Utility indifference valuation for non-smooth payoffs with an application to power derivatives^{*}

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Abstract

We consider the problem of exponential utility indifference valuation under the simplified framework where traded and nontraded assets are uncorrelated but where the claim to be priced possibly depends on both. Traded asset prices follow a multivariate Black and Scholes model, while nontraded asset prices evolve as generalized Ornstein-Uhlenbeck processes. We provide a BSDE characterization of the utility indifference price (UIP) for a large class of non-smooth, possibly unbounded, payoffs depending simultaneously on both classes of assets. Focusing then on Vanilla claims and using the Gaussian structure of the model allows us to employ some BSDE techniques (in particular, a Malliavin-type representation theorem due to [MZ02]) to prove the regularity of Z and to characterize the UIP for possibly discontinuous Vanilla payoffs as a viscosity solution of a suitable PDE with continuous space derivatives. The optimal hedging strategy is also identified essentially as the delta hedging strategy corresponding to the UIP. Since there are no closed-form formulas in general, we also obtain asymptotic expansions for prices and hedging strategies when the risk aversion parameter is small. Finally, our results are applied to pricing and hedging power derivatives in various structural models for energy markets.

Keywords : Utility Indifference Pricing, Optimal Investment, Backward Stochastic Differential Equations, Viscosity Solutions, Electricity Markets.

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1 Introduction

This paper deals with the pricing and hedging of derivatives in incomplete markets, where the source of incompleteness comes from the fact that some of the assets are assumed not to be traded. As it is well known, such a situation generally prevents from constructing a perfect hedge and therefore to obtain a unique price as a result of classical no-arbitrage arguments (at least when contingent claims also depend on non-traded assets). In the absence of a unique equivalent martingale measure, indeed, arbitrage theory only allows to identify intervals of viable prices, which makes it necessary to develop other criteria to actually choose a unique price. The easiest and most conservative choice would be (for the seller) to pick the super-replicating price, thus eliminating all the risks by transferring to the buyer the entire cost of the incompleteness. Unfortunately this procedure often gives rise to unreasonably high prices which do not usually match with real data, as it is quite unlikely that one counterpart will completely refuse to take any risk at all. For this reason, other paradigms have been introduced in the literature: one example is Local Risk Minimization (see [Sc01]) which does not aim at canceling the hedging risk but rather at minimizing it according to some suitable criterion. Another (partial) way out is the idea of introducing in the market some new assets which are correlated to the non-tradable ones and can therefore be exchanged in the hope of improving the quality of the hedge (see [Da97]).

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Of course when dealing with the optimal balancing of risks, the standard mathematical way to tackle the problem is the introduction of utility functions, which allow to describe in an easy and concise fashion the amount of uncertainty that an agent is willing to bear. This is at the basis of the well established economic principle of the *certainty equivalent*, stating that the price of a claim should be the one that makes the agent indifferent between possessing the claim or its (certain) price. Such a method has the advantage of being both economically sound and mathematically and computationally simple, requiring at most the numerical evaluation of an equation. This procedure, however, does not seem so appropriate when at least some of the assets can be traded on a financial market: in fact, if the agent is in the position of performing some kind of partial hedging, this should be incorporated in the pricing paradigm, and investors can no longer be expected to passively require an equivalent compensation for claims without engaging in any trading activity. This idea is at the heart of the pricing method that we consider in this paper, i.e. *utility indifference pricing*, a subject that has attracted quite a lot of attention in recent years (see Henderson and Hobson's survey [HH09]), in particular as a consequence of the important developments in the theory of optimal investment.

In this article we consider a model for traded and nontraded assets, that are supposed to be uncorrelated. Models of this type are usually called semi-complete product market models (as in, e.g., [Be03]). The prices of traded assets follow a complete multivariate Black-Scholes model, while the prices of non traded ones evolve as generalized Ornstein-Uhlenbeck processes. This is mainly motivated by the recent literature on structural models for electricity markets, which aim at describing electricity prices as a result of the interaction of some underlying structural factors that can be either exchanged on a financial markets (like fuels) or not (like demand and fuel capacities), and which are often supposed to have simple Gaussian dynamics.

In our framework the payoff is supposed to be a function of both traded and nontraded assets, contrarily to most of the literature where the payoff depends only on the nontraded assets which are assumed to be correlated to the traded ones, so that one usually works directly with the correlation of the traded assets with the payoff to be hedged (see, for example, [He02], [Be06], [AID10], [FS08], [IRR12]). An exception is [SZ04], where the payoff considered depends on both types of assets in a bidimensional stochastic volatility framework where the payoff is assumed to be smooth and bounded. Relying on correlation can be advantageous in some situations but not, in general, in the context of structural models, where the expressions for correlations usually become quite complex even if the model is relatively simple. In these cases it is often more convenient to avoid the computation of correlation, by leaving the payoff expressed as a function of both traded and nontraded assets (by eventually exploiting their particular structure, for example their independence or Gaussian properties, to simplify the problem).

The typical tool that is used to analyse utility indifference prices is the theory of (quadratic) BSDEs, that was first introduced in a similar context by the seminal paper [ER00] and which is particularly convenient as it generalizes with no additional effort to a large class of (possibly non-Markovian) settings (for example [Be06]). Classical results require, however, boundedness or at least exponential integrability of the claim and they are only capable to identify the optimal hedging strategy when the final claim is bounded. This is a serious drawback if we notice that common payoff functions in structural models for electricity prices are linear functions of geometric brownian motions (wich are neither bounded nor exponentially integrable).

The first contribution of this work is therefore to prove the existence of (exponential) utility indifference prices without requiring boundedness or exponential integrability for the payoff, but only using sub- and super-replicability instead. Nonetheless, the question remains of whether we can actually interpret the Z-part of the BSDE in terms of the optimal hedging strategy in this case, given in particular that we lack the BMO property that is generally used to verify this (see [HIM05]). With this motivation in mind, we proceed to study the regularity and to get some estimates on Z, by using the stochastic control representation of the problem or some Malliavin-type formulas for BSDEs in the spirit of [Zh05] or [MZ02]. This is why in the second part of the paper we focus on Vanilla payoffs, by allowing them in particular to be possibly discontinuous, which is often the case in models aiming to describe regime-changing features. Given our simple Gaussian modeling framework, considering Vanilla payoffs leads naturally to a link with PDEs: our second contribution, indeed, is to describe the price as a viscosity solution of a suitable PDE and, most importantly, to prove that the solution is sufficiently regular to possess continuous first derivatives (in space), providing a useful representation for Z which allows to write the candidate optimal hedging strategy in a similar way as the usual delta hedge. This candidate strategy is then proved to be optimal under some growth assumptions on the payoff (which does not, however, need to be bounded). We stress that our approach is crucially based on the fact that the driver in our BSDE is quadratic in the components of Z corresponding to the nontraded assets whereas it is linear in the other components. Since there is in general no hope to solve the PDE explicitly, we also provide asymptotic expansions for the price (adapting a result in [Mo12]) and (under some additional regularity) for the optimal hedging strategy. As already mentioned, we finally provide an application to the pricing of power derivatives under a structural modeling framework.

The paper is organized as follows. We introduce the model in Section 2, along with the definition of trading strategies and utility indifference prices, by also deriving some bounds and pointing out the connection with the related concept of certainty equivalent. In Section 3 we use some results of the theory of optimal investment (due to [HIM05] and [OZ09]) in order to derive a BSDE representation of the price, without the assumption of boundedness or exponential integrability of the claim that are usually encountered in the literature on quadratic BSDEs (for example [Ko00] or [BH07]). In Section 4 we focus on Vanilla payoffs and we express the price and the optimal hedge in terms of viscosity solutions of a certain PDE. Particular attention is devoted to the case of discontinuous payoffs, that we are able to treat by extending some of the techniques found in [Zh05]. Asymptotic expansions are also derived following essentially the lines of [Da97] and [Mo12]. In Section 5 we finally present some applications to electricity markets.

2 The model

Let T > 0 be a finite time horizon. We place ourselves on a filtered probability space $(\Omega, \mathbb{F} = (\mathcal{F}_t)_{0 \le t \le T}, P)$, where \mathbb{F} is the natural filtration generated by the (n + d)-dimensional Brownian motion $W = (W^S, W^X)$ and satisfying the usual conditions of right-continuity and P-saturatedness. Throughout the paper we will use the notation y^S and y^X to distinguish the first n and last d components of a vector $y = (y^S, y^X)$ of size n + d. The distinction is useful, as we will see, to separate tradable and non tradable assets. Moreover, we will denote $\mathbb{F}^S = (\mathcal{F}^S_t)_{0 \le t \le T}$ and $\mathbb{F}^X = (\mathcal{F}^X_t)_{0 \le t \le T}$ the natural filtrations generated, respectively, by W^S and W^X . The notation E_t will denote conditional expectations under P and with respect to the σ -field \mathcal{F}_t .

Moreover, for any positive integer $l \ge 1$ and any real number p > 0, we will denote $\mathbb{H}^p(\mathbb{R}^l)$ (resp. $\mathbb{H}^p_{\text{loc}}(\mathbb{R}^l)$) the set of all \mathbb{F} -predictable \mathbb{R}^l -valued processes $Z = (Z_t)_{0 \le t \le T}$ such that $E[\int_0^T ||Z_t||^p dt] < +\infty$ a.s. (resp. $\int_0^T ||Z_t||^p dt < +\infty$).

For a vector x, we denote x' its transpose and diag(x) the diagonal matrix such that diag $(x)_{ii} = x_i$ for all i. For a matrix α , we denote α_i , $\alpha_{\cdot j}$ its i'th row or j'th column and $\alpha^{-n} := (\alpha^{-1})^n$. For any positive integer $d \ge 1$, we denote 0_d the d-dimensional zero vector.

Tradable assets. We consider a finite horizon multivariate Black and Scholes market model with n tradable risky assets with dynamics

$$\frac{dS_t^i}{S_t^i} = \mu_i dt + \sigma_i \cdot dW_t^S, \quad i = 1, \dots, n$$

$$(2.1)$$

where σ is a $n \times n$ invertible matrix and σ_i . denotes its *i*-th row. We assume for the sake of simplicity that the interest rate is zero.

REMARK 2.1 The results of this paper can be easily extended to the case where the drift and the volatilities in the dynamics of the tradable assets S are bounded functions of these assets, i.e. of the form $\mu(S_t)$ and $\sigma(S_t)$. For the sake of simplicity, we will work under the assumption that they are linear as in (2.1).

Nontradable assets. Apart from traded assets, we introduce d non traded assets following the (generalized) Ornstein-Uhlenbeck processes

$$dX_{t}^{i} = (b_{i}(t) - \alpha_{i}X_{t}^{i})dt + \beta_{i}.dW_{t}^{X}, \quad i = 1, \dots, d,$$
(2.2)

where α_i is a constant, $b_i : [0,T] \to \mathbb{R}$ is a bounded measurable function and β_i . is the *i*-th row of the $d \times d$ -dimensional matrix β . It is important to remark that as they are defined, tradable and non tradable assets are independent. This is a crucial assumption in what follows. From the modeling viewpoint this is pretty natural since the application we have in mind is to energy markets, where the non tradable assets typically are the electricity demand and the power plant capacities, while the tradable ones are the fuels used in the power production process (such as, for instance, gas, oil and coal).

Equivalent martingale measures. Since the market filtration \mathbb{F} is generated by both Brownian motions W^S and W^X , the resulting market model is clearly incomplete and the set \mathcal{M} of absolutely continuous martingale measures for $S = (S^1, \ldots, S^n)$ does not reduce to a singleton. It is well known from the literature (see Schweizer's survey [Sc01]) that the minimal martingale measure (MMM henceforth) plays an important role for pricing and hedging derivatives. We denote such a measure Q^0 and we recall that it is defined as

$$\frac{dQ^0}{dP} = \mathcal{E}_T(-\theta \cdot W^S),$$

where $\theta = \sigma^{-1}\mu$ and \mathcal{E} denotes the stochastic exponential. Remark that in our case the elements of \mathcal{M} are of the form $\zeta_T = \frac{dQ^0}{dP}M_T$, where the process M is nonnegative and satisfies $E[\zeta_T] = 1$. The dynamics of M can be written as

$$dM_t = \eta_t dW_t^X \quad M_0 = 1 \tag{2.3}$$

for some \mathbb{F} -predictable process η . The choice $\eta = 0$ (i.e. M = 1) corresponds to the MMM. We denote $W^{S,0} = W^S + \theta t$, $W^0 = (W^{S,0}, W^X)$, and E^0 the expectation operator under Q^0 . Notice that Girsanov's theorem clearly implies that W^0 is a (n+d)-dimensional Brownian motion under this measure.

Trading strategies. In this model, the wealth process of an agent starting from an initial capital $v \in \mathbb{R}$ and trading in the risky assets S in a self-financing way over the period [0, T] can be written

$$V_t^v(\pi) = v + \int_0^t \pi'_s(\mu ds + \sigma dW_s^S) = v + \int_0^t \pi'_s \sigma(\theta ds + dW_s^S)$$

where π_s is a $n \times 1$ vector representing the investor's trading strategy (in euros) at time s and μ is a column vector containing the μ_i 's. We will need to be more precise later about admissibility conditions on strategies. It is then useful to introduce the following sets:

 $\mathcal{H} = \{ \pi \in \mathbb{H}^2_{\text{loc}}(\mathbb{R}^n) : V^0(\pi) \text{ is a } Q - \text{supermartingale for all } Q \in \mathcal{M}_E \}$ $\mathcal{H}_M = \{ \pi \in \mathbb{H}^2_{\text{loc}}(\mathbb{R}^n) : V^0(\pi) \text{ is a } Q - \text{martingale for all } Q \in \mathcal{M}_E \}$ $\mathcal{H}_b = \{ \pi \in \mathbb{H}^2_{\text{loc}}(\mathbb{R}^n) : V^0(\pi) \text{ is uniformly bounded from below by a constant} \},$

where \mathcal{M}_E denotes the subset of measures in \mathcal{M} with finite relative entropy.

Utility indifference pricing. We will focus our interest in contingent claims which can depend on both tradable and non tradable assets and which satisfy the following assumption.

Assumption 2.1 The claim f belongs to $L^2(Q^0, \mathcal{F}_T)$, it is super/sub-replicable, i.e.

$$V_T^{v_1}(\pi_1) \le f \le V_T^{v_2}(\pi_2)$$

for some $v_1, v_2 \in \mathbb{R}$ and $\pi_1 \in \mathcal{H}_M, \pi_2 \in \mathcal{H}$. The random variables $V_T^{v_1}(\pi_1), V_T^{v_2}(\pi_2)$ lie in $L^1(Q^0, \mathcal{F}_T)$.

