# INTERACTING GENERALIZED PÓLYA URN SYSTEMS 

GIACOMO ALETTI AND ANDREA GHIGLIETTI


#### Abstract

We consider a system of interacting Generalized Pólya Urns (GPUs) having irreducible mean replacement matrices. The interaction is modeled through the probability to sample the colors from each urn, that is defined as convex combination of the urn proportions in the system. From the weights of these combinations we individuate subsystems of urns evolving with different behaviors. We provide a complete description of the asymptotic properties of urn proportions in each subsystem by establishing limiting proportions, convergence rates and Central Limit Theorems. The main proofs are based on a detailed eigenanalysis and stochastic approximation techniques.


Keywords. Interacting systems, Generalized Pólya urn models, Central Limit Theorems, Strong Consistency, Stochastic approximation.

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## 1. Introduction

The stochastic evolution of systems composed by elements which interact among each other has always been of great interest in several areas of application, e.g. in medicine a tumor growth is the evolution of a system of interacting cells [34, in socio-economics and life sciences a collective phenomenon reflects the result of the interactions among the individuals [27], in physics the concentration of certain molecules within cells varies over time due to interactions between different cells [31. In the last decade several models have been proposed in which the elements of the system are represented by urns containing balls of different colors, in which the urn proportions reflect the status of the elements, and the evolution of the system is established by studying the dynamics at discrete times of this collection of dependent urn processes. The main reason of this popularity is concerned with the urn dynamics, which is (i) suitable to describe random phenomena in different scientific fields (see e.g. [21), (ii) flexible to cover a wide range of possible asymptotic behaviors, (iii) intuitive and easy to be implemented in several fields of application.

The dynamics of a single urn typically consists in a sequential repetition of a sampling phase, when a ball is sampled from the urn, and a replacement phase, when a certain quantity of balls is replaced in the urn. The basic model is the Pólya's urn proposed in [16]: from an urn containing balls of two colors, balls are sequentially sampled and then replaced in the urn with a new ball of the same color. This updating scheme is then iterated generating a sequence of urn proportions whose almost sure limit is random and Beta distributed. Starting from this simple model, several interesting variations have been suggested by considering different distributions in the sampling phase, e.g. [19, 20], or in the replacement phase, e.g. [3, 18, 30]. In a general $K$-colors urn model, the sampled color is usually represented by a vector $\mathbf{X}_{n}$ such that $X_{k, n}=1$ when the color is $k \in\{1, . ., K\}, X_{k, n}=0$ otherwise; the quantities of balls replaced in the urn are typically defined by a matrix $D_{n}$ such that $D_{i k, n}$ indicates the number of balls of color $i$ replaced in the urn when the color $k$ is sampled. Considering $\left\{D_{n} ; n \geq 1\right\}$ as an i.i.d. sequence, a crucial element to characterize the asymptotic behavior of the urn is the mean replacement matrix $H:=\mathbf{E}\left[D_{n}\right]$, typically called generating matrix.

The class of urn models considered in this paper is commonly denoted by Generalized Polya's Urn (GPU), or Generalized Friedman's Urn (GFU). The GPU model was introduced in 18 and its extensions and their asymptotic behavior have been studied in several works, see e.g. [4, 5, 6, 33. The GPU considered in this paper is characterized by a non-negative irreducible generating matrix $H$ with average constant balance, i.e. the columns of $H$ sum up at the same constant $\sum_{i=1}^{K} H_{i k}=c>0$ for any $k \in\{1, . ., K\}$, which implies that its maximum eigenvalues $\lambda_{\max }(H)=c$ has multiplicity one. The irreducibility of $H$ distinguishes the GPU from the Randomly Reinforced Urn (RRU) model, which includes the classical Pòlya's Urn, whose replacement matrix is diagonal: when the color $k$ is sampled, the GPU replaces in the urn more colors following the distribution of the $k^{\text {th }}$ column of $D_{n}$ while the RRU only adds balls of colors $k$; hence, the probability to sample color $k$ at next step is reinforced in the RRU, while it may increase or decrease according to the current urn composition in the GPU. As a consequence, the asymptotic behavior is in general very different: in a GPU the urn proportion converges to a deterministic equilibrium identified by $H$ (see e.g. [4, 5, 6, [33), while in a RRU the limit is random and its distribution depends on the initial composition (see e.g. [1, 2, 15]).

The model proposed in this paper is a collection of $N \geq 1$ GPUs that interact among each other during the sampling phase: the probability to sample a color $k$ in each $\operatorname{urn} j$ is a convex combination of the urn proportions of the entire system. Hence, a crucial role to describe the system dynamics is played by the interacting matrix $W$ made by the weights of those combinations. Since the properties of the single GPUs are determined by the corresponding generating matrices $\left\{H^{j} ; 1 \leq j \leq N\right\}$ and the interaction among them are ruled by $W$, the system dynamics has been studied by defining a new object $\mathbf{Q}$ that merges the information contained in $\left\{H^{j} ; 1 \leq j \leq N\right\}$ and $W$. From the analysis of the eigenstructure of $\mathbf{Q}$, we are able to establish the convergence and the second-order asymptotic behavior of the urn proportions in the entire system. Hence, this paper extends the theory on GPU models in the sense that, in the special case of no interaction, i.e. $W=I$, the results presented for the system reduce to the well-known results for a single GPU.

Several interacting urn models have been proposed in the last decade, especially for RRU models. An early work is represented by [29] that considered a collection of two-colors RRU in which the sequence $\left\{D_{n} ; n \geq 1\right\}$ is not i.i.d. since the replacements in each urn depend on the colors sampled in the rest of the system. Therefore, in [29] the interaction is modeled through the definition of $D_{n}$, instead of $\mathbf{X}_{n}$ as in our model. A complete different updating rule has been used in the two-color urn model proposed in [26], in which sampling color 1 in the urn $j$ increases the composition of color 1 in the urn $j$, while sampling color 2 increases the composition of color 2 in the neighbor urns $i \neq j$ and the urn $j$ comes back to the initial composition. Asymptotic properties for this system have been obtained in [26] where there is no convergence of the urn proportions. Other models in which the interaction enters in the replacement matrices are for instance [11, 10, 8].

Recently there have been more works concerning urn systems in which the interaction is modeled through the sampling probabilities as in our model. They differ from this paper since all of them consider RRUs and the interaction is only modeled as mean-field interaction tuned by a parameter $\alpha \in(0,1)$, i.e. the urns interact among each other only through the average composition in the entire system. As a consequence, their asymptotic results lead to the synchronization property in which all the urn proportions of the system converge to the same random limit. In particular, in [24, 25] the asymptotic behavior of the urn system has been studied for a model that defines the sampling probabilities through the exponential of the urn compositions. In [13, 12] the sampling probabilities are defined directly using the urn compositions and the synchronization property has been proved; moreover, different convergence rates and second-order asymptotic distributions for the urn proportion have been established for different values of the tuning parameter $\alpha$. Since we
consider GPU models the asymptotic results established in this paper are totally different from those proved in [13, 12], e.g. our limiting proportion is not random and it does not depend on the initial compositions.

It is also significant to highlight that this work allows a general structure for the urn interaction, which reduces to the mean-filed interaction only for a particular choice of the interacting matrix $W$. Moreover, from the analysis of the structure of $W$ we are able to individuate subsystems of urns evolving with different behaviors: (i) the leading systems, whose dynamics is independent of the rest of the system and (ii) the following systems, whose dynamics "follows" the evolution of other urns of the system; in the special case of irreducible interacting matrix, which includes the mean-filed interaction considered in [13, 12], there is a unique leading system and no following systems. These two classes of systems have been studied separately, in order to provide an exhaustive description of the asymptotic behavior in any part of the system. In fact, since different systems may converge at different rates, a unique central limit theorem would not been able to characterize the convergence of any urn proportion. Hence, through a careful analysis on the eigen-structure of $\mathbf{Q}$, we individuate the components of the urn processes in the system that actually "lead" or influence the following systems, so that we can establish the right convergence rate and a non-degenerate asymptotic distribution for any subsystem.

A pivotal technique in the proofs consists in revisiting the dynamics of the urn proportions of the system in the stochastic approximation (SA) framework, as suggested for the composition of a single GPU in [23. To this end, the dynamics of the urn proportions has been properly modified here to embed the processes of the urn proportion into the whole space $\mathbb{R}^{K}$.

The structure of the paper is the following. In Section 2 the interacting GPU model is described and the main assumptions are presented. Section 2 is also dedicated to analyze the structure of the interacting matrix and hence to define the leading and the following systems. In Section 3 the system dynamics is expressed in the stochastic approximation form and the necessary notation is introduced. The asymptotic results for the leading and following systems are presented in Section 4 and 5, respectively. Section 6 contains a brief discussion on further possible extensions of the interacting GPU model. Finally, the proofs are presented in Section 7.

## 2. Model Setting and main Assumptions

Consider a collection of $N \geq 1$ urns containing balls of $K \geq 1$ different colors. At any time $n \geq 0$ and for any urn $j \in\{1, . ., N\}$, let $Y_{k, n}^{j}>0$ be the number of balls of color $k \in\{1, . ., K\}$, $T_{n}^{j}:=\sum_{k=1}^{K} Y_{k, n}^{j}$ be the total number of balls and let $Z_{k, n}^{j}:=Y_{k, n}^{j} / T_{n}^{j}$ be the proportion of color $k$.
2.1. Model. We now describe precisely how the system evolves at any time $n \geq 1$. Denote by $\mathcal{F}_{n-1}$ the $\sigma$-algebra generated by the urn compositions of the entire system up to time ( $n-1$ ), i.e.

$$
\mathcal{F}_{n-1}:=\sigma\left(Y_{k, n-1}^{j}, 1 \leq j \leq N, 1 \leq k \leq K\right)
$$

The dynamics of the system is described by two main phases: sampling and replacement.
Sampling phase: for each urn $j \in\{1, . ., N\}$, a ball is virtually sampled and its color is represented as follows: $X_{k, n}^{j}=1$ indicates that the sampled ball is of color $k, X_{k, n}^{j}=0$ otherwise. We denote by $\tilde{Z}_{k, n-1}^{j}$ the probability to sample a ball of color $k$ in the urn $j$ at time $n$, i.e.

$$
\tilde{Z}_{k, n-1}^{j}:=\mathbf{E}\left[X_{k, n}^{j} \mid \mathcal{F}_{n-1}\right] .
$$

Given the sampling probabilities $\left\{\tilde{Z}_{k, n-1}^{j}, 1 \leq j \leq N, 1 \leq k \leq K\right\}$, the colors are sampled independently in all the urns of the system and hence, for any $k \in\{1, . ., K\}, X_{k, n}^{1}, . ., X_{k, n}^{N}$ are independent conditionally on $\mathcal{F}_{n-1}$. We define the sampling probabilities as convex combinations of the urn proportions of the system. Formally, for any urn $j \in\{1, . ., N\}$ we introduce the weights $\left\{w_{j h} ; 1 \leq h \leq N\right\}$ such that $0 \leq w_{j h} \leq 1$ and $\sum_{h=1}^{N} w_{j h}=1$. Thus, the probability to sample the color $k$ in the urn $j$ is defined as follows

$$
\begin{equation*}
\tilde{Z}_{k, n-1}^{j}:=\sum_{h=1}^{N} w_{j h} Z_{k, n-1}^{h} \tag{1}
\end{equation*}
$$

Replacement phase: after that a ball of color $k$ has been sampled from the urn $j$, we replace $D_{i k, n}^{j}$ balls of color $i \in\{1, \ldots, K\}$ in the urn $j$. For any urn $j$ we assume that $\left\{D_{n}^{j} ; n \geq 1\right\}$ is a sequence of i.i.d. non-negative random matrices, where $D_{n}^{j}:=\left[D_{i k, n}^{j}\right]_{i k}$. We will refer to $D_{n}^{j}$ as replacement matrix and to $H^{j}:=\mathbf{E}\left[D_{n}^{j}\right]$ as generating matrix. Notice that $H^{j}$ are time-independent since $\left\{D_{n}^{j} ; n \geq 1\right\}$ are identically distributed (see Subsection 6 for possible extensions). Moreover, we assume that at any time $n$ the replacement matrix for the urn $j$, i.e. $D_{n}^{j}$, is independent of the sampled colors, i.e. $\left\{X_{k, n}^{j} ; 1 \leq j \leq N\right\}$, and independent of the replacement matrices of the other urns of the system, i.e. $D_{n}^{j_{0}}$ with $j_{0} \neq j$.

In conclusion, the composition of the color $i \in\{1, . ., K\}$ in the urn $j \in\{1, . ., N\}$ evolves at time $n \geq 1$ as follows:

$$
\begin{equation*}
Y_{i, n}^{j}=Y_{i, n-1}^{j}+\sum_{k=1}^{K} D_{i k, n}^{j} X_{k, n}^{j} . \tag{2}
\end{equation*}
$$

2.2. Main assumptions. We now present the main conditions required to establish the results of the paper. The first assumption is concerned with bounds for the moments of the replacement distributions. Specifically, we require the following condition:
(A1) there exists $\delta>0$ and a constant $0<C_{\delta}<\infty$ such that, for any $j \in\{1, . ., N\}$ and any $i, k \in\{1, . ., K\}, \mathbf{E}\left[\left(D_{i k, n}^{j}\right)^{2+\delta}\right]<C_{\delta}$.
Note that $C_{\delta}$ does not depend on $n$ since $\left\{D_{n}^{j} ; n \geq 1\right\}$ are identically distributed.
The second assumption is the average constant balance of the urns in the system and it is imposed by the following condition on the generating matrices $H^{1}, . ., H^{N}$ :
(A2) for any $j \in\{1, . ., N\}$ and $k \in\{1, . ., K\}$, there exists a constant $0<c^{j}<\infty$ such that $\sum_{i=1}^{K} H_{i k}^{j}=c^{j}$.
Note that (A2) guarantees that the average number of balls replaced in any urn is constant, regardless its composition. Assumption (A2) is essential to obtain the asymptotic configuration of the system, i.e. the limiting urn proportions. The second-order asymptotic properties of the interacting urn system, namely the rate of convergence and the limiting distributions, are obtained by assuming a stricter assumption than (A2). This condition is expressed as follows:
(A'2) for any $j \in\{1, . ., N\}, k \in\{1, . ., K\}, \mathbf{P}\left(\sum_{i=1}^{K} D_{i k, n}^{j}=c^{j}\right)=1$, i.e. each urn is updated with a constant total amount of balls.

