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# Polynomial Algebras and Smooth Functions in Banach Spaces 

MAT/05

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## Introduction

According to the fundamental Stone-Weierstrass theorem, if $X$ is a finite dimensional real Banach space, then every continuous function on the unit ball $B_{X}$ can be uniformly approximated by polynomials.

Before venturing out into infinite-dimensional Banach spaces, let us touch upon what polynomials on such spaces are like.

Definition. Let $X, Y$ be Banach spaces, ${ }^{1} n \in \mathbb{N}$ and let $\mathcal{L}\left({ }^{n} X ; Y\right)$ be the space of $n$-linear $Y$-valued mappings on $X$.

- A mapping $P: X \longrightarrow Y$ is called an $n$-homogeneous polynomial if there exists $M \in \mathcal{L}\left({ }^{n} X ; Y\right)$ such that $P(x)=M(x, \ldots, x)$ for all $x \in X$. For convenience, we also define 0-homogeneous polynomials as constant mappings from $X$ to $Y$. We denote by $\mathcal{P}\left({ }^{n} X ; Y\right), n \in \mathbb{N}_{0}$, the space of all $n$-homogeneous polynomials from $X$ into $Y$. When the target space is the scalar field, we use a shortened notation $\mathcal{P}\left({ }^{n} X\right)=$ $\mathcal{P}\left({ }^{n} X ; Y\right)$.
- A mapping $P: X \longrightarrow Y$ is called a polynomial of degree at most $n$ if there exist $P_{k} \in \mathcal{P}\left({ }^{k} X ; Y\right), k=0, \ldots, n$, such that $P=\sum_{k=0}^{n} P_{k}$. If $P_{n} \neq 0$ we say that $P$ has degree $n$. We denote by $\mathcal{P}^{n}(X ; Y)$ the space of all polynomials of degree at most $n$.
- We denote by $\mathcal{P}(X ; Y)=\bigcup_{n=0}^{\infty} \mathcal{P}^{n}(X ; Y)$ the space of all polynomials.
- We say that $P \in \mathcal{P}\left({ }^{n} X ; Y\right)$ (resp. $\left.\mathcal{P}^{n}(X ; Y), \mathcal{P}(X ; Y)\right)$ is bounded whenever $\|P\|=\sup _{x \in B_{X}}\|P(x)\|<+\infty$. We denote by $\left(\mathcal{P}\left({ }^{n} X ; Y\right),\|\cdot\|\right)$

[^0](resp. $\left.\left(\mathcal{P}^{n}(X ; Y),\|\cdot\|\right),(\mathcal{P}(X ; Y),\|\cdot\|)\right)$ the normed linear space of all continuous ${ }^{2} n$-homogeneous polynomials (resp. all continuous polynomials of degree at most $n$, all continuous polynomials).

- We denote by $\mathcal{A}_{n}(X)$ the algebra generated by $\mathcal{P}^{n}(X)$.

For infinite dimensional Banach spaces the statement of the Stone-Weierstrass Theorem is false, even if we replace continuous functions by the uniformly continuous ones (which is a natural condition that coincides with continuity in the finite dimensional setting): in fact, on every infinite-dimensional Banach space $X$ there exists a uniformly continuous real function not approximable by continuous polynomials (see [53]).
The natural problem of the proper generalization of the result for infinite dimensional spaces was posed by Shilov [59] (in the case of a Hilbert space). Aron [2] (see also Aron and Prolla [8]) observed that the uniform closure on $B_{X}$ of the space of all polynomials of the finite type, denoted by $\mathcal{P}_{f}(X)$, which consists of all polynomials admitting a formula $P(x)=\sum_{j=1}^{n}\left\langle\phi_{j}, x\right\rangle^{n_{j}}, \phi_{j} \in X^{*}, n_{j} \in \mathbb{N}$, is precisely the space of all functions which are weakly uniformly continuous on $B_{X}$ (Theorem 3.1.1):

Theorem ([2], [8]). Let $X, Y$ be Banach spaces. Then $\overline{\mathcal{P}_{f}(X ; Y)}=\mathcal{C}_{w u}\left(B_{X} ; Y\right)$.
Since there exist infinite dimensional Banach spaces such that all bounded polynomials are weakly uniformly continuous on $B_{X}$ (e.g. $c_{0}$ or more generally all Banach spaces not containing a copy of $\ell_{1}$ and such that all bounded polynomials are weakly sequentially continuous on $B_{X}$ ), this result gives a very satisfactory solution to the problem.
Unfortunately, most Banach spaces, including $L_{p}, p \in[1, \infty)$, do not have the special property used in [8]. In this case, no characterization of the uniform limits of polynomials is known.
But the problem has a more subtle formulation as well. Let us consider the algebras $\mathcal{A}_{n}(X)$ consisting of all polynomials which can be generated by finitely many algebraic operations of addition and multiplication, starting from polynomials on $X$ of degree not exceeding $n \in \mathbb{N}$. Of course, such polynomials can have arbitrarily high degree. The first mentioned result can

[^1]now be formulated as stating that $\overline{\mathcal{A}_{1}(X)}$ consists precisely of all functions which are weakly uniformly continuous on $B_{X}$. It is clear that, if $n$ is the lowest degree such that there exists a polynomial $P$ in $\mathcal{P}\left({ }^{n} X\right)$ which is not weakly uniformly continuous, then
$$
\overline{\mathcal{A}_{1}(X)}=\overline{\mathcal{A}_{2}(X)}=\cdots=\overline{\mathcal{A}_{n-1}(X)} \subsetneq \overline{\mathcal{A}_{n}(X)} .
$$

The problem of what happens from $n$ on has been studied in several papers, notably [53], [41] and [29]. The natural conjecture appears to be that once the chain of equalities has been broken, it is going to be broken at each subsequent step.
The proof of this latter statement given in [41], for all classical Banach spaces, based on the theory of algebraic bases, is unfortunately not entirely correct, as was pointed out by our colleague Michal Johanis. It is not clear to us if the theory of algebraic bases developed therein can be salvaged. Fortunately, the main statement of this theory, Lemma 1.5.4, can be proved using another approach. The complete proof, which will appear in [22], can be found in Chapter 2. Most of the results in this area which used [41] are therefore safe.
The aforementioned statement coincides with the following
Lemma. For every $n \in \mathbb{N}$, there exists an $\varepsilon>0$ such that, for every $m \geqslant$ $M(n)$,

$$
\sup _{\sum_{i=1}^{m}\left|x_{i}\right| \leqslant 1}\left|p\left(x_{1}, \ldots, x_{m}\right)-s_{n+1}\left(x_{1}, \ldots, x_{m}\right)\right| \geqslant \varepsilon
$$

for every $p$ from the algebra $S_{n}\left(\mathbb{R}^{m}\right)$ generated by subsymmetric polynomials of degree at most $n$.

The above quantitative lemma implies the following
Theorem. Let $X$ be an infinite dimensional Banach space, and $P \in \mathcal{P}\left({ }^{n} X\right)$ be a polynomial with the following property: for every $N \in \mathbb{N}$ and $\varepsilon>0$, there exists a normalized finite basic sequence $\left\{e_{j}\right\}_{j=1}^{N}$ such that

$$
\sup _{\sum_{j=1}^{N}\left|a_{j}\right| \leqslant 1}\left|P\left(\sum_{j=1}^{N} a_{j} e_{j}\right)-\sum_{j=1}^{N} a_{j}^{n}\right| \leqslant \varepsilon
$$

Then $P \notin \overline{\mathcal{A}_{n-1}(X)}$.

This fundamental criterion, in combination with some new results on the asymptotic behaviour of polynomials on infinite dimensional spaces, is one of the keys to prove our main result (see [21]), dealt with in Chapter 3 (Theorem 3.2.1).

Theorem. Let $X$ be a Banach space and $m$ be the minimal integer such that there is a non-compact $P \in \mathcal{P}\left({ }^{m} X ; \ell_{1}\right)$. Then $n \geqslant m$ implies $\mathcal{P}\left({ }^{n} X\right) \not \nmid$ $\overline{\mathcal{A}_{n-1}(X)}$.

Theorem 3.2.1 implies, together with the positive results of [2] and [8] (see the first theorem mentioned above), plus the corollary below (see [6]), all previously known results in this area (all confirming the above conjecture) as special cases.

Corollary ([6]). Let $X, Y$ be Banach spaces and suppose that $X$ does not contain a subspace isomorphic to $\ell_{1}$. Then $\mathcal{P}_{w u}\left({ }^{n} X ; Y\right)=\mathcal{P}_{\text {wsc }}\left({ }^{n} X ; Y\right)$.

For example, in the following cases it can be easily inferred that the algebra chain is broken, from a certain point (which we can determine) onward, at each subsequent step: if $X$ is a Banach space admitting a non-compact linear operator $T \in \mathcal{L}\left(X ; \ell_{p}\right), p \in[1, \infty)$ (see [41]); if $X=L_{p}([0,1]), 1 \leqslant p \leqslant \infty$, or $X=\ell_{\infty}$ or $X=C(K)$, where $K$ is a non-scattered compact; if $\ell_{1} \hookrightarrow X$ ([41]); if $X=\ell_{p}, 1 \leqslant p<\infty$; if $X^{*}$ has type $q$; if $X$ has an unconditional FDD, $\ell_{1} \leftrightarrow X$ and there exists a $P \in \mathcal{P}\left({ }^{n} X\right)$ which is not weakly sequentially continuous...

In Chapter 4 we also give solutions to three other problems posed in the literature, which are concerning smooth functions rather than polynomials, but which belong to the same field of study of smooth mappings on a Banach space.