We focus in this paper on the case of exponential utility $U(x) = -e^{-\gamma x}$, $\gamma > 0$, and we look at the buying utility indifference price p^b of the claim f as implicitly defined as a solution to

$$\sup_{\pi} E\left[U\left(V_T^{v-p^b}(\pi) + f\right)\right] = \sup_{\pi} E\left[U(V_T^v(\pi))\right]$$
(2.4)

where $v \in \mathbb{R}$ is the initial wealth and the supremum is either taken over \mathcal{H} or \mathcal{H}_b . It is easily seen that under exponential utility the price is independent of the initial agent's wealth. By Theorem 1.2 in [OZ09] the suprema in definition (2.4) are unchanged whether the optimizing set is \mathcal{H} or \mathcal{H}_b , though the maximum will in general be attained in the larger set \mathcal{H} .

We will call *optimal hedging strategy* and denote it Δ the difference between the maxima $\hat{\pi}^f$ and $\hat{\pi}^0$ in, respectively, the LHS and RHS of (2.4), i.e. $\Delta = \hat{\pi}^f - \hat{\pi}^0$.

The selling price p^s is defined similarly as the solution to

$$\sup_{\pi} E\left[U\left(V_T^{v+p^s}(\pi) - f\right)\right] = \sup_{\pi} E\left[U(V_T^v(\pi))\right].$$

We start with a simple preliminary result showing how these prices are related to the expected payoff under the MMM (which can also be interpreted as a price under a certain risk minimizing criterion, see [Sc01]). The next result can also be found in [Ho05], Theorem 3.1 under slightly different assumptions. We provide here another proof which allows for a little bit more general result as it is only based on a duality formula (without requiring the Assumption 2.2 in [Ho05], even though it would be satisfied in our particular context), and which is also useful to compare utility indifference prices with certainty equivalents (see Remark 2.3).

LEMMA 2.1 It holds that

$$v_1 \le p^b \le E^0[f] \le p^s \le v_2$$

where v_1, v_2 are the same as in Assumption 2.1.

Proof. We start from the well-known duality result (see [OZ09], Theorem 1.1):

$$\sup_{\pi} E[U(V_T^{v-p^b}(\pi)+f)] = \inf_{\delta>0} \inf_{\zeta_T \in \mathcal{M}} \left\{ \delta(v-p^b) + \delta E[\zeta_T f] + E[U^*(\delta\zeta_T)] \right\}$$
(2.5)

where $\zeta_T = \frac{dQ^0}{dP} M_T$ as in (2.3) and U^* is the conjugate of U. By taking M = 1 (equivalently, $\eta = 0$) we get

$$\sup_{\pi} E[U(V_T^{v-p^b}(\pi)+f)] \le \inf_{\delta>0} \left\{ \delta\left(v-p^b+E^0\left[f\right]\right) + E\left[U^*\left(\delta\frac{dQ^0}{dP}\right)\right] \right\}$$

Now by using (2.4) and (2.5) for f = 0, we get that

$$\inf_{\delta>0} \inf_{\zeta_T \in \mathcal{M}} \left\{ \delta v + E[U^*(\delta\zeta_T)] \right\} \le \inf_{\delta>0} \left\{ \delta \left(v - p^b + E^0[f] \right) + E\left[U^*\left(\delta \frac{dQ^0}{dP} \right) \right] \right\}.$$
(2.6)

We want to show that the minimizer in the LHS corresponds to the MMM. Remark now that for each $\delta > 0$ and $\zeta_T = \frac{dQ^0}{dP} M_T$ by using convexity of U^* and conditional Jensen's inequality we get

$$E[U^*(\delta\zeta_T)] = E\left[U^*\left(\delta\frac{dQ^0}{dP}M_T\right)\right] = E\left[E\left[U^*\left(\delta\frac{dQ^0}{dP}M_T\right)|\mathcal{F}_T^S\right]\right]$$
$$\geq E\left[U^*\left(\delta E\left[\frac{dQ^0}{dP}M_T|\mathcal{F}_T^S\right]\right)\right] = E\left[U^*\left(\delta\frac{dQ^0}{dP}E\left[M_T|\mathcal{F}_T^S\right]\right)\right]$$
$$= E\left[U^*\left(\delta\frac{dQ^0}{dP}\right)\right]$$
(2.7)

where we used the fact that $E[M_T | \mathcal{F}_T^S] = 1$ a.s., which can be shown as follows. By defining $N_t = E_t \left[\frac{dQ^0}{dP} \right] = E \left[\frac{dQ^0}{dP} | \mathcal{F}_t^S \right]$ we have that

$$E[N_T M_T] = 1 = N_0 M_0$$

since $N_T M_T$ is a martingale measure density for S. Since S and X are independent, the process M in (2.3) is a positive local martingale in the larger filtration $(\mathcal{F}_T^S \vee \mathcal{F}_t^X)_{0 \le t \le T}$, hence a supermartingale, implying in particular

$$E[M_T | \mathcal{F}_T^S] \le E[M_0 | \mathcal{F}_T^S] = 1.$$

If the previous inequality was strict on a set $F \in \mathcal{F}_T^S$ of strictly positive probability then we would get the contradiction

$$E[N_T M_T] = E\left[N_T E[M_T | \mathcal{F}_T^S]\right] < M_0 E[N_T] = 1.$$

Therefore if we had $E^{0}[f] - p^{b} < 0$ by using (2.6) and the previous argument we would get the contradiction

$$\inf_{\delta>0} \left\{ \delta v + E[U^*(\delta\zeta_T^0)] \right\} < \inf_{\delta>0} \left\{ \delta v + E[U^*(\delta\zeta_T^0)] \right\}.$$

This proves $p^b \leq E^0[f]$.

Now consider the super-replicating strategy π_2 for the claim f, starting from a given initial capital v_2 . Since

$$\sup_{\pi} E\left[U\left(V_T^{v+v_2}(\pi) - f\right)\right] \ge E\left[U\left(V_T^v(\pi) + V_T^{v_2}(\pi_2) - f\right)\right] \ge E\left[U(V_T^v(\pi))\right]$$

and therefore

$$\sup E\left[U\left(V_T^{v+v_2}(\pi) - f\right)\right] \ge \sup E\left[U(V_T^v(\pi))\right]$$

 $\sup_{\pi} E\left[U\left(v_T + \frac{\pi}{2}(\pi) - J\right)\right] \ge \sup_{\pi} E\left[U\left(v_T(\pi)\right)\right]$ we deduce that the selling price p^s must verify $p^s \le v_2$. The other inequalities are obtained by similar arguments.

REMARK 2.2 The previous result confirms that utility indifference valuation gives rise to a sort of bid-ask spread and the price computed under the MMM can be interpreted as a mid price. The fact that utility indifference buying (selling) prices are always higher (lower) than sub(super)-replication prices also justifies their interest.

REMARK 2.3 A related pricing method is given by the *certainty equivalent*, which is quite popular in the economic literature and which has been explored by Benth et al. ([BCK07]) in the context of electricity markets. In that paper, there is no financial market where the investor could possibly trade. This is one of the main differences with respect to our approach. In the absence of correlation between traded and nontraded assets, the certainty equivalent method provides the same prices as utility indifference evaluation when the payoff is just a bounded function of the nontraded assets. To see this, remark that when the payoff is bounded we can always perform a probability change and write

$$E[U(V_T^0(\pi) + f - p^b)] = E[e^{-\gamma(f - p^b)}]E^{Q^f}[U(V_T^0(\pi))] = E^{Q^f}[cU(V_T^0(\pi))]$$

with c > 0 and the change of measure $\frac{dQ^f}{dP} = \frac{e^{-\gamma(f-p^b)}}{E[e^{-\gamma(f-p^b)}]}$ only affecting the nontraded assets. Let U^* denote the conjugate of U. By using $(cU)^*(y) = cU^*(y/c)$, the definition (2.4), the duality results (2.5) and (2.7) we get

$$\inf_{\delta>0} E\left[U^*\left(\delta\frac{dQ^0}{dP}\right)\right] = \inf_{\delta>0} E^{Q^f}\left[(cU)^*\left(\delta\frac{dQ^0}{dP}\right)\right]$$

which becomes

$$\inf_{\delta>0} E\left[U^*\left(\delta \frac{dQ^0}{dP}\right)\right] = E\left[e^{-\gamma(f-p^b)}\right] \inf_{\delta>0} E\left[U^*\left(\frac{\delta}{E\left[e^{-\gamma(f-p^b)}\right]}\frac{dQ^0}{dP}\right)\right],$$

that is trivially satisfied by the certainty equivalent $p^b = -\frac{1}{\gamma} \ln E[e^{-\gamma f}]$. However, when the payoff does depend on the traded assets (as in the examples of power derivatives given in Section 5) the two methods can provide completely different results due to the existence of additional investment opportunities offered by some financial market as it is the case in our model. Notice for instance that the certainty equivalent applied to a payoff which is linear in s (uniformly in x) can produce an infinite buying or selling price (since geometric Brownian motion does not have all exponential moments), while by the previous lemma utility indifference prices will always be finite, as the payoff is super/sub-replicable.

3 Utility indifference pricing via BSDEs

In this section we extend to our setting the classical characterization of the utility indifference price of a contingent claim f in terms of the solution of a suitable BSDE. This characterization has to be proved in our framework since we are not assuming boundedness of f nor that it has finite exponential moments, which are the usual conditions imposed in the existing literature. These conditions would not be satisfied in the application to power derivatives that we have in mind (see Section 5). From now on we will only focus on buying prices, the selling counterpart being easily obtained by symmetry (see Remark 3.4).

The following result shows how the utility indifference price (UIP for short) is linked to the solution of the BSDE^{*}

$$Y_t = f - \int_t^T \left(\frac{\gamma}{2} \|Z_s^X\|^2 + \mu' \sigma^{-1} Z_s^S\right) ds - \int_t^T Z_s dW_s$$
(3.1)

which can also be written under the MMM Q^0 in the simpler form

$$Y_t = f - \int_t^T \frac{\gamma}{2} \|Z_s^X\|^2 ds - \int_t^T Z_s dW_s^0.$$
 (3.2)

We start by assuming that f is bounded. The next step will consist in replacing the boundedness of f with its sub/super-replicability as in Assumption 2.1.

LEMMA 3.1 Suppose f is bounded. Then $p^b = Y_0$, where (Y, Z) is the unique solution of BSDE (3.1) satisfying

$$E\left[\sup_{0\leq t\leq T}|Y_t|^2+\int_0^T\|Z_t\|^2dt\right]<\infty.$$

Moreover, the optimal trading strategy is given by $\Delta_t = -\sigma^{-1} Z_t^S$.

Proof. We use the results in [HIM05]. By definition of UIP we are allowed to only consider strategies in \mathcal{H}_b , so that the admissibility conditions in Definition 1 in [HIM05] are satisfied (apart from square integrability of $\pi'\sigma$, which is not necessary for what follows). A simple application of Theorem 7 in [HIM05] gives the results.

REMARK 3.1 The result can be also easily derived by properly modifying the proof of Lemma 2.4 in [HL11]. However that approach requires a BMO property for admissible strategies which we do not assume.

We now want to show that (3.1) still admits a solution when f is possibly unbounded but still satisfies Assumption 2.1. We insist once more on the fact that the result is not immediately obvious from the standard literature since f does not necessarily possess exponential moments (e.g. if it depends linearly on the final value of some tradable assets as in our examples in Section 5 of the paper).

LEMMA 3.2 Under Assumption 2.1 BSDE (3.2) admits a solution in the space of predictable processes $(Y, Z) = (Y, (Z^S, Z^X))$ with values in $\mathbb{R} \times \mathbb{R}^{n+d}$ such that \mathbb{P} -a.s., $t \mapsto Y_t$ is continuous, $t \mapsto Z_t$ belongs to $L^2(0,T)$ and $t \mapsto ||Z_t^X||^2$ belongs to $L^1(0,T)$.

Proof. We adapt the arguments in the proof of Proposition 3 in [BH07]. Let us first suppose that f is nonnegative. Rewrite equation (3.2) as

$$Y_t = f + \int_t^T g(Z_s) ds - \int_t^T Z_s dW_s^0,$$
(3.3)

with $g(z) = -\frac{\gamma}{2} ||z^X||^2$, and denote $f_n = f \wedge n$, $L_t = E_t^0[f] + E_t^0[|V_T^{v_1}(\pi_1)|]$, $L_t^n = E_t^0[f_n] + E_t^0[|V_T^{v_1}(\pi_1)|]$ (which are well defined thanks to Assumption 2.1). Let (Y^n, Z^n) be the minimal bounded solution

^{*}It can be viewed as an uncoupled FBSDE since traded and nontraded assets entering in f have forward dynamics.

to (3.3) where f is replaced by f_n (it exists by [Ko00], Theorem 2.3). By (3.7) and (3.8) we have that $|Y_t^n| \leq L_t^n \leq L_t$ for all n. Moreover the sequence $(Y^n)_{n\geq 1}$ is nondecreasing by the comparison theorem (see [Ko00], Theorem 2.3). From now on the proof follows verbatim the one of Proposition 3 in [BH07]. It is therefore omitted.

We would like now to be able to interpret the solution Y constructed in the previous lemma as the UIP of the claim f. We borrow and adapt the next result from [OZ09], which gives some sufficient conditions ensuring this property. Those conditions are quite easy to verify in our setting for a large class of contingent claims (see Section 5), since the independence between tradable and non tradable assets implies a very simple product structure for the set \mathcal{M} of all absolutely continuous martingale measures for S.

LEMMA 3.3 Let f be a contingent claim satisfying Assumptions 2.1 and let $f_n = (-n) \lor f \land n, n \ge 1$. If

$$\sup_{Q \in \mathcal{M}_E} E^Q[f_n - f] \to 0, \quad \inf_{Q \in \mathcal{M}_E} E^Q[f_n - f] \to 0$$
(3.4)

as $n \to \infty$ then $Y_0 = p^b$, where Y solves (3.1).

Proof. Following the previous proof, we know that $Y_0^n = p^b(f_n)$, the buying UIP of f_n , and that $Y_0^n \to Y_0$, where Y solves (3.1). By Proposition 5.1 (iii) in [OZ09] we know that

$$\sup_{\pi} E\left[-e^{-\gamma\left(V_T^{v-p^b(f_n)}(\pi)+f_n\right)}\right] \to \sup_{\pi} E\left[-e^{-\gamma\left(V_T^{v-Y_0}(\pi)+f\right)}\right]$$
$$Y_0 = p^b.$$

which implies that $Y_0 = p^b$.

REMARK 3.2 Even though the uniqueness of the solution to the BSDE (3.2) is not guaranteed, due to the unboundedness of the terminal condition, the previous result implies the convergence of the (unique) bounded minimal solution corresponding to the truncated claim to the good price, meaning that the UIP of the claim f can be arbitrarily approximated by the (unique) solution Y^n of the BSDE with truncated final value f_n with n sufficiently large.