Without loss of generality, we may (and do) assume that $c^{j}=1$ for all $j \in\{1, . ., N\}$. In fact, by defining $\widehat{Y}_{k, n}^{j}=\left(c^{j}\right)^{-1} Y_{k, n}^{j}$ and $\widehat{D}_{i k, n}^{j}=\left(c^{j}\right)^{-1} D_{i k, n}^{j}$ for all $n \geq 1$, the urn dynamics in (2) can be expressed in the following equivalent form:

$$
\widehat{Y}_{i, n}^{j}=\widehat{Y}_{i, n-1}^{j}+\sum_{k=1}^{K} \widehat{D}_{i k, n}^{j} \cdot X_{k, n}^{j}, \quad \widehat{Z}_{k, n-1}^{j}=\frac{\widehat{Y}_{k, n-1}^{j}}{\sum_{k=1}^{K} \widehat{Y}_{k, n-1}^{j}}=\frac{Y_{k, n-1}^{j}}{\sum_{k=1}^{K} Y_{k, n-1}^{j}}=Z_{k, n-1}^{j} .
$$

Therefore, from now on we will denote by $Y_{k, n}^{j}$ and $D_{i k, n}^{j}$ the normalized quantities $\widehat{Y}_{k, n}^{j}$ and $\widehat{D}_{i k, n}^{j}$ and hence (A2) and (A'2) are replaced by the following conditions:
(A2) for any $j \in\{1, . ., N\}$ and $k \in\{1, . ., K\}, \sum_{i=1}^{K} H_{i k}^{j}=1$.
(A'2) for any $j \in\{1, . ., N\}$ and $k \in\{1, . ., K\}, \mathbf{P}\left(\sum_{i=1}^{K} D_{i k, n}^{j}=1\right)=1$.
Finally, we consider Generalized Pòlya urn (GPU) with irreducible generating matrices, as expressed in the following condition:
(A3) for any $j \in\{1, . ., N\}, H^{j}$ is irreducible.
This assumption will guarantee deterministic asymptotic configurations for the urn proportions in the system. Less restrictive conditions to establish deterministic limiting proportion are possible but this analysis is not the focus of this paper.

Remark 2.1. It is worth highlighting that extensions to non-homogeneous generating matrices $\left\{H_{n} ; n \geq 0\right\}$ are possible, as discussed in Section 6. In that case, assumption (A2) should be referred to the the limiting matrix $H^{j}:=$ a.s. $-\lim _{n \rightarrow \infty} H_{n}^{j}$.
2.3. A preliminary result. Assumptions (A2) and (A'2) on the constant balance are essential to obtain the following result on the total number of balls in the urns of the system:

Theorem 2.1. Under assumptions (A1) and (A2), $\left\{T_{n}^{j}-n ; n \geq 1\right\}$ is an $L^{2}$ martingale and, for any $\alpha<1 / 2$,

$$
\begin{equation*}
n^{\alpha}\left(\frac{T_{n}^{j}}{n}-1\right) \xrightarrow{\text { a.s. } / L^{2}} 0 . \tag{3}
\end{equation*}
$$

Moreover, under assumption ( $A^{\prime}$ '), $T_{n}^{j}=T_{0}^{j}+n$ a.s. and hence (3) holds for any $\alpha<1$.
2.4. The interacting matrix. The interaction among the urns of the system is modeled through the sampling probabilities $\tilde{Z}_{k, n-1}^{j}$, that are defined in (1) as convex combination of the urn proportions of the system. Formally, we denote by $W$ the $N \times N$ matrix composed by the weights $\left\{w_{j h}, 1 \leq j, h \leq N\right\}$ of such linear combinations and we refer to it as interacting matrix. We now consider a particular decomposition of $W$ that individuates subsystems of urns evolving with different behaviors. The same decomposition is applied to the transition matrix in the context of discrete-time Markov chains (see [28]) to individuate communicating classes $S^{l}, l \in \mathcal{L}$, and to establish which classes are recurrent, $l \in \mathcal{L}_{L}$, and which are transient, $l \in \mathcal{L}_{F}$.

Accordingly, let us denote by $n_{L} \geq 1$ the multiplicity of $\lambda_{\max }(W)=1$, and define the integers $n_{F} \geq 0$ and $1 \leq r^{L_{1}}<. .<r^{L_{n}}<r^{F_{1}}<. .<r^{F_{n_{F}}}=N$ such that the interacting matrix can be
decomposed as follows:

$$
\begin{array}{rlrl}
W & :=\left[\begin{array}{ll}
W^{L} & 0 \\
W^{L F} & W^{F}
\end{array}\right], & W^{L} & :=\left[\begin{array}{llll}
0 & W^{L_{2}} & \ldots & \ldots \\
\ldots & \ldots & \ldots & 0 \\
0 & 0 & \ldots & W^{L_{n_{L}}}
\end{array}\right], \\
W^{L F} & :=\left[\begin{array}{lll}
W^{L_{1} F_{1}} & \ldots & W^{L_{n_{L}} F_{1}} \\
\ldots & \ldots & \ldots \\
W^{L_{1} F_{n_{F}}} & \ldots & W^{L_{n_{L}} F_{n_{F}}}
\end{array}\right], \quad W^{F}:=\left[\begin{array}{llll}
W^{F_{1}} & 0 & \ldots & 0 \\
W^{F_{1} F_{2}} & W^{F_{2}} & \ldots & 0 \\
\ldots & \ldots & \ldots & \ldots \\
W^{F_{1} F_{n_{F}}} & W^{F_{2} F_{n_{F}}} & \ldots & W^{F_{n_{F}}}
\end{array}\right] . \tag{4}
\end{array}
$$

where:
(1) $\mathcal{L}:=\mathcal{L}_{L} \cup \mathcal{L}_{F}, \mathcal{L}_{L}:=\left\{L^{1}, \ldots, L^{n_{L}}\right\}$ and $\mathcal{L}_{F}:=\left\{F^{1}, . ., F^{n_{F}}\right\}$ are sets of labels that identify subsystems of urns ( $\mathcal{L}_{F}=\emptyset$ when $n_{F}=0$ );
(2) for any $l \in \mathcal{L}, W^{l}$ is an $s^{l} \times s^{l}$ irreducible matrix, where we let $s^{l}:=r^{l}-r^{l^{-}}$and $l^{-}$indicates the element in $\mathcal{L}$ that precedes $l$ (by convention $L_{1}^{-} \equiv \emptyset$ and $F_{1}^{-} \equiv L_{n_{L}}$ );
(3) for any $l_{2} \in \mathcal{L}_{F}$, there is at least an $l_{1} \in \mathcal{L}, l_{1} \neq l_{2}$, such that $W^{l_{1} l_{2}} \neq 0$; hence, $\lambda_{\max }\left(W^{l}\right)=1$ if $l \in \mathcal{L}_{L}$ and $\lambda_{\text {max }}\left(W^{l}\right)<1$ if $l \in \mathcal{L}_{F}$.
Naturally, when $n_{F}=0$ the elements in $W^{L F}$ and $W^{F}$ do not exist and we consider $r^{L_{n}}=N$. This occurs, for instance, when $W$ is irreducible and hence $n_{L}=1$ and $r^{1}=N$.
Remark 2.2. It is worth highlighting that extensions to random and time-dependent interacting matrices $\left\{W_{n} ; n \geq 0\right\}$ are possible, as discussed in Section 6. In that case, the structure presented in (4) is concerned with the limiting matrix $W:=a . s .-\lim _{n \rightarrow \infty} W_{n}$.
Since the urns of the system interact among each other only through the sampling probabilities $\tilde{Z}_{n, k}^{j}$, the structure of the matrix $W$ that characterizes such interaction is essential to describe the asymptotic behavior of the system. Specifically, from (4) we individuate
(i) the leading systems $S^{l}:=\left\{r^{l^{-}}+1<j \leq r^{l}\right\}, l \in \mathcal{L}_{L}$, that evolve independently with respect to the rest of the system;
(ii) if $n_{F} \geq 0$, the following systems $S^{l}:=\left\{r^{l^{-}}+1<j \leq r^{l}\right\}, l \in \mathcal{L}_{F}$, that evolve depending on the proportions of the urns in the leaders $S^{L_{1}}, . ., S^{L_{n_{L}}}$ and their upper followers $S^{F_{1}}, . ., S^{l^{-}}$.
As we will see in the following sections, the asymptotic behaviors of the leading systems and the following systems are quite different. For completeness of the paper, we will present the results for both the types of systems, assuming that $n_{F} \geq 1$.

## 3. The interacting urn system in the stochastic approximation framework

A crucial technique to characterize the behavior of the interacting urn system consists in revisiting its dynamics into the stochastic approximation (SA) framework. To this end, we need to rewrite the system dynamics expressed in (2) in the classical SA form: given a filtered probability space $\left(\Omega, \mathcal{A},\left(\mathcal{F}_{n}\right)_{n \geq 0}, \mathbf{P}\right)$, we consider the following recursive procedure

$$
\begin{equation*}
\forall n \geq 1, \quad \theta_{n}=\theta_{n-1}-\frac{1}{n} f\left(\theta_{n-1}\right)+\frac{1}{n}\left(\Delta M_{n}+R_{n}\right) \tag{5}
\end{equation*}
$$

where $f: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$ is a locally Lipschitz continuous function, $\theta_{n}$ an $\mathcal{F}_{n}$-measurable finite random vector and, for every $n \geq 1, \Delta M_{n}$ is an $\mathcal{F}_{n-1}$-martingale increment and $R_{n}$ is an $\mathcal{F}_{n}$-adapted
remainder term. To this end, we need a compact notation that jointly describes the composition of the urns in the same subsystem $S^{l}, l \in \mathcal{L}$.
3.1. Notation. The quantities related to the urn $j \in\{1, . ., N\}$ at time $n$ are denoted by:
(1) $Y_{n}^{j}=\left(Y_{1, n}^{j}, . ., Y_{K, n}^{j}\right)^{\prime} \in \mathbb{R}_{+}^{K}$,
(2) $X_{n}^{j}=\left(X_{1, n}^{j}, . ., X_{K, n}^{j}\right)^{\prime} \in\{0,1\}^{K}$,
(3) $Z_{n}^{j}=\left(Z_{1, n}^{j}, . ., Z_{K, n}^{j}\right)^{\prime} \in(0,1)^{K}$,
(4) $\tilde{Z}_{n}^{j}=\left(\tilde{Z}_{1, n}^{j}, . ., \tilde{Z}_{K, n}^{j}\right)^{\prime} \in(0,1)^{K}$,
while the corresponding terms of the system $S^{l}, l \in \mathcal{L}$, given by the $s^{l}$ urns labeled by $\left\{r^{l^{-}}+1, . ., r^{l}\right\}$, are denoted by:
(1) $\mathbf{Y}_{n}^{l}:=\left(Y_{n}^{r^{l^{-}}+1}, . ., Y_{n}^{r^{l}}\right)^{\prime} \in \mathbb{R}_{+}^{s^{l} K}$,
(2) $\mathbf{X}_{n}^{l}:=\left(X_{n}^{r^{l^{-}}+1}, . ., X_{n}^{r^{l}}\right)^{\prime} \in\{0,1\}^{s^{l} K}$,
(3) $\mathbf{Z}_{n}^{l}:=\left(Z_{n}^{r^{-}+1}, \ldots, Z_{n}^{r^{l}}\right)^{\prime} \in \mathcal{S}^{s^{l} K}$, where $\mathcal{S}^{s^{l} K}$ indicates the composition of $s^{l}$ simpleces where $Z_{n}^{r^{l^{-}}+1}, . ., Z_{n}^{r^{l}}$ are defined.
(4) $\tilde{\mathbf{Z}}_{n}^{l}:=\left(\tilde{Z}_{n}^{r^{-}}+1, . ., \tilde{Z}_{n}^{r^{l}}\right)^{\prime} \in \mathcal{S}^{s^{l} K}$,
(5) $\mathbf{T}_{n}^{l}:=\left(T_{n}^{r^{-}+1} \mathbf{1}_{K}, . ., T_{n}^{r^{l}} \mathbf{1}_{K}\right)^{\prime} \in \mathbb{R}_{+}^{s^{l} K}$, where $\mathbf{1}_{K}$ indicates the $K$-vector of all ones.

The replacement matrix for the system $S^{l}$ is defined by a block diagonal matrix $\mathbf{D}_{n}^{l} \in \mathbb{R}_{+}^{s^{l} K \times s^{l} K}$, where the $s^{l}$ blocks are the replacement matrices of the urns $\left\{r^{l^{-}}+1, \ldots, r^{l}\right\}$ in $S^{l}$, i.e. $D_{n}^{r^{l^{-}}+1}, \ldots, D_{n}^{r^{l}}$. Analogously, the generating matrix for $S^{l}$ is defined by a block diagonal matrix $\mathbf{H}^{l} \in \mathbb{R}_{+}^{s^{l} K \times s^{l} K}$, where the $s^{l}$ blocks are $H^{r^{l^{-}}+1}, \ldots, H_{n}^{r^{l}}$. The interaction within the system $S^{l}$ is modeled by the matrix $\mathbf{W}^{l} \in(0,1)^{s^{l} K \times s^{l} K}$ obtained by replacing in $W^{l}$ (4) the weights $w_{i n}$ with the corresponding diagonal matrix $w_{i h} I_{K}$, where $I_{K}$ indicates a $K$-identity matrix. Analogously, the interaction between a following system $S^{l_{1}}, l \in \mathcal{L}_{F}$, and another system $S^{l_{2}}, l_{2} \in\left\{L_{1}, . ., l_{1}^{-}\right\}$, is modeled by the matrix $\mathbf{W}^{l_{1} l_{2}} \in(0,1)^{s_{1}} K \times s^{l_{2}} K$, obtained by replacing in $W^{l_{1} l_{2}}$ (4) the weights $w_{i h}$ with the corresponding diagonal matrix $w_{i h} I_{K}$.
3.2. The system dynamics in the SA form. For any system $S^{l}, l \in \mathcal{L}$, the dynamics in (2) can be written, using the notation of Subsection 3.1, as follows:

$$
\begin{equation*}
\mathbf{Y}_{n}^{l}=\mathbf{Y}_{n-1}^{l}+\mathbf{D}_{n}^{l} \mathbf{X}_{n}^{l} . \tag{6}
\end{equation*}
$$

We now express (60) in the SA form (5), where the process $\left\{\theta_{n} ; n \geq 1\right\}$ is represented by the urn proportions of the system $S^{l}$, i.e. $\left\{\mathbf{Z}_{n}^{l} ; n \geq 1\right\}$. Since $\mathbf{Y}_{n}^{l}=\operatorname{diag}\left(\mathbf{T}_{n}^{l}\right) \mathbf{Z}_{n}^{l}$ for any $n \geq 1$, from (6) we have

$$
\operatorname{diag}\left(\mathbf{T}_{n}^{l}\right) \mathbf{Z}_{n}^{l}=\operatorname{diag}\left(\mathbf{T}_{n-1}^{l}\right) \mathbf{Z}_{n-1}^{l}+\mathbf{D}_{n}^{l} \mathbf{X}_{n}^{l}
$$

that is equivalent to

$$
\begin{equation*}
\operatorname{diag}\left(\mathbf{T}_{n}^{l}\right)\left(\mathbf{Z}_{n}^{l}-\mathbf{Z}_{n-1}^{l}\right)=-\operatorname{diag}\left(\mathbf{T}_{n}^{l}-\mathbf{T}_{n-1}^{l}\right) \mathbf{Z}_{n-1}^{l}+\mathbf{D}_{n}^{l} \mathbf{X}_{n}^{l} \tag{7}
\end{equation*}
$$

Now, notice that, for any $n \geq 1$,
(1) $\mathbf{E}\left[\operatorname{diag}\left(\mathbf{T}_{n}^{l}-\mathbf{T}_{n-1}^{l}\right) \mid \mathcal{F}_{n-1}\right]=\mathbf{I}$ by Theorem [2.1]
(2) $\mathbf{E}\left[\mathbf{D}_{n}^{l} \mathbf{X}_{n}^{l} \mid \mathcal{F}_{n-1}\right]=\mathbf{E}\left[\mathbf{D}_{n}^{l} \mid \mathcal{F}_{n-1}\right] \mathbf{E}\left[\mathbf{X}_{n}^{l} \mid \mathcal{F}_{n-1}\right]=\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}$, since $\mathbf{D}_{n}^{l}$ and $\mathbf{X}_{n}^{l}$ are independent conditionally on $\mathcal{F}_{n-1}$.