The first result is a construction of a non-equivalent $C^{k}$-smooth norm on every Banach space admitting a $C^{k}$-smooth norm, answering a problem posed in several places in the literature, e.g. in [12].

Theorem. Let $X$ be an infinite dimensional Banach space admitting a $C^{k}$ _ smooth norm, $k \geqslant 2$. Then $X$ admits a decomposition $X=Y \oplus Z$, where
$Y$ is infinite dimensional and separable. In particular, $X$ admits a noncomplete $C^{k}$-smooth renorming.

We solve a question in [11] by proving that a real Banach space admitting a separating real analytic function whose holomorphic extension is Lipschitz in some strip around $X$ admits a separating polynomial.

Theorem. Let $X$ be a real Banach space which admits a real analytic separating function whose complex extension exists and is Lipschitz on some strip around $X$, i.e. on $X+2 r B_{X^{\mathbb{C}}} \subset X^{\mathbb{C}}$, for some $r>0$. Then $X$ is superreflexive and admits a separating polynomial.

Eventually, we solve a problem posed by Benyamini and Lindenstrauss in [14], concerning the extensions of uniformly differentiable functions from the unit ball into a larger set, preserving the values in some neighbourhood of the origin. More precisely, we construct an example of a uniformly differentiable real-valued function $f$ on the unit ball of a certain Banach space $X$, such that there exists no uniformly differentiable function $g$ on $\lambda B_{X}$, for any $\lambda>1$, which coincides with $f$ in some neighbourhood of the origin. To do so, we construct suitable renormings of $c_{0}$, based on the theory of $\mathcal{W}$-spaces.

Example. There exist countably many norms $\left\{\|\cdot\|_{m}\right\}_{m=2}^{\infty}$ on $c_{0}$ such that, if we set $X=\oplus_{\ell_{2}} \sum_{m=2}^{\infty}\left(c_{0},\|\cdot\|_{m}\right)$, then there exists a uniformly differentiable function $f: B_{X} \rightarrow \mathbb{R}$ which cannot be extended to a uniformly differentiable function on any $\lambda B_{X}, \lambda>1$, preserving its original values in some neighbourhood of 0 .

## Chapter 1

## Background and preliminary results

In this chapter we collect some background results concerning polynomials in Banach spaces, which will be used in the sequel. We refer to [36] for the standard notation concerning Banach spaces and to [30] for the standard notation concerning polynomials. For the sake of conciseness we will omit the proofs that are not directly involved in the papers [21] and [22], which the reader can find (along with further references) in the comprehensive monograph on smoothness in Banach spaces [44].

We also employ numerous classic tools and results in Banach Space Theory (such as Gâteaux and Fréchet differentiability, Tsirelson's space, JamesGurarii theorem, Bessaga-Pełczyński theorem, Dunford-Pettis property, Rosenthal's $\ell_{1}$ theorem, biorthogonal systems, lifting properties, Asplund and weak-Asplund spaces, projectional resolutions of the identity, Weakly Lindelöf Determined (WLD) spaces, finite-dimensional decompositions (FDD), type and cotype, superreflexivity, Lipschitz mappings, holomorphy. . . ): should the reader need to delve into these topics, we suggest consulting [35], [46], [36] and [44], where they are widely treated.

### 1.1 Polynomials

By $\mathbb{N}_{0}$ we denote the set $\mathbb{N} \cup\{0\}$, i.e. the non-negative integers. The canonical basis of $\mathbb{R}^{N}$ will be denoted by $\left\{e_{j}\right\}_{j=1}^{N}$.

Definition 1.1.1. Let $X_{1}, X_{2}, \ldots, X_{n}, Y$ be vector spaces.

- We say that a mapping $M: X_{1} \times \cdots X_{n} \longrightarrow Y$ is $n$-linear if it is linear in each coordinate, that is $x \mapsto M\left(x_{1}, \ldots, x_{k-1}, x, x_{k+1}, \ldots, x_{n}\right)$ is a linear mapping from $X_{k}$ into $Y$ for each $x_{1} \in X_{1}, \ldots x_{n} \in X_{n}$ and each $k \in\{1, \ldots, n\}$.
- By $L\left(X_{1}, \ldots X_{n} ; Y\right)$ we denote the vector space of all $n$-linear mappings from $X_{1} \times \cdots \times X_{n}$ to $Y$. Whenever $X_{k}=X, 1 \leqslant k \leqslant n$, we use the short notation $L\left({ }^{n} X ; Y\right)$.
- A map is called multilinear if it is $n$-linear for some $n \in \mathbb{N}$. A 2-linear mapping will also be called bilinear.
- We say that $M \in L\left({ }^{n} X ; Y\right)$ is symmetric if $M\left(x_{1}, \ldots, x_{n}\right)=$ $M\left(x_{\pi(1)}, \ldots, x_{\pi(n)}\right)$ for every permutation $\pi$ of $\{1, \ldots, n\}$ and every $x_{1}, \ldots, x_{n} \in X$.
- By $L^{s}\left({ }^{n} X ; Y\right)$ we denote the vector space of all $n$-linear symmetric mappings from $X^{n}$ to $Y$.

Definition 1.1.2. Let $X_{1}, X_{2}, \ldots, X_{n}, Y$ be normed linear spaces.

- We say that $M \in L\left(X_{1}, \ldots, X_{n} ; Y\right)$ is a bounded $n$-linear mapping if

$$
\|M\|:=\sup _{x_{1} \in B_{X_{1}}, \ldots, x_{n} \in B_{X_{n}}}\left\|M\left(x_{1}, \ldots, x_{n}\right)\right\|<+\infty . .^{1}
$$

- By $\left(\mathcal{L}\left(X_{1}, \ldots, X_{n} ; Y\right) ;\|\cdot\|\right)$, resp. $\left(\mathcal{L}\left({ }^{n} X ; Y\right) ;\|\cdot\|\right)$, resp. $\left(\mathcal{L}^{s}\left({ }^{n} X ; Y\right) ;\|\cdot\|\right)$, we denote the normed linear space of all respective $n$-linear bounded mappings. For bounded $n$-linear forms, we use the shortened notation $\mathcal{L}\left({ }^{n} X\right)=\mathcal{L}\left({ }^{n} X ; \mathbb{K}\right)$.

[^2]Remark 1.1.3. Let $M \in \mathcal{L}\left(X_{1}, \ldots, X_{n} ; Y\right)$. Then by homogeneity we have

$$
\left\|M\left(x_{1}, \ldots, x_{n}\right)\right\| \leqslant\|M\|\left\|x_{1}\right\| \cdots\left\|x_{n}\right\| \text { for } x_{j} \in X, j=1, \ldots, n
$$

It turns out that for multilinear mappings an analogous result to that of continuity of linear functionals holds, i.e. polynomials are continuous mappings whenever they have at least one point of continuity.

Proposition 1.1.4. Let $X_{1}, \ldots, X_{n}, Y$ be normed linear spaces and $M \in$ $\mathcal{L}\left(X_{1}, \ldots, X_{n} ; Y\right)$. The following are equivalent:
(i) $M$ is bounded;
(ii) $M$ is Lipschitz on bounded sets;
(iii) $M$ is continuous;
(iv) $M$ is bounded on a neighbourhood of some point.

A particular property comes in handy: homogeneous polynomials are in a canonical one-to-one correspondence with the symmetric multilinear forms via the Polarization formula, as the following proposition states.

Proposition 1.1.5 (Polarization formula). Let $X, Y$ be vector spaces and $M \in L\left({ }^{n} X ; Y\right)$. Then

$$
M^{s}\left(x_{1}, \ldots, x_{n}\right)=\frac{1}{2^{n} n!} \sum_{\varepsilon_{j}= \pm 1} \varepsilon_{1} \cdots \varepsilon_{n} M\left(a+\sum_{j=1}^{n} \varepsilon_{j} x_{j}, \ldots, a+\sum_{j=1}^{n} \varepsilon_{j} x_{j}\right)
$$

for every $a, x_{1}, \ldots, x_{n} \in X$. In particular, if $M$ is symmetric, then it is uniquely determined by its values $M(x, \ldots, x), x \in X$, along the diagonal.

Definition 1.1.6. Let $X, Y$ be vector spaces and $n \in \mathbb{N}$.

- A mapping $P: X \longrightarrow Y$ is said to be an $n$-homogeneous polynomial if there exists an $n$-linear mapping $M \in L\left({ }^{n} X, Y\right)$ such that $P(x)=M(x, \ldots, x)$. We use the notation $P=\widehat{M}$. For the sake of convenience, we also define 0 -homogeneous polynomials as constant mappings from $X$ to $Y$.
- We denote by $P\left({ }^{n} X ; Y\right), n \in \mathbb{N}_{0}$, the vector space of all $n$-homogeneous polynomials from $X$ into $Y$.

Suppose $X, Y$ are normed linear spaces, $n \in \mathbb{N}_{0}$.

- We say that $P \in P\left({ }^{n} X ; Y\right)$ is a bounded polynomial if

$$
\|P\|=\sup _{x \in B_{X}}\|P(x)\|<+\infty .
$$

- We denote by $\left(\mathcal{P}\left({ }^{n} X ; Y\right),\|\cdot\|\right)$ the normed linear space of all $n$-homogeneous bounded polynomials from $X$ into $Y$. When the target space is the scalar field, we use the shortened notation $\mathcal{P}\left({ }^{n} X\right)=\mathcal{P}\left({ }^{n} X ; \mathbb{K}\right)$.