REMARK 3.3 Notice that the conditions in (3.4) are automatically satisfied whenever the super/subreplicating portfolio strategies are \mathbb{F}^S -predictable and the portfolio values $V_T^{v_1}(\pi_1)$ and $V_T^{v_2}(\pi_2)$ are in $L^2(Q^0, \mathcal{F}_T)$. This follows from the fact that, for any $Q \in \mathcal{M}_E$, we have

$$\begin{split} E^{Q}[|f_{n} - f|] &= E^{Q}[|f_{n} - f|\mathbf{1}_{|f|\geq n}] \leq \|f_{n} - f\|_{L^{2}(Q)}Q(|f|\geq n)^{1/2} \\ &\leq \|f_{n} - f\|_{L^{2}(Q)}Q(|V_{T}^{v_{1}}(\pi_{1})| + |V_{T}^{v_{2}}(\pi_{2})|\geq n)^{1/2} \\ &\leq C\|f\|_{L^{2}(Q)}Q(|V_{T}^{v_{1}}(\pi_{1})| + |V_{T}^{v_{2}}(\pi_{2})|\geq n)^{1/2} \\ &\leq C(\|V_{T}^{v_{1}}(\pi_{1})\|_{L^{2}(Q)} + \|V_{T}^{v_{2}}(\pi_{2})\|_{L^{2}(Q)})Q(|V_{T}^{v_{1}}(\pi_{1})| + |V_{T}^{v_{2}}(\pi_{2})|\geq n)^{1/2} \\ &= C(\|V_{T}^{v_{1}}(\pi_{1})\|_{L^{2}(Q^{0})} + \|V_{T}^{v_{2}}(\pi_{2})\|_{L^{2}(Q^{0})})Q^{0}(|V_{T}^{v_{1}}(\pi_{1})| + |V_{T}^{v_{2}}(\pi_{2})|\geq n)^{1/2} \\ &\rightarrow 0 \end{split}$$

as $n \to \infty$, where C > 0 is some constant varying from line to line. This will be the case under, e.g., the Assumptions 4.1 and 4.2 that we will introduce in the next section.

We will now focus on Vanilla claims. This will allow, under proper assumptions, to get more information about the process Z and therefore on the hedging strategy. In particular, representation results like those found in [MZ02] or [Zh05] will reveal to be useful to study the continuity of Z and the possibility to express it starting from the spacial (classical) derivatives of the solution of a given partial differential equation. This will also allow to obtain some estimates on Z which permit to interpret it in terms of the optimal hedging strategy under some less restrictive hypotheses than the boundedness of f (which is required in the standard martingale optimality approach of [HIM05] to prove a BMO property for Z which is needed to identify it with the hedging strategy). REMARK 3.4 We decide to focus the discussion on buying prices, however most of the results can be adapted to selling prices. In particular the usual relation $p^s(f) = -p^b(-f)$ holds between selling and buying prices. The natural candidate for the selling price is the solution to the BSDE

$$Y_t = f + \int_t^T \frac{\gamma}{2} \|Z_s^X\|^2 ds - \int_t^T Z_s dW_s^0.$$
(3.5)

Remark immediately the sort of symmetry with (3.2). Existence for (3.5) can be obtained by following the proof of Lemma 3.2, but using the super (instead of sub)-replicating process in Assumption 2.1 as a bound. Moreover, under the same conditions as in Lemma 3.3 we are able to interpret this solution as the selling price. All the other results still hold for selling prices with minor modifications. In particular, Lemma A.1 finds its analogue in Lemma A.5. Both are relegated in the Appendix for the sake of readability.

REMARK 3.5 We observe that definition (2.4) can be easily extended to the conditional case by defining the (buying) price p_t^b as the \mathcal{F}_t -measurable r.v. satisfying

$$\operatorname{ess\,sup}_{\pi} E_t \left[U \left(V_T^{v-p_t^b}(\pi) + f \right) \right] = \operatorname{ess\,sup}_{\pi} E_t \left[U (V_T^v(\pi)) \right], \tag{3.6}$$

where the set of admissible strategies is restrained to those starting at t from an \mathcal{F}_t -measurable wealth v. We denote $p_0^b = p^b$. Lemma 2.1 can therefore be slightly generalized to obtain that

$$V_t^{v_1}(\pi_1) \le p_t^b \le p_t^s \le V_t^{v_2}(\pi_2).$$
(3.7)

Generalizing the other bounds to obtain $p_t^b \leq E_t^0[f]$ is a little bit more delicate since the duality results in [OZ09] are not extended to the conditional primal problem. A partial result can be obtained using the representation (3.2), which extends to the dynamic UIP as well. Indeed the classical comparison result for quadratic BSDEs applies and allows to obtain

$$p_t^b \le E_t^0[f], \quad t \in [0, T].$$
 (3.8)

4 Pricing and hedging of Vanilla payoffs

In this section we address the problem of computing the utility indifference price and the corresponding optimal hedging strategy of a Vanilla contingent claim f, which is a function of both tradable and non tradable assets at the terminal date T, i.e. we assume (with a slight abuse of notation) that $f = f(S_T, X_T)$ for some measurable function $f : \mathbb{R}^n_+ \times \mathbb{R}^d \to \mathbb{R}$. We denote $f_{s^i \pm}(s, x)$ and $f_{x^j \pm}(s, x)$ the right/left derivatives of the function f(s, x) with respect to, respectively, s^i and x^j for $i = 1, \ldots, n$ and $j = 1, \ldots, d$.

We use the notation $A_t = (S_t, X_t)$ when we wish to consider asset processes with no distinction. The standard notation $E_{t,a}$ denotes expectation with respect to \mathcal{F}_t given that the process A takes the value a = (s, x) at time t. Our goal is to obtain a complete characterization of the optimal hedging strategy Δ as well as asymptotic expansions of the price of the contingent claim f for a small risk aversion parameter γ . Using BSDE techniques and thanks to the Markovian framework, we are able to do so for a large class of non-smooth contingent claims. More precisely, we consider the following two kinds of assumptions for f.

ASSUMPTION 4.1 (Continuous non-smooth payoffs) The payoff function f is continuous and a.e. differentiable. Moreover, f and its right/left derivatives grow polynomially in s, uniformly in x, i.e.

$$|f(s,x)| + |f_{s^i\pm}(s,x)| + |f_{x^j\pm}(s,x)| \le C(1+\|s\|^q), \quad (s,x) \in \mathbb{R}^n_+ \times \mathbb{R}^d_+$$

for all i = 1, ..., n and j = 1, ..., d and for some $q \ge 1$, where the constant C does not depend on x.

Assumptions 4.2 (Discontinuous payoffs) The payoff function f is bounded from below and a.e. differentiable. Moreover

- (i) f may have finitely many discontinuities only in the x-variables and outside these points f is continuously differentiable.
- (ii) Where it exists, its derivative $f_{s^i\pm}(s,x)$ is bounded, and in particular $f_{s^i\pm}(s,x) = O(1/s^i)$ for s^i large enough, for all i = 1, ..., n uniformly in x.
- (iii) Where it exists, its derivative $f_{x^j\pm}(s,x)$ verifies $|f_{x^j\pm}(s,x)| \le C(1+||s||^q)$ for all $j=1,\ldots,d$ and some $q \ge 1$, where the constant C > 0 does not depend on x.

We see that if we want to treat discontinuous payoffs we need stronger growth assumptions than in the continuous case. In particular the hypothesis (ii) in Assumptions 4.2 implies a uniform logarithmic growth of f in the traded assets. The main example we think of in this case is a payoff which separates the contributions of traded and nontraded assets in a multiplicative way (see Section 5 for some examples coming from electricity markets).

Since $f = f(A_T) = f(S_T, X_T)$ we can exploit the Markovian setting and look for a solution to (3.1) of the form $Y_t = \varphi(t, A_t)$ where $\varphi(t, a) = \varphi(t, s, x)$ solves the PDE

$$\begin{cases} \mathcal{L}\varphi - \frac{\gamma}{2} \sum_{j=1}^{d} (\beta'_{.j}\varphi_x)^2 = 0\\ \varphi(T, a) = f(a) \end{cases}$$
(4.1)

where $\beta_{.j}$ denotes the *j*-th column of the matrix β and

$$\mathcal{L}\varphi = \varphi_t + (b - \alpha x)\varphi_x + \frac{1}{2}\sum_{i,j=1}^n \sigma_{i} \cdot \sigma_{\cdot j} s^i s^j \varphi_{s^i s^j} + \frac{1}{2}\sum_{i,j=1}^d \beta_{i} \cdot \beta_{\cdot j} \varphi_{x^i x^j}.$$

When the claim is smooth, it is a standard result that φ is a classical solution to the PDE above and moreover we expect to have $Z^{X,i} = \beta'_i \varphi_x$, where φ_x is the (*d*-dimensional) gradient of φ with respect to x (see, e.g. Step 1 of the proof of Lemma 4.1 below). Otherwise, the more difficult case of a non-smooth claim is the content of Theorem 4.1 below. Before stating it, denote

$$h(q) = \frac{\gamma}{2} \|q\|^2 = \sup_{\delta \in \mathbb{R}^d} \left\{ -q\delta - \frac{1}{2\gamma} \|\delta\|^2 \right\}, \quad q \in \mathbb{R}^d.$$

In this way (4.1) can be written as

$$\begin{cases} -\mathcal{L}\varphi + h(\beta'\varphi_x) = 0\\ \varphi(T,a) = f(a). \end{cases}$$
(4.2)

The main result of this section can be summarized in the following theorem.

THEOREM 4.1 Let $f = f(A_T) = f(S_T, X_T)$ be a given Vanilla type contingent claim for some measurable payoff function $f : \mathbb{R}^n_+ \times \mathbb{R}^d \to \mathbb{R}$. We have the following properties.

- (i) Under Assumption 4.1 or Assumptions 4.2 the buying UIP φ of the claim f is a viscosity solution of (4.1) on $[0,T) \times \mathbb{R}^n_+ \times \mathbb{R}^d$, which is also differentiable in all the space variables.
- (ii) The optimal hedging strategy is given by

$$\Delta_t = -\sigma^{-1} Z_t^S = -\sigma^{-1} \sigma(S_t) \varphi_s(t, A_t),$$

where (Y,Z) is solution to (3.2) and $\sigma(S)$ the $n \times n$ matrix whose *i*-th row is given by $\sigma_i S^i$.

The same observations made in Remark 3.2 about uniqueness apply to these results as well. The rest of this section is devoted to prove Theorem 4.1 and to deduce some asymptotic expansions of the price and of the optimal hedging strategy for a small risk aversion parameter γ .

4.1 Proof of the main theorem

Before giving the technical details, we briefly sketch the main ideas underlying our proofs. Equation (4.2) suggests that we can look at our pricing problem as a stochastic control problem with a quadratic cost function: following this intuition, the idea of the proof is to start with a slightly modified reformulation (using some ideas developed in [Ph02]) in which the control space is forced to be compact. When the payoff is regular enough, this trick allows us to prove the existence of a smooth solution to the modified problem, which immediately extends to the original one by using some estimates on the derivatives which do not depend on the size of the control space. When the payoff is continuous but not smooth enough, we approximate it with a sequence of smooth ones (to which our previous results apply) and study the behavior of prices in the limit: in particular, by using a Malliavin-type representation of the derivatives which does not rely on the regularity of the payoff (which is due to [MZ02]), we are able to prove that the limiting price function remains differentiable in the state variables (though it possibly fails to be $C^{1,2}$). The case of discontinuous payoffs is a little bit more delicate: again the aim is to obtain some estimates on the derivatives which do not depend on the approximating sequence for the payoff, but here we can exploit neither the derivatives of the approximating sequence (which may explode due to the discontinuities) nor the Malliavin-type estimates in [MZ02] and [Zh05] which do not apply to quadratic BSDEs. We tackle the problem by performing a suitable change of measure, which however requires stronger assumptions with respect to the case of continuous payoffs.

4.1.1 An auxiliary problem with compact control space and smooth terminal condition

We start analyzing (4.2) by forcing the space of controls to be compact, in particular by replacing the function h(q) in (4.2) by $h^m(q)$ defined as

$$h^{m}(q) = \sup_{\delta \in \mathcal{B}^{m}(\mathbb{R}^{d})} \left\{ -q\delta - \frac{1}{2\gamma} \|\delta\|^{2} \right\}$$

where $\mathcal{B}^m(\mathbb{R}^d)$ is the ball in \mathbb{R}^d centered at zero and of radius m > 0. Thus, the PDE we consider in this section is

$$\begin{cases} -\mathcal{L}\varphi^m + h^m(\beta'\varphi_x^m) = 0\\ \varphi^m(T,a) = f(a). \end{cases}$$
(4.3)

We also write its associated BSDE

$$Y_t^m = f - \int_t^T h^m (Z_r^{X,m}) dr - \int_t^T Z_r^m dW_r^0$$
(4.4)

that we will refer to in the sequel. Existence and uniqueness of the solution for this BSDE are guaranteed by classical results in [PP90], since the generator h^m is a Lipschitz function.

LEMMA 4.1 Let m > 0. If $f \in C^3$ and f and all its first derivatives have polynomial growth, then there exists a classical solution φ^m to (4.3). If f is only of polynomial growth (and possibly discontinuous), then φ^m is characterized as a continuous viscosity solution to (4.3) with continuous first derivatives in all the space variables, which have the representation

$$\varphi_a^m(t,a) = E_{t,a}^0 \left[f(A_T) N_T - \int_t^T h^m (Z_r^{X,m}) N_r dr \right]$$
(4.5)

(where φ_a^m is to be interpreted as a column vector in \mathbb{R}^{n+d} containing the derivatives with respect to the traded and nontraded assets) with

$$N_r = \left(\begin{array}{c} \frac{1}{r-t}\sigma^{-1}(S_t)'(W_t^S - W_r^S)\\ \frac{1}{r-t}\int_t^r \operatorname{diag}(e^{-\alpha(u-t)})'\beta^{-1}dW_u^X \end{array}\right).$$

Moreover the following stochastic control representation holds:

$$\varphi^m(t,a) = \inf_{\delta \in \mathcal{A}_t^m} E_{t,a}^Q \left[\frac{1}{2\gamma} \int_t^T \|\delta_r\|^2 dr + f(A_T) \right]$$
(4.6)

for some auxiliary probability measure Q, under which

$$\begin{cases} \frac{dS_t^i}{S_t^i} = \sigma_i . dW_t^{S,Q}, \quad i = 1, \dots, n\\ dX_t^i = (b_i(t) - \alpha_i X_t^i + \beta_i . \delta_t) dt + \beta_i . dW_t^{X,Q} \quad i = 1, \dots, d \end{cases}$$
(4.7)

where $(W^{S,Q}, W^{X,Q})$ is a n-dimensional BM under the measure Q and \mathcal{A}_t^m stands for the class of adapted \mathbb{R}^d -valued controls δ_s starting from time t and such that $\|\delta_s\| \leq m$.