Hence, defining the martingale increment

$$
\begin{equation*}
\Delta \mathbf{M}_{n}^{l}:=\mathbf{D}_{n}^{l} \mathbf{X}_{n}^{l}-\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}-\left(\operatorname{diag}\left(\mathbf{T}_{n}^{l}-\mathbf{T}_{n-1}^{l}\right)-\mathbf{I}\right) \mathbf{Z}_{n-1}^{l} \tag{8}
\end{equation*}
$$

we can express (7) as follows:

$$
\begin{equation*}
\operatorname{diag}\left(\mathbf{T}_{n}^{l}\right)\left(\mathbf{Z}_{n}^{l}-\mathbf{Z}_{n-1}^{l}\right)=-\mathbf{Z}_{n-1}^{l}+\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}+\Delta \mathbf{M}_{n}^{l} \tag{9}
\end{equation*}
$$

Now, multiplying by $\operatorname{diag}\left(\mathbf{T}_{n}^{l}\right)^{-1}$ and defining the remainder term

$$
\begin{equation*}
\mathbf{R}_{n}^{l}:=\left(n \cdot \operatorname{diag}\left(\mathbf{T}_{n}^{l}\right)^{-1}-\mathbf{I}\right)\left(-\mathbf{Z}_{n-1}^{l}+\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}+\Delta \mathbf{M}_{n}^{l}\right) \tag{10}
\end{equation*}
$$

we can write (9) as follows:

$$
\begin{equation*}
\mathbf{Z}_{n}^{l}-\mathbf{Z}_{n-1}^{l}=-\frac{1}{n}\left(\mathbf{Z}_{n-1}^{l}-\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}\right)+\frac{1}{n}\left(\Delta \mathbf{M}_{n}^{l}+\mathbf{R}_{n}^{l}\right) \tag{11}
\end{equation*}
$$

The term $\left(\mathbf{Z}_{n-1}^{l}-\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}\right)$ in (11) should represent the function $f$ in (55) in the SA form. However, although in a leader $S^{l}, l \in \mathcal{L}_{L}$, we have that $\tilde{\mathbf{Z}}_{n-1}^{l}$ only depends on $\mathbf{Z}_{n-1}^{l}$, in a follower $S^{l}$, $l \in \mathcal{L}_{F}$, the term $\tilde{\mathbf{Z}}_{n-1}^{l}$ is in general a function of the composition of all the urns of the system, i.e. $\mathbf{Z}_{n-1}^{L_{1}}, . ., \mathbf{Z}_{n-1}^{l}$. Hence, the dynamics of a leading system can be expressed as in (11), while the dynamics of a following system needs to be incorporated with other systems to be fully described. For this reason, the asymptotic behavior of these two types of systems are studied separately: the leading systems in Section 4 and the following systems in Section 5 .

## 4. Leading systems

In this section we present the main asymptotic results concerning the leading systems $S^{l}, l \in \mathcal{L}_{L}$. We recall that these systems are characterized by irreducible interacting matrices $W^{l}$ such that $\lambda_{\max }\left(W^{l}\right)=1$ (see (4) in Subsection [2.4). For this reason, their dynamics is independent of the rest of the system and hence, by using $\tilde{\mathbf{Z}}_{n-1}^{l}=\mathbf{W}^{l} \mathbf{Z}_{n-1}^{l}$ in (11), we have

$$
\begin{align*}
\mathbf{Z}_{n}^{l}-\mathbf{Z}_{n-1}^{l} & =-\frac{1}{n} h^{l}\left(\mathbf{Z}_{n-1}^{l}\right)+\frac{1}{n}\left(\Delta \mathbf{M}_{n}^{l}+\mathbf{R}_{n}^{l}\right),  \tag{12}\\
h^{l}(\mathbf{x}) & :=\left(\mathbf{I}-\mathbf{Q}^{l}\right) \mathbf{x}, \quad \mathbf{Q}^{l}:=\mathbf{H}^{l} \mathbf{W}^{l}
\end{align*}
$$

4.1. Extension of the urn dynamics to $\mathbb{R}^{s^{l} K}$. Since $h^{l}$ is defined on $\mathbb{R}^{s^{l} K}$, while the process $\left\{\mathbf{Z}_{n}^{l} ; n \geq 0\right\}$ takes values in the subset $\mathcal{S}^{s^{l} K}$, then applying theorems based on the SA directly to (12) may lead to improper results for the process $\mathbf{Z}_{n}^{l}$. To address this issue, we appropriately modify the dynamics (12) by replacing $h^{l}$ with a suitable function $f_{m}^{l}:=h^{l}+m g^{l}$, where $m>0$ is an arbitrary constant and $g^{l}$ is a function defined in $\mathbb{R}^{s^{l} K}$ that satisfies the following properties:
(i) the derivative $\mathcal{D} g^{l}$ is positive semi-definite and its kernel is $\operatorname{Span}\left\{(x-y): x, y \in \mathcal{S}^{s^{l} K}\right\}$ : hence, $g^{l}$ does not modify the eigen-structure of $\mathcal{D} h^{l}(\mathbf{x})$ on the subspace $\mathcal{S}^{s^{l} K}$, where the process $\mathbf{Z}_{n}^{l}$ is defined, while the eigen-structure outside $\mathcal{S}^{s^{l} K}$ can be arbitrary redefined;
(ii) $g^{l}(\mathbf{z})=0$ for any $\mathbf{z} \in \mathcal{S}^{s^{l} K}$ : hence, since $f_{m}^{l}(\mathbf{z})=h^{l}(\mathbf{z})$ for any $\mathbf{z} \in \mathcal{S}^{s^{l} K}$, the modified dynamics restricted to the subset $\mathcal{S}^{s^{l} K}$ represents the same dynamics as in (12).
Let us now provide an analytic expression of $g^{l}$. First note that, since by definition of convex combination we always have $W^{l} \mathbf{1}_{s^{l}}=\mathbf{1}_{s^{l}}$, the left eigenvectors of $W^{l}$ are such that $U_{1}^{\prime} \mathbf{1}_{s^{l}}=1$ and $U_{i}^{\prime} \mathbf{1}_{s^{l}}=0$ for all $i \neq 1$. Denote by $S p(A)$ the set of the eigenvalues of a matrix $A$ and note that, since by (A2) we always have $\mathbf{1}_{K}^{\prime} H^{j}=\mathbf{1}_{K}^{\prime}$, then $S p\left(W^{l}\right) \subset S p\left(\mathbf{Q}^{l}\right)$ and the $s^{l}$ left eigenvectors of $\mathbf{Q}^{l}$ associated to any $\lambda_{i} \in S p\left(W^{l}\right) \subset S p\left(\mathbf{Q}^{l}\right), i \in\left\{1, . ., s^{l}\right\}$, present the following structure:
$\mathbf{U}_{i}:=\left(U_{i 1} \mathbf{1}_{K}, . ., U_{i s^{l}} \mathbf{1}_{K}\right)^{\prime}$. As a consequence, for any $\mathbf{z} \in \mathcal{S}^{s^{l} K}$, we have $\mathbf{U}_{1}^{\prime} \mathbf{z}=U_{1}^{\prime} \mathbf{1}_{s^{l}}=1$ and $\mathbf{U}_{i}^{\prime} \mathbf{z}=U_{i}^{\prime} \mathbf{1}_{s^{l}}=0$ for all $i \in\left\{2, . ., s^{l}\right\}$. Hence, denoting by $\mathbb{V}_{2}$ and $\mathbb{U}_{2}$ the matrices whose columns are $\mathbf{V}_{2}, \ldots, \mathbf{V}_{s^{l}}$ and $\mathbf{U}_{2}, . ., \mathbf{U}_{s^{l}}$, respectively, we define the function $g^{l}$ as follows:

$$
\begin{equation*}
g^{l}(\mathbf{x}):=\mathbf{V}_{1}\left(\mathbf{U}_{1}^{\prime} \mathbf{x}-1\right)+\mathbb{V}_{2} \mathbb{U}_{2}^{\prime} \mathbf{x} \tag{13}
\end{equation*}
$$

and the dynamics of the process $\mathbf{Z}_{n}^{l}$ in (12) can be replaced by the following:

$$
\begin{align*}
\mathbf{Z}_{n}^{l}-\mathbf{Z}_{n-1}^{l} & =-\frac{1}{n} f_{m}^{l}\left(\mathbf{Z}_{n-1}^{l}\right)+\frac{1}{n}\left(\Delta \mathbf{M}_{n}^{l}+\mathbf{R}_{n}^{l}\right)  \tag{14}\\
f_{m}^{l}(\mathbf{x}) & :=\left(\mathbf{I}-\mathbf{Q}^{l}\right) \mathbf{x}+m \mathbf{V}_{1}\left(\mathbf{U}_{1}^{\prime} \mathbf{x}-1\right)+m \mathbb{V}_{2} \mathbb{U}_{2}^{\prime} \mathbf{x}
\end{align*}
$$

4.2. First-order asymptotic results. We now present the main convergence result concerning the limiting proportion of the urns in the leading systems.
Theorem 4.1. Assume (A1), (A2) and (A3). Thus, for any leading system $S^{l}, l \in \mathcal{L}_{L}$, we have that

$$
\begin{equation*}
\mathbf{Z}_{n}^{l} \xrightarrow{\text { a.s. }} \mathbf{Z}_{\infty}^{l}:=\mathbf{V}_{1}, \tag{15}
\end{equation*}
$$

where $\mathbf{V}_{1}$ indicates the right-eigenvector associated to the simple eigenvalue $\lambda=1$ of the matrix $\mathbf{Q}^{l}$, with $\sum_{i} V_{1 i}=1$.
Remark 4.1. Note that when the interacting matrix is the identity matrix, i.e. $W=I, n_{L}=N$ and $n_{F}=0$, each urn represents a leading system and it evolves independently of the rest of the system. In this case, (15) expresses the usual result for a single GPU, where the urn proportion converges to the eigenvector associated to the maximum eigenvalue of the generating matrix, see e.g. [4, 5, 6, 33].

Remark 4.2. In Theorem 4.1, condition (A3) implies that the maximum eigenvalue $\lambda=1$ of $\mathbf{Q}^{l}$ has multiplicity one, which guarantees $\mathbf{V}_{1}$ to be the unique global attractor for the system $S^{l}$. Without assumption (A3), there could be multiple attractors and hence the limiting proportions of the system would be a random variable, as in [13, 12] where the RRU model is considered.
4.3. Second-order asymptotic results. We now establish the rate of convergence and the asymptotic distribution of the urn proportions in the leading systems $S^{l}, l \in \mathcal{L}_{L}$. Since to obtain these results we need to apply the Central Limit Theorem of the SA (see Theorem A. 2 in Appendix) to the dynamics (14), a crucial role is played by the spectrum of the $K s^{l} \times K s^{l}$-matrix of the first-order derivative of $f_{m}^{l}$ defined as follows: for any $\mathbf{x} \in \mathbb{R}^{K s^{l}}$

$$
\begin{equation*}
\mathbf{F}_{m}^{l}:=\mathcal{D} f_{m}^{l}(\mathbf{x})=\left(\mathbf{I}-\mathbf{Q}^{l}\right)+m \mathbf{V}_{1} \mathbf{U}_{1}^{\prime}+m \mathbb{V}_{2} \mathbb{U}_{2}^{\prime} . \tag{16}
\end{equation*}
$$

Moreover, since the asymptotic variance depends on the second moments of the replacement matrices, we denote by $C^{j}(k)$ the covariance matrix of the $k^{t h}$ column of $D_{n}^{j}$, i.e. $C^{j}(k):=\mathbf{C o v}\left[D_{\cdot k, n}^{j}\right]$, where $D_{k, n}^{j}:=\left(D_{1 k, n}^{j}, . ., D_{K k, n}^{j}\right)^{\prime} ;$ note that $(A 1)$ ensures the existence of $C^{j}(k)$. Hence, denoting by $H^{j}(k):=E\left[H_{. k}^{j}\left(H_{\cdot k}^{j}\right)^{\prime}\right]$ where $H_{\cdot k}^{j}:=\left(H_{1 k}^{j}, . ., H_{K k}^{j}\right)^{\prime}$, we let

$$
\begin{equation*}
G^{j}:=\sum_{k=1}^{K}\left(C^{j}(k)+H^{j}(k)\right) \tilde{Z}_{k, \infty}^{j}-Z_{\infty}^{j}\left(Z_{\infty}^{j}\right)^{\prime}, \tag{17}
\end{equation*}
$$

where $\tilde{Z}_{k, \infty}^{j}=\sum_{i=1}^{N} w_{j i} Z_{k, \infty}^{i}$. Then, for any leading system $S^{l}, l \in \mathcal{L}_{L}$, we denote by $\mathbf{G}^{l}$ the block diagonal matrix made by the $s^{l}$ blocks $G^{r^{r^{-}}+1}, . ., G^{r^{l}}$.

The following theorem shows the rate of convergence and the limiting distribution of the urn proportions in the leading systems.