For a given $n$-homogeneous polynomial $P$, the $n$-linear mapping $M$ that gives rise to $P$ is not uniquely determined. In particular, the symmetrized $n$-linear mapping leads to the same polynomial: for every $M \in L\left({ }^{n} X ; Y\right)$, we have $\widehat{M}=\widehat{M^{s}}$. However, the following fundamental result holds.

Proposition 1.1.7 (Polarization formula, [17], [51]). Let $X, Y$ be vector spaces and $n \in \mathbb{N}$. For every $P \in P\left({ }^{n} X ; Y\right)$, there exists a unique symmetric $n$-linear mapping $\check{P} \in L^{s}\left({ }^{n} X ; Y\right)$ such that $P(x)=\check{P}(x, \ldots, x)$. It satisfies the formula

$$
\check{P}\left(x_{1}, \ldots, x_{n}\right)=\frac{1}{2^{n} n!} \sum_{\varepsilon_{j}= \pm 1} \varepsilon_{1} \cdots \varepsilon_{n} P\left(a+\sum_{j=1}^{n} \varepsilon_{j} x_{j}\right),
$$

where $a \in X$ can be chosen arbitrarily. Moreover, if $X, Y$ are normed linear spaces and $P$ is bounded, then $\check{P}$ is also bounded and we have

$$
\|P\| \leqslant\|\check{P}\| \leqslant \frac{n^{n}}{n!}\|P\| \text {. }
$$

On the other hand, for every $m>n$ and $a, x_{1}, \ldots, x_{m} \in X$, the following holds:

$$
\sum_{\varepsilon_{j}= \pm 1} \varepsilon_{1} \cdots \varepsilon_{m} P\left(a+\sum_{j=1}^{m} \varepsilon_{j} x_{j}\right)=0
$$

Most of the time we will be concerned with the restrictions of the polynomials whose domain is a Banach space $X$ to a suitable subspace $Y \hookrightarrow X$ with a Schauder basis $\left\{e_{j}\right\}_{j=1}^{\infty}$ (resp. a finite-dimensional Banach space). In this case it is possible, and very useful, to rely on the concrete representation of (the restriction of) the polynomial using the monomial expansion in terms of the vector coordinates.

Definition 1.1.8. Let $n \in \mathbb{N}$. For a multi-index $\alpha \in \mathbb{N}_{0}^{n}$ we denote its order by $|\alpha|=\sum_{j=1}^{n} \alpha_{j}$. We denote the set of multi-indices of order $d \in \mathbb{N}_{0}$ by

$$
\mathcal{J}(n, d)=\left\{\alpha \in\{0, \ldots, d\}^{n}:|\alpha|=d\right\}
$$

In order to treat infinite dimensional Banach spaces, we extend the definition also to the case when $n=\infty$, setting

$$
\mathcal{J}(\infty, d)=\left\{\alpha \in\{0, \ldots, d\}^{\mathbb{N}}:|\alpha|=\sum_{j=1}^{\infty} \alpha_{j}=d\right\}
$$

For $n, d \in \mathbb{N}$ we denote $\mathcal{J}^{+}(n, d)=\left\{\alpha \in \mathcal{J}(n, d): \alpha_{j}>0, j=1, \ldots, n\right\}$ and $\mathcal{J}^{+}(d)=\bigcup_{n=1}^{d} \mathcal{J}^{+}(n, d)$.
For $n \in \mathbb{N}$ we denote

$$
\mathcal{N}(n)=\left\{\rho \in \mathbb{N}^{n}: \rho_{1}<\rho_{2}<\cdots<\rho_{n}\right\}
$$

For $n \in \mathbb{N}$ we have $|\mathcal{J}(n, d)|=\binom{n+d-1}{n-1} .{ }^{2}$
A given $\left(k_{j}\right)_{j=1}^{d} \in\{1, \ldots, n\}^{d}$ determines a unique $\alpha \in \mathcal{J}(n, d)$ by the relation

$$
\begin{equation*}
\alpha=\left(\left|\left\{j: k_{j}=1\right\}\right|,\left|\left\{j: k_{j}=2\right\}\right|, \ldots,\left|\left\{j: k_{j}=n\right\}\right|\right) . \tag{1.1}
\end{equation*}
$$

Conversely, a given $\alpha \in \mathcal{J}(n, d)$ determines a unique $k(\alpha)=\left(k_{1}(\alpha), \ldots, k_{d}(\alpha)\right)$, $k_{1}(\alpha) \leqslant \cdots \leqslant k_{d}(\alpha)$, such that (1.1) holds.
Given $x=\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{K}^{n}$ and $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right) \in \mathcal{J}(n, d)$ we use the standard multi-index notation

$$
x^{\alpha}=\prod_{l=1}^{n} x_{l}^{\alpha_{l}}=\prod_{j=1}^{d} x_{k_{j}(\alpha)}
$$

The case $n=\infty$ is similar and corresponds to multi-indices whose domain is $\mathbb{N}$. More precisely, for a fixed Schauder basis $\left\{e_{j}\right\}_{j=1}^{\infty}$ of $X$, with a dual basis $\left\{x_{j}^{*}\right\}_{j=1}^{\infty} \subset X^{*}, \alpha \in \mathcal{J}(\infty, d)$ and $x=\sum_{j=1}^{\infty} x_{j} e_{j}$,

$$
x^{\alpha}=\prod_{\alpha_{l} \neq 0} x_{l}^{\alpha_{l}}=\prod_{\alpha_{l} \neq 0}\left\langle x_{l}^{*}, x\right\rangle^{\alpha_{l}} .
$$

Note that $x \mapsto x^{\alpha} \in \mathcal{P}\left({ }^{d} \mathbb{K}^{n}\right)$ for any $\alpha \in \mathcal{J}(n, d)$.

[^3]Given $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right) \in \mathcal{J}(n, d)$, we denote $\alpha!=\alpha_{1}!\times \cdots \times \alpha_{n}!$. We also use the corresponding multinomial coefficient by

$$
\binom{d}{\alpha}=\binom{d}{\alpha_{1}, \ldots, \alpha_{n}}=\frac{d!}{\alpha_{1}!\cdots \alpha_{n}!}=\frac{d!}{\alpha!} .
$$

We also put a partial ordering on multiindices defined as follows. If $\alpha=$ $\left(\alpha_{1}, \ldots, \alpha_{n}\right) \in \mathcal{J}(n, d), \beta=\left(\beta_{1}, \ldots, \beta_{n}\right) \in \mathcal{J}(n, p), p \leqslant d$, and $\alpha_{j} \geqslant \beta_{j}$ holds for all $j \in\{1, \ldots, n\}$ then we say that $\alpha \geqslant \beta$, and we also denote $\alpha-\beta=\left(\alpha_{1}-\beta_{1}, \ldots, \alpha_{n}-\beta_{n}\right) \in \mathcal{J}(n, d-p)$.

Proposition 1.1.9 (Multinomial formula). Let $X, Y$ be vector spaces, $d \in$ $\mathbb{N}, P \in P\left({ }^{d} X ; Y\right)$ and $x_{1}, \ldots, x_{n} \in X$. Then

$$
P\left(x_{1}+\cdots+x_{n}\right)=\sum_{\alpha \in \mathcal{J}(n, d)}\binom{d}{\alpha} \check{P}\left({ }^{\alpha_{1}} x_{1}, \ldots,{ }^{\alpha_{n}} x_{n}\right)
$$

The next proposition asserts that the abstract definition of homogeneous polynomials coincides on $\mathbb{K}^{n}$ with the classical definition that uses coordinates. Note that in this case all homogeneous polynomials are automatically bounded.

Proposition 1.1.10. Let $n, d \in \mathbb{N}$ and $Y$ be a vector space over $\mathbb{K}$. $A$ mapping $P: \mathbb{K}^{n} \longrightarrow Y$ is a d-homogeneous polynomial if and only if there exist $\left\{y_{\alpha}\right\}_{\alpha \in \mathcal{J}(n, d)} \subset Y$ such that $P(x)=\sum_{\alpha \in \mathcal{J}(n, d)} x^{\alpha} y_{\alpha}$. Moreover, each $y_{\alpha}$ is uniquely determined by

$$
y_{\alpha}=\binom{d}{\alpha} \check{P}\left({ }^{\alpha_{1}} e_{1}, \ldots,{ }^{\alpha_{n}} e_{n}\right)
$$

where $\left\{e_{j}\right\}_{j=1}^{n}$ is the canonical basis of $\mathbb{K}^{n}$.
In the special case $Y=\mathbb{K}$, this reduces to the familiar formula

$$
P(x)=\sum_{\alpha \in \mathcal{J}(n, d)} a_{\alpha} x^{\alpha}
$$

where the coefficients $a_{\alpha} \in \mathbb{K}$.

Proposition 1.1.11. Let $X$ be a normed linear space with a Schauder basis $\left\{e_{j}\right\}_{j=1}^{\infty}, Y$ a vector space, $d \in \mathbb{N}$ and $P \in P\left({ }^{d} X ; Y\right)$. Denote $X_{0}=$
$\operatorname{span}\left\{e_{j}\right\}_{j=1}^{\infty}$. Then there is a unique collection of vectors $\left\{y_{\alpha}\right\}_{\alpha \in \mathcal{J}(n, d)} \subset Y$ such that the formula

$$
\begin{equation*}
P(x)=\sum_{\alpha \in \mathcal{J}(n, d)} x^{\alpha} y_{\alpha} \tag{1.2}
\end{equation*}
$$

holds for every $x \in X_{0}$. The coefficients $y_{\alpha}$ are given by

$$
y_{\alpha}=\binom{n}{\alpha} \check{P}\left({ }^{\alpha_{1}} e_{1},{ }^{\alpha_{2}} e_{2}, \ldots\right)
$$

Conversely, any $\left\{y_{\alpha}\right\}_{\alpha \in \mathcal{J}(n, d)} \subset Y$ uniquely determines a polynomial $P \in$ $P\left({ }^{d} X_{0} ; Y\right)$ by formula (1.2).