REMARK 4.1 Recall that only the dynamics of nontraded assets are touched under the new measure Q, while traded assets still evolve as under the MMM Q^0 .

Proof. We split the proof into two main steps.

Step 1: The case where f is smooth follows by Theorem 6.2 in [FR75] (or Theorem IV.4.3 in [FS06]). The reason for introducing the index m comes from the fact that those theorems require that controls must take values in a compact space.[†] The regularity of φ^m implies (by an application of Itô's lemma) that $\varphi^m(t, A_t) = Y_t^m$, where Y^m solves (4.4) and $Z_t^{X,m} = \beta' \varphi_x^m(t, A_t)$, $Z_t^{S,m} = \sigma(S_t)' \varphi_s^m(t, A_t)$. We need to introduce the tangent process of A, ∇A (see, e.g., equation (2.9) in [MZ02] for a definition),

which has the following characterization in our particular case: $(\nabla A_t)_{ii} = S_t^i / S_0^i$ if $i \leq n$, $(\nabla A_t)_{ii} =$ $e^{-\alpha_i t}$ if $n+1 \leq i \leq n+d$, $(\nabla A_t)_{ij} = 0$ if $i \neq j$. Now, define $\Sigma(S)$ as the $(n+d) \times (n+d)$ matrix composed by $\sigma(S)$ on the upper left side and β on the lower right side, being zero everywhere else. The $n \times n$ matrix $\sigma^{-1}(S)$ coincides with the matrix where the *i*-th column is equal to the *i*-th column of σ^{-1} divided by S^i . Then $\Sigma^{-1}(S_t)\nabla A_t$ is equal to $\sigma^{-1}(S_0)$ on the upper-left corner and β^{-1} on the lower-right corner, being zero everywhere else. Define the (n + d)-dimensional processes

$$M_r = \int_t^r (\Sigma^{-1}(S_u) \nabla A_u)' dW_u^0 = \begin{pmatrix} \sigma^{-1}(S_0)' (W_t^{S,0} - W_r^{S,0}) \\ \int_t^r \operatorname{diag}(e^{-\alpha u})' \beta^{-1} dW_u^X \end{pmatrix}$$

and

$$N_r = \frac{1}{r-t} M'_r (\nabla A_t)^{-1} = \begin{pmatrix} \frac{1}{r-t} \sigma^{-1} (S_t)' (W_t^S - W_r^S) \\ \frac{1}{r-t} \int_t^r \operatorname{diag}(e^{-\alpha(u-t)})' \beta^{-1} dW_u^X \end{pmatrix}.$$
(4.8)

Since h^m is a Lipschitz function for all fixed $m \ge 0$, we can apply the results in [MZ02] (in particular Theorem 4.2) to the processes M and N just defined to show that (4.5) is true. Theorem 4.2 in [MZ02] requires uniform parabolicity which is not respected in our case, however again this is not a problem for geometric Brownian motions since only the process M defined above enters in its proof.

Step 2: In order to prove the result for a general (possibly discontinuous) f we can adapt the proof of Theorem 3.2 in [Zh05] to our framework. In particular, we can take a sequence f^l of smooth functions with bounded first derivatives such that $f^l \to f$ a.e. as $l \to \infty$. Then we have $f^l(A_T) \to f(A_T)$ Q^0 -a.s. since all the processes have absolutely continuous densities. Then one defines

$$\varphi^{m,l}(t,a) = Y_t^{m,l} = f^l - \int_t^T h^m (Z_r^{X,m,l}) dr - \int_t^T Z_r^{m,l} dW_r^0$$

$$\varphi^{m,l}_a(t,a) = E_{t,a}^0 \left[f^l (A_T) N_T - \int_t^T h^m (Z_r^{X,m,l}) N_r dr \right]$$
(4.9)

We have

$$\varphi_a^{m,l}(t,a) = E_{t,a}^0 \left[f^l(A_T) N_T - \int_t^T h^m(Z_r^{X,m,l}) N_r dr \right]$$
(4.9)

[†]The lack of uniform parabolicity here can be handled by a standard logarithmic transformation in the tradable assets. Under the new logarithmic variable, however, the payoff will not preserve polynomial growth in general. Therefore the result should first be applied to PDE (4.3) (under the new variable) where the payoff is replaced by $f(s \wedge C, x)$ for some constant C > 0, then undoing the logarithmic change of variable and letting $C \to \infty$ will get the final result.

and with the same arguments as in [Zh05], Theorem 3.2 (slightly modified to our multivariate setting) we can also obtain the estimate

$$\|\varphi_a^{m,l}(t,a)\| \le C \frac{\|a\|^q}{\sqrt{T-t}}.$$
(4.10)

for some $q \ge 0$. Here the constant C does not depend on l but it depends on m through the Lipschitz constant of h^m . Applying classical stability results for BSDE established in, e.g., [MY07], Theorem 4.4, we have the convergence

$$E^{0}\left[\sup_{0 \le t \le T} |Y_{t}^{m,l} - Y_{t}^{m}|^{2} + \int_{0}^{T} ||Z_{t}^{m,l} - Z_{t}^{m}||^{2} dt\right] \to 0$$

as $l \to \infty$, where (Y^m, Z^m) solve (4.4) (but with a nonsmooth f as terminal condition). We deduce from Lemma 6.2 in [FS06] and the estimate (4.10) (which gives uniform convergence on compact subsets of $[0, T) \times \mathbb{R}^{n+d}$) that $\varphi^{m,l} \to \varphi^m$, where φ^m the unique viscosity solution of (4.3), which is continuous except possibly at T. Following the last part of Zhang's proof of Theorem 3.2 in [Zh05] we also obtain that φ^m is differentiable and we have

$$\varphi_a^m(t,a) = E_{t,a}^0 \left[f(A_T) N_T - \int_t^T h^m(Z_r^{X,m}) N_r dr \right].$$

It remains to prove that the stochastic representation (4.6) holds for φ^m . Clearly it holds for $\varphi^{m,l}$ as the approximating functions f^l are smooth, so one can apply Theorem 6.2 in [FR75] to get

$$\varphi^{m,l}(t,a) = \inf_{\delta \in \mathcal{A}_t^m} E_{t,a}^Q \left[\frac{1}{2\gamma} \int_t^T \|\delta_r\|^2 dr + f^l(A_T) \right]$$

with Q and \mathcal{A}_t^m as in the statement of the present lemma. Hence we have

$$\varphi^{m,l}(t,a) \le E_{t,a}^Q \left[\frac{1}{2\gamma} \int_t^T \|\delta_r\|^2 dr + f^l(A_T) \right]$$

for any $\delta \in \mathcal{A}_t^m$ and therefore

$$\varphi^m(t,a) \le E_{t,a}^Q \left[\frac{1}{2\gamma} \int_t^T \|\delta_r\|^2 dr + f(A_T) \right]$$

by dominated convergence (since f has polynomial growth), and

$$\varphi^m(t,a) \le \inf_{\delta \in \mathcal{A}_t^m} E_{t,a}^Q \left[\frac{1}{2\gamma} \int_t^T \|\delta_r\|^2 dr + f(A_T) \right]$$

To obtain the reverse inequality it suffices to note that we can choose $f^l \ge f$.

4.1.2 Continuous non-smooth payoffs

The next step is now to remove the dependence on the parameter m and to characterize the price φ . We work in this section under Assumption 4.1. We start with a useful probabilistic characterization of the derivatives of φ^m under this assumption (such derivatives exist even if φ^m is only a viscosity solution by Lemma 4.1).

LEMMA 4.2 Let m > 0. Under Assumption 4.1 we have the following representations:

$$\varphi_{s^{i}}^{m}(t,a) = E_{t,a}^{Q} \left[f_{s^{i}\pm}(A_{T}) \frac{S_{T}^{i}}{S_{t}^{i}} \right], \quad \varphi_{x^{j}}^{m}(t,a) = e^{-\alpha_{j}(T-t)} E_{t,a}^{Q} \left[f_{x^{j}\pm}(A_{T}) \right]$$
(4.11)

for i = 1, ..., n, j = 1, ..., d, where the processes evolve as in (4.7) with $\delta = \hat{\delta}$, the maximizer in $h^m(\beta' \varphi_x^m)$.

Proof. We adapt the arguments in [FS06], Lemma 11.4, to our slightly different framework. First assume that f is smooth (in the sense of Lemma 4.1), then there exists an optimal Markov feedback $\hat{\delta} \in \mathcal{A}_0^m$ (the one achieving the max in $h^m(\beta' \varphi_x^m)$) such that

$$\varphi^m(t,a) = E_{t,a}^Q \left[\frac{1}{2\gamma} \int_t^T \|\widehat{\delta}_r\|^2 dr + f(A_T) \right]$$

By using the same control but with different initial condition we clearly obtain

$$\varphi^m(t, a + \varepsilon e_i) \le E_{t, a + \varepsilon e_i}^Q \left[\frac{1}{2\gamma} \int_t^T \|\widehat{\delta}_r\|^2 dr + f(A_T) \right], \quad i = 1, \dots, n + d$$

Taking the difference and dividing by $\varepsilon > 0$ we get

$$\frac{\varphi^m(t, a + \varepsilon e_i) - \varphi^m(t, a)}{\varepsilon} \le E_t^Q \left[\frac{f(A_T^{t, a + \varepsilon e_i}) - f(A_T^{t, a})}{\varepsilon} \right], \quad i = 1, \dots, n + d,$$

where for clarity we wrote here $A_T^{t,a}$ to stress that the process starts at time t with value a. The polynomial growth property in the traded assets of the derivatives of f allows us to apply dominated convergence (since traded assets have the same dynamics under Q and Q^0 , see (4.7)) to get

$$\varphi_{a^i}^m(t,a) \le E_t^Q \left[f_{a^i}(A_T^{t,a}) \frac{\partial}{\partial a^i} A_T^{t,a,i} \right], \quad i = 1, \dots, n+d.$$

By repeating the argument with $-\varepsilon$ we finally obtain

$$\varphi^m_{a^i}(t,a) = E^Q_{t,a} \left[f_{a^i}(A_T) \frac{\partial}{\partial a^i} A^i_T \right]$$

for i = 1, ..., n + d, which gives the result by considering traded and non traded assets separately. The general result follows by considering an approximating sequence f^l as in the proof of Lemma 4.1 and using dominated convergence.

If the payoff f is sufficiently regular we can immediately remove the dependence on m, as is shown in the next result.

LEMMA 4.3 If f satisfies Assumption 4.1 and is C^3 then (4.1) admits a classical solution φ .

Proof. By the representation (4.11) we have

$$\varphi_{x^{i}}^{m}(t,a) = e^{-\alpha_{i}(T-t)} E_{t,a}^{Q} \left[f_{x^{i}}(A_{T}) \right] \le C E_{t,a}^{0} \left[\|S_{T}\|^{q} \right] \le C \|s\|^{q}$$

where the constant is independent of m, since this parameter only modifies through δ the dynamics of X, and by the growth assumptions on f.

For M > 0 arbitrarily large we can find D > 0 such that $\gamma \|\beta' \varphi_x^m\| \leq D$ if $\|s\| \leq M$, uniformly in m. Therefore if $m \geq D$ then

$$\sup_{\delta \in \mathcal{B}^m(\mathbb{R}^d)} \left\{ -(\beta' \varphi_x^m) \delta - \frac{1}{2\gamma} \|\delta\|^2 \right\} = \sup_{\delta \in \mathbb{R}^d} \left\{ -(\beta' \varphi_x^m) \delta - \frac{1}{2\gamma} \|\delta\|^2 \right\},\tag{4.12}$$

for $||s|| \leq M$. Since M is arbitrary, this implies that (4.1) admits a classical solution on the whole domain $[0,T] \times \mathbb{R}^n_+ \times \mathbb{R}^d$.

We can finally prove the part (i) in Theorem 4.1 for a continuous payoff f satisfying Assumption 4.1.

Proof of Theorem 4.1 (i) under Assumption 4.1. We approximate the payoff by a sequence of C^3 functions f^l satisfying Assumption 4.1 and converging pointwise to f. We assume f^l to be bounded

and with bounded derivatives for each l. When a smooth f^l is used as terminal condition by Lemma 4.3 we can define the classical solution φ^l to PDE (4.1) as a limit of a sequence $\varphi^{m,l}$ when $m \to \infty$. By Lemma 4.2 for each m we have

$$|\varphi_{s^{i}}^{m,l}(t,a)| + |\varphi_{x^{j}}^{m,l}(t,a)| \le C \|s\|^{q} \wedge l$$
(4.13)

where

$$dX_t^i = (b^i(t) - \alpha_i X_t^i + \beta_i \cdot \widehat{\delta}_t^m) dt + \beta_i \cdot dW_t^{X,Q} \quad i = 1, \dots, d,$$

and $\hat{\delta}^m$ is the maximizer in LHS of (4.12). Here *C* is independent of *m* (because of the uniformity property in the nontraded assets as in Assumption 4.1) and of *l* (because of continuity). Moreover, bounding with *l* can always be done since the derivatives of f^l are bounded for each *l*. Remark therefore that, since $\gamma\beta'\varphi_x^l(t,a)$ is the maximizer in the RHS of (4.12), one necessarily has $\|\hat{\delta}_t^m\| \leq \|\gamma\beta'\varphi_x^l(t,A_t)\|$. Therefore $\hat{\delta}_t^m = -\gamma\beta'\varphi_x^l(t,A_t)$ when *m* is big enough and therefore

$$\varphi_{x^{j}}^{l}(t,a) = e^{-\alpha_{j}(T-t)} E_{t,a}^{Q} \left[f_{x^{j}}^{l}(A_{T}) \right] \le C \|s\|^{q}$$
(4.14)

and similarly for $\varphi_{s^i}^l$, where

$$dX_t^j = (b^j(t) - \alpha_j X_t^j - \gamma \beta_j \beta' \varphi_x^l(t, A_t)) dt + \beta_j dW_t^{X,Q} \quad j = 1, \dots, d.$$

$$(4.15)$$

For fixed m we recall the Zhang representation in [Zh05], Theorem 3.2 (as in (4.9))

$$\varphi_a^{m,l}(t,a) = E_{t,a}^0 \left[f^l(A_T) N_T - \int_t^T h^m(Z_r^{X,m,l}) N_r dr \right]$$

where

$$Y_t^{m,l} = f^l - \int_t^T h^m (Z_r^{X,m,l}) dr - \int_t^T Z_r^{m,l} dW_r^0.$$

Hence

$$\varphi_a^l(t,a) = E_{t,a}^0 \left[f^l(A_T) N_T - \frac{\gamma}{2} \int_t^T \|Z_r^{X,l}\|^2 N_r dr \right]$$

by dominated convergence and the previous estimates (4.13) applied to

$$Z_t^{X,m,l} = \sigma(S_t)' \varphi_s^{m,l}(t, A_t),$$

and the fact that $Z^{X,m,l} \to Z^{X,l}$ in $\mathbb{H}^{q'}(\mathbb{R}^d)$ for all q' > 0 as $m \to \infty$ using classical results on quadratic BSDEs in [Ko00] (since we can assume without loss of generality that f^l is bounded for fixed l), where

$$Y_t^l = f^l - \int_t^T \frac{\gamma}{2} \|Z_r^{X,l}\|^2 dr - \int_t^T Z_r^l dW_r^0.$$
(4.16)

Now by using an argument like in Lemma 3.2 we get that $Y^l \to Y$ as $l \to \infty$ where

$$Y_t = f - \int_t^T \frac{\gamma}{2} \|Z_r^X\|^2 dr - \int_t^T Z_r dW_r^0$$
(4.17)

and also $Z^l \to Z$ in $\mathbb{H}^{q'}(\mathbb{R}^d)$ for all q' > 0. By the definition of the process N in (4.8), we obtain that $E_t^0[|N_T||^p] \leq C(T-t)^{-p/2}$ for any $p \geq 1$ and some constant C > 0. Therefore again by dominated convergence

$$\varphi_a^l(t,a) \to g(t,a) := E_{t,a}^0 \left[f(A_T) N_T - \frac{\gamma}{2} \int_t^T \|Z_r^X\|^2 N_r dr \right].$$

Similarly as in the last part of our Lemma 4.3, using Lemma 6.2 in [FS06] we deduce that φ^l converges, uniformly on compact sets of $[0, T] \times \mathbb{R}^n_+ \times \mathbb{R}^d$, to φ , viscosity solution to (4.1), which is also continuous.

