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## Sentinel-1A/B imagery for terrain deformation monitoring: a strategy for Atmospheric Phase Screening (APS) estimation

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### Abstract

This work focus on terrain deformation monitoring by means of C-band Synthetic Aperture Radar (SAR) Sentinel-1A/B imagery exploiting the Persistent Scatterer Interferometry (PSI) technique. The deformation monitoring strategy described in this article is related to a specific monitoring scenario where a relatively small urban area is potentially affected by deformation and its surroundings are stable. In the case study considered in this work, the scenario corresponds to an area of potential subsidence induced by underground water pumping covering an area of interest with a radius of approximately 1 km. The proposed monitoring strategy takes advantage of the specific scenario at hand and, in particular, of the availability of stable areas in the vicinity of the area potentially affected by ground deformation, to estimate the Atmospheric Phase Screen (APS), i.e. signal propagation delay caused by the Earth's atmosphere, in an attempt to minimize the underestimation of the deformation rate.

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## 1. Introduction

The Persistent Scatterer Interferometry (PSI) technique represents an advanced category of the differential interferometric Synthetic Aperture Radar (DInSAR) techniques. PSI exploits a set of multiple SAR images acquired over the same geographical area to, by means of appropriate processing tools, isolate the deformation signal of interest from the other components contained within the PSI observations, such as the Residual Topographic Error (RTE) component, the Atmospheric Phase Screening (APS) component and the phase noise. See Crosetto et al. (2016) for a comprehensive review of the PSI technique.

PSI techniques have experienced major developments since they were first proposed almost two decades ago (Ferretti et al., 2001), when they were mainly related to C-band imagery such as ERS-1/2, Envisat and Radarsat sensors. The advent of very high resolution X-band data (TerraSAR-X and CosmoSkyMed) in 2007 enabled a major step forward for this kind of techniques and innovative approaches were proposed (Strozzi et al., 2009; Crosetto et al., 2010; Gernhardt and Bamler, 2012; Lan et al., 2012).

The new generation of C-band data acquired by the sensors on board the Sentinel-1A and 1B satellites represents a new wave of further developments, whose potential is already being analysed and some case studies are available in the literature. For example, Sentinel-1 based PSI has been exploited for several applications such as landslide detection and mapping (Barra et al., 2016 and 2017), monitoring of a mega-landslide (Dai et al., 2016), volcano monitoring (González et al., 2015; De Luca et al., 2016), terrain subsidence monitoring (Crosetto et al., 2015; Shirzaei et al., 2017) or infrastructure monitoring (Huang et al., 2017).

The focus of this work is terrain deformation monitoring by means of the PSI technique and C-band Sentinel-1A/B imagery. In particular, an urban area located in Barcelona, Spain (Fig. 1) was analysed and a specific monitoring scenario is considered by assuming that the area to be monitored, potentially affected by subsidence induced by underground water pumping, is surrounded by a stable area. A strategy to estimate the APS component using an external area while minimizing the impact on the terrain deformation estimates is described. This approach was successfully used by Crosetto et al. (2014) using ground-based SAR observations and was first described in Crosetto et al (2002) using DInSAR observations. The main advantage of the approach is to avoid filtering the APS based on a set of spatial and temporal filters.

## 2. Methodology

The input data used in this work include a stack of 43 co-registered SAR Sentinel-1 images (Table 1), the amplitude dispersion (DA) and a redundant network of 487 wrapped interferograms, generated using most of the 43 Sentinel-1 images as master images (not only single master or consecutive). The main processing stages of the PSI chain proposed in this work are briefly described in this section:

1. 2+1D phase unwrapping of the redundant interferograms (Devanathéry et al., 2014). A spatial 2D phase unwrapping is performed over the redundant set of interferograms followed by a pixel wise 1D phase unwrapping, which uses a robust iterative least squares procedure. This procedure works on the so-called residuals of the interferometric observation equations (with one residual per each of the M interferograms), and fully exploits the integer nature of the unwrapping errors. This stage generates a set of N unwrapped phase images, which are temporally ordered in correspondence with the dates of the SAR images processed.
2. Identification of a stable area in the surroundings of the area of interest.
3. APS component estimation using the stable area. The APS component of the image phases is modelled using a linear model and masking the deformation area.
4. Removal of the estimated APS component from the original single-look interferograms.
5. Estimation of linear deformation velocity and RTE using the periodogram (Biescas et al., 2007).
6. Removal of the residual topographic error from the original single-look interferograms.
7. 2+1D phase unwrapping of the redundant single-look (residual topographic error-free) interferograms. Generation of the deformation time series.
8. Estimation of the deformation velocity from the time series.
9. Geocoding of the results.



