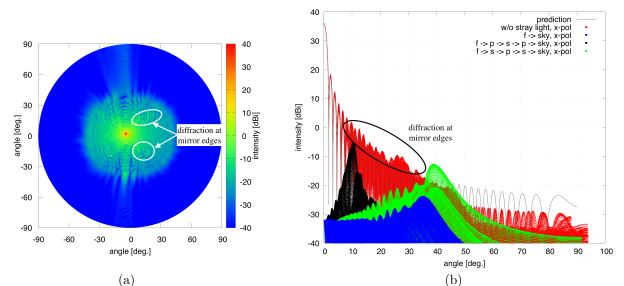


Figure 8. Physical optical simulation for 30 GHz, which is out of the band. (a) 2D map. The features from the diffraction at the mirror edges can be found at the right side of the main lobe. (b) 1D cut.

Table 5. specifications for temperature stability on the scale of 50 seconds of LFT optical components. The optical load fraction (η_o) is a typical value, because it depends on the focal plane position, the feed sidelobe, and frequency. ϵ_o is the emissivity of the optical components.

Components	Temperature [K]		η_o	ϵ_o	Stability
	min.	max.			[mK]
Front hood	5	6	0.004	0.99	3
PMU/HWP	4.5	20	0.63	0.01	0.5
PMU mount	4.5	20	0.004	0.99	0.7
Around aperture stop	4.5	4.8	0.2	0.99	0.02
$5\mathrm{K}$ frame	4.5	5	0.1	0.99	0.03
LFT reflectors	4.5	5	0.9	0.002	1.6
Detector hood	1.8	2	0.08	0.99	0.04
Low-pass filter	1.7	2	0.9	0.01	0.3

specifications on the stability of the LFT optical components are shown in Table 5. Those specifications give a rough estimate for temperature stability of $\delta T_o/T_o \sim 10^{-5}$ in the worst case, but, more accurate estimates are required, because the optical load fraction (η_o) depends on the focal plane position, the feed sidelobe and the frequency, as described in section 4.2 and in Figure 7.

The temperature of the aperture stop, and other optical components, are planned to be stabilized with heaters to reduce the 1/f noise level.

5. STRUCTURE DESIGN

The structural design of LFT is shown in Figure 9. The frame and reflectors of LFT are made of aluminum in order to shrink similarly within 0.4% from 300 K to 5 K.³⁵ Structural and thermal stability of the telescope is required for the all sky survey of CMB polarization observations. Aluminum has good thermal conductance at 5 K and is mechanically stable. The frame has structural interfaces at 5 K with PMU and the focal plane, which is operated at 0.1 K. The fastener between the reflector and the frame is planned to use SUS (stainless steel) bolts. The SUS bolts generate local deformations with an area of several mm, which does not affect on the global shape of the reflectors. The telescope is supported by trusses made of aluminum on the 5 K interface plate. The total mass of LFT, including the trusses, the PMU and the focal plane, is estimated to be 200 kg.

Requirement	Primary (M1)	Secondary (M2)	Frame	Combined
Mechanical shape error	$15 \ \mu m$ r.m.s.	$15 \ \mu m$ r.m.s.		$30 \ \mu m$ r.m.s.
Alignment dx	$\pm 0.1 \text{ mm}$	$\pm 0.1 \text{ mm}$	$\pm 0.2 \text{ mm}$	$\pm 0.4 \text{ mm}$
Alignment dy	$\pm 0.1 \text{ mm}$	$\pm 0.1 \text{ mm}$	$\pm 0.2 \text{ mm}$	$\pm 0.4 \text{ mm}$
Alignment dz	$\pm 0.2 \text{ mm}$	$\pm 0.2 \text{ mm}$	$\pm 0.2 \text{ mm}$	$\pm 0.6 \text{ mm}$
Tilt Rot-x	± 0.5 arcmin	± 0.5 arcmin	± 0.6 arcmin	\pm 1.6 arcmin
Tilt Rot-y	± 0.4 arcmin	± 0.4 arcmin	± 0.2 arcmin	\pm 1.0 arcmin
Tilt Rot-z	\pm 0.1 arcmin	± 0.1 arcmin	± 0.2 arcmin	$\pm 0.4 \operatorname{arcmin}$

Table 6. Alignment specifications of LFT. All values are maxima.

Optical tolerance analysis leads to alignment specifications of LFT (Table 6), which are derived from the polarization angle variation. The gravitation deformation of LFT is estimated to be δx of $-14 \,\mu\text{m}$, δy of $-23 \,\mu\text{m}$, δz of $22 \,\mu\text{m}$, which are all reasonably small. Then, we can plan the ground verification and calibration without directional constraints due to gravitational effects. According to a scaled model (see Section 8), the alignment can be achieved with careful design and assembly.