We now show that g is continuous and that $g = \varphi_a$. To do so we can adapt the last part of Zhang's proof of Theorem 3.2 in [Zh05], we give all the details for reader's convenience. For all $\varepsilon > 0$ we can choose an open set O_{ε} with Lebesgue measure smaller than ε and a continuous function f^{ε} such that $f^{\varepsilon} = f$ outside O_{ε} . Denote

$$g_{\varepsilon}(t,a) := E_{t,a}^0 \left[f^{\varepsilon}(A_T) N_T - \frac{\gamma}{2} \int_t^T \|Z_r^X\|^2 N_r dr \right]$$

(where Z is solution to the limit BSDE (4.17), with f and not f^{ε} as terminal condition). Denoting g^i and g^i_{ε} the *i*-th component of, respectively, g and g_{ε} we get

$$\begin{aligned} |g_{\varepsilon}^{i} - g^{i}|(t,a) &= |E_{t,a}^{0} \left[(f^{\varepsilon}(A_{T}) - f(A_{T}))N_{T}^{i} \right] | \leq E_{t,a}^{0} \left[|f^{\varepsilon}(A_{T}) - f(A_{T})| |N_{T}^{i}|; X_{T} \in O_{\varepsilon} \right] \\ &\leq E_{t,a}^{0} \left[|f^{\varepsilon}(A_{T}) + f(A_{T})| |N_{T}^{i}|; X_{T} \in O_{\varepsilon} \right] \leq C(t,a)\sqrt{\varepsilon}. \end{aligned}$$

for some constant C(t, a). Now taking a sequence (t_{κ}, A_{κ}) tending to (t, a) we have

$$\begin{aligned} |g^{i}(t_{\kappa}, A_{\kappa}) - g^{i}(t, a)| \\ &\leq |g^{i}(t_{\kappa}, A_{\kappa}) - g^{i}_{\varepsilon}(t_{\kappa}, A_{\kappa})| + |g^{i}_{\varepsilon}(t_{\kappa}, A_{\kappa}) - g^{i}_{\varepsilon}(t, a)| + |g^{i}_{\varepsilon}(t_{\kappa}, A_{\kappa}) - g^{i}(t, a)| \\ &\leq [C(t, a) + C(t_{\kappa}, A_{\kappa})]\sqrt{\varepsilon} + |g^{i}_{\varepsilon}(t_{\kappa}, A_{\kappa}) - g^{i}_{\varepsilon}(t, a)|. \end{aligned}$$

Since g_{ε}^i is continuous and ε is arbitrary we deduce that g^i is continuous as well. Now for any $(t, \tilde{a}) \in [0, T] \times \mathbb{R}^n_+ \times \mathbb{R}^d$ we have

$$\varphi^l(t,\tilde{a}) = \varphi^l(t,I^i\tilde{a}) + \int_0^{\tilde{a}^i} \varphi^l_{a^i}(t,I^i\tilde{a} + e_iy)dy$$

where we denoted I^i the \mathbb{R}^{n+d} -identity matrix whose *i*-th diagonal entry is zero, and e_i is the canonical basis vector in \mathbb{R}^{n+d} . By dominated convergence (using (4.13)) we deduce

$$arphi(t, ilde{a}) = arphi(t,I^i ilde{a}) + \int_0^{ ilde{a}^i} g^i(t,I^i ilde{a} + e_iy)dy,$$

implying that $g = \varphi_a$.

REMARK 4.2 In the representation (4.15) it would be tempting to pass from measure Q (coming from the stochastic control representation) to the MMM Q^0 by identifying

$$dW_t^{X,0} = dW_t^{X,Q} - \gamma \beta' \varphi_x^l(t, A_t) dt.$$

This may however not be possible in general due to the growth properties of φ_x^l and the fact that geometric Brownian motion does not have exponential moments.

We will perform a similar change of measure in the next section under more restrictive assumptions on the derivatives of the payoff function f.

4.1.3 Discontinuous payoffs

In this part of the paper, we show that the continuity of the payoff f can be partially removed. The price to pay for that is imposing stronger conditions on its derivatives as in Assumptions 4.2.

The idea that lies at the heart of the proof that follows is showing that, when we approximate our discontinuous payoff f with a smooth sequence f^l , the derivatives of the price φ^l does not explode when $l \to \infty$ for t < T. This is easily seen if we take, for example, the digital payoff $f(x) = \mathbf{1}_{[0,\infty)}(x)$ which does not depend on the traded assets. Setting $\alpha = 0$ in the dynamics (2.2) we have

$$\varphi_x^l(t,x) = E^Q[f_x^l(X_T)]$$

$$dX_t = -\gamma \varphi_x^l(t, X_t) dt + \beta dW_t^{X,Q}$$

and $\varphi_x^l(T-t,x) \to g(t,x)$, where g solves the Burgers' equation

$$g_t + \gamma g_x g = \frac{1}{2}\beta^2 g_x$$

which has the solution

$$g(t,x) = \frac{\beta e^{-\frac{x^2}{2\beta^2 t}} (1 - e^{-\frac{\gamma}{\beta^2}})}{\gamma \sqrt{2\pi t} \left[(e^{-\frac{\gamma}{\beta^2}} - 1) \Phi\left(\frac{x}{\beta\sqrt{t}}\right) + 1 \right]}$$

In particular we clearly have $g(t,x) \leq \frac{C}{\sqrt{t}}$, where $C = \frac{\beta}{\gamma\sqrt{2\pi}}(e^{\frac{\gamma}{\beta^2}} - 1)$. Unfortunately the Burgers-type equation that results by adding traded assets does not seem to have an explicit solution, therefore we will need to employ a different method to get a similar estimate. Here is the proof of our main result concerning discontinuous payoffs.

Proof of Theorem 4.1 (i) under Assumptions 4.2. Take again a sequence f^l of approximating smooth functions with bounded first derivatives such that $f^l \to f$ a.e. for $l \to \infty$ as in step 2 of the proof of Lemma 4.1. Each function f^l of the sequence satisfies the assumptions of Lemma 4.2, so that the representation formula therein applies and we have that

$$|\varphi_{x^{i}}^{l}(t,a)| \le C^{l}(1+\|s\|^{q}), \tag{4.18}$$

with the constant C^l depending on l. Remark that this is not the same constant appearing in the characterization of uniform growth with respect to x: since we are dealing with discontinuous payoffs, the derivatives of the approximating functions f^l may well explode close to the discontinuities for large l. We have

$$|f_{x^{i}}^{l}(a)| \leq C^{l}(x)(1+\|s\|^{q}) \quad i=1,\ldots,d,$$
(4.19)

where $C^{l}(x)$ is a function which stays bounded on compact sets which do not include discontinuity points, but that may explode at these points for large l. In order to see this, we can explicitly write the mollified sequence f^{l} as

$$f^{l}(s,x) = \int_{\mathbb{R}^{d}} f(s,x+y)\psi^{l}(y)dy = \int_{\mathbb{R}^{d}} f(s,z)\psi^{l}(z-x)dz$$

where

$$\tilde{\psi}^{l}(x) = K \exp\left(\frac{-1}{1 - \|x\|^{2}}\right) \mathbf{1}_{\{\|x\| \le 1\}}, \quad \psi^{l}(x) = l\tilde{\psi}^{l}(lx)$$

Recall that ψ^l is a mollifier with support on $\mathcal{B}_d(1/l)$. If ||x - I|| > 1/l, where I is the discontinuity point closest to x, then

$$f^l_{x^i}(s,x) = \int_{\mathbb{R}^d} f_{x^i}(s,x+y)\psi^l(y)dy$$

and so $|f_{x^i}^l(s,x)| \leq C(1+||s||^q)$. For $||x-I|| \leq 1/l$ we use the representation (recall that $f(s,\cdot)$ is bounded for fixed s)

$$f_{x^i}^l(s,x) = -\int_{\mathbb{R}^d} f(s,z)\psi_{x^i}^l(z-x)dz$$

which yields

$$|f_{x^{i}}^{l}(s,x)| \leq C(1+\|s\|^{q}) \int_{\mathbb{R}^{d}} |\psi_{x^{i}}^{l}(z-x)| dz \leq Cl(1+\|s\|^{q})$$

since f has uniform polynomial growth in s. Therefore

$$|f_{x^i}^l(s,x)| \le C^l(x)(1 + \|s\|^q)$$

with

where

$$C^{l}(x) = Cl\mathbf{1}_{\{\|x-I\| \le 1/l\}}$$

Also by Lemma 4.2 and Assumptions 4.2 (iii) we have

$$|\varphi_{s^i}^l(t,a)| \le C \frac{1}{s^i} \tag{4.20}$$

for s^i big enough (since discontinuities can only occur in the x-variables) and for some constant C > 0independent of l and x. If we consider the pricing BSDE (4.16) associated with f^l we can identify $Z_t^{X,l} = \beta' \varphi_x^l(t, A_t)$ and $Z_t^{S,l} = \sigma(S_t)' \varphi_s^l(t, A_t)$. By estimate (4.20) we deduce that $Z^{S,l}$ is bounded for each l (with a bound independent on l). By estimate (4.18) we can assume $Z^{X,l}$ to be bounded for each l (by possibly bounding the growth in the traded assets with l), which allows us to perform a probability measure change to get

$$\begin{aligned} |\varphi_{x^{i}}^{l}(t,a)| &=^{(i)} \left| E_{t,a}^{0} \left[\frac{\mathcal{E}_{T}}{\mathcal{E}_{t}} (-\gamma Z^{X,l} \cdot W^{X}) e^{-\alpha_{i}(T-t)} f_{x^{i}}^{l}(A_{T}) \right] \right| \\ &\leq^{(ii)} C E_{t,a}^{0} \left[e^{\gamma (Y_{t}^{l} - f^{l} + \int_{t}^{T} Z_{r}^{S,l} dW_{r}^{S,0})} |f_{x^{i}}^{l}(A_{T})| \right] \\ &\leq^{(iii)} C e^{\gamma Y_{t}^{l}} E_{t,a}^{0} \left[e^{\gamma \int_{t}^{T} Z_{r}^{S,l} W_{r}^{S,0}} |f_{x^{i}}^{l}(A_{T})| \right] \\ &\leq^{(iv)} C e^{\gamma Y_{t}^{l}} E_{t,a}^{0} \left[\frac{\mathcal{E}_{T}}{\mathcal{E}_{t}} (\gamma Z^{S,l} \cdot W^{S,0}) |f_{x^{i}}^{l}(A_{T})| \right] \\ &=^{(v)} C e^{\gamma Y_{t}^{l}} E_{t,a}^{\bar{Q}} \left[|f_{x^{i}}^{l}(A_{T})| \right] \leq^{(vi)} C ||s||^{q} e^{\gamma Y_{t}^{l}} E_{t,x}^{0} \left[C^{l}(X_{T}) \right] \\ &\leq^{(vii)} \frac{C ||s||^{q} ||x||^{q'}}{\sqrt{T-t}} e^{\gamma Y_{t}^{l}} \leq^{(viii)} \frac{C ||s||^{q} ||x||^{q'}}{\sqrt{T-t}} e^{\gamma C(1+||s||^{q})} \end{aligned}$$

where the constant C changes from line to line and the inequalities above can be justified as follows:

- (i) is due to the second equality in (4.11) applied to the sequence $\varphi^{l}(t, a)$, which has bounded derivatives.
- (ii) comes from the pricing BSDE (4.16) under the MMM Q^0 , which implies

$$\frac{\mathcal{E}_T}{\mathcal{E}_t}(-\gamma Z^{X,l} \cdot W^X) = e^{-\gamma \left(\int_t^T Z_r^{X,l} dW_r^X + \frac{\gamma}{2} \int_t^T \|Z_r^{X,l}\|^2 dr\right)} = e^{\gamma (Y_t^l - f^l + \int_t^T Z_r^{S,l} dW_r^{S,0})}$$

- (iii) is a consequence of boundedness from below of f.
- (iv) is derived from boundedness of $Z^{S,l}$, uniformly in l (so that C does not depend on l).
- (v) is obtained by applying the measure change $\frac{d\bar{Q}}{dQ^0} = \mathcal{E}_T(\gamma Z^{S,l} \cdot W^{S,0}).$
- (vi) the inequality comes from Assumptions 4.2 (ii) and the fact that the drift changes induced by the measure change $\frac{d\bar{Q}}{dQ^0}$ are bounded and only pertain the tradable assets. In particular the dynamics of S^i under \bar{Q} can be controlled by noticing

$$S_T^i = S_t^i e^{\gamma \sigma_i \cdot \int_t^T Z_u^{S,l} du - \frac{\|\sigma_i \cdot\|^2}{2} (T-t) + \sigma_i \cdot (W_T^{S,\bar{Q}} - W_t^{S,\bar{Q}})} \le C S_t^i e^{-\frac{\|\sigma_i \cdot\|^2}{2} (T-t) + \sigma_i \cdot (W_T^{S,\bar{Q}} - W_t^{S,\bar{Q}})}.$$

The inequality above is due to the fact that, by Assumptions 4.2 (ii), there exist a threshold M > 0 such that $|\varphi_{s^i}^l(t, A_t)| \leq C/S_t^i$ when $|S_t^i| \geq M$, otherwise it is bounded. Thus one obtains

$$|\gamma Z_t^{S,l}| = |\gamma \sigma(S_t)' \varphi_s^l(t, A_t)| \le C\gamma \left\| \sigma(S_t) \frac{1}{S_t} \right\|,$$
(4.22)

where one can easily check that the last term on the RHS is constant.