Definition 1.1.12. Let $X, Y$ be vector spaces and $n \in \mathbb{N}_{0}$.

- A mapping $P: X \longrightarrow Y$ is called a polynomial of degree at most $n$ if there are $P_{k} \in P\left({ }^{k} X ; Y\right), k=0, \ldots, n$, such that $P=\sum_{k=0}^{n} P_{k}$. If $P_{n} \neq 0$, we say that $P$ has degree $n$ and we use the notation $\operatorname{deg} P=n .{ }^{3}$
- We denote by $P^{n}(X ; Y)$ the space of all polynomials of degree at most $n$. We denote by $P(X ; Y)=\bigcup_{n=0}^{\infty} P^{n}(X ; Y)$ the space of all polynomials.

Suppose $X, Y$ are normed linear spaces, $n \in \mathbb{N}_{0}$.

- A mapping $P: X \longrightarrow Y$ is called a bounded polynomial of degree at most $n$ if there are $P_{k} \in \mathcal{P}\left({ }^{k} X ; Y\right), k=0, \ldots, n$, such that $P=$ $\sum_{k=0}^{n} P_{k}$.
- We denote by $\mathcal{P}^{n}(X ; Y)$ the space of all bounded polynomials of degree at most $n$. We denote by $\mathcal{P}(X ; Y)=\bigcup_{n=0}^{\infty} \mathcal{P}^{n}(X ; Y)$ the space of all bounded polynomials.


### 1.2 Differentiability

In this section we briefly list some facts concerning the derivative of polynomials.

[^4]Fact 1.2.1. Let $P \in \mathcal{P}\left({ }^{d} X ; Y\right), v \in X$. The directional derivative

$$
\frac{\partial P}{\partial v}(x)=\lim _{\lambda \rightarrow 0} \frac{P(x+\lambda v)-P(x)}{\lambda}
$$

is easily shown to be a polynomial in $x$ which satisfies the formula

$$
\frac{\partial P}{\partial v}(x)=d \cdot \check{P}\left(v,{ }^{d-1} x\right) \in \mathcal{P}\left({ }^{d-1} X ; Y\right) .
$$

By induction, for a fixed $\alpha \in \mathcal{J}(\infty, p), p \leqslant d$, where $\alpha_{i}=0(i>k)$ and $y_{1}, \ldots, y_{k} \in X$, we get

$$
\begin{equation*}
\frac{\partial^{p} P}{\partial^{\alpha_{1}} y_{1} \ldots \partial^{\alpha_{k}} y_{k}}(x)=\frac{d!}{(d-p)!} \check{P}\left({ }^{\alpha_{1}} y_{1}, \ldots,{ }^{\alpha_{k}} y_{k},{ }^{d-p} x\right) \in \mathcal{P}\left({ }^{d-p} X ; Y\right) \tag{1.3}
\end{equation*}
$$

Fact 1.2.2. Let $X$ be a Banach space with a Schauder basis $\left\{e_{j}\right\}_{j=1}^{\infty}, Y$ be a Banach space, $P \in \mathcal{P}\left({ }^{d} X ; Y\right)$. There is a unique set of vectors $y_{\alpha}^{\rho} \in Y, \alpha=$ $\left(\alpha_{1}, \ldots, \alpha_{k}\right) \in \mathcal{J}(\infty, d), \rho_{j} \in \mathbb{N}, 1 \leqslant \rho_{1}<\rho_{2}<\cdots<\rho_{k}$,

$$
\begin{equation*}
y_{\alpha}^{\rho}=\frac{1}{\alpha_{1}!\cdots \alpha_{k}!} \frac{\partial^{d} P}{\partial^{\alpha_{1}} e_{\rho_{1}} \ldots \partial^{\alpha_{k}} e_{\rho_{k}}}(0) \tag{1.4}
\end{equation*}
$$

such that the formula

$$
\begin{equation*}
P\left(\sum_{j=1}^{\infty} x_{j} e_{j}\right)=\sum_{\alpha \in \mathcal{J}(\infty, d)} \sum_{1 \leqslant \rho_{1}<\cdots<\rho_{k}} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{k}}^{\alpha_{k}} y_{\alpha}^{\rho} \tag{1.5}
\end{equation*}
$$

holds for every finitely supported vector $x \in X$. In the special case $Y=\mathbb{R}$ the coefficients are just real numbers $a_{\alpha}^{\rho}$.

### 1.3 Symmetric and sub-symmetric polynomials

This section is motivated by the following fact: the concept of sub-symmetric polynomials on $\mathbb{R}^{N}$ can be used to capture the essential information on the behaviour of a given general polynomial.

Definition 1.3.1. A Schauder basis $\left\{e_{j}\right\}_{j=1}^{\infty}$ of a Banach space $X$ is called symmetric if there exists $K>0$ such that for any bijection $\sigma: \mathbb{N} \rightarrow \mathbb{N}$, the formal linear operator $I_{\sigma}\left(\sum_{j=1}^{\infty} a_{j} e_{j}\right)=\sum_{j=1}^{\infty} a_{\sigma(j)} e_{j}$ is an isomorphism of $X$ such that $\left\|I_{\sigma}\right\|\left\|I_{\sigma}^{-1}\right\|<K$.

A Schauder basis $\left\{e_{j}\right\}_{j=1}^{\infty}$ of a Banach space $X$ is called spreading invariant if there exists $K>0$ such that for any increasing mapping $\sigma: \mathbb{N} \rightarrow \mathbb{N}$, the formal linear operator $I_{\sigma}\left(\sum_{j=1}^{\infty} a_{j} e_{j}\right)=\sum_{j=1}^{\infty} a_{j} e_{\sigma(j)}$ is an isomorphism into a subspace of $X$ such that $\left\|I_{\sigma}\right\|\left\|I_{\sigma}^{-1}\right\|<K$.
A spreading invariant and unconditional basis is called sub-symmetric.
We remark that a symmetric basis is automatically unconditional.
A subset $U$ of a Banach space $X$ with a Schauder basis $\left\{e_{j}\right\}_{j=1}^{\infty}$ is called symmetric (resp. spreading invariant) if for any bijection $\sigma: \mathbb{N} \rightarrow \mathbb{N}$ (resp. for any increasing mapping $\sigma: \mathbb{N} \rightarrow \mathbb{N}), I_{\sigma}(U) \subset U$.

Definition 1.3.2. Let $\left\{e_{j}\right\}_{j=1}^{\infty}$ be a Schauder basis of a Banach space $X$, $U \subset X$ be symmetric (resp. spreading invariant) and $f: U \rightarrow Y$ be a function. If

$$
f\left(\sum_{j=1}^{\infty} a_{j} e_{j}\right)=f\left(\sum_{j=1}^{\infty} a_{j} e_{\sigma(j)}\right), \quad \sum_{j=1}^{\infty} a_{j} e_{j} \in U
$$

for any bijection $\sigma: \mathbb{N} \rightarrow \mathbb{N}$ (resp. for any increasing mapping $\sigma: \mathbb{N} \rightarrow \mathbb{N}$ ), then we say that $f$ is symmetric (resp. sub-symmetric) on $U$.

These notions will typically be applied to functions whose domain is a Banach space with a symmetric (resp. spreading invariant) basis or a subspace of a space with a Schauder basis consisting of finitely supported vectors.
We use the same terminology also for functions acting on $X=\mathbb{R}^{n}$, with the fixed and linearly ordered linear basis $\left\{e_{j}\right\}_{j=1}^{n}$. In this case the notion of subsymmetric is reduced to the identity $f(x)=f(y)$ being valid for every pair $x=\left(x_{1}, \ldots, x_{n}\right), y=\left(y_{1}, \ldots, y_{n}\right)$ of elements of $\mathbb{R}^{n}$ such that the sequences formed by all non-zero coordinates of $x$ and $y$ coincide (e.g. $x=(2,0,0,1.5, \pi, 0) y=(0,2,1.5,0,0, \pi))$.

## Definition 1.3.3.

- For a given $d \in \mathbb{N}$ denote

$$
\mathcal{J}(d)=\left\{\alpha=\left(\alpha_{1}, \ldots, \alpha_{k}\right): \quad k \in \mathbb{N}, \alpha_{j} \in\{1, \ldots, d\}, \sum_{j=1}^{k} \alpha_{j}=d\right\} \cdot 4
$$

[^5]- Given $\alpha=\left(\alpha_{1}, \ldots, \alpha_{k}\right) \in \mathcal{J}(d)$ we let

$$
\begin{equation*}
P_{\alpha}\left(\sum_{j=1}^{\infty} x_{j} e_{j}\right)=\sum_{1 \leqslant \rho_{1}<\cdots<\rho_{k}} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{k}}^{\alpha_{k}}, \tag{1.6}
\end{equation*}
$$

for all finitely supported $\sum_{j=1}^{\infty} x_{j} e_{j} \in c_{00}$, and set $P_{\varnothing}=1$. Clearly, $P_{\alpha}$ is a subsymmetric polynomial. Polynomials which satisfy (1.6) are called standard or elementary. ${ }^{5}$

- Further, we denote $s_{d}=P_{(d)}$, i.e.

$$
s_{d}(x)=\sum_{j=1}^{\infty} x_{j}^{d}
$$

for all finitely-supported vectors $x=\sum x_{j} e_{j}$. Each $s_{d}$ is a symmetric polynomial and it is called a power sum symmetric polynomial.