The surface roughness of the reflectors are designed to be $2-4 \,\mu\text{m}$ in R_a on the scale of 10 mm, which reduces infrared radiation, mainly from the Galactic plane. According to the Ruze fomula $\eta_e = \exp\left[-\left(\frac{4\pi\epsilon}{\lambda}\right)^2\right]$, infrared radiation more than 5–10 THz (30–60 μm) can be scattered.

The telescope is tightly covered with aluminum and absorbers to reduce the stray light from the inner surface of the 30 K V-groove (see Figure 1). The absorber, made of plastic and carbon, is adhered to a panel with epoxy, then the panel is fixed to the 5 K frame. The cryogenic contraction of the absorber and the epoxy will be carefully designed not to deform the frame.

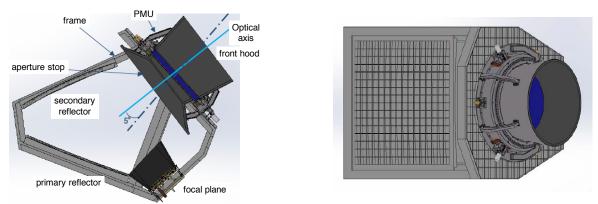


Figure 9. (Left) Lateral view of structural design of LFT. The side panel is covered with millimeter absorbers. (Right) Top view of LFT.

6. LFT POLARIZATION MODULATION UNIT (PMU)

A polarization modulation unit with a transmissive sapphire HWP has been developed for LiteBIRD (Figure 10).^{36–38} The progress of the PMU is separately reported.¹⁶ The PMU/HWP is placed in front of the aperture stop or entrance pupil of 400 mm diameter. The HWP continuously rotates with 46 rpm = 0.77 Hz. PMU uses superconducting magnets for levitation.³⁶ The eddy current and magnetic hysteresis dissipate and increase the temperature of the rotating HWP from 5 K to 20 K. The HWP rotation axis is tilted by 5° with respect to the optical axis to mitigate multiple reflections including optical ghosts between the HWP and the focal plane.

We have derived following the interface specifications on LFT PMU and focal plane from the LFT specifications (Section 3) and system designs during ISAS pre-phase $A2.^{2,3}$

1. The optical effects of the observation frequency of 34–161 GHz due to the PMU are minimized to meet the near and far sidelobes specifications of LFT.

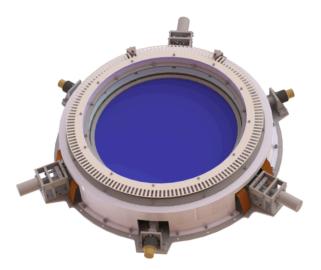


Figure 10. LFT Polarization Modulation Unit (PMU).¹⁶ The sapphire half-wave plate is shown in blue.

- 2. The opaque 20 K parts of PMU are designed to reduce the optical loading.
- 3. The mass of PMU is 30 kg.
- 4. The heat loads to the $5\,\mathrm{K}$ stage including the PMU wire harness are less than $3\,\mathrm{mW}$.
- 5. AC magnetic field variation and DC magnetic field are minimized to reduce the effects on the focal plane.

7. LFT FOCAL PLANE

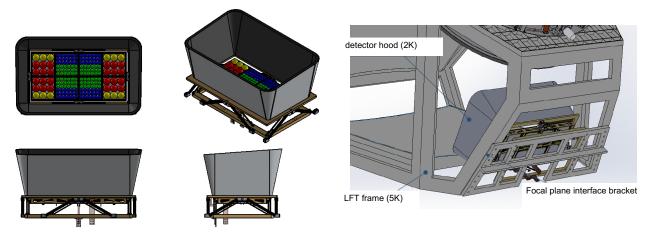


Figure 11. (Left) LFT focal plane assembly. (Right) Structural interface between the focal plane and LFT.

The LFT focal plane has been designed and developed with antenna-coupled TES detectors.¹² The lens and sinuous antenna have broadband capability.³¹ The focal plane with AlMn TES is cooled to 100 mK with ADRs.¹⁵ The cold readout with SQUID amplifiers is also cooled to 100 mK. Cosmic ray mitigation has been extensively investigated.^{39,40} The progress of the LFT focal plane is separately reported.¹³

The focal plane consists of eight square (10 cm \times 10 cm) tiles, as shown in Figure 11. The focal plane is shielded with a hood at 2 K to reduce stray light (see Figure 2). A quasi-optical metal-mesh low-pass filter¹⁷ is put in front of square modules to reduce thermal loads from far-infrared radiation of the Galactic plane and the

 $20 \,\mathrm{K}$ radiation of PMU. A magnetic shield to reduce magnetic variation from the PMU covers the focal plane except for the optical input. The structural interface at $5 \,\mathrm{K}$ between the focal plane and LFT is designed as shown in Figure 11.