(vii) is the derived from the definition of C^l and using the density of X_T (i.e. the multivariate Gaussian). In fact, taking for simplicity just one discontinuity point at zero we immediately see that

$$E_{t,x}^{0}\left[C^{l}(X_{T})\right] = ClP_{t,x}(\|X_{T}\| \le 1/l) \le Cl\frac{1}{l}\frac{1}{\det(\operatorname{Var}_{t,x}(X_{T}))^{1/2}} \le \frac{C}{\sqrt{T-t}}$$

with the obvious notations for conditional variance and probability.

(viii) Since f has uniform polynomial growth in s, the same holds for f^l (uniformly in l). Therefore $Y_t^l \leq E_{t,a}^0[f^l(A_T)] \leq C + CE_{t,s}^0[\|S_T\|^q] \leq C(1+\|s\|^q).$

Using the previous estimate (4.21), we can apply the usual stability properties (Lemma 6.2 in [FS06]) to get $Y_t = \lim_l \varphi^l(t, A_t) = \varphi(t, A_t)$, where φ is a viscosity solution of (4.1).

We now would like to prove that φ has continuous first derivatives in all space variables. Since $Z^{X,l}$ is locally bounded uniformly in l by (4.21) we can use Lemma A.3 componentwise (together with Lemma A.1) to get the uniform integrability property allowing us to use dominated convergence and obtain

$$\varphi_a^l(t,a) \to g(t,a) := E_{t,a}^0 \left[f(A_T) N_T - \frac{\gamma}{2} \int_t^T \|Z_r^X\|^2 N_r dr \right].$$

To conclude it suffices to show that g is continuous and that $g = \varphi_a$. This can be done by exactly the same arguments that we used at the end of the proof of Theorem 4.1 (i) under Assumption 4.1. For this reason, we omit this part of the proof.

REMARK 4.3 Had we supposed directly the multiplicative form f(s,x) = g(x)h(s) with a bounded g then we could have allowed for a countable (and not simply finite) number of discontinuities in g. This is true by remarking that in (4.21) we could have used Theorem 3.2 in [Zh05], by considering the function $u^l(t,x) = E^0_{t,x}[g^l(X_T)]$ (corresponding to the trivial linear BSDE arising from the martingale representation theorem) and the estimates on its derivative $u^l_x(t,x) = E^0_{t,x}[g^l_x(X_T)]$.

REMARK 4.4 Here we focused on the case of discontinuities only taking place in the x-variables, as it turns out to be the most useful case in the applications (See Section 5). The arguments in the previous proof (in particular estimate (4.21)) could, however, be easily adapted to the case where discontinuities take place only in the s variables, provided the payoff has polynomial growth in x, uniformly in s.

4.1.4 The optimal hedging strategy

The previous results (stating the differentiability of UIP) allows us to represent Z^S in terms of the derivatives of the solution of a PDE. Indeed, when f is bounded, the optimal strategy can be immediately recovered by $\Delta_t = -\sigma^{-1}Z_t^S$, using Lemma 3.1. The next result gives a slight generalization to the case where f has polynomial growth in the traded assets.

Proof of Theorem 4.1 (ii). Approximate f as in Lemma 4.1 with a sequence f^l , where each of its elements can always be taken to be bounded. By Lemma 3.1, the corresponding optimal strategies with the claims f^l are given by $\hat{\pi}_t^l = -\sigma^{-1}\sigma(S_t)\varphi_s^l(t, A_t) + \frac{1}{\gamma}\sigma^{-2}\mu$ and the value functions are

$$u^{l}(t,v,a) = \sup_{\pi} E_{t,a} \left[-e^{-\gamma \left(V_{T}^{v}(\pi) + f^{l} \right)} \right] = E_{t,a} \left[-e^{-\gamma \left(V_{T}^{v}(\widehat{\pi}^{l}) + f^{l} \right)} \right]$$

By the growth assumptions in s (uniform in x) we deduce that the assumptions of Lemma 3.3 are satisfied and therefore

$$u^l \to u \tag{4.23}$$

for all $(t, v, a) \in [0, T] \times \mathbb{R} \times \mathbb{R}^n_+ \times \mathbb{R}^d$, where

$$u(t, v, a) = E_{t,a} \left[-e^{-\gamma(V_T^v(\hat{\pi}) + f)} \right]$$

for some optimal $\hat{\pi}$. We would like to identify $\hat{\pi}$ with $\tilde{\pi}_t := -\sigma^{-1}\sigma(S_t)\varphi_s(t, A_t) + \frac{1}{\gamma}\sigma^{-2}\mu$. An application of the reverse Fatou's Lemma gives

$$\limsup_{l} E_{t,a} \left[-e^{-\gamma \left(V_T^v(\widehat{\pi}^l) + f^l \right)} \right] \le E_{t,a} \left[\lim_{l} -e^{-\gamma \left(V_T^v(\widehat{\pi}^l) + f^l \right)} \right], \tag{4.24}$$

where the limit on the LHS is meant to be in probability. To show that this limit exists, remark first that $\hat{\pi}^l \to \tilde{\pi}$ in $\mathbb{H}^2(\mathbb{R}^n)$, which implies that $V_T^v(\hat{\pi}^l)$ converges to $V_T^v(\tilde{\pi})$ in $L^2(\Omega, P)$, hence in probability. In the same way, $f^l \to f$ in probability. By using (4.23) and the continuity of the exponential function, (4.24) becomes

$$E_{t,a}\left[-e^{-\gamma(V_T^v(\hat{\pi})+f)}\right] \le E_{t,a}\left[-e^{-\gamma(V_T^v(\tilde{\pi})+f)}\right],$$

which implies that $\tilde{\pi}$ is optimal. Indeed, one can show that $\tilde{\pi}$ belongs to \mathcal{H}_M using the uniform estimate (4.13) in the continuous payoff case or the estimate (4.22) in the discontinuous case together with the fact that S has moments of all positive orders.

4.2 Asymptotic expansions

In this subsection we turn to the problem of computing effectively the UIP and the corresponding optimal hedging strategy for a given contingent claim. It is well-known that solving PDE (4.1) numerically can be impractical for time reasons when the number of assets is large. It is therefore useful to derive some asymptotic expansions which allow to approximate the price and the hedging strategy when the risk aversion parameter γ is small. The formulas are given in terms of the noarbitrage price and strategy, which can usually be computed in a much simpler way either explicitly or by numerical integration or by Monte Carlo methods.

Consider a contingent claim with payoff $f(A_T)$ integrable under the MMM Q^0 , whose no-arbitrage price under Q^0 is denoted by $p^0(t, a) = E^0_{t,a}[f(A_T)]$. Now define

$$\zeta(t,a):=E^0_{t,a}\left[\int_t^T\|\beta'p^0_x\|^2(s,A_s)ds\right].$$

The next result is due to a recent preprint by Monoyios ([Mo12]).

LEMMA 4.4 Under Assumption 4.1 or Assumptions 4.2 for the contingent claim $f(A_T)$, the following asymptotic expansion holds:

$$\varphi(t,a) = p^0(t,a) - \frac{\gamma}{2}\zeta(t,a) + O(\gamma^2).$$
(4.25)

Proof. This is a reformulation of [Mo12], Theorem 5.3. It is enough to remark that our growth assumptions on f ensure that it is in $L^2(Q)$ for any $Q \in \mathcal{M}_E$.

The next result provides asymptotic expansions for the derivatives of the price, and therefore of the optimal hedging strategy.

LEMMA 4.5 Suppose Assumption 4.1 holds, and moreover that $f_{x\pm}$ is bounded. Then the following asymptotic expansions hold

$$\begin{split} \varphi_{x^{i}}(t,a) &= e^{-\alpha_{i}(T-t)}E^{0}_{t,a}\left[f_{x^{i}\pm}(A_{T})\right] - \gamma e^{-\alpha_{i}(T-t)}E^{0}_{t,a}\left[f_{x^{i}\pm}(A_{T})\int_{t}^{T}\beta'\varphi^{0}_{x}(u,A_{u})dW^{X}_{u}\right] + O(\gamma^{2}) \\ \varphi_{s^{i}}(t,a) &= E^{0}_{t,a}\left[\frac{S^{i}_{T}}{S^{i}_{t}}f_{s^{i}\pm}(A_{T})\right] - \gamma E^{0}_{t,a}\left[\frac{S^{i}_{T}}{S^{i}_{t}}f_{s^{i}\pm}(A_{T})\int_{t}^{T}\beta'\varphi^{0}_{x}(u,A_{u})dW^{X}_{u}\right] + O(\gamma^{2}), \end{split}$$

where $\varphi_{x^{i}}^{0}(t,a) = e^{-\alpha_{i}(T-t)} E_{t,a}^{0} [f_{x^{i}\pm}(A_{T})].$

Proof. In the rest of the proof for simplifying the notation, we prove the expansions for $\alpha_i = 0$ and only at time t = 0, otherwise the same arguments (conditionally to \mathcal{F}_t) apply and get the result for any t. By considering as usual a sequence of approximating functions we get from equality (4.14) and a simple application of Girsanov's theorem that

$$\varphi_{x^i}^l(0,a) = E^0 \left[\mathcal{E}_T(-\gamma \beta' \varphi_x^l \cdot W^X) f_{x^i}^l(A_T) \right]$$

which is bounded, uniformly in l. By taking $l \to \infty$ we get

$$\varphi_{x^i}(0,a) = E^0 \left[\mathcal{E}_T(-\gamma \beta' \varphi_x \cdot W^X) f_{x^i}(A_T) \right],$$

which is also bounded. Now we write φ^{γ} to emphasize dependence on γ . So we have

$$\frac{\varphi_{x^i}^{\gamma} - \varphi_{x^i}^0}{\gamma}(0, a) = E^0 \left[\frac{\mathcal{E}_T(-\gamma \beta' \varphi_x^{\gamma} \cdot W^X) - 1}{\gamma} f_{x^i}(A_T) \right]$$

Moreover, we denote the process $\varphi_x^{\gamma}(t, A_t)$ by φ_x^{γ} with a slight abuse of notation. Remark that, defining M^{γ} as the unique solution to $dM_t^{\gamma} = -\gamma M_t^{\gamma} \beta' \varphi_x^{\gamma}(t, A_t) dW_t^X$ with initial condition $M_0^{\gamma} = 1$, we have

$$\begin{split} E^{0} \left[\left(\frac{\mathcal{E}_{T}(-\gamma\beta'\varphi_{x}^{\gamma}\cdot W^{X}) - 1}{\gamma} + \int_{0}^{T}\beta'\varphi_{x}^{0}dW_{s}^{X} \right)^{2} \right] &= E^{0} \left[\left(\int_{0}^{T} (\beta'\varphi_{x}^{0} - M_{s}^{\gamma}\beta'\varphi_{x}^{\gamma})dW_{s}^{X} \right)^{2} \right] \\ &= E^{0} \left[\int_{0}^{T} \|\beta'\varphi_{x}^{0} - M_{s}^{\gamma}\beta'\varphi_{x}^{\gamma}\|^{2}ds \right] \\ &\leq 2E^{0} \left[\int_{0}^{T} \|\beta'\varphi_{x}^{0} - \beta'\varphi_{x}^{\gamma}\|^{2}ds \right] + 2E^{0} \left[\int_{0}^{T} \|\beta'\varphi_{x}^{\gamma}\|^{2}(1 - M_{s}^{\gamma})^{2}ds \right] \\ &\leq CE^{0} \left[\int_{0}^{T} (1 - M_{s}^{\gamma})^{2}ds \right], \end{split}$$

where the second equality is due to Itô's isometry, since the integrand therein belongs to $\mathbb{H}^2(\mathbb{R}^d)$. Since $f_{x^i\pm}$ is bounded by assumption, φ_x^{γ} is also bounded and this implies that $E^0[\int_0^T (1-M_s^{\gamma})^2 ds]$ tends to zero as $\gamma \to 0$ by dominated convergence. Thus

$$\frac{\mathcal{E}_T(-\gamma\beta'\varphi_x^\gamma\cdot W^X)-1}{\gamma}\to -\int_0^T\beta'\varphi_x^0dW_t^X$$

in L^2 as $\gamma \to 0$, and therefore

$$\frac{\partial}{\partial\gamma}\varphi_{x^{i}}^{\gamma}\Big|_{\gamma=0} = \lim_{\gamma\to 0} \frac{\varphi_{x^{i}}^{\gamma} - \varphi_{x^{i}}^{0}}{\gamma} = -E^{0} \left[f_{x^{i}\pm}(A_{T}) \int_{0}^{T} \beta' \varphi_{x}^{0} dW_{s}^{X} \right]$$

The proof for φ_{s^i} is analogous.

We conclude this section with a lower bound on the utility indifference price of f.

LEMMA 4.6 Under Assumptions 4.1 or Assumptions 4.2 the following bound on the price holds:

$$\varphi(t,a) \ge -\frac{1}{\gamma} \log E^0_{t,a} \left[e^{-\gamma f(A_T)} \right].$$

Proof. Define

$$h(t,a) = E_{t,a}^0 \left[e^{-\gamma f(A_T)} \right]$$

which solves

$$\begin{cases} \mathcal{L}h = 0\\ h(T, a) = e^{-\gamma f(a)} \end{cases}$$

in the classical sense (assuming f to be smooth). Now set $g = -\frac{1}{\gamma} \log h$, so that g solves

$$\begin{cases} \mathcal{L}g - \frac{\gamma}{2} \|\sigma(S)'g_s\|^2 - \frac{\gamma}{2} \|\beta'g_x\|^2 = 0\\ g(T, a) = f(a). \end{cases}$$

By the comparison theorem for PDEs we have that $g(t, a) \leq \varphi(t, a)$. By our approximation arguments the same bound holds true when f is not smooth.

5 Application to electricity markets

Our framework can be particularly useful to evaluate derivatives in situations where the underlying asset prices are determined by the interplay between several factors, but only some of these can be actually traded on a financial market (while the others may be of a totally different nature, for example macroeconomic or even behavioral factors). This is the case in particular for structural models of electricity prices, where the relevant components that influence the price are typically both tradable (like fuels) and non tradable (like market demand or production capacities)[‡].