Remark 1.3.4. The standard polynomials form a linear basis of the finite dimensional linear space of all $d$-homogeneous subsymmetric (and not necessarily bounded) polynomials on $\operatorname{span}\left\{e_{j}\right\}$.

More precisely, we have the following well-known fact.

Fact 1.3.5. Let $X$ be the linear span of a Schauder basis $\left\{e_{j}\right\}_{j=1}^{\infty}$ (resp. $X=$ $\left.\mathbb{R}^{n}\right)$ and $Y$ a vector space. If a polynomial $P \in \mathcal{P}^{d}(X ; Y)$ is subsymmetric, then, for fixed $\alpha=\left(\alpha_{1}, \ldots, \alpha_{k}\right)$, the constants $y_{\alpha}^{\rho}$ do not depend on the choice of $\rho=\rho_{1}<\cdots<\rho_{k}$. In particular, the following equality holds

$$
\begin{equation*}
P\left(\sum_{j=1}^{\infty} x_{j} e_{j}\right)=\sum_{k=0}^{d} \sum_{\alpha \in \mathcal{J}(k)} P_{\alpha}\left(\sum_{j=1}^{\infty} x_{j} e_{j}\right) y_{\alpha} \tag{1.7}
\end{equation*}
$$

for all finitely supported $\sum_{j=1}^{\infty} x_{j} e_{j} \in X$ (resp. for all $x \in \mathbb{R}^{n}$ ). ${ }^{6}$
We will also rely on a finite dimensional version of the above result.

[^6]
### 1.4 Spreading models

Definition 1.4.1. Given a set $X$, we let $X^{(n)}$ be the set of all subsets of $X$ of cardinality $n$. We say that a system of $k$ disjoint sets $\left\{S_{i}\right\}_{i=1}^{k}$ forms a partitioning of $X^{(n)}$ whenever $X^{(n)}=\bigcup_{i=1}^{k} S_{i}$.

Proposition 1.4.2 (Ramsey). Let $k, n \in \mathbb{N}$. Then for every partitioning $\left\{S_{i}\right\}_{i=1}^{k}$ of $\mathbb{N}^{(n)}$ there exists $i \in\{1, \ldots, k\}$ and an infinite set $M \subset \mathbb{N}$ such that $M^{(n)} \subset S_{i}$.

This result can be reformulated in the following ways:

- Let $n$ be a natural number. Let $\psi$ be a mapping from $\mathbb{N}^{(n)}$ to some finite set $C$. Then there is an infinite subset $M$ of $\mathbb{N}$ such that $\psi$ is constant on $M^{(n)}$.
- If a coloring (with a finite number of colors) of sets of natural numbers of a given length $n$ is defined, then there is an infinite subset $M$ of $\mathbb{N}$ such that all subsets of $M$ of length $n$ have the same color.

Proposition 1.4.3 (Ramsey). Let $k, n, m \in \mathbb{N}$. Then there exists $M=$ $M(k, n, m)$ such that, for every partitioning $\left\{S_{i}\right\}_{i=1}^{k}$ of $\{1, \ldots, M\}^{(n)}$, there exists $i \in\{1, \ldots, k\}$ and a subset $A \subset\{1, \ldots, m\},|A|=m$, such that $A^{(n)} \subset$ $S_{i}$.

We will now list some basic facts concerning the spreading model construction for a Banach space $X$, which leads to a Banach space with a subsymmetric basis which captures the asymptotic behaviour of infinite sequences in $X$.

Definition 1.4.4. Let $K \geqslant 1$. We say that a sequence $\left\{x_{n}\right\}_{n=1}^{\infty}$ in a normed linear space is $K$-spreading if

$$
\left\|\sum_{j=1}^{k} a_{j} x_{m_{j}}\right\| \leqslant K\left\|\sum_{j=1}^{k} a_{j} x_{n_{j}}\right\|
$$

whenever $k \in \mathbb{N}, a_{1}, \ldots, a_{k}$ are any scalars and $m_{j}, n_{j} \in \mathbb{N}$ are such that $m_{1}<m_{2}<\cdots<m_{k}, n_{1}<n_{2}<\cdots<n_{k}$.

Remark 1.4.5. From Rosenthal's $\ell_{1}$-theorem it follows that any $K$-spreading sequence in a Banach space $X$ is either equivalent to the canonical basis of $\ell_{1}$ or it is weakly Cauchy: indeed, the linear operator $T: \operatorname{span}\left\{x_{n_{j}}\right\} \longrightarrow \operatorname{span}\left\{x_{j}\right\}$ such that $T\left(x_{n_{j}}\right)=x_{j}$ is bounded and hence $w-w$ uniformly continuous.

Proposition 1.4.6 ([13]). Let $\left\{e_{n}\right\}$ be a $K$-spreading sequence in a Banach space $X$. Then $\left\{e_{n}\right\}$ is a basic sequence if and only if it is not weakly convergent to a non-zero element of $X$. If moreover $\left\{e_{n}\right\}$ is weakly null, then $\left\{e_{n}\right\}$ is an unconditional basic sequence.

## Remark 1.4.7.

- A symmetric basis is automatically unconditional and in fact subsymmetric (see [60]).
- If $\left\{e_{n}\right\} \subset X$ is a sub-symmetric basis that is $K$-spreading, then the sequence $\left\{f_{n}\right\} \subset X^{*}$, biorthogonal to $\left\{e_{n}\right\}$, is a sub-symmetric basic sequence that is $2 C K$-spreading, where $C$ is the unconditional basis constant of $\left\{e_{n}\right\}$.

Definition 1.4.8. Let $\left\{x_{n}\right\}$ be a sequence in a Banach space $X$. We say that a sequence $\left\{e_{n}\right\}$ in a Banach space $Y$ is a spreading model of the sequence $\left\{x_{n}\right\}$ if for every $\varepsilon>0$ and $k \in \mathbb{N}$ there is $N \in \mathbb{N}$ such that

$$
(1-\varepsilon)\left\|\sum_{j=1}^{k} a_{j} e_{j}\right\| \leqslant\left\|\sum_{j=1}^{k} a_{j} x_{n_{j}}\right\| \leqslant(1+\varepsilon)\left\|\sum_{j=1}^{k} a_{j} e_{j}\right\|
$$

for all $N \leqslant n_{1}<n_{2}<\cdots<n_{k}$ and all scalars $a_{1}, \ldots, a_{k}$. If $\varepsilon_{k}=\frac{1}{2^{k}}, N_{k}=2^{k}$ we call $\left\{x_{n_{j}}\right\}_{j=1}^{\infty}$ a characteristic subsequence of $\left\{x_{n}\right\}_{n=1}^{\infty}$.

Theorem 1.4.9 (Brunel, Sucheston, [19]). Let X be a Banach space and suppose that $\left\{x_{n}\right\} \subset X$ is a bounded sequence such that $\left\{x_{n}\right\}_{n \in \mathbb{N}}$ is not relatively compact. Then $\left\{x_{n}\right\}$ has a subsequence with a spreading model.

The proof is based on a repeated use of the finite Ramsey theorem, and can be found in e.g. in [36], p. 294.

Proposition 1.4.10. Let $X$ be a Banach space and $\left\{x_{n}\right\} \subset X$ a weakly null sequence with a spreading model $\left\{e_{n}\right\}$. Then $\left\{e_{n}\right\}$ is a sub-symmetric basic sequence with the unconditional basis constant at most 2 .

The relation (1.8) below is the fundamental result of the theory of spreading models. It can be obtained from the previous results by passing to subsequences and diagonalizing.

Proposition 1.4.11 (Brunel, Sucheston, see [13]). Let $\left\{\varepsilon_{n}\right\}_{n=1}^{\infty}$ be a sequence of positive real numbers decreasing to zero, $\{N(k)\}_{k=1}^{\infty}$ be an increasing sequence of natural numbers and $\left\{x_{n}\right\}_{n=1}^{\infty}$ be a normalised basic sequence in a Banach space $X$. Then there exists a subsequence $\left\{y_{n}\right\}_{n=1}^{\infty}$ of $\left\{x_{n}\right\}_{n=1}^{\infty}$ and a Banach space $(Y,\| \| \cdot\| \|)$ with a spreading invariant basis $\left\{e_{n}\right\}_{n=1}^{\infty}$, such that, for all $k \in \mathbb{N}$ and all scalars $a_{j}, j=1, \ldots, N(k)$,

$$
\begin{equation*}
\left(1-\varepsilon_{k}\right)\left\|\sum_{j=1}^{N(k)} a_{j} e_{j}\right\|\|\leqslant\| \sum_{j=1}^{N(k)} a_{j} y_{n_{j}}\left\|\leqslant\left(1+\varepsilon_{k}\right)\right\| \sum_{j=1}^{N(k)} a_{j} e_{j}\| \| \tag{1.8}
\end{equation*}
$$

whenever $k \leqslant n_{1}<\cdots<n_{N(k)}$.

The following additional result will be made use of later on. We prefer to omit the standard proof of the estimate (1.9) concerning sub-symmetric polynomials, which can be obtained by modifying the proof of Theorem 1.4.9, by working simultaneously with the original norm $\|\cdot\|$ and $P$, and keeping in mind that $d$-homogeneous polynomials form a closed set in the topology of uniform convergence on the unit ball.