Theorem 4.2. Assume (A1), ( $\left.A^{\prime} 2\right)$ and (A3). For any leading system $S^{l}, l \in \mathcal{L}_{L}$, let $\lambda^{* l}$ be the maximum eigenvalue in $S p\left(\mathbf{Q}^{l}\right) \backslash S p\left(W^{l}\right)$. Thus, we have that $\lambda^{* l} \equiv 1-\min S p\left(\mathbf{F}_{m}^{l}\right)$ and
(a) if $\lambda^{* l}<1 / 2$, then

$$
\sqrt{n}\left(\mathbf{Z}_{n}^{l}-\mathbf{Z}_{\infty}^{l}\right) \xrightarrow{d} \mathcal{N}\left(0, \Sigma^{l}\right), \quad \Sigma^{l}:=\lim _{m \rightarrow \infty} \int_{0}^{\infty} e^{u\left(\frac{1}{2}-\mathbf{F}_{m}^{l}\right)} \mathbf{G}^{l} e^{u\left(\frac{1}{2}-\mathbf{F}_{m}^{l}\right)^{\prime}} d u .
$$

(b) if $\lambda^{* l}=1 / 2$, then

$$
\sqrt{\frac{n}{\log (n)}}\left(\mathbf{Z}_{n}^{l}-\mathbf{Z}_{\infty}^{l}\right) \xrightarrow{d} \mathcal{N}\left(0, \Sigma^{l}\right) .
$$

(c) if $\lambda^{* l}>1 / 2$, then there exists a finite random variable $\psi^{l}$ such that

$$
n^{1-\lambda^{* l}}\left(\mathbf{Z}_{n}^{l}-\mathbf{Z}_{\infty}^{l}\right) \xrightarrow{\text { a.s. }} \psi^{l} .
$$

Remark 4.3. When the interacting matrix $W$ is the identity matrix, each urn represents a leading system and hence $W^{l}=1$ and $\mathbf{Q}^{l} \equiv H^{l}$. In that case, $\lambda^{*}$ is the second largest eigenvalue of the generating matrix $H^{l}$ and hence Theorem 4.2 expresses the usual Central Limit Theorem for a single GPU, see e.g. [4, [5, (6, 33].
Remark 4.4. The role of $\mathbf{Q}^{l}$ in Theorem 4.2 shows that the convergence rate of the urns in $S^{l}$ does not depend only on their generating matrices $\left\{H^{j}, r^{l^{-}}+1 \leq j \leq r^{l}\right\}$ but also on their interaction expressed in $W^{l}$. For instance, consider two single GPUs whose generating matrices $H^{1}$ and $H^{2}$ are such that the convergence rates of the urn proportions $Z_{n}^{1}$ and $Z_{n}^{2}$ are different. Then, an interaction between these urns with an irreducible $W^{l}$ would make $Z_{n}^{1}$ and $Z_{n}^{2}$ converge at the same rate that would depend on the choice of $W^{l}$.

## 5. Following systems

In this section we establish asymptotic properties concerning the following systems $S^{l}, l \in \mathcal{L}_{F}$. Since the dynamics of these systems can be properly expressed in the SA form (5) only through a joint model with the urns in the systems $\left\{S^{L_{1}}, . ., S^{l}\right\}$, we need a special notation to study collections of more systems. In particular, we will replace the label $l$ with $(l)$ whenever an object is referred to the joint system $S^{(l)}:=\left\{S^{L_{1}}, \ldots, S^{l}\right\}$ instead of to the single system $S^{l}$. For instance, the vector $\mathbf{Y}_{n}^{(l)} \in \mathbb{R}^{K r^{l}}$ indicates $\left(\mathbf{Y}_{n}^{L_{1}}, \ldots, \mathbf{Y}_{n}^{l}\right)^{\prime}$, and $\mathbf{D}_{n}^{(l)}$ indicates the block diagonal $\left(K r^{l} \times K r^{l}\right)$-matrix, whose blocks are made by $\mathbf{D}_{n}^{L_{1}}, . ., \mathbf{D}_{n}^{l}$. Then, from (4) we can express the sampling probabilities in the follower $S^{l}$ as follows:

$$
\tilde{\mathbf{Z}}_{n-1}^{l}=\sum_{i \in\left\{L_{1}, . l^{-}\right\}} \mathbf{W}^{i l} \mathbf{Z}_{n-1}^{i}+\mathbf{W}^{l} \mathbf{Z}_{n-1}^{l} .
$$

Hence, from (11) we obtain

$$
\begin{align*}
\mathbf{Z}_{n}^{l}-\mathbf{Z}_{n-1}^{l} & =-\frac{1}{n} h^{l}\left(\mathbf{Z}_{n-1}^{\left(l^{-}\right)}, \mathbf{Z}_{n-1}^{l}\right)+\frac{1}{n}\left(\Delta \mathbf{M}_{n}^{l}+\mathbf{R}_{n}^{l}\right), \\
h^{l}\left(\mathbf{x}_{1}, \mathbf{x}_{2}\right) & :=-\mathbf{Q}^{l\left(l^{-}\right)} \mathbf{x}_{1}+\left(\mathbf{I}-\mathbf{Q}^{l}\right) \mathbf{x}_{2},  \tag{18}\\
\mathbf{Q}^{l\left(l^{-}\right)} & :=\left[\mathbf{H}^{l} \mathbf{W}^{L_{1} l} \ldots \mathbf{H}^{l} \mathbf{W}^{l^{-} l}\right], \quad \mathbf{Q}^{l}:=\mathbf{H}^{l} \mathbf{W}^{l}
\end{align*}
$$

Since $h^{l}$ is not only a function of $\mathbf{Z}_{n-1}^{l}$, the dynamics in (18) is not already expressed in the SA form (5). To address this issue, we need to consider a joint model for the global system $S^{(l)}=S^{\left(l^{-}\right)} \cup S^{l}=S^{L_{1}} \cup . . \cup S^{l}$ as follows:

$$
\begin{align*}
\mathbf{Z}_{n}^{(l)}-\mathbf{Z}_{n-1}^{(l)} & =-\frac{1}{n} h^{(l)}\left(\mathbf{Z}_{n-1}^{(l)}\right)+\frac{1}{n}\left(\Delta \mathbf{M}_{n}^{(l)}+\mathbf{R}_{n}^{(l)}\right),  \tag{19}\\
h^{(l)}(\mathbf{x}) & :=\left(\mathbf{I}-\mathbf{Q}^{(l)}\right) \mathbf{x},
\end{align*}
$$

where $\mathbf{Q}^{(l)}$ can be recursively defined as follows:

$$
\mathbf{Q}^{(l)}:=\left[\begin{array}{ll}
\mathbf{Q}^{\left(l^{-}\right)} & 0  \tag{20}\\
\mathbf{Q}^{\left(l^{-}\right) l} & \mathbf{Q}^{l}
\end{array}\right], \quad \mathbf{Q}^{\left(L_{n_{L}}\right)}:=\left[\begin{array}{lll}
\mathbf{Q}^{L_{1}} & . . & 0 \\
\ldots & \ldots & \ldots \\
0 & . . & \mathbf{Q}^{L_{n_{L}}}
\end{array}\right]
$$

where by convention $F_{1}^{-}=L_{n_{L}}$.
5.1. Extension of the urn dynamics to $\mathbb{R}^{r^{l} K}$. Since $h^{(l)}$ in (19) is defined in $\mathbb{R}^{r^{l} K}$, while the process $\left\{\mathbf{Z}_{n}^{(l)} ; n \geq 0\right\}$ lies in the subspace $\mathcal{S}^{{ }^{l} K}$, then applying theorems based on the SA directly to (18) may lead to improper results for the process $\mathbf{Z}_{n}^{(l)}$.

For this reason, we replace $h^{(l)}$ in (18) with a suitable function $f_{m}^{(l)}:=h^{(l)}+m g^{(l)}$ such that $m>0$ is an arbitrary constant and $g^{(l)}$ is a function defined as in (13), where in this case $\left\{\mathbf{U}_{i} ; 1 \leq i \leq r^{l}\right\}$ and $\left\{\mathbf{V}_{i} ; 1 \leq i \leq r^{l}\right\}$, indicate, respectively, the left and right eigenvectors of $\mathbf{Q}^{(l)}$. Hence, the dynamics of the process $\mathbf{Z}_{n}^{(l)}$ (18) is replaced by the following:

$$
\begin{align*}
\mathbf{Z}_{n}^{(l)}-\mathbf{Z}_{n-1}^{(l)} & =-\frac{1}{n} f_{m}^{(l)}\left(\mathbf{Z}_{n-1}^{(l)}\right)+\frac{1}{n}\left(\Delta \mathbf{M}_{n}^{(l)}+\mathbf{R}_{n}^{(l)}\right)  \tag{21}\\
f_{m}^{(l)}(\mathbf{x}) & :=\left(\mathbf{I}-\mathbf{Q}^{(l)}\right) \mathbf{x}+m \mathbf{V}_{1}\left(\mathbf{U}_{1}^{\prime} \mathbf{x}-1\right)+m \mathbb{V}_{2} \mathbb{U}_{2}^{\prime} \mathbf{x} .
\end{align*}
$$

Note that in the joint system $S^{(l)}$ the eigenvalue $\lambda=1$ of $\mathbf{Q}^{(l)}$ may not have multiplicity one; in that case, $\mathbf{V}_{1}$ is univocally identified as the right eigenvector of $\mathbf{Q}^{(l)}$ associated to $\lambda=1$ such that, letting $\mathbf{U}_{i}:=\left(U_{i 1} \mathbf{1}_{K}, . ., U_{i r} \mathbf{1}_{K}\right)^{\prime}$ and $U_{i}^{\prime} W^{(l)}=\lambda_{i} U_{i}^{\prime}$ for any $i \in\left\{1, . ., r^{l}\right\}$, we have $\mathbf{U}_{1}^{\prime} \mathbf{V}_{1}=U_{1}^{\prime} \mathbf{1}_{r^{l}}=1$ and $\mathbf{U}_{i}^{\prime} \mathbf{V}_{1}=U_{i}^{\prime} \mathbf{1}_{r^{l}}=0$ when $i \neq 1$.
5.2. Removal of unnecessary components. The following system $S^{l}$ may not depend on all the components of $S^{\left(l^{-}\right)}$and hence the convergence in $S^{l}$ may be faster than the rate in $S^{\left(l^{-}\right)}$. When this occurs, the asymptotic distribution obtained for the urn proportions in $S^{(l)}$ restricted to the urns in $S^{l}$ is degenerate. To address this issue and characterize the asymptotic behavior in the following system $S^{l}$, we need to reduce the dimensionality of $\mathbf{Z}_{n}^{(l)}$ by deleting those components which do not influence the dynamics of $\mathbf{Z}_{n}^{l}$. Since the interaction between $S^{l}$ and the systems in $S^{\left(l^{-}\right)}$is expressed by $\mathbf{Q}^{(1) 1^{-}}$, we exclude the components of $\mathbf{Z}_{n}^{\left(l^{-}\right)}$defined on the Kernel of $\mathbf{Q}^{\left(l^{-}\right) l}$. Formally, consider the following decomposition:

$$
S p\left(\mathbf{Q}^{(\mathbf{1})}\right)=S p\left(\mathbf{Q}^{\mathbf{1}}\right) \cup S p\left(\mathbf{Q}^{\left(1^{-}\right)}\right)=\mathcal{A}_{I N} \cup \mathcal{A}_{O U T},
$$

where

$$
\begin{aligned}
\mathcal{A}_{\text {OUT }} & :=\left\{\lambda \in S p\left(\mathbf{Q}^{\left(1^{-}\right)}\right): \exists v\left\{\mathbf{Q}^{\left(1^{-}\right)} v=\lambda v\right\} \cap\left\{\mathbf{Q}^{\left(1^{-}\right) \mathbf{1}} v=0\right\}\right\} \\
\mathcal{A}_{I N} & :=S p\left(\mathbf{Q}^{1}\right) \cup\left(S p\left(\mathbf{Q}^{\left(1^{-}\right)}\right) \backslash \mathcal{A}_{\text {OUT }}\right) .
\end{aligned}
$$

Then, the eigenspace of $\mathbf{Q}^{(1)}$ associated to $\lambda \in \mathcal{A}_{\text {OUT }}$ will be removed from the dynamics in (21). To do this, let us denote by:
(1) $\mathbf{U}_{I N}$ and $\mathbf{V}_{I N}$ the matrices whose columns are the left and right eigenvectors of $\mathbf{Q}^{(1)}$, respectively, associated to eigenvalues in $\mathcal{A}_{I N}$;
(2) $\mathbf{U}_{\text {OUT }}$ and $\mathbf{V}_{\text {OUT }}$ the matrices whose columns are the left and right eigenvectors of $\mathbf{Q}^{(1)}$, respectively, associated to eigenvalues in $\mathcal{A}_{\text {OUT }}$;
Since we do not want to modify the process $\mathbf{Z}_{n}^{(l)}$ on $S^{l}$, i.e. $\mathbf{Z}_{n}^{l}$, we now construct two conjugate basis in $\operatorname{Im}\left(\mathbf{U}_{I N}\right)$ and $\operatorname{Im}\left(\mathbf{V}_{I N}\right)$ that are invariant on $S^{l}$. Note that, since $S p\left(\mathbf{Q}^{\mathbf{1}}\right) \subset \mathcal{A}_{I N}$, there exists a non-singular matrix $\mathbf{P}$ such that the following decompositions hold:

$$
\mathbf{B}:=\mathbf{V}_{I N} \mathbf{P}=\left[\begin{array}{cc}
\hat{\mathbf{B}} & 0 \\
0 & \mathbf{I},
\end{array}\right], \quad \mathbf{C}:=\mathbf{P}^{-1} \mathbf{U}_{I N}^{\prime}=\left[\begin{array}{cc}
\hat{\mathbf{C}} & 0 \\
0 & \mathbf{I}
\end{array}\right]
$$