The seminal contribution in the direction of structural electricity models has been the Barlow's model ([Ba02]), which describes the electricity spot price as a function of a one-dimensional diffusion representing the evolution of market demand. Since there is only a non tradable asset in his framework, utility indifference valuation here reduces to the computation of the certainty equivalent (see Remark 2.3), at least when prices are bounded (an assumption which is suggested by Barlow himself and which reflects the reality of electricity markets, where prices are usually capped). Similar considerations hold for the models in [SGI00] or [CV08], where an exponential function is used and an additional non tradable factor is added describing maximal capacity.

Building on this literature, several authors have proposed more developed structural models with the aim of capturing the contribution of other assets, notably the (marginal) fuels employed in electricity generation along with their production capacities. Since fuels are commodities which are typically traded on financial markets, their introduction fully justifies the employment of pricing techniques that allow for some kind of partial hedging (such as local risk minimization or, in our case, utility indifference pricing). For example, in [PJ08] the authors describe the spot price as the product of two components accounting for a traded and a non traded asset (following, respectively, a geometric Brownian motion and an Ornstein-Uhlenbeck process as in our framework). Multi-asset models have then followed, with the aim of considering the whole stack of available fuels, which typically present different levels of correlation with the spot price depending on their available capacities and market demand. They enter in our framework, possibly with some minor adaptations.

In this paper we focus especially on the model introduced in [ACL10], where the authors directly model the spreads between fuels as geometric Brownian motions, hence the tradable assets of our model S_t^i can be interpreted in this case as those fuel spreads by using the relation

$$S_t^i = h_i K_t^i - h_{i-1} K_t^{i-1},$$

where K_t^i is the price at time t of *i*-th fuel and the h_i 's are heat rates associated to each fuel. The model also includes fuel capacities C_t^i and a process D_t describing the demand for electricity, which make for d = n + 1 nontradable assets. In [ACL10], the dynamics postulated for tradable and nontradable assets perfectly fit into our setting, since the spread between two fuels follows a multidimensional Black-Scholes model while the non tradable ones follow Ornstein-Uhlenbeck processes with non zero mean-reversion and a seasonality component that can be embedded in the function b(t) as in (2.2). More precisely, we have

$$\frac{dS_t^i}{S_t^i} = \mu_i dt + \sigma_i dW_t^{S,i}, \quad i = 1, \dots, n$$
(5.1)

$$dC_t^j = (b_{C^j}(t) - \alpha_{C^j}C_t^j)dt + \beta_{C^j}dW_t^{C^j} \quad j = 1, \dots, n$$
(5.2)

$$dD_t = (b_D(t) - \alpha_D D_t)dt + \beta_D dW_t^D, \qquad (5.3)$$

 $^{^{\}ddagger}\mathrm{We}$ refer the reader to [CC12] for a comprehensive survey of structural models.

where we also supposed that the stochastic components of the assets are independent (compare with equation (4.2) in [ACL10]), i.e. the Brownian motions W^{C^j} and W^D are assumed to be independent. The coefficients $\mu_i, \alpha_{C^j}, \alpha_D$ are arbitrary constants while $\sigma_i, \beta_{C^j}, \beta_D$ are strictly positive real numbers. Moreover, $b_{C^j}(t)$ and $b_D(t)$ are deterministic bounded functions that possibly include the seasonality component of nontraded asset dynamics.

One of the main goals of structural models for energy markets (included the one in [ACL10]) is to have a realistic and tractable setting where pricing and hedging power derivatives. One of the most important derivatives to price and hedge is the forward contract on electricity, with payoff given by the value at maturity of the electricity spot price, which in [ACL10] can be written as

$$f(a) = f(s, c, y) = g\left(\sum_{i=1}^{n} c^{i} - y\right) \sum_{i=1}^{n} h_{i} k^{i} \mathbf{1}_{\{y \in I^{i}\}} = g\left(\sum_{i=1}^{n} c^{i} - y\right) \sum_{j \le i \le n} s^{j} \mathbf{1}_{\{y \in I^{i}\}}$$
(5.4)

where g is a bounded function with bounded first derivatives, c^i and y stand for fuel capacities and market demand, and we used the fact that $h_i K_t^i = \sum_{j \leq i} S_t^j$. The function g is called *scarcity function*, it has a crucial role for producing spikes in electricity spot prices (see the paper [ACL10] for further details).

We recall that Aïd et al. [ACL10] computed explicitly the price of power derivatives such as forward contracts and options on spread using the local risk minimisation approach, which consists in evaluating the expectation under the MMM Q^0 of the corresponding discounted payoff. This can also be viewed as the first term in the asymptotic expansion of the UIP for a small risk aversion parameter γ . Here we are going to provide an explicit expression for the second term in such an expansion in the case of a forward contracts, which would give an economically more sensible price incorporating the buyer attitude towards risk. More precisely, the BSDE approach developed in Section 3 can be applied to get the buying UIP of a forward contract written on electricity spot prices. Indeed, for the payoff (5.4) (as well as for call options on spread) the sufficient conditions established in Lemma 3.3 are easily checked, due to the simple multiplicative structure of the set of equivalent martingale densities implied by the independence between tradable and non tradable assets. On the other hand the payoff (5.4), as it is, does not satisfy neither Assumption 4.1 or Assumptions 4.2, however it can be made to satisfy

- Assumption 4.1 by suitably modifying the scarcity function as in, e.g., [ACLP12], where the payoff of a forward contract is a Lipschitz continuous functions of all the assets.
- Assumptions 4.2 by bounding the payoff by some constant M (which makes sense since in reality, as already remarked, electricity prices are capped).

The same observations hold for the utility indifference pricing of the quite popular spread options, which present a payoff which is either bounded or linearly growing in the electricity price.

REMARK 5.1 Substantially equivalent considerations hold for the electricity spot price model proposed in [CCS12] (equation (6)), which still uses a multiplicative form separating the contributions of traded and non traded assets (in a more involved way than in [ACL10], with the drawback of becoming rather messy when more than two assets are considered): bounding the payoff of the forward contract makes it satisfy Assumptions 4.2 (remark that it is usually discontinuous in the non traded assets). More generally, as reported in [CC12] (Chapter 5), most of the structural models found in the literature assume lognormal fuel prices, OU-driven demand and an electricity price which is multiplicative in the marginal fuel, which justifies our standing assumptions. Markov switching models like the one described in [CC12], equation (10), can also be treated in our framework as the structure of the payoff is standard, and additional indicator functions can be added to describe the different regimes (which create discontinuities in the non traded assets).

When the payoff f is linear or concave in the traded assets (as in the case of the forward contract in [ACL10]) we have the following result.

LEMMA 5.1 If f(s, x) is concave in s, the same holds for its UIP $\varphi(t, s, x)$.

Proof. By Lemma 4.1 and using an approximating sequence f^l , the price is represented as

$$\varphi^l(t,s,x) = E_{t,a}^Q \left[\frac{1}{2\gamma} \int_t^T \|\widehat{\delta}_r\|^2 dr + f^l(S_T, X_T) \right]$$

and therefore, setting $\tilde{a} = (\tilde{s}, x)$, we have

$$\begin{split} \varphi^{l}(t,\lambda s+(1-\lambda)\tilde{s},x) \\ &\geq \lambda E^{Q}_{t,a}\left[\frac{1}{2\gamma}\int_{t}^{T}\|\widehat{\delta}_{r}\|^{2}dr + f^{l}(S_{T},X_{T})\right] + (1-\lambda)E^{Q}_{t,\tilde{a}}\left[\frac{1}{2\gamma}\int_{t}^{T}\|\widehat{\delta}_{r}\|^{2}dr + f^{l}(S_{T},X_{T})\right] \\ &\geq \lambda \inf_{\delta}E^{Q}_{t,a}\left[\frac{1}{2\gamma}\int_{t}^{T}\|\delta_{r}\|^{2}dr + f^{l}(S_{T},X_{T})\right] \\ &+ (1-\lambda)\inf_{\delta}E^{Q}_{t,\tilde{a}}\left[\frac{1}{2\gamma}\int_{t}^{T}\|\delta_{r}\|^{2}dr + f^{l}(S_{T},X_{T})\right] \\ &= \lambda \varphi^{l}(t,s,x) + (1-\lambda)\varphi^{l}(t,\tilde{s},x), \quad \lambda \in [0,1]. \end{split}$$

Now it is enough to take limits to get the result.

EXAMPLE 5.1 (FORWARD CONTRACT FOR n = 2 FUELS) We derive here a more explicit expression for the first term $\zeta(0, a)$ of the asymptotic expansion (4.25) of the price at time zero for a forward contract with two fuels as described in [ACL10], with payoff §

$$f(a) = f(s, c, y) = g\left(c^{1} + c^{2} - y\right)\left(s^{1} + s^{2}\mathbf{1}_{\{y-c^{1}>0\}}\right).$$

The assets dynamics are given in (5.1), where we also assume the seasonality components to be zero for clearness (they would only appear as a mean component in the expressions for the derivatives of ψ below). The no-arbitrage price under the MMM Q^0 is

$$p^{0}(t,a) = E^{0}_{t,a}[f(A_{T})] = \psi^{1}(t,x)s^{1} + \psi^{2}(t,x)s^{2}$$

where $a = (s, x), s = (s^1, s^2), x = (c^1, c^2, y)$, and

$$\psi^{i}(t,x) = \int_{\mathbb{R}^{2}} \Psi_{C_{T}^{1} - D_{T}}(t,z) \Psi_{C_{T}^{2}}(t,c) g(c+z) \chi^{i}(z) dcdz$$

for i = 1, 2, where we set

$$\chi^{i}(z) := \mathbf{1}_{\{z < 0\}} + \mathbf{1}_{\{z \ge 0, i = 1\}}$$

and $\Psi_{C_T^1-D_T}(t,\cdot)$ stands for the conditional density of $C_T^1-D_T$ given $C_t^1=c^1, D_t=y$ (and similarly for $\Psi_{C_T^2}(t,\cdot)$). Notice that an explicit expression for the price $p^0(t,a)$ has been obtained in [ACL10] together with an efficient numerical method to compute it.

Based on the previous expression, we can obtain an explicit formula for the derivatives of $p^0(t, a)$ as an intermediate step towards the optimal hedging strategy. We have

$$p_x^0(t,a) = \begin{pmatrix} \psi_{C^1}^1(t,x)s^1 + \psi_{C^1}^2(t,x)s^2 \\ \psi_{C^2}^1(t,x)s^1 + \psi_{C^2}^2(t,x)s^2 \\ \psi_D^1(t,x)s^1 + \psi_D^2(t,x)s^2 \end{pmatrix}$$

[§]Such a payoff, as already noticed, does not satisfy the assumption in Lemma 4.4. Nonetheless, it clearly belongs to $L^2(Q)$ for all measures $Q \in \mathcal{M}_E$ and the results in Monoyios [Mo12] can still be applied getting the same asymptotic expansion as in (4.25).

where

$$\psi_{C^{1}}^{i}(t,x) = \frac{e^{-\alpha_{C^{1}}(T-t)}}{\operatorname{Var}_{t}(C_{T}^{1}-D_{T})} \int_{\mathbb{R}^{2}} (z - c^{1}e^{-\alpha_{C^{1}}(T-t)} + ye^{-\alpha_{D}(T-t)}) \Psi_{C_{T}^{1}-D_{T}}(t,z) \Psi_{C_{T}^{2}}(t,c)g(c+z)\chi^{i}(z)dcdz$$

$$\psi_{C^2}^i(t,x) = \frac{e^{-\alpha_{C^2}(T-t)}}{\operatorname{Var}_t(C_T^2)} \int_{\mathbb{R}^2} (c - c^2 e^{-\alpha_{C^2}(T-t)}) \Psi_{C_T^1 - D_T}(t,z) \Psi_{C_T^2}(t,c) g(c+z) \chi^i(z) dc dz$$

$$\psi_D^i(t,x) = -\frac{e^{-\alpha_D(T-t)}}{\operatorname{Var}_t(C_T^1 - D_T)} \int_{\mathbb{R}^2} (z - c^1 e^{-\alpha_{C^1}(T-t)} + y e^{-\alpha_D(T-t)}) \Psi_{C_T^1 - D_T}(t,z) \Psi_{C_T^2}(t,c) g(c+z) \chi^i(z) dcdz$$

for i = 1, 2 with Var_t denoting the conditional variance at time t, which in our case can be explicitly computed since $C^1 - D$ and C^2 are generalized Ornstein-Uhlenbeck processes with time-dependent deterministic coefficients. By defining

$$\phi^{i}(j,x) = \int_{0}^{T} e^{\sigma_{i}^{2}(T-t)} E_{0,x}[\beta_{j}^{2}\psi_{j}^{i}(t,X_{t})^{2}]dt, \quad \phi^{12}(j,x) = \int_{0}^{T} E_{0,x}[\beta_{j}^{2}\psi_{j}^{1}(t,X_{t})\psi_{j}^{2}(t,X_{t})]dt,$$

for i = 1, 2 and $j \in \{C^1, C^2, D\}$, we finally obtain

$$\begin{split} \zeta(0,a) &= \left(\sum_{j \in \{C^1, C^2, D\}} \phi^1(j, x)\right) (s^1)^2 + \left(\sum_{j \in \{C^1, C^2, D\}} \phi^2(j, x)\right) (s^2)^2 \\ &+ \left(\sum_{j \in \{C^1, C^2, D\}} \phi^{12}(j, x)\right) s^1 s^2. \end{split}$$

REMARK 5.2 By direct computation as above, one can also obtain similar expressions for spread call options. Pricing spread call options is particularly important in energy markets since such derivatives constitute the building blocks for evaluating the central plants in the real option approach as in, e.g., [CCS12].

6 Conclusions

In this paper we considered the utility indifference pricing problem in a particular market model that includes tradable and nontradable assets, and where the derivatives' payoffs possibly depend on both classes. Using BSDE techniques, we established some existence and regularity results for the price, showing in particular how they can be applied to the pricing and hedging of power derivatives under a structural modeling framework. Although we did not aim for the greatest generality we believe that, under suitable assumptions, most of the results could be extended to a broader set of asset dynamics. Nevertheless, we remark that our framework already allows to consider derivatives written on underlyings that possibly exhibit spikes and discontinuities (as it is the case for electricity prices).

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A Auxiliary results and their proofs

LEMMA A.1 Let $f \in L^1(Q_0)$ be bounded from below and let (Y, Z), with $Z = (Z^S, Z^X)$, be a solution to the BSDE (3.2). Assume that for some q > 0 there exists a constant C > 0 such that $||Z_t^S|| \leq C ||S_t||^q$ for all $t \in [0, T]$. Then the solution of (3.2) satisfies, for all p > 1

$$E^{0}\left[\left(\int_{0}^{t} \|Z_{u}^{X}\|^{2} du\right)^{p}\right] \leq C E^{0}\left[\left(\int_{0}^{t} \|\xi_{u}\|^{2} du\right)^{p/2} + 1\right]$$

where ξ comes from the martingale representation of f under the MMM Q^0 .