Theorem 1.4.12. Let $X$ be a Banach space, $P \in \mathcal{P}\left({ }^{d} X\right)$ and let $Y$ be the Banach space whose existence is guaranteed by Proposition 1.4.11. Then there exists a sub-symmetric polynomial $R \in \mathcal{P}\left({ }^{d} Y\right)$ such that, for all $k \in \mathbb{N}$, we have

$$
\begin{equation*}
R\left(\sum_{j=1}^{N(k)} a_{j} e_{j}\right)-\varepsilon_{k} \leqslant P\left(\sum_{j=1}^{N(k)} a_{j} y_{n_{j}}\right) \leqslant R\left(\sum_{j=1}^{N(k)} a_{j} e_{j}\right)+\varepsilon_{k} \tag{1.9}
\end{equation*}
$$

whenever $k \leqslant n_{1}<\cdots<N(k), \sum_{j=1}^{N(k)} a_{j} y_{n_{j}} \in B_{X}$.

It is clear that in general a basic sequence may admit many non-isomorphic spreading models. We say that $Y$ is a spreading model of $X$ provided $Y$ results as a spreading model built on some normalised basic sequence in $X$. The Ramsey theorems and the theory of spreading models allow us to infer the following useful result.

Theorem 1.4.13. Let $d, n \in \mathbb{N}$ and $\varepsilon>0$. There exists $N=N(d, n, \varepsilon)$ such that, for every $P \in \mathcal{P}\left({ }^{d} \ell_{1}^{N}\right),\|P\| \leqslant 1$, there exists $A \subset\{1, \ldots, N\},|A|=n$, and a subsymmetric polynomial $Q \in \mathcal{P}\left({ }^{d} Y\right)$ such that $\left\|P \upharpoonright_{Y}-Q\right\|<\varepsilon$, where $Y=\operatorname{span}\left\{e_{k}\right\}_{k \in A}$ and $\left\{e_{k}\right\}_{k=1}^{N}$ is the canonical basis of $\ell_{1}^{N}$.

Proof. Given $P \in \mathcal{P}\left({ }^{d} \ell_{1}^{N}\right)$ with $\|P\| \leqslant 1$, there are $a_{\alpha, \rho} \in \mathbb{R}$ such that $P=\sum_{\alpha \in \mathcal{J}+(d)} R_{\alpha}$, where

$$
\begin{equation*}
R_{\alpha}(x)=\sum_{\rho \in \mathcal{N}(k, N)} a_{\alpha, \rho} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{k}}^{\alpha_{k}} \tag{1.10}
\end{equation*}
$$

for $\alpha \in \mathcal{J}^{+}(k, d)$. By combining formulas (1.3), (1.4), (1.5) and the Polarization formula, we see that each $a_{\alpha, \rho}$ is such that $\left|a_{\alpha, \rho}\right|<\binom{d}{\alpha}\|\check{P}\| \leqslant d^{d}$.
We show that, for any $n \in \mathbb{N}, \varepsilon>0, K>0$ and $\alpha \in \mathcal{J}^{+}(d)$, there is $N=N_{\alpha}(n, \varepsilon, K)$ such that, for any polynomial $R \in \mathcal{P}\left({ }^{d} \ell_{1}^{N}\right)$ of the form (1.10), with $\left|a_{\alpha, \rho}\right| \leqslant K$, and for all $\rho \in \mathcal{N}(k, N)$, there is $A \subset\{1, \ldots, N\}$, $|A|=n$, and $c \in \mathbb{R}$ such that $\left\|R \upharpoonright_{Y}-c P_{\alpha}^{n}\right\|<\varepsilon$, where $Y=\operatorname{span}\left\{e_{k}\right\}_{k \in A}$. It is clear that we may take

$$
N(n, d, \varepsilon)=N_{\alpha^{v}}\left(\ldots N_{\alpha^{2}}\left(N_{\alpha^{1}}\left(n, \frac{\varepsilon}{v}, d^{d}\right), \frac{\varepsilon}{v}, d^{d}\right) \ldots, \frac{\varepsilon}{v}, d^{d}\right)
$$

where $\alpha^{1}, \ldots, \alpha^{v}$ is an enumeration of $\mathcal{J}^{+}(d)$.
So fix $\alpha \in \mathcal{J}^{+}(k, d), n \in \mathbb{N}, \varepsilon>0$ and $K>0$. Let $\delta=\frac{\varepsilon}{2 n!}$ and $M=$ $\left[\frac{K}{\delta}\right]$. By Ramsey's theorem there is $N \in \mathbb{N}$ such that, for every $2(M+1)$ colouring of $k$-subsets (i.e. subsets of cardinality $k$ ) of $\{1, \ldots, N\}$, there is $A \subset\{1, \ldots, N\},|A|=n$, such that all $k$-subsets of $A$ have the same colour. Now, given $R \in \mathcal{P}\left({ }^{d} \ell_{1}^{N}\right)$ of the form (1.10) with $\left|a_{\alpha, \rho}\right| \leqslant K$ for all $\rho \in$ $\mathcal{N}(k, N)$, we put $m(\rho)=\left[\frac{a_{\alpha, \rho}}{\delta}\right] \in\{-M-1,-M, \ldots, M\}$.
Note that $\left|a_{\alpha, \rho}-\delta m(\rho)\right|<\delta$. Each $\rho \in \mathcal{N}(k, N)$ uniquely determines a $k$-subset of $\{1, \ldots, N\}$ and vice versa, therefore the function $m$ induces a $2(M+1)$-colouring of the $k$-subsets of $\{1, \ldots, N\}$. Let $A \subset\{1, \ldots, N\}$,
$|A|=n$, be such that there is $m_{0} \in \mathbb{N}$ satisfying $m(\rho)=m_{0}$ for all $\rho \subset A$.
Then

$$
\left|R\left(\sum_{j \in A} x_{j} e_{j}\right)-\delta m_{0} P_{\alpha}^{n}\left(\sum_{j \in A} x_{j} e_{j}\right)\right| \leqslant \delta \sum_{\rho \subset A}\left|x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{k}}^{\alpha_{k}}\right| \leqslant \delta\binom{n}{k}<\varepsilon
$$

whenever $\left\|\sum_{j \in A} x_{j} e_{j}\right\| \leqslant 1$.

### 1.5 Algebras

In this thesis we are going to work with algebras $\mathcal{A}$ of polynomials on a Banach space $X$, i.e. subsets of $\mathcal{P}(X)$ that are closed with respect to addition, pointwise multiplication, and scalar multiplication.

Definition 1.5.1. Given an algebra $\mathcal{A} \subset \mathcal{P}(X)$, we say that the set $B \subset \mathcal{A}$ generates the algebra $\mathcal{A}$ if $\mathcal{A}$ is the smallest algebra containing $B$, i.e. it is the intersection of all algebras containing $B$.
It is easy to see that $B$ generates $\mathcal{A}$ if and only if for every $p \in \mathcal{A}$ there is a finite set $\left\{b_{1}, \ldots, b_{l}\right\} \subset B$ and a polynomial $P \in \mathcal{P}\left(\mathbb{R}^{l}\right)$ such that $p=P\left(b_{1}, \ldots, b_{l}\right)$.

Definition 1.5.2. Let $X$ be a Banach space.

- We denote by $\mathcal{A}_{n}(X)$ the algebra generated by polynomials from $\bigcup_{i=0}^{n} \mathcal{P}_{n}(X)$.
- The space of subsymmetric $d$-homogeneous polynomials on $\mathbb{R}^{N}$ will be denoted by $H_{d}\left(\mathbb{R}^{N}\right)$.
- We denote by $S_{k}\left(\mathbb{R}^{N}\right)$ the algebra of subsymmetric polynomials generated by the set of polynomials $\bigcup_{l=0}^{k} H_{l}\left(\mathbb{R}^{N}\right)$.


## Remark 1.5.3.

- Given $\alpha=\left(\alpha_{1}, \ldots, \alpha_{k}\right) \in \mathcal{J}(d)$ and $N \geqslant k$, we let

$$
\begin{equation*}
P_{\alpha}^{N}\left(\sum_{j=1}^{N} x_{j} e_{j}\right)=\sum_{1<\rho_{1}<\cdots<\rho_{k}} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{k}}^{\alpha_{k}} \tag{1.11}
\end{equation*}
$$

and set $P_{\varnothing}^{N}=1$. For $N \geqslant d$, the polynomials $P_{\alpha}^{N}$, for $\alpha \in \mathcal{J}(d)$, form a linear basis of $H_{d}\left(\mathbb{R}^{N}\right)$.

- As we pointed out, if $k \leqslant N$, then $H_{k}\left(\mathbb{R}^{N}\right)$ has a linear basis consisting of $P_{\alpha}^{N}, \alpha \in \mathcal{J}(k)$ (see (1.11)). In other words, $P \in H_{k}\left(\mathbb{R}^{n}\right)$ has the unique standard form

$$
\begin{equation*}
P\left(x_{1}, \ldots, x_{N}\right)=\sum_{\alpha \in \mathcal{Z}(k)} a_{\alpha} P_{\alpha}^{N}\left(x_{1}, \ldots, x_{N}\right), \quad a_{\alpha} \in \mathbb{R} \tag{1.12}
\end{equation*}
$$

- The spaces of subsymmetric polynomials $H_{k}\left(\mathbb{R}^{k}\right)$ and $H_{k}\left(\mathbb{R}^{N}\right), N>k$, are canonically isomorphic, as their linear bases can be indexed with the same set $\mathcal{J}(k)$.