Fig 1. Amplitude image indicating the location of the area of interest.

### 3. Results and discussion

The monitoring case study considered in this work concerns an urban area undergoing construction works involving underground water pumping, which can potentially induce subsidence in an area of approximately 1 km radius around the construction area, hereafter referred to as study area. A wider area of approximately 16 km<sup>2</sup>, considered stable, was monitored.

In this work, the APS component of the phases is modelled using a linear model which, although very simple (more complex atmospheric filters could have been implemented), is quite an effective approach in the specific context of the work at hand. Besides, the deformation area is masked prior to estimating the APS. The assumption made in this study is that in a small area, such as the study area under analysis, the APS behaves like a plane. Figure 2 displays the autocorrelation function of an image phase characterized by a strong atmospheric signal (a) and the autocorrelation function of the same image phase after removing the linear atmospheric component (b). The standard deviation of the phase drops from 0.44 rad to 0.32 rad. The autocorrelation function crosses the axis at 90 pixels (i.e. at a distance of approximately 3600 m) before APS correction, while it crosses the axis at pixel 38 (i.e. at a distance of approximately 1500 m) after corrections.

The final processing was carried out with 43 images because, after APS correction, one of the images showed a rather strong phase variation in comparison with the other images. Therefore, this image, probably affected by strong local atmospheric artefacts, was discarded.

Table 1. Sentinel-1 dataset processed for this work.

#	Orbit	Date	#	Orbit	Date	#	Orbit	Date	#	Orbit	Date
1	6132	20150529	12	8757	20151125	23	10682	20160405	34	12782	20160827
2	6307	20150610	13	8932	20151207	24	10857	20160417	35	12957	20160908
3	6657	20150704	14	9107	20151219	25	11032	20160429	36	13132	20160920
4	6832	20150716	15	9282	20151231	26	11207	20160511	37	13482	20161014
5	7007	20150728	16	9457	20160112	27	11382	20160523	38	13657	20161026
6	7357	20150821	17	9632	20160124	28	11557	20160604	39	13832	20161107
7	7707	20150914	18	9807	20160205	29	11907	20160628	40	14007	20161119
8	7882	20150926	19	9982	20160217	30	12082	20160710	41	14182	20161201
9	8057	20151008	20	10157	20160229	31	12257	20160722	42	14357	20161213
10	8407	20151101	21	10332	20160312	32	12432	20160803	43	14532	20161225
11	8582	20151113	22	10507	20160324	33	12607	20160815			

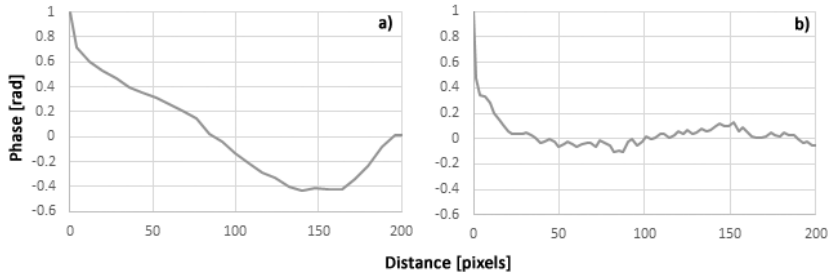


Fig. 2. (a) Autocorrelation function of a phase with APS; (b) Autocorrelation function after APS correction.

The linear deformation velocity and RTE were estimated after the APS correction. The RTE was subsequently removed from the interferograms and the time series were then calculated using the 2+1D phase unwrapping. The deformation velocity was finally estimated from the time series. Figure 3 shows an example of deformation velocity map, in which the spatial density of the Sentinel-1 based measurements can be appreciated. In general, the area shown in Figure 3 is stable. Moreover, the time series of two Persistent Scatterers (PSs) are shown.

The PS located at the lower left part of Fig. 3 displays deformation moving away from the satellite, which accumulates approximately 6 mm in the radar line-of-sight. Notwithstanding the rather noisy appearance of the time series, the deformation pattern is well-defined. In addition, the point is also clearly visible in the deformation velocity map.



Fig. 3. Deformation velocity map displaying a portion of the area of interest. The time series of two Persistent Scatterers are shown.

The PS located at the upper right part of Fig. 3 shows a more complex deformation pattern, which is approximately sinusoidal. It is worth noting that this PS correctly seems as “stable” in the deformation velocity map. This point shows displacements caused by thermal expansion. This is evident by considering the plot of the temperature of the area of interest in correspondence to the time of acquisition of the Sentinel-1 images (Fig. 3. Upper right graph). The black (displacement) and grey (temperature) lines show a strong temporal correlation. This example illustrates the deformation monitoring potential of medium resolution Sentinel-1 data.

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