Since $\hat{\mathbf{C}}^{\prime} \hat{\mathbf{B}}=\mathbf{I}$ and $\hat{\mathbf{B}} \hat{\mathbf{C}}^{\prime}=\mathbf{V}_{\mathbf{I N}} \mathbf{U}_{\mathbf{I N}}{ }^{\prime}, \hat{\mathbf{C}}$ and $\hat{\mathbf{B}}$ represent conjugate basis in $\mathcal{I} m\left(\mathbf{U}_{I N}\right)$ and $\operatorname{Im}\left(\mathbf{V}_{I N}\right)$, respectively. Thus, for any $\mathbf{x}=\left(\mathbf{x}^{\left(l^{-}\right)}, \mathbf{x}^{l}\right)^{\prime} \in \mathbb{R}^{K r^{l}}$, we have the following decomposition

$$
\begin{equation*}
\mathrm{x}=\mathrm{V}_{\mathrm{IN}} \mathrm{U}_{\mathbf{I N}}{ }^{\prime} \mathrm{x}+\mathbf{V}_{\text {OUT }} \mathrm{U}_{\text {OUT }}{ }^{\prime} \mathbf{x}=\hat{\mathbf{B}} \hat{\mathbf{x}}+\mathbf{V}_{\text {OUT }} \mathrm{x}_{\text {OUT }} \tag{22}
\end{equation*}
$$

where

$$
\hat{\mathbf{x}}:=\hat{\mathbf{C}}^{\prime} \mathbf{x}=\left[\begin{array}{l}
\mathbf{C}^{\prime} \mathbf{x}^{\left(l^{-}\right)} \\
\mathbf{x}^{l}
\end{array}\right], \quad \mathrm{x}_{\text {OUT }}:=\mathbf{U}_{\text {OUT }}{ }^{\prime} \mathbf{x} .
$$

In particular, we consider the process $\left\{\hat{\mathbf{Z}}_{n}^{(l)}, n \geq 1\right\}$ defined as follows:

$$
\hat{\mathbf{Z}}_{n}^{(l)}:=\hat{\mathbf{C}}^{\prime} \mathbf{Z}_{n}^{(l)}=\left[\begin{array}{l}
\mathbf{C}^{\prime} \mathbf{Z}_{n}^{\left(l^{-}\right)}  \tag{23}\\
\mathbf{Z}_{n}^{l}
\end{array}\right]
$$

now, multiplying by $\hat{\mathbf{C}}^{\prime}$ to (21) and applying the decomposition (22) in (21), since $\hat{\mathbf{C}}^{\prime} \mathbb{V}_{2} \mathbb{U}_{2}^{\prime} \mathbf{V}_{\text {OUT }}=$ $0, \mathbf{U}_{1}^{\prime} \mathbf{V}_{\text {OUT }}=0$ and $\hat{\mathbf{C}}^{\prime} \mathbf{V}_{\text {OUT }}=0$, we have that

$$
\begin{align*}
\hat{\mathbf{Z}}_{n}^{(l)}-\hat{\mathbf{Z}}_{n-1}^{(l)} & =-\frac{1}{n} \hat{f}_{m}^{(l)}\left(\hat{\mathbf{Z}}_{n-1}^{(l)}\right)+\frac{1}{n} \hat{\mathbf{C}}^{\prime}\left(\Delta \mathbf{M}_{n}^{(l)}+\mathbf{R}_{n}^{(l)}\right),  \tag{24}\\
\hat{f}_{m}^{(l)}(\hat{\mathbf{x}}) & :=\left(\mathbf{I}-\hat{\mathbf{C}}^{\prime} \mathbf{Q}^{(l)} \hat{\mathbf{B}}\right) \hat{\mathbf{x}}+m \hat{\mathbf{V}}_{1}\left(\hat{\mathbf{U}}_{1}^{\prime} \hat{\mathbf{x}}-1\right)+m \hat{\mathbb{V}}_{2} \hat{\mathbb{U}}_{2}^{\prime} \hat{\mathbf{x}}
\end{align*}
$$

where $\hat{\mathbf{U}}_{1}^{\prime}:=\mathbf{U}_{1}^{\prime} \hat{\mathbf{B}}, \hat{U}_{2}:=\mathbb{U}_{2}^{\prime} \hat{\mathbf{B}}, \hat{\mathbf{V}}_{1}:=\hat{\mathbf{C}}^{\prime} \mathbf{V}_{1}$ and $\hat{\mathbb{V}}_{2}:=\hat{\mathbf{C}}^{\prime} \mathbb{V}_{2}$ represent the left and right eigenvectors of $\hat{\mathbf{C}}^{\prime} \mathbf{Q}^{(l)} \hat{\mathbf{B}}$ associated to $\lambda \in S p\left(W^{(l)}\right) \backslash \mathcal{A}_{\text {OUT }}$. Since $\hat{f}_{m}^{(l)}$ is a function of $\hat{\mathbf{Z}}_{n}^{(l)}$, the dynamics in (24) is now expressed in the SA form (5).

Remark 5.1. It is worth highlighting that the interacting matrix $W$ lonely is not enough to individuate the components of the system that actually influence a following system, but it is necessary to study the eigen-structure of $\mathbf{Q}^{(l)}$, that joins the information of $W$ and of the generating matrices $\left\{H^{j}, 1 \leq j \leq r^{l}\right\}$ of the urns in $S^{(l)}$. This may be surprising since $W$ is the only element that defines the interaction among the urns in the system. Nevertheless, when $H^{j}$ is singular, different values of $\tilde{Z}_{n}^{j}$ may give the same average replacements, $H^{j} \tilde{Z}_{n}^{j}$, which is equivalent as having singularities in $W$, where different values of $\left\{Z_{n}^{i} ; 1 \leq i \leq r^{l}\right\}$ may give the same $\tilde{Z}_{k, n}^{j}$, and hence same $H^{j} \tilde{Z}_{n}^{j}$. For instance, if all the columns of $H^{j}$ were equal to a given vector $v^{j}$, the urn $j$ would be updated on average by $v^{j}$ regardless the value of $\tilde{Z}_{n-1}^{j}$ and hence the urns in $S^{\left(l^{-}\right)}$would not play any role in the dynamics of the urn $j$ for any choice of $W$. The eigen-structure of $\mathbf{Q}^{(l)}$ perfectly
explains this behavior, since in this case the matrix $\mathbf{Q}^{\left(l^{-}\right) l}$ would be composed by all zeros and hence $S p\left(\mathbf{Q}^{\left(l^{-}\right)}\right) \equiv A_{\text {OUT }}$ and $S p\left(\mathbf{Q}^{l}\right) \equiv A_{\text {IN }}$.
5.3. First-order asymptotic results. We now present the convergence result concerning the limiting proportion of the urns in the following systems. The asymptotic behavior of $\mathbf{Z}_{n}^{(l)}$ is obtained recursively from $\mathbf{Z}_{\infty}^{\left(l^{-}\right)}:=a . s .-\lim _{n \rightarrow \infty} \mathbf{Z}_{n}^{(l-)}$.
Theorem 5.1. Assume (A1), (A2) and (A3). Thus, for any $l \in \mathcal{L}_{F}$, we have that

$$
\hat{\mathbf{Z}}_{n}^{(l)} \xrightarrow{\text { a.s. }} \hat{\mathbf{Z}}_{\infty}^{(l)}:=\hat{\mathbf{V}}_{1} ;
$$

hence, from (23), in the following system $S^{l}$ we have that

$$
\mathbf{Z}_{n}^{l} \xrightarrow{\text { a.s. }} \mathbf{Z}_{\infty}^{l}:=\left(\mathbf{I}-\mathbf{Q}^{l}\right)^{-1} \mathbf{Q}^{\left(l^{-}\right) l} \mathbf{Z}_{\infty}^{\left(l^{-}\right)} .
$$

5.4. Second-order asymptotic results. We now present the results concerning the rate of convergence and the asymptotic distribution of the urn proportions in the following systems. To this end, let us introduce the $K s^{l} \times K s^{l}$-matrix of the first-order derivative of $\hat{f}_{m}^{l}$ :

$$
\begin{align*}
\hat{\mathbf{F}}_{m}^{(l)} & :=\hat{\mathbf{C}}^{\prime} \mathbf{F}_{m}^{(l)} \hat{\mathbf{B}} \\
& =\left(\mathbf{I}-\hat{\mathbf{C}}^{\prime} \mathbf{Q}^{(l)} \hat{\mathbf{B}}\right)+m \hat{\mathbf{V}}_{1} \hat{\mathbf{U}}_{1}^{\prime}+m \hat{\mathbb{V}}_{2} \hat{\mathbb{U}}_{2}^{\prime} . \tag{25}
\end{align*}
$$

Moreover, the asymptotic variance will be based on the quantity $\hat{\mathbf{G}}^{(l)}:=\hat{\mathbf{C}}^{\prime} \mathbf{G}^{(l)} \hat{\mathbf{B}}$, where $\mathbf{G}^{(l)}$ is the block diagonal matrix made by $G^{1}, . ., G^{r^{l}}$ (see (17)).

The following theorem shows the rate of convergence and the limiting distribution of the urn proportions in the following systems.
Theorem 5.2. Assume (A1), ( $\left.A^{\prime} 2\right)$ and (A3). For any following system $S^{l}, l \in \mathcal{L}_{F}$, let $\lambda^{* l}$ be the maximum eigenvalue in $S p\left(\mathbf{Q}^{(l)}\right) \backslash\left(S p\left(W^{(l)}\right) \cup \mathcal{A}_{\text {OUT }}\right)$. Thus, we have that $\lambda^{* l} \equiv 1-\min S p\left(\hat{\mathbf{F}}_{m}^{(l)}\right)$ and
(a) if $\lambda^{* l}<1 / 2$, then

$$
\sqrt{n}\left(\hat{\mathbf{Z}}_{n}^{(l)}-\hat{\mathbf{Z}}_{\infty}^{(l)}\right) \xrightarrow{d} \mathcal{N}\left(0, \hat{\Sigma}^{(l)}\right), \quad \hat{\Sigma}^{(l)}:=\lim _{m \rightarrow \infty} \int_{0}^{\infty} e^{u\left(\frac{\mathbf{I}}{2}-\hat{\mathbf{F}}_{m}^{(l)}\right)} \hat{\mathbf{G}}^{(l)} e^{u\left(\frac{\mathbf{I}}{2}-\hat{\mathbf{F}}_{m}^{(l)}\right)^{\prime}} d u .
$$

(b) if $\lambda^{* l}=1 / 2$, then

$$
\sqrt{\frac{n}{\log (n)}}\left(\hat{\mathbf{Z}}_{n}^{(l)}-\hat{\mathbf{Z}}_{\infty}^{(l)}\right) \xrightarrow{d} \mathcal{N}\left(0, \Sigma^{(l)}\right) .
$$

(c) if $\lambda^{* l}>1 / 2$, then there exists a finite random variable $\psi^{(l)}$ such that

$$
n^{1-\lambda^{*} l}\left(\hat{\mathbf{Z}}_{n}^{(l)}-\hat{\mathbf{Z}}_{\infty}^{(l)}\right) \xrightarrow{\text { a.s. }} \psi^{(l)} .
$$

Remark 5.2. It is worth noticing that, since from (23) $\hat{\mathbf{Z}}_{n}^{(l)}=\left(\mathbf{C}^{\prime} \mathbf{Z}_{n}^{\left(l^{-}\right)}, \mathbf{Z}_{n}^{l}\right)^{\prime}$, Theorem 5.2 explicitly states the limiting distribution and the asymptotic covariance structure of the urn proportions in any following system $\mathbf{Z}_{n}^{l}, l \in \mathcal{L}_{F}$. In addition, Theorem 5. ${ }^{2}$ also determines the correlation between $\mathbf{Z}_{n}^{l}$ and the components of the urn proportions in the other systems $S^{l}, l \in\left\{L_{1}, . ., l^{-}\right\}$, that actually influence the dynamics of $\mathbf{Z}_{n}^{l}$.
Remark 5.3. We highlight that condition (A3), i.e. irreducibility of the generating matrices $H^{j}$, may be relaxed in Theorems 5.1 and 5.2, by requiring (A3) only for the urns in the leading systems. In fact, we can note from the proof that (A3) is not needed for the urns that belong to the following systems.

## 6. Further extensions

In this section, we discuss some possible extensions of the interacting urn model presented in this paper.
6.1. Random and time-dependent interacting matrix. Although we consider a constant interacting matrix $W$, the results of this paper may be extended to a system characterized by a random sequence of interacting matrices $\left\{W_{n} ; n \geq 0\right\}$, i.e. $W_{n}=\left[w_{j h, n}\right] \in \mathcal{F}_{n}$ and $Z_{k, n}^{j}=$ $\sum_{h=1}^{N} w_{j h, n} Z_{k, n}^{h}$ for any $k \in\{1, . ., K\}$. In that case, it is essential to assume the existence of a deterministic matrix $W$ such that $W_{n} \xrightarrow{\text { a.s. }} W$, which individuates the leading and the following systems, as in Subsection 2.4.

The dynamics with random and time-dependent interacting matrices could be also expressed in the SA form (5), by including the difference $\left(W_{n}-W\right)$ in the remainder term (10). Naturally, the asymptotic behavior of the urn proportions would depend on the limiting interacting matrix $W$ and on the rate of convergence of the sequence $\left\{W_{n} ; n \geq 0\right\}$. Specifically, the convergence of the urn proportions could be obtained with the only assumption $W_{n} \xrightarrow{\text { a.s. }} W$, while extensions for the second-order results presented in would require $n \mathbf{E}\left[\left\|W_{n}-W\right\|^{2}\right] \rightarrow 0$.
6.2. Non-homogeneous generating matrices. The independence and identically distribution of the replacement matrices is an assumption that could be relaxed by assuming that the sequence of generating matrices $\left\{H_{n}^{j} ; n \geq 0\right\}, H_{n-1}^{j}:=\mathbf{E}\left[D_{n}^{j} \mid \mathcal{F}_{n-1}\right]$, converges to some deterministic matrix $H^{j}$. Thus, the urn dynamics could be expressed in the SA form (5), by including the difference $\left(H_{n}^{j}-H^{j}\right)$ in the remainder term (10), and the asymptotic behavior would depend on $H^{j}$ and on the rate of convergence of $H_{n}^{j}$. Specifically, the second-order results would require an additional assumption as $n \mathbf{E}\left[\left\|H_{n}^{j}-H^{j}\right\|^{2}\right] \rightarrow 0$.

## 7. Proofs

The proof of Theorem 2.1 requires the following auxiliary result on the martingale convergence:
Lemma 7.1. Let $\left\{S_{n} ; n \geq 1\right\}, S_{n}:=\sum_{i=1}^{n} \Delta S_{i}$, be a zero-mean martingale with respect to $a$ filtration $\left\{\mathcal{F}_{n} ; n \geq 1\right\}$ and let $\left\{b_{n} ; n \geq 1\right\}$ be a non-decreasing sequence of positive numbers such that

$$
\begin{equation*}
\sum_{i=1}^{\infty} b_{i}^{-2} \mathbf{E}\left[\left(\Delta S_{i}\right)^{2} \mid \mathcal{F}_{i-1}\right]<\infty, \quad \text { a.s. } \tag{26}
\end{equation*}
$$

Then, $b_{n}^{-1} S_{n} \xrightarrow{\text { a.s. }} 0$.
Proof. Let us define the zero-mean martingale $\tilde{S}_{n}:=\sum_{i=1}^{n} b_{i}^{-1} \Delta S_{i}$, where by (26) we have that $\tilde{S}_{n}$ converges a.s. Thus, the result follows by using Kronacker's Lemma (see Lemma IV.3.2 in [32]).