The following result is the key lemma for proving plenty of results in [41]. Unfortunately, as we mentioned in the introduction, the theory of algebraic bases developed there is not entirely correct. Fortunately, the core of this theory, Lemma 1.5.4, can be proved otherwise. Its proof is treated in Chapter 2.

Lemma 1.5.4. For every $n \in \mathbb{N}$, there exists an $\varepsilon>0$ such that, for every $m \geqslant M(n)$,

$$
\sup _{\sum_{i=1}^{m}\left|x_{i}\right| \leqslant 1}\left|p\left(x_{1}, \ldots, x_{m}\right)-s_{n+1}\left(x_{1}, \ldots, x_{m}\right)\right| \geqslant \varepsilon,
$$

for every $p$ in the algebra $S_{n}\left(\mathbb{R}^{m}\right)$, generated by subsymmetric polynomials of degree at most $n$.

The above quantitative lemma implies the following fundamental criterion.

Theorem 1.5.5. Let $X$ be an infinite dimensional Banach space, $n \in \mathbb{N}$ and $P \in \mathcal{P}\left({ }^{n} X\right)$ be a polynomial with the following property: for every $N \in \mathbb{N}$ and $\varepsilon>0$ there exists a normalized finite basic sequence $\left\{e_{j}\right\}_{j=1}^{N}$ such that

$$
\sup _{\sum_{j=1}^{N}\left|a_{j}\right| \leqslant 1}\left|P\left(\sum_{j=1}^{N} a_{j} e_{j}\right)-\sum_{j=1}^{N} a_{j}^{n}\right| \leqslant \varepsilon .
$$

Then $P \notin \overline{\mathcal{A}_{n-1}(X)}$.
Proof. Denote by $S^{n}\left(\ell_{1}^{m}\right)$ the algebra generated by all sub-symmetric polynomials on $\ell_{1}^{m}$ of degree at most $n$. By Lemma 1.5.4, there are $m \in \mathbb{N}$ and $\varepsilon>0$ such that $\left\|Q-s_{n}\right\| \geqslant 3 \varepsilon$ for all $Q \in S^{n-1}\left(\ell_{1}^{m}\right)$. Let $P \in \mathcal{P}\left({ }^{n} X\right)$ be the polynomial whose existence is guaranteed by the assumptions of the theorem. We claim that $P \notin \overline{\mathcal{A}_{n-1}(X)}$.
By contradiction, suppose that there exist $P_{1}, \ldots, P_{k} \in \mathcal{P}^{n-1}(X)$ and $r \in$ $\mathcal{P}\left(\mathbb{R}^{k}\right)$ such that, for $R=r \circ\left(P_{1}, \ldots, P_{k}\right)$, we have $\|P-R\|<\varepsilon$. Put $K=1+\max _{j}\left\|P_{j}\right\|$ and let $0<\eta \leqslant 1$ be such that $|r(u)-r(v)|<\varepsilon$, whenever $u, v \in K B_{\ell_{\infty}^{k}},\|u-v\|_{\ell_{\infty}^{k}}<\eta$. Using Theorem 1.4.13 recursively $k n$ times, we find $N \in \mathbb{N}$ such that, for any linearly independent $\left\{e_{j}\right\}_{j=1}^{N} \subset$ $S_{X}$, there exist $A \subset\{1, \ldots, N\},|A|=m$, and sub-symmetric polynomials $Q_{1}, \ldots, Q_{k} \in \mathcal{P}^{n-1}(Y)$ such that $\left\|P_{j} \upharpoonright_{Y}-Q_{j}\right\|<\eta, j=1, \ldots, k$, where $Y=\operatorname{span}\left\{e_{j}\right\}_{j \in A}$ with $\ell_{1}$-norm.
Let $\left\{e_{j}\right\}_{j=1}^{N}$ be the linearly independent set from the assumptions of the theorem and $A \subset\{1, \ldots, N\}, Q_{1}, \ldots, Q_{k} \in \mathcal{P}^{n-1}(Y)$ as above. Note that since $\left\{e_{j}\right\}$ is normalized, $\left\|R \upharpoonright_{Y}-P \upharpoonright_{Y}\right\|_{Y} \leqslant\left\|R \upharpoonright_{Y}-P \upharpoonright_{Y}\right\|_{X}<\varepsilon$. Put $Q=$ $r \circ\left(Q_{1}, \ldots, Q_{k}\right)$. Then $Q \in S^{n-1}\left(\ell_{1}^{m}\right)$ and $\left\|Q-s_{n}\right\| \leqslant\left\|Q-R \upharpoonright_{Y}\right\|+$ $\left\|R \upharpoonright_{Y}-P \upharpoonright_{Y}\right\|+\left\|P \upharpoonright_{Y}-s_{n}\right\|<3 \varepsilon$, which is a contradiction.

### 1.6 Tensor products

This section is aimed at collecting basic definitions and elementary facts concerning tensor products. Tensor products offer an important point of view on polynomials and multilinear mappings.

Definition 1.6.1. Let $X_{1}, \ldots, X_{n}$ be vector spaces over $\mathbb{K}$.

- By $\Lambda$ we denote the vector space of all formal linear combinations $\sum_{k=1}^{N} a_{k}\left(x_{1}^{k} \otimes \cdots \otimes x_{n}^{k}\right), a_{k} \in \mathbb{K}, x_{j}^{k} \in X_{j}$.
- By $\Lambda_{0}$ we denote the linear subspace of $\Lambda$ spanned by the vectors

$$
a\left(x_{1} \otimes \cdots \otimes x_{n}\right)-\left(x_{1} \otimes \cdots \otimes a x_{k} \otimes \cdots \otimes x_{n}\right)
$$

and
$\left(x_{1} \otimes \cdots \otimes\left(x_{k}+y_{k}\right) \otimes \cdots \otimes x_{n}\right)-\left(x_{1} \otimes \cdots \otimes x_{k} \otimes \cdots \otimes x_{n}\right)-\left(x_{1} \otimes \cdots \otimes y_{k} \otimes \cdots \otimes x_{n}\right)$,
where $k \in\{1, \ldots, n\}, x_{j}, y_{j} \in X_{j}, a \in \mathbb{K}$.

- The quotient space $\frac{\Lambda}{\Lambda_{0}}$ is called tensor product of $X_{1}, \ldots, X_{n}$ and will be denoted by

$$
X_{1} \otimes \cdots \otimes X_{n}=\bigotimes_{j=1}^{n} X_{j} .
$$

## Remark 1.6.2.

- By the definition of $\Lambda_{0}$, each $z \in X_{1} \otimes \cdots \otimes X_{n}$ has a representation

$$
z=\sum_{j=1}^{k} x_{1}^{j} \otimes \cdots \otimes x_{n}^{j}
$$

An element of $X_{1} \otimes \cdots \otimes X_{n}$ that admits a representation $x_{1} \otimes \cdots \otimes x_{n}$ is called elementary tensor.

- Given $\phi_{j} \in X_{j}^{\prime},{ }^{8}$ the function

$$
\begin{equation*}
\sum_{j=1}^{k} a_{j}\left(x_{1}^{j} \otimes \cdots \otimes x_{n}^{j}\right) \mapsto \sum_{j=1}^{k} a_{j} \phi_{1}\left(x_{1}^{j}\right) \cdots \phi_{n}\left(x_{n}^{j}\right) \tag{1.13}
\end{equation*}
$$

is a linear form on the vector space $\Lambda$.

We can infer a useful criterion for distinguishing vectors in a tensor product.

[^7]Proposition 1.6.3. Let $X_{1}, \ldots, X_{n}$ be vector spaces and $A_{j} \subset X_{j}^{\prime}$ be subsets that separate the points of $X_{j}, j=1, \ldots, k$. Then $\sum_{j=1}^{k} a_{j} x_{1}^{j} \otimes \cdots \otimes x_{n}^{j}=0$ in $X_{1} \otimes \cdots \otimes X_{n}$ if and only if

$$
\sum_{j=1}^{k} a_{j} \phi_{1}\left(x_{1}^{j}\right) \cdots \phi_{n}\left(x_{n}^{j}\right)=0
$$

for every choice of $\phi_{j} \in A_{j}$.
Definition 1.6.4. By $\otimes$ we define the $n$-linear mapping $\otimes: X_{1} \times \cdots \times X_{n} \longrightarrow$ $\otimes_{j=1}^{n} X_{j}$ such that $\otimes\left(x_{1}, \ldots, x_{n}\right)=x_{1} \otimes \cdots \otimes x_{n}$.

Theorem 1.6.5 (Universality of tensor products - algebraic setting). Let $X_{1}, \ldots, X_{n}, Y$ be vector spaces. For every $n$-linear mapping $M \in L\left(X_{1}, \ldots, X_{n} ; Y\right)$ there exists a unique linear operator $L_{M} \in L\left(X_{1} \otimes \cdots \otimes X_{n} ; Y\right)$ such that $M=L_{M} \circ \otimes:$


The operator $L_{M}$ satisfies

$$
\begin{equation*}
L_{M}\left(x_{1} \otimes \cdots \otimes x_{n}\right)=M\left(x_{1}, \ldots, x_{n}\right) \tag{1.14}
\end{equation*}
$$

$L_{M}$ is therefore called the linearization of $M$.
Theorem 1.6.6. Let $X_{1}, \ldots, X_{n}$ be vector spaces. For $M \in L\left(X_{1}, \ldots, X_{n} ; \mathbb{K}\right)$ and $z=\sum_{j=1}^{k} x_{1}^{j} \otimes \cdots \otimes x_{n}^{j} \in X_{1} \otimes \cdots \otimes X_{n}$ put

$$
\langle M, z\rangle=\sum_{j=1}^{k} M\left(x_{1}^{j}, \ldots, x_{n}^{j}\right)=\sum_{j=1}^{k} L_{M}\left(x_{1}^{j} \otimes \cdots \otimes x_{n}^{j}\right)=L_{M}(z)
$$

Then $\left\langle L\left(X_{1}, \ldots, X_{n} ; \mathbb{K}\right), X_{1} \otimes \cdots \otimes X_{n}\right\rangle$ forms a dual pair.
We will now introduce an important example of natural norm on tensor products of Banach spaces (see [57]).