Proof. Consider the BSDE (3.3)

$$Y_t = f + \int_t^T g(Z_r) dr - \int_t^T Z_r dW_r^0$$

and write the generator as $g(z) = -\frac{\gamma}{2} ||(0, z^X)||^2 = -\frac{\gamma}{2} ||z||^2 + \frac{\gamma}{2} ||(z^S, 0)||^2$. Notice that $g(Z_r)$ can also be expressed as

$$g(Z_r) = -\frac{\gamma}{2} ||Z_r||^2 + a(t),$$

with $a(t) = \frac{\gamma}{2} ||(Z_t^S, 0_d)||^2$, which satisfies $|a(t)| \leq C' ||S_t||^{2q}$ for some constant C' > 0. We now assume that f is positive, the case where it is only bounded from below being analogous. Consider the function

$$u(x) = \frac{1}{\gamma^2} (e^{-\gamma x} - 1 + \gamma x), \quad x \ge 0,$$

from \mathbb{R}_+ to itself. Remark that $u(x) \ge 0$ and $u'(x) \ge 0$ for $x \ge 0$. Moreover, $\gamma u'(x) + u''(x) = 1$ and $u(x) \le \frac{x}{\gamma}$, $u'(x) \le \frac{1}{\gamma}$, $u''(x) \le 1$ for $x \ge 0$. Defining

$$\tau_{\kappa} = \inf\{t \ge 0 : \int_0^t \|Z_u\|^2 du \ge n\}, \quad \inf \emptyset = +\infty,$$

and applying Itô's lemma we get

$$\begin{split} u(Y_{0}) &= u(Y_{t\wedge\tau_{\kappa}}) + \int_{0}^{t\wedge\tau_{\kappa}} \left(u'(Y_{s})g(Z_{s}) - \frac{1}{2}u''(Y_{s})\|Z_{s}\|^{2} \right) ds - \int_{0}^{t\wedge\tau_{\kappa}} u'(Y_{s})Z_{s}dW_{s}^{0} \\ &\leq u(Y_{t\wedge\tau_{\kappa}}) + \int_{0}^{t\wedge\tau_{\kappa}} u'(Y_{s})a(s) - \int_{0}^{t\wedge\tau_{\kappa}} \frac{1}{2}\left(\gamma u'(Y_{s}) + u''(Y_{s})\right)\|Z_{s}\|^{2}ds \\ &- \int_{0}^{t\wedge\tau_{\kappa}} u'(Y_{s})Z_{s}dW_{s}^{0} \\ &= u(Y_{t\wedge\tau_{\kappa}}) + \int_{0}^{t\wedge\tau_{\kappa}} u'(Y_{s})a(s) - \int_{0}^{t\wedge\tau_{\kappa}} \frac{1}{2}\|Z_{s}\|^{2}ds - \int_{0}^{t\wedge\tau_{\kappa}} u'(Y_{s})Z_{s}dW_{s}^{0} \end{split}$$

therefore

$$\begin{split} \frac{1}{2} \int_0^{t \wedge \tau_\kappa} \|Z_s\|^2 ds &\leq u(Y_{t \wedge \tau_\kappa}) + \int_0^{t \wedge \tau_\kappa} u'(Y_s)a(s)ds - \int_0^{t \wedge \tau_\kappa} u'(Y_s)Z_s dW_s^0 \\ &\leq Y_{t \wedge \tau_\kappa} + \int_0^{t \wedge \tau_\kappa} u'(Y_s)a(s)ds + \sup_{0 \leq t \leq T} \left| \int_0^{t \wedge \tau_\kappa} u'(Y_s)Z_s dW_s^0 \right| \end{split}$$

and using the Burholder-Davis-Gundy inequalities we obtain

$$\begin{split} E^{0}\left[\left(\int_{0}^{t\wedge\tau_{\kappa}}\|Z_{s}\|^{2}ds\right)^{p}\right] &\leq CE^{0}\left[Y_{t\wedge\tau_{\kappa}}^{p}+\left(\int_{0}^{t\wedge\tau_{\kappa}}u'(Y_{s})a(s)ds\right)^{p}\right] \\ &+CE^{0}\left[\left(\int_{0}^{t\wedge\tau_{\kappa}}u'(Y_{s})^{2}\|Z_{s}\|^{2}ds\right)^{p/2}\right] \\ &\leq CE^{0}\left[Y_{t\wedge\tau_{\kappa}}^{p}+\left(\int_{0}^{t\wedge\tau_{\kappa}}u'(Y_{s})a(s)ds\right)^{p}+1\right] \\ &+\frac{1}{2}E^{0}\left[\left(\int_{0}^{t\wedge\tau_{\kappa}}\|Z_{s}\|^{2}ds\right)^{p}\right] \end{split}$$

where we used Young's inequality in the last line. Therefore

$$E^{0}\left[\left(\int_{0}^{t\wedge\tau_{\kappa}} \|Z_{s}\|^{2} ds\right)^{p}\right] \leq CE^{0}\left[\sup_{r\in[0,t]} (E_{r}^{0}[f])^{p} + \left(\int_{0}^{t} \|S_{r}\|^{2} dr\right)^{p} + 1\right]$$
$$\leq CE^{0}\left[\left(\sup_{r\in[0,t]} \int_{0}^{r} \xi_{s} dW_{s}\right)^{p} + 1\right]$$
$$\leq CE^{0}\left[\left(\int_{0}^{t} \|\xi_{s}\|^{2} ds\right)^{p/2} + 1\right]$$

where ξ comes from the martingale representation of f under Q^0 . The result follows by Fatou's lemma.

LEMMA A.2 Let W be a \mathbb{R}^{n+d} -valued Brownian Motion, T > 0, p > 1 and $0 < \alpha < p/2$. Define $U_t = \int_0^t u(r) dW_r$, where u is a \mathbb{R}^{n+d} -valued deterministic bounded process. Then

$$E\left[\sup_{0\le t\le T}\frac{|U_t|^p}{t^\alpha}\right]<\infty$$

Proof. By Dumbis-Dubins-Schwarz representation of the martingale U_t , there exists a Brownian motion \widetilde{W} such that $U_t = \widetilde{W}_{\tau_t}$ where $\tau_t = \langle U \rangle_t = \int_0^t ||u(r)||^2 dr$ is a deterministic bounded time change. Thus, using the scaling property of Brownian motion we have

$$E\left[\sup_{0\leq t\leq T}\frac{|U_t|^p}{t^{\alpha}}\right] = E\left[\sup_{0\leq t\leq T}\frac{|\widetilde{W}_{\tau_t}|^p}{t^{\alpha}}\right] = E\left[|\widetilde{W}_1|^p\right]\sup_{0\leq t\leq T}\frac{\tau_t^{p/2}}{t^{\alpha}}$$
$$\leq CE\left[|\widetilde{W}_1|^p\right]\sup_{0\leq t\leq T}t^{p/2-\alpha} < \infty,$$

for some constant C > 0. This ends the proof.

LEMMA A.3 Let W be a \mathbb{R}^{n+d} -valued Brownian motion, U be defined as in Lemma A.2 and let K be a process in $\mathbb{H}^{q'}(\mathbb{R})$ for some $q' \geq 1$. Suppose, moreover, that $|K_t| \leq F(t, W_t)$ for all $t \in [0, T)$ for some continuous function $F : [0, T) \times \mathbb{R}^{n+d} \to \mathbb{R}$. Then there exists p' > 1 such that

$$E_t\left[\left(\int_t^T \frac{U_r - U_t}{(r-t)} K_r dr\right)^{p'}\right] < \infty.$$

Proof. We have, by choosing $0 < \alpha' < 1/2$ and applying Hölder's inequality

$$\begin{split} E_t \left[\left(\int_t^T \frac{U_r - U_t}{(r-t)} K_r dr \right)^{p'} \right] &= E_t \left[\left(\int_t^T \frac{U_r - U_t}{(r-t)^{\alpha'}} \frac{K_r}{(r-t)^{1-\alpha'}} dr \right)^{p'} \right] \\ &\leq E_t \left[\left(\sup_{t \le r \le T} \frac{|U_r - U_t|}{(r-t)^{\alpha'}} \right)^{p'} \left(\int_t^T \frac{K_r}{(r-t)^{1-\alpha'}} dr \right)^{p'} \right] \\ &\leq E_t \left[\left(\sup_{t \le r \le T} \frac{|U_r - U_t|}{(r-t)^{\alpha'}} \right)^{pp'} \right]^{1/p} E_t \left[\left(\int_t^T \frac{K_r}{(r-t)^{1-\alpha'}} dr \right)^{p'q} \right]^{1/q} \\ &= E_t \left[\sup_{t \le r \le T} \frac{|U_r - U_t|^{pp'}}{(r-t)^{pp'\alpha'}} \right]^{1/p} E_t \left[\left(\int_t^T \frac{K_r}{(r-t)^{1-\alpha'}} dr \right)^{p'q} \right]^{1/q} \\ &\leq CE_t \left[\left(\int_t^T \frac{K_r}{(r-t)^{1-\alpha'}} dr \right)^{p'q} \right]^{1/q} \end{split}$$

by Lemma A.2, where the p > 1 used above is arbitrary. Now set p'q = q' and recall that q' > 1 and it can be chosen arbitrarily close to 1. Now define

$$\tau = \inf\{r > t : \|W_r - W_t\| \ge M\}, \quad \inf \emptyset = +\infty,$$

and notice that, for any $0 < \varepsilon < T - t$, when $t \leq r \leq \tau \wedge (T - \varepsilon)$ we have $|K_r| \leq \tilde{M}$, where \tilde{M} is a constant depending on M and on the function F. Thus we obtain

$$\begin{split} E_t \left[\left(\int_t^T \frac{K_r}{(r-t)^{1-\alpha'}} dr \right)^{q'} \right] \\ &\leq E_t \left[\left(\int_t^{\tau \wedge (T-\varepsilon)} \frac{K_r}{(r-t)^{1-\alpha'}} dr \right)^{q'} + \left(\int_{\tau \wedge (T-\varepsilon)}^T \frac{K_r}{(r-t)^{1-\alpha'}} dr \right)^{q'} \right] \\ &\leq C + E_t \left[\left(\int_{\tau \wedge (T-\varepsilon)}^T \frac{K_r}{(r-t)^{1-\alpha'}} dr \right)^{q'} \right] \\ &\leq C + E_t \left[\frac{1}{(\tau \wedge (T-\varepsilon) - t)^{q'(1-\alpha')}} \left(\int_{\tau \wedge (T-\varepsilon)}^T |K_r| dr \right)^{q'} \right] \\ &\leq C + E_t \left[\frac{1}{(\tau \wedge (T-\varepsilon) - t)^{lq'(1-\alpha')}} \right]^{1/l} E_t \left[\left(\int_{\tau \wedge (T-\varepsilon)}^T |K_r| dr \right)^{q' \frac{1}{1-l}} \right]^{\frac{1-l}{l}} \\ &\leq C + CE_t \left[\frac{1}{(\tau \wedge (T-\varepsilon) - t)^{lq'(1-\alpha')}} \right]^{1/l}. \end{split}$$

To conclude the proof it suffices to show that the expectation in the RHS of the last inequality is finite. This is a straightforward consequence of Lemma A.4 below since, conditionally to \mathcal{F}_t , the process $(\|W_{t+u} - W_t\|)_{u \ge 0}$ is clearly a Bessel process of dimension n + d and $lq'(1 - \alpha') > 1$. \Box

LEMMA A.4 Let R be a Bessel process of any positive integer dimension $k \ge 1$ with $R_0 = 0$. Let $\tau_b := \inf\{t \ge 0 : R_t = b\}$ (with the convention $\inf \emptyset = \infty$) its first hitting time of a level b > 0. Then we have that $E[\tau_b^{-p}] < \infty$ for any $p \ge 1$.

Proof. First notice that $t^{-(n+1)} = n! \int_0^\infty x^n e^{-tx} dx$ for all $n \ge 0$. Replacing t with τ_b , taking expectations on both sides and using Fubini's theorem, we get

$$E\left[\tau_b^{-(n+1)}\right] = n! \int_0^\infty x^n E\left[e^{-x\tau_b}\right] dx.$$

The Laplace transform for the hitting time τ_b (b > 0) of a k-dimensional Bessel process starting from zero is given by (see, e.g., [GJY03])

$$E\left[e^{-x\tau_b}\right] = \left(\frac{x}{2}\right)^{\nu/2} \Gamma^{-1}(\nu+1) \frac{b^{\nu}}{I_{\nu}(b\sqrt{2x})},$$

where $\nu = k/2 - 1$ is the index of the Bessel process R, Γ denotes the Gamma function and I_{ν} is the modified Bessel function of the first kind of order ν . Thus, to conclude the proof it suffices to show that

$$\int_0^\infty \frac{x^{n+\frac{\nu}{2}}}{I_{\nu}(b\sqrt{2x})} dx = C \int_0^\infty \frac{y^{\nu+1+2n}}{I_{\nu}(y)} dy < \infty,$$

for a constant C > 0, which easily follows from the asymptotic behavior of the modified Bessel function $I_{\nu}(y)$ for small and large y given in [Le72] (relations 5.16.4 and 5.16.5).

LEMMA A.5 Let f be a payoff satisfying Assumption 2.1 with super-replicating portfolio process $V_t := V_t^{v_1}(\pi_1)$ expressed under the MMM Q^0 as

$$V_t = \tilde{f} - \int_t^T L_s dW_s^{S,0}, \quad \tilde{f} = V_T,$$

where L is some adapted process satisfying

$$E^0\left[\left(\int_0^T \|L_s\|^2 ds\right)^p\right] < \infty$$

for some p > 1. Then the solution (Y, Z) of (3.5) also verifies

$$E^0\left[\left(\int_0^T \|Z_s\|^2 ds\right)^p\right] < \infty.$$

Proof. Define

$$U_t = V_t - Y_t = \tilde{f} - f + \frac{\gamma}{2} \int_t^T \|Z_s^X\|^2 ds - \int_t^T ((L_s, 0) - Z_s) dW_s^0.$$

Clearly $U_t \ge 0$. Now if the conditions are satisfied, then following the proof of Lemma A.1 we deduce that

$$E^{0}\left[\left(\int_{0}^{t} \|(L_{s},0) - Z_{s}\|^{2} ds\right)^{p}\right] \leq CE^{0}\left[\left(\int_{0}^{t} \|L_{s}\|^{2} ds\right)^{p/2} + 1\right]$$

for some constant C, which implies the result.