Proof of Theorem [2.1. By using Lemma 7.1 with $b_{n}:=n^{1-\alpha}$ and $S_{n}:=T_{n}^{j}-n$, the proof follows by showing that $T_{n}^{j}-n$ is a martingale whose increments have bounded second moments. Now, since

$$
T_{n}^{j}-T_{n-1}^{j}=\sum_{k=1}^{K}\left(Y_{k, n}^{j}-Y_{k, n-1}^{j}\right)=\sum_{k=1}^{K} \sum_{i=1}^{K}\left(D_{k i, n}^{j} X_{i, n}^{j}\right)
$$

the result follows by establishing that
(a) $\sup _{n \geq 1} \mathbf{E}\left[\left(\sum_{k=1}^{K} \sum_{i=1}^{K} D_{k i, n}^{j} X_{i, n}^{j}\right)^{2} \mid \mathcal{F}_{n-1}\right]<\infty ;$
(b) $\sum_{k=1}^{K} \sum_{i=1}^{K} \mathbf{E}\left[D_{k i, n}^{j} X_{i, n}^{j} \mid \mathcal{F}_{n-1}\right]=1$.

For part (a), by using $\left|X_{i, n}^{j}\right| \leq 1$ and (A1), we have that

$$
\sup _{n \geq 1} \mathbf{E}\left[\left(\sum_{k=1}^{K} \sum_{i=1}^{K}\left(D_{n, k i}^{j} X_{i, n}^{j}\right)\right)^{2} \mid \mathcal{F}_{n-1}\right] \leq K^{2} \sup _{n \geq 1} \max _{j \in\{1, ., N\}} \max _{i, k \in\{1, \ldots, K\}} \mathbf{E}\left[\left(D_{k i, n}^{j}\right)^{2}\right]<\infty
$$

For part (b), since $\sum_{k=1}^{K} H_{k i}^{j}=1$ by (A2) and since $D_{k i, n}^{j}$ and $X_{i, n}^{j}$ are independent conditionally on $\mathcal{F}_{n-1}$, we obtain

$$
\sum_{k=1}^{K} \sum_{i=1}^{K} \mathbf{E}\left[D_{k i, n}^{j} X_{i, n}^{j} \mid \mathcal{F}_{n-1}\right]=\sum_{k=1}^{K} \sum_{i=1}^{K} H_{k i}^{j} \tilde{Z}_{i, n-1}^{j}=\sum_{i=1}^{K} \tilde{Z}_{i, n-1}^{j} \sum_{k=1}^{K} H_{k i}^{j}=\sum_{i=1}^{K} \tilde{Z}_{i, n-1}^{j}
$$

Finally, by the definition of $\tilde{Z}_{i, n-1}^{j}$ in (1), we have

$$
\sum_{i=1}^{K} \tilde{Z}_{i, n-1}^{j}=\sum_{i=1}^{K} \sum_{h=1}^{N} w_{j h} Z_{i, n-1}^{h}=\sum_{h=1}^{N} w_{j h} \sum_{i=1}^{K} Z_{i, n-1}^{h}=\sum_{h=1}^{N} w_{j h}=1
$$

which concludes the proof of (3) for $\alpha<1 / 2$ under assumption (A2).
Concerning the proof of (3) for $\alpha<1$, first note that under assumption (A'2) we have

$$
T_{n}^{j}-T_{n-1}^{j}=\sum_{k=1}^{K} \sum_{i=1}^{K}\left(D_{n, k i}^{j} X_{i, n}^{j}\right)=\sum_{i=1}^{K} X_{i, n}^{j}=1
$$

hence, $T_{n}^{j}=T_{0}^{j}+n$ a.s. and, for any $\alpha<1$,

$$
n^{\alpha}\left(\frac{T_{n}^{j}}{n}-1\right)=\frac{T_{0}^{j}}{n^{1-\alpha}} \xrightarrow{\text { a.s. } / L^{2}} 0 .
$$

### 7.1. Proofs on the leading systems.

Proof of Theorem 4.1. Fix $l \in \mathcal{L}_{L}$ and consider the leading system $S^{l}=\left\{r^{l^{-}}+1 \leq j \leq r^{l}\right\}$ with interacting matrix $W^{l}$. Since the dynamic of the urn proportions $\mathbf{Z}_{n}^{l}$ in $S^{l}$ has been expressed in (14) in the SA form (5), we can establish the convergence result stated in Theorem4.1by applying Theorem A. 1 in Appendix. To this end, we will show that the assumptions of Theorem A. 1 are satisfied by the process $\left\{\mathbf{Z}_{n}^{l} ; n \geq 1\right\}$ of the system $S^{l}$ :
(1) the function $f_{m}^{l}$ defined in (14) is a linear transformation and hence locally Lipschitz.
(2) from (8), we have that $\sup _{n \geq 1} \mathbf{E}\left[\left\|\Delta \mathbf{M}_{n}^{l}\right\|^{2} \mid \mathcal{F}_{n-1}\right]<\infty$ is satisfied by establishing
(2a) $\sup _{n \geq 1} \mathbf{E}\left[\left\|\mathbf{D}_{n}^{l} \mathbf{X}_{n}^{l}\right\|^{2} \mid \mathcal{F}_{n-1}\right]<\infty$;
(2b) $\sup _{n \geq 1} \mathbf{E}\left[\left\|\operatorname{diag}\left(\mathbf{T}_{n}^{l}-\mathbf{T}_{n-1}^{l}\right) \mathbf{Z}_{n-1}^{l}\right\|^{2} \mid \mathcal{F}_{n-1}\right]<\infty$.
Concerning (2a), since $X_{k, n}^{j} \in\{0,1\}$ a.s., we have that

$$
\left\|\mathbf{D}_{n}^{l} \mathbf{X}_{n}^{l}\right\|^{2} \leq \sum_{j \in S^{l}} \sum_{k=1}^{K} \sum_{i=1}^{K}\left(D_{k i, n}^{j}\right)^{2}, \text { a.s. }
$$

Thus, (2a) follows by assumption (A1), since

$$
\sup _{n \geq 1} \mathbf{E}\left[\left\|\mathbf{D}_{n}^{l} \mathbf{X}_{n}^{l}\right\|^{2} \mid \mathcal{F}_{n-1}\right] \leq \sum_{j \in S^{l}} \sum_{k=1}^{K} \sum_{i=1}^{K} \sup _{n \geq 1} \mathbf{E}\left[\left(D_{k i, n}^{j}\right)^{2}\right] \leq s^{l} K^{2} C_{\delta}
$$

Concerning (2b), since $\sum_{k=1}^{K}\left(Z_{k, n}^{j}\right)^{2} \leq 1$, we have

$$
\begin{equation*}
\left\|\operatorname{diag}\left(\mathbf{T}_{n}^{l}-\mathbf{T}_{n-1}^{l}\right) \mathbf{Z}_{n-1}^{l}\right\|^{2} \leq \sum_{j \in S^{l}}\left(T_{n}^{j}-T_{n-1}^{j}\right)^{2}, \quad \text { a.s. } \tag{27}
\end{equation*}
$$

where we recall that

$$
T_{n}^{j}-T_{n-1}^{j}=\sum_{k=1}^{K}\left(Y_{k, n}^{j}-Y_{k, n-1}^{j}\right)=\sum_{k=1}^{K} \sum_{i=1}^{K}\left(D_{k i, n}^{j} X_{i, n}^{j}\right) .
$$

Hence, combining (27) and (28), since $X_{i, n}^{j} \in\{0,1\}$ and $\sum_{i=1}^{K} X_{i, n}^{j}=1$ a.s., we obtain that

$$
\begin{aligned}
\left\|\operatorname{diag}\left(\mathbf{T}_{n}^{l}-\mathbf{T}_{n-1}^{l}\right) \mathbf{Z}_{n-1}^{l}\right\|^{2} & \leq \sum_{j \in S^{l}}\left(\sum_{k=1}^{K} \sum_{i=1}^{K}\left(D_{k i, n}^{j} X_{i, n}^{j}\right)\right)^{2} \\
& \leq \sum_{j \in S^{l}} \sum_{i=1}^{K}\left(\sum_{k=1}^{K} D_{k i, n}^{j}\right)^{2}, \text { a.s. }
\end{aligned}
$$

Finally, using the relation ( $\sum_{k=1}^{K} a_{k}^{2} \leq K^{2} \sum_{k=1}^{K} a_{k}^{2}$, (2b) follows by assumption (A1), since

$$
\sup _{n \geq 1} \mathbf{E}\left[\left\|\operatorname{diag}\left(\mathbf{T}_{n}^{l}-\mathbf{T}_{n-1}^{l}\right) \mathbf{Z}_{n-1}^{l}\right\|^{2} \mid \mathcal{F}_{n-1}\right] \leq \sup _{n \geq 1} \sum_{j \in S^{l}} \sum_{i=1}^{K} K^{2} \sum_{k=1}^{K} \mathbf{E}\left[\left(D_{k i, n}^{j}\right)^{2}\right] \leq s^{l} K^{4} C_{\delta} .
$$

(3) from (10), we show $\left\|\mathbf{R}_{n}^{l}\right\| \xrightarrow{\text { a.s. }} 0$ by establishing that, for any $(2+\delta)^{-1}<\alpha<2^{-1}$,
(3a) $n^{\alpha}\left\|n \cdot \operatorname{diag}\left(\mathbf{T}_{n}^{l}\right)^{-1}-\mathbf{I}\right\| \xrightarrow{\text { a.s. }} 0$,
(3b) $n^{-\alpha}\left\|\mathbf{Z}_{n-1}^{l}-\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}\right\| \xrightarrow{\text { a.s. }} 0$,
(3c) $n^{-\alpha}\left\|\Delta \mathbf{M}_{n}^{l}\right\| \xrightarrow{\text { a.s. }} 0$,
where we recall that $\delta>0$ is defined in assumption (A1) (see Subsection 2.2). Since (3a)
follows straightforwardly by Theorem [2.1, consider (3b). For any $\epsilon>0$, using Markov's inequality we obtain

$$
\mathbf{P}\left(\left\|\mathbf{Z}_{n-1}^{l}-\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}\right\|>\epsilon n^{\alpha}\right) \leq\left(\epsilon n^{\alpha}\right)^{-(2+\delta)} \mathbf{E}\left[\left\|\mathbf{Z}_{n-1}^{l}-\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}\right\|^{(2+\delta)}\right]
$$

Hence, (3b) follows by Borel-Cantelli Lemma since $\alpha \cdot(2+\delta)>1$ and

$$
\sup _{n \geq 0} \mathbf{E}\left[\left\|\mathbf{Z}_{n-1}^{l}-\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}\right\|^{(2+\delta)}\right] \leq \sum_{j \in S^{l}} 2^{(2+\delta)}<\infty .
$$

Concerning (3c), we can apply again Markov's inequality and the same arguments of part (3b) since by assumption (A1) we have that

$$
\sup _{n \geq 0} \mathbf{E}\left[\left\|\mathbf{D}_{n}^{l} \mathbf{X}_{n}^{l}-\mathbf{H}^{l} \tilde{\mathbf{Z}}_{n-1}^{l}\right\|^{(2+\delta)}\right] \leq \sup _{n \geq 0} \sum_{j \in S^{l}} \sum_{k=1}^{K} \sum_{i=1}^{K} \mathbf{E}\left[\left(D_{k i, n}^{l}\right)^{(2+\delta)}\right]<\infty
$$

Thus, by applying Theorem A.1 to the dynamics in (14), we have that the limiting values of $\mathbf{Z}_{n}^{l}$ are included in the set

$$
\left\{\mathbf{x} \in \mathbb{R}^{K s_{l}}: f_{m}^{l}(\mathbf{x})=0\right\}
$$

Now, denote by $\mathbb{V}_{3}$ and $\mathbb{U}_{3}$ the matrices whose columns are, respectively, the right and left eigenvectors of $\mathbf{Q}^{l}$ associated to the eigenvalues $\lambda \in S p\left(\mathbf{Q}^{l}\right) \backslash S p\left(W^{l}\right)$. Hence, we have the following decomposition

$$
\begin{equation*}
\mathbf{Q}^{l}=\mathbf{V}_{1} \mathbf{U}_{1}^{\prime}+\mathbb{V}_{2} \mathbf{J}_{2} \mathbb{U}_{2}^{\prime}+\mathbb{V}_{3} \mathbf{J}_{3} \mathbb{U}_{3}^{\prime} \tag{29}
\end{equation*}
$$

where $\mathbf{J}_{2}$ and $\mathbf{J}_{3}$ represent the corresponding jordan blocks. Since the eigenvectors of $\mathbf{Q}^{l}$ represent a basis of $\mathbb{R}^{K s_{l}}$, for any $\mathbf{x} \in \mathbb{R}^{K s_{l}}$ there exists $a \in \mathbb{R}, b \in \mathbb{R}^{s^{l}-1}$ and $c \in \mathbb{R}^{s^{l}(K-1)}$ such that

$$
\begin{equation*}
\mathbf{x}=\mathbf{V}_{1} a+\mathbb{V}_{2} b+\mathbb{V}_{3} c \tag{30}
\end{equation*}
$$

Hence, by using (29) and (30), we obtain

$$
\begin{aligned}
h^{l}(\mathbf{x}) & =\mathbb{V}_{2}\left(\mathbf{I}-\mathbf{J}_{2}\right) b+\mathbb{V}_{3}\left(\mathbf{I}-\mathbf{J}_{3}\right) c \\
g^{l}(\mathbf{x}) & =\mathbf{V}_{1}(a-1)+\mathbb{V}_{2} b
\end{aligned}
$$

which, since $f_{m}^{l}(\mathbf{x})=h^{l}(\mathbf{x})+m g^{l}(\mathbf{x})$, it gives us

$$
\begin{equation*}
f_{m}^{l}(\mathbf{x})=m \mathbf{V}_{1}(a-1)+\mathbb{V}_{2}\left((1+m) \mathbf{I}-\mathbf{J}_{2}\right) b+\mathbb{V}_{3}\left(\mathbf{I}-\mathbf{J}_{3}\right) c \tag{31}
\end{equation*}
$$

From the irreducibility of $H^{j}$ assumed in (A3), for all $\lambda \in S p\left(\mathbf{Q}^{l}\right) \backslash S p\left(W^{l}\right)$ we have $\lambda<1$ and hence $\left(\mathbf{I}-\mathbf{J}_{3}\right)$ is positive definite. Therefore, since $m>0$, from (31) we have that $f_{m}^{l}(\mathbf{x})=0$ if and only if $a=1$ and $b=c=0$, i.e. $\mathbf{x}=\mathbf{V}_{1}$.