The following interface specifications on the focal plane are flown down from the LFT specifications and system designs.

- 1. The optical efficiency of each detector is higher than 0.69.
- 2. The return loss of the feeds in the in-band frequencies is better than $-10 \, \text{dB}$.
- 3. The main beam width of the feeds is consistent with the Gaussian beam radius defined in Table 4 within 5%.
- 4. The sidelobes of each detector are less than $-17 \,\mathrm{dB}$. Figure 7 shows the effects of the feed sidelobes.
- 5. The optical cross talk among pixels is less than 0.03 %.
- 6. The lower frequency edges of 34 GHz and 60 GHz of the 40 GHz band and the 68 GHz band, respectively, have sharper cut-offs to reduce the contamination of sidelobes of the lower frequencies. Figure 8 shows the beam pattern at 30 GHz.
- 7. The polarization efficiency of the feeds should be higher than 98 %, which corresponds to the cross polarization of <-17 dB.
- 8. The polarization angle of each detector across the frequency band changes by less than $\pm 5^{\circ}$.
- 9. The detector noise is basically the photon noise limit of the cosmic microwave background of 2.7 K. The NET is tabulated in Table 1.
- 10. The common mode 1/f knee noise of the detector module is stable to be better than 100 mHz.
- 11. The 1/f knee of each detector is stable to be better than 20 mHz.
- 12. Micro-vibration of the 5 K interface is less than 30 μ G/ \sqrt{Hz} and 80 μ G/ \sqrt{Hz} over 10–200 Hz and 200– 500 Hz, respectively. Under this condition, the focal plane shall perform the required sensitivity. This requirement is based on the experience of the Hitomi X-ray satellite.⁴¹
- 13. The detector yield including the readout electronics is larger than 80 %.
- 14. The dead time fraction due to cosmic ray glitches is less than 0.05.
- 15. The mass of the focal plane assembly is assumed to be 17 kg without the magnetic shield.
- 16. The first eigen-frequency of the focal plane is required to larger than 141 Hz for all three axes.

8. SCALED MODEL DEMONSTRATION

A quarter (1/4)-size scaled model of the LFT antenna has been designed and developed to verify the wide-field design. Measured frequencies are also scaled, so the antenna pattern of the scaled model reveals that of the full size.

The near-field measurement system with the scaled LFT has been developed as shown in Figure 12.⁴² Measured amplitude and phase data are transformed to far fields. Figure 12 shows far-field beam patterns at three focal positions (see Figure 6), center, top-right edge, and bottom-right edge, at the frequency of 220 GHz, which corresponds to 55 GHz in the full size LFT. We confirmed the suppression of far sidelobes based on the scaled model measurements.

Rotation of polarization angle over the field of view is another key parameter for the wide-field design. A dedicated compact antenna test range (CATR), or a collimated millimeter-wave source has been developed to

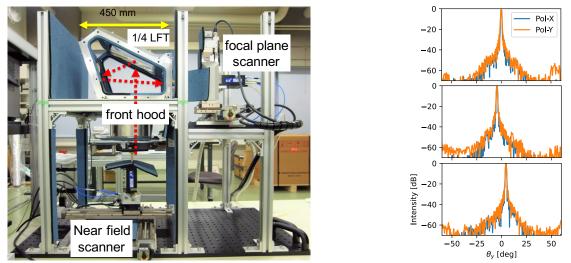


Figure 12. (Left) LFT quarter (1/4) scaled model and the near-field measurement system.⁴² (Right) Far-field patterns of the quarter LFT at the center (top) and edges (middle and bottom) of the focal plane, measured at 220 GHz, which corresponds to 55 GHz in the full model.⁴²

measure the polarization angle across the wide field of view of the 1/4 LFT. The polarization angle of the 1/4-scaled LFT has been measured with a resolution of 0.1'.⁴³ The polarization angle of polarization x or horizontal polarization was measured to rotate by around 60' across the focal plane, while the angle of polarization y or vertical polarization rotates by around 30' across the focal plane.

The structural design of the LFT antenna has been studied with the 1/4-scaled LFT. The frame structure of the 1/4-LFT as shown in Figure 13, was assembled with plates and rectangular bars. The reflector alignment of the assembled 1/4 LFT was measured with a coordinated machine (Mitsutoyo Legex 12128), as shown in Figure 13. The fitted curve of the optical surfaces referring to the aperture center is different from the designed values by $36 \,\mu\text{m}$ and 22'' at the maximum. The measured alignment met the quarter values of the alignment requirement of Table 6.