It just remains to prove that $\mathbf{V}_{1}$ is a global attractor in $\mathbb{R}^{K s_{l}}$. To this end, we will show that $\mathcal{D} f_{m}^{l}(\mathbf{x})$ is positive definite for any $\mathbf{x} \in \mathbb{R}^{K s_{l}}$. We recall that, from (16) we have

$$
\begin{equation*}
\mathbf{F}_{m}^{l}=\mathcal{D} f_{m}^{l}(\mathbf{x})=m \mathbf{V}_{1} \mathbf{U}_{1}^{\prime}+\mathbb{V}_{2}\left((1+m) \mathbf{I}-\mathbf{J}_{2}\right) \mathbb{U}_{2}^{\prime}+\mathbb{V}_{3}\left(\mathbf{I}-\mathbf{J}_{3}\right) \mathbb{U}_{3}^{\prime} \tag{32}
\end{equation*}
$$

Hence, since $m>0$ and $\left(\mathbf{I}-\mathbf{J}_{3}\right)$ is positive definite by assumption (A3), we have that $\mathbf{F}_{m}^{l}$ is positive definite for any $m>0$. This concludes the proof.

Proof of Theorem 4.2. The proof consists in showing that the assumptions of the CLT for processes in the $S A$ form (Theorem A.2 in Appendix) are satisfied by the dynamics in (21) of the urn proportions $\mathbf{Z}_{n}^{l}$ in the leading system $S^{l}$.

First, we show that condition $\left\{S p\left(D f\left(\theta^{*}\right)\right)>1 / 2\right\}$ in Theorem A.2 is equivalent to $\left\{\lambda^{* l}<1 / 2\right\}$. Note that the function $f$ of the SA form (5) is represented in our case by $f_{m}^{l}$ defined in (14). Similarly, the term $\theta^{*}$ in Appendix indicates the deterministic limiting proportion $\mathbf{Z}_{\infty}^{l}$, while $D h\left(\theta^{*}\right)$ is represented by $\mathbf{F}_{m}^{l}$ defined in (16).

Now, consider the eigen-structure of $\mathbf{Q}^{l}$ and note that $\mathbf{F}_{m}^{l}$ has been expressed in (32) as follows:

$$
\mathbf{F}_{m}^{l}=m \mathbf{V}_{1} \mathbf{U}_{1}^{\prime}+\mathbb{V}_{2}\left((1+m) \mathbf{I}-\mathbf{J}_{2}\right) \mathbb{U}_{2}^{\prime}+\mathbb{V}_{3}\left(\mathbf{I}-\mathbf{J}_{3}\right) \mathbb{U}_{3}^{\prime}
$$

Hence, it is easy to see that the eigenvectors of $\mathbf{F}_{m}^{l}$ and $\mathbf{Q}^{l}$ are the same, since
(1) $\mathbf{F}_{m}^{l} \mathbf{V}_{1}=m \mathbf{V}_{1}$,
(2) $\mathbf{F}_{m}^{l} \mathbb{V}_{2}=\mathbb{V}_{2}\left((1+m) \mathbf{I}-\mathbf{J}_{2}\right)$,
(3) $\mathbf{F}_{m}^{l} \mathbb{V}_{3}=\mathbb{V}_{3}\left(\mathbf{I}-\mathbf{J}_{3}\right)$,
and hence

$$
S p\left(\mathbf{F}_{m}^{l}\right)=\{m\} \cup\left\{(1+m)-\lambda, \lambda \in S p\left(W^{l}\right) \backslash\{1\}\right\} \cup\left\{1-\lambda, \lambda \in \operatorname{Sp}\left(\mathbf{Q}^{l}\right) \backslash S p\left(W^{l}\right)\right\},
$$

which, setting $m>0$ arbitrary large, implies that $\left\{\operatorname{Sp}\left(\mathcal{D} f\left(\theta^{*}\right)\right)>1 / 2\right\} \equiv\left\{\lambda^{* l}<1 / 2\right\}$.
Then, by following analogous arguments of point (2) in the proof of Theorem 4.1, assumption (A1) implies that condition (36) is satisfied, since

$$
\sup _{n \geq 1} \mathbf{E}\left[\left\|\Delta \mathbf{M}_{n}^{l}\right\|^{2+\delta} \mid \mathcal{F}_{n-1}\right] \leq K^{2+\delta} \sum_{j=1}^{N} \sum_{i=1}^{K} \sum_{k=1}^{K} \sup _{n \geq 1} \mathbf{E}\left[\left(D_{i k, n}^{j}\right)^{2+\delta}\right] \leq N K^{4+\delta} C_{\delta} ;
$$

moreover, concerning condition (37), we will show that for any $l \in \mathcal{L}_{L}$

$$
\mathbf{E}\left[\Delta \mathbf{M}_{n}^{l}\left(\Delta \mathbf{M}_{n}^{l}\right)^{\prime} \mid \mathcal{F}_{n-1}\right] \xrightarrow{\text { a.s. }} \mathbf{G}^{l}, \quad \mathbf{E}\left[\Delta \mathbf{M}_{n}^{l_{1}}\left(\Delta \mathbf{M}_{n}^{l_{2}}\right)^{\prime}\right]=0 \quad \forall l_{1} \neq l_{2} .
$$

To this end, we first show that, for any urn $j \in S^{l}, \mathbf{E}\left[\Delta M_{n}^{j}\left(\Delta M_{n}^{j}\right)^{\prime} \mid \mathcal{F}_{n-1}\right] \xrightarrow{\text { a.s. }} G^{j}$. Note that

$$
\mathbf{E}\left[\Delta M_{n}^{j}\left(\Delta M_{n}^{j}\right)^{\prime} \mid \mathcal{F}_{n-1}\right]=\mathbf{E}\left[\left(D_{n}^{j} X_{n}^{j}\right)\left(D_{n}^{j} X_{n}^{j}\right)^{\prime} \mid \mathcal{F}_{n-1}\right]-\left(H^{j} \tilde{Z}_{n-1}^{j}\right)\left(H^{j} \tilde{Z}_{n-1}^{j}\right)^{\prime} ;
$$

then, concerning the first term, we have that

$$
\begin{aligned}
\mathbf{E}\left[\left(D_{n}^{j} X_{n}^{j}\right)\left(D_{n}^{j} X_{n}^{j}\right)^{\prime} \mid \mathcal{F}_{n-1}\right] & =\sum_{k=1}^{K} \mathbf{E}\left[D_{\cdot k, n}^{j}\left(D_{\cdot k, n}^{j}\right)^{\prime} \mid \mathcal{F}_{n-1}\right] \mathbf{P}\left(X_{k, n}^{j}=1 \mid \mathcal{F}_{n-1}\right) \\
& =\sum_{k=1}^{K}\left(C^{j}(k)+H^{j}(k)\right) \tilde{Z}_{k, n}^{j} .
\end{aligned}
$$

Hence, letting $n$ increase to infinity, from (17) we have

$$
\mathbf{E}\left[\Delta M_{n}^{j}\left(\Delta M_{n}^{j}\right)^{\prime} \mid \mathcal{F}_{n-1}\right] \xrightarrow{\text { a.s. }} \sum_{k=1}^{K}\left(C^{j}(k)+H^{j}(k)\right) \tilde{Z}_{k, \infty}^{j}-Z_{\infty}^{j}\left(Z_{\infty}^{j}\right)^{\prime}=G^{j} .
$$

Since, for any $j_{1} \neq j_{2}, D_{n}^{j_{1}} X_{n}^{j_{1}}$ and $D_{n}^{j_{2}} X_{n}^{j_{2}}$ are independent conditionally on $\mathcal{F}_{n-1}$, we have that $\mathbf{E}\left[\Delta M_{n}^{j_{1}}\left(\Delta M_{n}^{j_{2}}\right)^{\prime} \mid \mathcal{F}_{n-1}\right]=0$ and hence $\mathbf{E}\left[\Delta \mathbf{M}_{n}^{l_{1}}\left(\Delta \mathbf{M}_{n}^{l_{2}}\right)^{\prime}\right]=0$ for any $l_{1} \neq l_{2}$.

It remains to check that the remainder sequence $\left\{\mathbf{R}_{n}^{l} ; n \geq 1\right\}$ satisfies (38) for any $\epsilon>0$, i.e.

$$
\begin{equation*}
\mathbf{E}\left[n\left\|\mathbf{R}_{n}^{l}\right\|^{2} \mathbb{1}_{\left\{\left\|\mathbf{Z}_{n}^{l}-\mathbf{Z}_{\infty}^{l}\right\| \leq \epsilon\right\}}\right] \longrightarrow 0 \tag{33}
\end{equation*}
$$

Combining (10) and part (3b) in the proof of Theorem 4.1, we can obtain (33) by establishing

$$
\mathbf{E}\left[n\left\|n \cdot \operatorname{diag}\left(\mathbf{T}_{n}^{l}\right)^{-1}-\mathbf{I}\right\|^{2}\right] \longrightarrow 0
$$

that follows by using assumption ( $\mathrm{A}^{\prime} 2$ ) in Theorem 2.1.
Since the assumptions are all satisfied, we can apply Theorem A. 2 to any leading system $S^{l}$, $l \in \mathcal{L}_{L}$, so obtaining the CLT of Theorem 4.2, with asymptotic variance

$$
\Sigma^{l}=\lim _{m \rightarrow \infty} \int_{0}^{\infty} e^{u\left(\frac{\mathrm{I}}{2}-\mathbf{F}_{m}^{l}\right)} \mathbf{G}^{l} e^{u\left(\frac{\mathrm{I}}{2}-\mathbf{F}_{m}^{l}\right)^{\prime}} d u
$$

This concludes the proof.

### 7.2. Proofs on the following systems.

Proof of Theorem 5.1. Consider the joint system $S^{(l)}=\cup_{i \in\left\{L_{1}, . . l\right\}} S^{i}$, for $l \in \mathcal{L}_{F}$, composed by the leading systems $S^{L_{1}}, . . S^{L_{n}}$ and the following systems $S^{F_{1}}, . . S^{l}$, where we recall $S^{l}:=\left\{r^{l^{-}}+1 \leq\right.$ $\left.j \leq r^{l}\right\}$. As explained in Section 廻, we focus on the reduced process $\hat{\mathbf{Z}}_{n}^{(l)}:=\hat{\mathbf{C}}^{\prime} \mathbf{Z}_{n}^{(l)}$, whose dynamics is expressed in (24) as follows:

$$
\begin{align*}
\hat{\mathbf{Z}}_{n}^{(l)}-\hat{\mathbf{Z}}_{n-1}^{(l)} & =-\frac{1}{n} \hat{f}_{m}^{(l)}\left(\hat{\mathbf{Z}}_{n-1}^{(l)}\right)+\frac{1}{n} \hat{\mathbf{C}}^{\prime}\left(\Delta \mathbf{M}_{n}^{(l)}+\mathbf{R}_{n}^{(l)}\right)  \tag{34}\\
\hat{f}_{m}^{(l)}(\hat{\mathbf{x}}) & :=\left(\mathbf{I}-\hat{\mathbf{C}}^{\prime} \mathbf{Q}^{(l)} \hat{\mathbf{B}}\right) \hat{\mathbf{x}}+m \hat{\mathbf{V}}_{1}\left(\hat{\mathbf{U}}_{1}^{\prime} \hat{\mathbf{x}}-1\right)+m \hat{\mathbb{V}}_{2} \hat{U}_{2}^{\prime} \hat{\mathbf{x}}
\end{align*}
$$

where the function $f$ in the SA form (5) is here represented by $\hat{f}_{m}^{(l)}$ that takes values in $\operatorname{Span}\left\{\mathbf{V}_{I N}\right\}$.
Analogously to the proof of Theorem 4.1 for the leading systems, one can show that all the assumptions of Theorem A. 1 are satisfied by the dynamics in (34) and hence the limiting values of $\hat{\mathbf{Z}}_{n}^{(l)}$ are represented by those $\mathbf{x} \in \operatorname{Span}\left\{\mathbf{V}_{I N}\right\}$ such that $\hat{f}_{m}^{(l)}(\mathbf{x})=0$. By using the analogous decompositions of (29) for $\hat{\mathbf{C}}^{\prime} \mathbf{Q}^{(l)} \hat{\mathbf{B}}$ and (30) for $\mathbf{x} \in \operatorname{Span}\left\{\mathbf{V}_{I N}\right\}$, we have that

$$
\begin{equation*}
\hat{f}_{m}^{l}(\mathbf{x})=m \hat{\mathbf{V}}_{1}(a-1)+\hat{\mathbb{V}}_{2}\left((1+m) \mathbf{I}-\hat{\mathbf{J}}_{2}\right) b+\hat{\mathbb{V}}_{3}\left(\mathbf{I}-\hat{\mathbf{J}}_{3}\right) c \tag{35}
\end{equation*}
$$

where $\hat{\mathbf{J}}_{2}:=\hat{\mathbf{C}}^{\prime} \mathbf{J}_{2} \hat{\mathbf{B}}$ and $\hat{\mathbf{J}}_{3}:=\hat{\mathbf{C}}^{\prime} \mathbf{J}_{3} \hat{\mathbf{B}}$. From the irreducibility of $H^{j}$ required in (A3), for all $\lambda \in \mathcal{A}_{I N} \backslash S p\left(W^{(l)}\right)$ we have $\lambda<1$ and hence $\left(\mathbf{I}-\hat{\mathbf{J}}_{3}\right)$ is positive definite. Therefore, since $m>0$, from (35) we have that $\hat{f}_{m}^{l}(\mathbf{x})=0$ if and only if $a=1$ and $b=c=0$, i.e. $\mathbf{x}=\hat{\mathbf{V}}_{1}$.

We highlight that, when (A3) does not hold, the matrix $\left(\mathbf{I}-\mathbf{J}_{3}\right)$ in (35) may not be positive definite and hence the solution $\hat{\mathbf{V}}_{1}$ would not be unique. However, since in the following systems $S^{l}, l \in \mathcal{L}_{F}$, we have $\lambda_{\max }\left(W^{l}\right)<1$ and this implies $\lambda_{\max }\left(\mathbf{Q}^{l}\right)<1$, the irreducibility assumption of $H^{j}$ required in (A3) is not necessary for the following systems, but it is only essential in the leading systems in which $\lambda_{\max }\left(W^{l}\right)=1$.