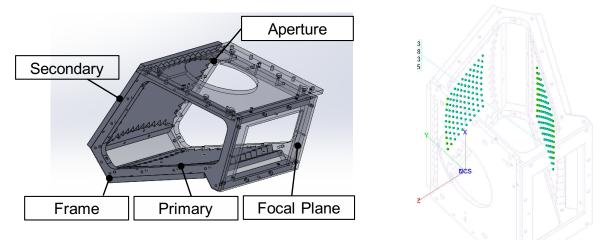


Figure 13. (Left) LFT quarter (1/4) scaled model. (Right) Measurement of reflector surfaces with a coordinated machine.

9. VERIFICATION PLAN

Verification and calibration of a cryogenic telescope at the ground facilities before launch are challenging. A verification plan is tabulated in Table 7. Two development models $(DM/EM \text{ and } FM^*)$ are planned.²

	DM/EM	FM
LFT-antenna tests at room temperature		
Shape measurements with a 3D coordinated machine	\checkmark	\checkmark
Millimeter-wave antenna pattern with horns	\checkmark	\checkmark
V-grooves/MHFT diffraction	\checkmark	_
LFT-antenna cryogenic tests at 5 K		
Strain measurements	\checkmark	_
Deformation measurements: photogrammetry or laser sensing	optional	optional
Millimeter-wave antenna pattern with horns	optional	optional
LFT AIV and calibration with FP and PMU		
Antenna pattern	\checkmark	\checkmark
Polarization angle	\checkmark	\checkmark
Frequency response	\checkmark	\checkmark

Table 7. Verification plan of LFT.

The antenna pattern of LFT before integration with the focal plane will be tested at room temperature. A possible method is a near-field beam measurement⁴² or a CATR measurement.⁴³

Diffraction effects due to V-grooves and structures of MHFT will be evaluated and modeled to be small enough (< -60 dB) as designed at room temperature. A structure thermal model (STM) of the mission payload is constructed and tested with mechanical coolers to verify structural and thermal performance.² It will be used to measure the electromagnetic effects of V-grooves at room temperature.

Then, the cryogenic deformation of LFT will be measured to be small enough, as designed. There are a few methods to measure cryogenic deformation of LFT: 1) strain measurements with strain gauges; 2) photogrammetric measurements; and 3) laser reflection measurements.

To verify the requirements of LFT and to calibrate LFT with the focal plane and the PMU, we have a plan to build a beam measurement system in a cryogenic environment. There are three methods to measure cryogenic beam patterns, polarization angles and spectral response (Table 8). One approach is near-field beam measurements in front of the front hood of LFT. To obtain the far-field pattern from the near-field measurements, the phase distribution must be retrieved with a reference source.⁴⁴

Another method is direct measurement of far-field pattern with a collimated source or a compact antenna test range (CATR), which needs larger volume for the cryogenic environment, as shown in Figure 14. This concept has three merits over the phase retrieval near-field beam measurement.

1. The polarization angle of LFT is also measured with a collimated beam, as demonstrated by H. Takakura et al. 2020.⁴³

*DM: demonstration model, EM: engineering model, FM: flight model

Table 8. Possible cryogenic RF measurements. CATR: compact antenna test range. CW : continuous wave/coherent source.

	Near Field	CATR with CW	CATR with blackbody
Phase retrieval	necessary	unnecessary	unnecessary
Volume	compact	large	large
Time	longer	fast	faster
Standing wave	no concern	little concern	no concern
Pol. angle	difficult	possible	possible
Spectral response	difficult	possible	_

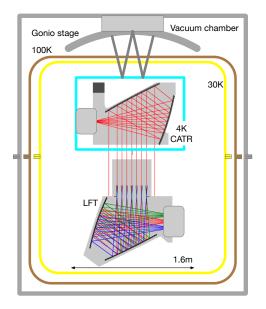


Figure 14. Schematic drawing of cryogenic set-up with a CATR (compact antenna test range), which moves threedimensionally with two Gonio stages. It is planned to measure co-polar and cross-polar beam pattens, polarization angle, and spectral response of LFT with CW and blackbody sources.

- 2. The frequency spectral response is measured with a broadband coherent source. A few broadband photomixers have been demonstrated at millimeter-wave frequencies.^{45,46}
- 3. It is possible to measure beam patterns with continuum sources as well as coherent sources. Beam measurements with a continuum source are faster than those of multiple frequencies with coherent sources.

In either method, it is crucial to de-couple the mechanics at room temperature from the sources at cryogenic temperature, or to develop moving mechanics operated at low temperature.

10. SUMMARY

Based on the performance specifications of LFT, a wide field-of-view design has been studied as well as structural and thermal designs. A 1/4-scaled model of LFT has been developed to verify the design. The measured beam pattern was consistent with the optical model at a level of -50 dB. Interface specifications of the LFT PMU and LFT focal plane are presented. The verification scheme of LFT is planned as the ISAS/JAXA pre-phase A activity.

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