Now, since by definition of $\mathbf{Q}^{(l)}$ in (20) we have that

$$
\hat{\mathbf{C}}^{\prime} \mathbf{Q}^{(l)} \hat{\mathbf{B}}=\left[\begin{array}{ll}
\mathbf{C}^{\prime} \mathbf{Q}^{\left(l^{-}\right)} \mathbf{B} & 0 \\
\mathbf{Q}^{\left(l^{-}\right) l} \mathbf{B} & \mathbf{Q}^{l}
\end{array}\right],
$$

we can express $\hat{\mathbf{V}}_{1}=\left(\hat{\mathbf{V}}_{1}^{\left(l^{-}\right)}, \hat{\mathbf{V}}_{1}^{l}\right)^{\prime}$ as follows:

$$
\hat{\mathbf{V}}_{1}=\left[\begin{array}{l}
\hat{\mathbf{V}}_{1}^{\left(l^{-}\right)} \\
\left(\mathbf{I}-\mathbf{Q}^{l}\right)^{-1} \mathbf{Q}^{\left(l^{-}\right) l} \mathbf{B} \hat{\mathbf{V}}_{1}^{\left(l^{-}\right)}
\end{array}\right]=\left[\begin{array}{l}
\mathbf{C}^{\prime} \mathbf{V}_{1}^{\left(l^{-}\right)} \\
\left(\mathbf{I}-\mathbf{Q}^{l}\right)^{-1} \mathbf{Q}^{\left(l^{-}\right) l} \mathbf{B C}^{\prime} \mathbf{V}_{1}^{\left(l^{-}\right)}
\end{array}\right]
$$

Then, notice that, since $\mathbf{V}_{1}^{\left(l^{-}\right)} \in \mathcal{I} m\left(\mathbf{V}_{I N}\right)$, we have $\mathbf{B C}^{\prime} \mathbf{V}_{1}^{\left(l^{-}\right)}=\mathbf{V}_{I N} \mathbf{U}_{I N}^{\prime} \mathbf{V}_{1}^{\left(l^{-}\right)}=\mathbf{V}_{1}^{\left(l^{-}\right)}$.
Finally, since from (25) $\hat{\mathbf{F}}_{m}^{(l)}=\hat{\mathbf{C}}^{\prime} \mathbf{F}_{m}^{(l)} \hat{\mathbf{B}}$, we have that $S p\left(\hat{\mathbf{F}}_{m}^{(l)}\right) \subset S p\left(\mathbf{F}_{m}^{(l)}\right)$ and hence $\hat{\mathbf{F}}_{m}^{(l)}$ is positive definite for any $m>0$. As a consequence, $\hat{\mathbf{V}}_{1}$ is a global attractor in $\operatorname{Span}\left\{\mathbf{V}_{I N}\right\}$ and this concludes the proof.

Proof of Theorem 5.2. Consider the joint system $S^{(l)}=\cup_{i \in\left\{L_{1}, . . l\right\}} S^{i}$, for $l \in \mathcal{L}_{F}$, composed by the leading systems $S^{L_{1}}, . . S^{L_{n}}$ and the following systems $S^{F_{1}}, . . S^{l}$, where we recall $S^{l}:=\left\{r^{l^{-}}+1 \leq\right.$ $\left.j \leq r^{l}\right\}$. As explained in Section [5, we focus on the reduced process $\hat{\mathbf{Z}}_{n}^{(l)}:=\hat{\mathbf{C}}^{\prime} \mathbf{Z}_{n}^{(l)}$, whose dynamics
is expressed in (24) as follows:

$$
\begin{aligned}
\hat{\mathbf{Z}}_{n}^{(l)}-\hat{\mathbf{Z}}_{n-1}^{(l)} & =-\frac{1}{n} \hat{f}_{m}^{(l)}\left(\hat{\mathbf{Z}}_{n-1}^{(l)}\right)+\frac{1}{n} \hat{\mathbf{C}}^{\prime}\left(\Delta \mathbf{M}_{n}^{(l)}+\mathbf{R}_{n}^{(l)}\right), \\
\hat{f}_{m}^{(l)}(\hat{\mathbf{x}}) & :=\left(\mathbf{I}-\hat{\mathbf{C}}^{\prime} \mathbf{Q}^{(l)} \hat{\mathbf{B}}\right) \hat{\mathbf{x}}+m \hat{\mathbf{V}}_{1}\left(\hat{\mathbf{U}}_{1}^{\prime} \hat{\mathbf{x}}-1\right)+m \hat{\mathbf{V}}_{2} \hat{U}_{2}^{\prime} \hat{\mathbf{x}}
\end{aligned}
$$

where the function $f$ in the SA form in (5) is here represented by $\hat{f}_{m}^{(l)}$. The proof will be realized by showing that the assumptions of the $C L T$ for processes in the $S A$ form (Theorem A.2 in Appendix) are satisfied by the process $\hat{\mathbf{Z}}_{n}^{(l)}$. Hence the results of Theorem 5.2 follow by applying TheoremA.2, where $\theta^{*}$ indicates the deterministic limiting proportion $\hat{\mathbf{Z}}_{\infty}^{(l)}$, while $\mathcal{D} f\left(\theta^{*}\right)$ is represented by $\hat{\mathbf{F}}_{m}^{(l)}$ defined in (25).

First, we show that condition $\left\{\operatorname{Sp}\left(D f\left(\theta^{*}\right)\right)>1 / 2\right\}$ in Theorem A. 2 is equivalent to $\left\{\lambda^{* l}<1 / 2\right\}$. To this end, analogously to the proof of Theorem 4.2 for the leading systems, note that
(1) $\hat{\mathbf{F}}_{m}^{(l)} \hat{\mathbf{V}}_{1}=m \hat{\mathbf{V}}_{1}$,
(2) $\hat{\mathbf{F}}_{m}^{(l)} \hat{\mathbb{V}}_{2}=\hat{\mathbb{V}}_{2}\left((1+m) \mathbf{I}-\mathbf{J}_{2}\right)$,
(3) $\hat{\mathbf{F}}_{m}^{(l)} \hat{\mathbb{V}}_{3}=\hat{\mathbb{V}}_{3}\left(\mathbf{I}-\mathbf{J}_{3}\right)$.

Hence, the eigenvectors of $\hat{\mathbf{F}}_{m}^{(l)}$ and $\hat{\mathbf{C}}^{\prime} \mathbf{Q}^{(l)} \hat{\mathbf{B}}$ are the same and then
$S p\left(\hat{\mathbf{F}}_{m}^{(l)}\right)=\{m\} \cup\left\{(1+m)-\lambda, \lambda \in S p\left(W^{(l)}\right) \backslash\left(\{1\} \cup \mathcal{A}_{\text {OUT }}\right)\right\} \cup\left\{1-\lambda, \lambda \in S p\left(\mathbf{Q}^{(l)}\right) \backslash\left(S p\left(W^{(l)}\right) \cup \mathcal{A}_{\text {OUT }}\right)\right\}$,
which implies $\left\{\operatorname{Sp}\left(\mathcal{D} f\left(\theta^{*}\right)\right)>1 / 2\right\} \equiv\left\{\lambda^{* l}<1 / 2\right\}$.
Then, by using analogous arguments of the proof of Theorem 4.2 for the leading systems, it is straightforward showing that

$$
\mathbf{E}\left[\hat{\mathbf{C}}^{\prime} \Delta \mathbf{M}_{n}^{(l)}\left(\Delta \mathbf{M}_{n}^{(l)}\right)^{\prime} \hat{\mathbf{C}} \mid \mathcal{F}_{n-1}\right] \xrightarrow{\text { a.s. }} \hat{\mathbf{G}}^{(l)}, \quad \mathbf{E}\left[\hat{\mathbf{C}}^{\prime} \Delta \mathbf{M}_{n}^{\left(l_{1}\right)}\left(\Delta \mathbf{M}_{n}^{\left(l_{2}\right)}\right)^{\prime} \hat{\mathbf{C}}\right]=0 \quad \forall l_{1} \neq l_{2},
$$

and for any $\epsilon>0$

$$
\mathbf{E}\left[n\left\|\hat{\mathbf{C}}^{\prime} \mathbf{R}_{n}^{(l)}\right\|^{2} \mathbb{1}_{\left\{\left\|\hat{\mathbf{z}}_{n}^{(l)}-\hat{\mathbf{z}}_{\infty}^{(l)}\right\| \leq \epsilon\right\}}\right] \longrightarrow 0
$$

Since the assumptions are all satisfied, we can apply Theorem A. 2 to obtain the CLT with asymptotic variance

$$
\hat{\Sigma}^{(l)}:=\int_{0}^{\infty} e^{u\left(\frac{1}{2}-\hat{\mathbf{F}}_{m}^{(l)}\right)} \hat{\mathbf{G}}^{(l)} e^{u\left(\frac{\mathrm{I}}{2}-\hat{\mathbf{F}}_{m}^{(l)}\right)^{\prime}} d u .
$$

This concludes the proof.

## Appendix

## Appendix A. Basic tools of Stochastic Approximation

Consider the recursive procedure define in (5) on a filtered probability space $\left(\Omega, \mathcal{A},\left(\mathcal{F}_{n}\right)_{n \geq 0}, \mathbf{P}\right)$, i.e.

$$
\forall n \geq 1, \quad \theta_{n}=\theta_{n-1}-\frac{1}{n} f\left(\theta_{n-1}\right)+\frac{1}{n}\left(\Delta M_{n}+R_{n}\right),
$$

where $f: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$ is a locally Lipschitz continuous function, $\theta_{n}$ an $\mathcal{F}_{n}$-measurable finite random vector and, for every $n \geq 1, \Delta M_{n}$ is an $\mathcal{F}_{n-1}$-martingale increment and $R_{n}$ is an $\mathcal{F}_{n}$-adapted remainder term.

Theorem A.1. (A.s. convergence with $O D E$ method, see e.g. [9, 14, 22, 17, 7). Assume that $f$ is locally Lipschitz, that

$$
R_{n} \xrightarrow{\text { a.s. }} 0 \quad \text { and } \quad \sup _{n \geq 1} \mathbf{E}\left[\left\|\Delta M_{n}\right\|^{2} \mid \mathcal{F}_{n-1}\right]<+\infty \quad \text { a.s.. }
$$

Then the set $\Theta^{\infty}$ of its limiting values as $n \rightarrow+\infty$ is a.s. a compact connected set, stable by the flow of

$$
O D E_{f} \equiv \dot{\theta}=-f(\theta)
$$

Furthermore if $\theta^{*} \in \Theta^{\infty}$ is a uniformly stable equilibrium on $\Theta^{\infty}$ of $O D E_{f}$, then

$$
\theta_{n} \xrightarrow{\text { a.s. }} \theta^{*} .
$$

Comments. By uniformly stable we mean that

$$
\sup _{\theta \in \Theta^{\infty}}\left|\theta\left(\theta_{0}, t\right)-\theta^{*}\right| \longrightarrow 0 \quad \text { as } \quad t \rightarrow+\infty
$$

where $\theta\left(\theta_{0}, t\right)_{\theta_{0} \in \Theta^{\infty}, t \in \mathbb{R}_{+}}$is the flow of $O D E_{f}$ on $\Theta^{\infty}$.
We say that the function $f$ is $\epsilon$-differentiable, $\epsilon>0$, at $\theta^{*}$ if

$$
f(\theta)=f\left(\theta^{*}\right)+\mathcal{D} f\left(\theta^{*}\right)\left(\theta-\theta^{*}\right)+o\left(\left\|\theta-\theta^{*}\right\|^{1+\epsilon}\right) \quad \text { as } \quad \theta \rightarrow \theta^{*} .
$$

Theorem A.2. (Rate of convergence see [14] Theorem 3.III. 14 p. 131 (for CLT see also e.g. [9, [22])). Let $\theta^{*}$ be an equilibrium point of $\{f=0\}$. Assume that the function $f$ is differentiable at $\theta^{*}$ and all the eigenvalues of $\mathcal{D} f\left(\theta^{*}\right)$ have positive real parts. Assume that for some $\delta>0$,

$$
\begin{equation*}
\sup _{n \geq 1} \mathbf{E}\left[\left\|\Delta M_{n}\right\|^{2+\delta} \mid \mathcal{F}_{n-1}\right]<+\infty \text { a.s. } \tag{36}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbf{E}\left[\Delta M_{n} \Delta M_{n}^{\prime} \mid \mathcal{F}_{n-1}\right] \underset{n \rightarrow+\infty}{\text { a.s. }} \Gamma, \tag{37}
\end{equation*}
$$

where $\Gamma \in \mathcal{S}^{+}(d, \mathbb{R})$ (deterministic symmetric positive matrix) and for an $\epsilon>0$,

$$
\begin{equation*}
n \mathbf{E}\left[\left\|R_{n}\right\|^{2} \mathbb{1}_{\left\{\left\|\theta_{n-1}-\theta^{*}\right\| \leq \epsilon\right\}}\right] \underset{n \rightarrow+\infty}{\longrightarrow} 0 \tag{38}
\end{equation*}
$$

(a) If $\Lambda:=\Re e\left(\lambda_{\min }\right)>\frac{1}{2}$, where $\lambda_{\min }$ denotes the eigenvalue of $\mathcal{D} f\left(\theta^{*}\right)$ with lowest real part, the above a.s. convergence is ruled on the set $\mathcal{D} f\left\{\theta_{n} \rightarrow \theta^{*}\right\}$ by the following Central Limit Theorem

$$
\sqrt{n}\left(\theta_{n}-\theta^{*}\right) \underset{n \rightarrow \infty}{\stackrel{\mathcal{L}}{\longrightarrow}} \mathcal{N}(0, \Sigma) \quad \text { with } \quad \Sigma:=\int_{0}^{+\infty} e^{\left(I_{d} / 2-\mathcal{D} f\left(\theta^{*}\right)\right) u} \Gamma e^{\left(I_{d} / 2-\mathcal{D} f\left(\theta^{*}\right)\right)^{\prime} u} d u
$$

(b) If $\lambda_{\text {min }}=\frac{1}{2}$, then

$$
\sqrt{\frac{n}{\log n}}\left(\theta_{n}-\theta^{*}\right) \underset{n \rightarrow \infty}{\mathcal{L}} \mathcal{N}(0, \Sigma) \quad \text { as } n \rightarrow+\infty \text {. }
$$

(c) If $\lambda_{\min } \in\left(0, \frac{1}{2}\right)$, then $n^{\lambda_{\min }}\left(\theta_{n}-\theta^{*}\right)$ a.s. converges as $n \rightarrow+\infty$ towards a finite random variable.

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(G. Aletti) ADAMSS Center \& Department of Mathematics, Università degli Studi di Milano, 20133

Milano, Italy
E-mail address: giacomo.aletti@unimi.it
(A. Ghiglietti) ADAMSS Center \& Department of Mathematics, Università degli Studi di Milano, 20133 Milano, Italy

E-mail address: andrea.ghiglietti@unimi.it