Definition 1.6.7. Let $X_{1}, \ldots, X_{n}$ be normed linear spaces.

- The projective tensor norm $\pi$ on $X_{1} \otimes \cdots \otimes X_{n}$ is defined by the formula

$$
\pi(z)=\sup \left\{|\langle M, z\rangle|: M \in \mathcal{L}\left(X_{1}, \ldots, X_{n} ; \mathbb{K}\right),\|M\| \leqslant 1\right\}, z \in X_{1} \otimes \cdots \otimes X_{n}
$$

- The projective tensor product, denoted by $X_{1} \otimes_{\pi} \cdots \otimes_{\pi} X_{n}$, is the completion of the normed linear space $\left(X_{1} \otimes \cdots \otimes X_{n}, \pi\right)$.

Proposition 1.6.8. Let $X_{1}, \ldots, X_{n}$ be normed linear spaces. Then, for any $z \in X_{1} \otimes_{\pi} \cdots \otimes_{\pi} X_{n}$ there exist bounded sequences $\left\{x_{l}^{j}\right\}_{j=1}^{\infty} \subset X_{l}, l=1, \ldots, n$, such that $z=\sum_{j=1}^{\infty} x_{1}^{j} \otimes \cdots \otimes x_{n}^{j}$ is an absolute convergent series and

$$
\pi(z)=\inf \left\{\sum_{j=1}^{\infty}\left\|x_{1}^{j}\right\| \cdots\left\|x_{n}^{j}\right\|: z=\sum_{j=1}^{\infty} x_{1}^{j} \otimes \cdots \otimes x_{n}^{j}\right\} .
$$

Furthermore, $\pi\left(x_{1} \otimes \cdots \otimes x_{n}\right)=\left\|x_{1}\right\| \cdots\left\|x_{n}\right\|$ for every $x_{j} \in X_{j}, j=1, \ldots, n$.
This implies that $\otimes: X_{1} \times \cdots \times X_{n} \longrightarrow X_{1} \otimes_{\pi} \cdots \otimes_{\pi} X_{n}$ is a bounded $n$ linear mapping of norm 1. It follows that the projective norm is defined so that the universality property of the tensor product remains valid also in the topological sense:

Theorem 1.6.9 (Universality of the tensor product - topological setting). Let $X_{1}, \ldots, X_{n}, Y$ be normed linear spaces. For every $M \in \mathcal{L}\left(X_{1}, \ldots, X_{n} ; Y\right)$ there exists a unique $L_{M} \in \mathcal{L}\left(X_{1} \otimes_{\pi} \cdots \otimes_{\pi} X_{n} ; Y\right)$ such that $M=L_{M} \circ \otimes$ :


The operator $L_{M}$ satisfies (1.14) and the mapping $M \mapsto L_{M}$ is an isometry of the spaces $\mathcal{L}\left(X_{1}, \ldots, X_{n} ; Y\right)$ and $\mathcal{L}\left(X_{1} \otimes_{\pi} \cdots \otimes_{\pi} X_{n} ; Y\right)$.

Note that, if $Y=\mathbb{K}$, we obtain the following (simple but important) duality relation.

Theorem 1.6.10. Let $X_{1}, \ldots, X_{n}$ be normed linear spaces. Then

$$
\left(X_{1} \otimes_{\pi} \cdots \otimes_{\pi} X_{n} ; Y\right)^{*}=\mathcal{L}\left(X_{1}, \ldots, X_{n} ; \mathbb{K}\right) .
$$

Whenever $n=2$, observe that $\mathcal{L}\left(X_{1}, X_{2} ; \mathbb{K}\right)=\mathcal{L}\left(X_{1} ; X_{2}^{*}\right)$. This leads to an equivalent dual representation.

Fact 1.6.11. Let $X, Y$ be normed linear spaces. Then

$$
\left(X \otimes_{\pi} Y\right)^{*}=\mathcal{L}\left(X ; Y^{*}\right),
$$

where the evaluation is given by $\langle L, x \otimes y\rangle=L(x)(y)$.

We conclude this section by introducing symmetric tensor products, which turn out to have a close relationship with polynomials.

Definition 1.6.12. Let $X$ be a normed linear space.

- The symmetrization $\otimes_{s}: X \times \cdots \times X \longrightarrow X \otimes \cdots \otimes X$ is a symmetric $n$-linear mapping given by

$$
\otimes_{s}\left(x_{1}, \ldots, x_{n}\right)=\frac{1}{n!} \sum_{\eta \in S_{n}} \otimes\left(x_{\eta(1)}, \ldots, x_{\eta(n)}\right)=\frac{1}{n!} \sum_{\eta \in S_{n}} x_{\eta(1)} \otimes \cdots \otimes x_{\eta(n)}
$$

where $S_{n}$ is the set of all permutations of $\{1, \ldots, n\}$.
We also use the notation $\otimes_{s}\left(x_{1}, \ldots, x_{n}\right)=x_{1} \otimes_{s} \cdots \otimes_{s} x_{n}$ and $\otimes^{n} x=$ $\otimes\left({ }^{n} x\right)=x \otimes \cdots \otimes x$.

The Polarization formula yields that $\otimes_{s}^{n} X=\operatorname{span}\left\{\otimes^{n} x: x \in X\right\}$.

- The space $\otimes_{s}^{n} X$ is called symmetric tensor product and the elements of $\otimes_{s}^{n} X$ are called symmetric tensors.

When $\otimes_{s}^{n} X$ is equipped with the projective norm inherited from its superspace $\otimes_{\pi}^{n} X$, its completion becomes a closed subspace $\otimes_{\pi, s}^{n} X$ of $\otimes_{\pi}^{n} X$. Then the linearization $\sigma_{X}^{n}: \otimes_{\pi}^{n} X \longrightarrow \otimes_{\pi, s}^{n} X$ of $\otimes_{s}$ is a projection of norm 1. Thus the following result holds.

Theorem 1.6.13 (Universality of the symmetric tensor product). Let $X, Y$ be normed linear spaces. For every symmetric $M \in \mathcal{L}^{s}\left({ }^{n} X ; Y\right)$ there exists a unique $L_{M} \in \mathcal{L}\left(\otimes_{\pi, s}^{n} X ; Y\right)$ such that $M=L_{M} \circ \otimes_{s}=L_{M} \circ \sigma_{X}^{n} \circ \otimes$.


The mapping $M \mapsto L_{M}$ is an isometry of the spaces $\mathcal{L}^{s}\left({ }^{n} X ; Y\right)$ and $\mathcal{L}\left(\otimes_{\pi, s}^{n} X ; Y\right)$.
Corollary 1.6.14. Let $X, Y$ be normed linear spaces. Then the spaces $\mathcal{P}\left({ }^{n} X ; Y\right)$ and $\mathcal{L}\left(\otimes_{\pi, s}^{n} X ; Y\right)$ are canonically isomorphic.

In particular,

$$
\left(\otimes_{\pi, s}^{n} X\right)^{*}=\mathcal{P}\left({ }^{n} X\right)
$$

in the isomorphic sense, where the evaluation is given by $\left\langle P, \otimes^{n} x\right\rangle=P(x)$. More generally,

$$
\left(\left(\otimes_{\pi, s}^{n} X\right) \otimes_{\pi} Y\right)^{*}=\mathcal{L}\left(\otimes_{\pi, s}^{n} X ; Y^{*}\right)=\mathcal{P}\left({ }^{n} X ; Y^{*}\right)
$$

in the isomorphic sense, where the evaluation is given by $\left\langle P, \otimes^{n} x \otimes y\right\rangle=$ $P(x)(y)$.

### 1.7 Weak continuity and polynomials into $\ell_{1}$

We will now provide the reader with a list of various notions of weak continuity, which play a key role in our investigations, some of which have been introduced and studied by R. M. Aron and his co-authors, e.g. in [3], [6] and [8]; see also [30].

Definition 1.7.1. Let $X$ be a normed linear space, $Y$ a Banach space and $U \subset X$ a convex set.

- By $\mathcal{C}(U ; Y)$ we denote the space $C(U ; Y)$ endowed with the locally convex topology $\tau_{b}$ of uniform convergence on $\mathrm{CCB}^{9}$ subsets of $U .{ }^{10}$
- By $\mathcal{C}_{w}(U ; Y)$ we denote the linear subspace of $\mathcal{C}(U ; Y)$ consisting of all mappings that are $w-\|\cdot\|$ continuous on CCB subsets of $U$.
- By $\mathcal{C}_{w u}(U ; Y)$ we denote the linear subspace of $\mathcal{C}(U ; Y)$ consisting of all mappings that are $w-\|\cdot\|$ uniformly continuous on CCB subsets of $U .{ }^{11}$
- By $\mathcal{C}_{w s c}(U ; Y)$ we denote the linear subspace of $\mathcal{C}(U ; Y)$ consisting of all mappings that are $w-\|\cdot\|$ sequentially continuous on CCB subsets

[^8]of $U$, i.e. that map weakly convergent sequences in CCB subsets of $U$ to convergent sequences in $Y$.

- By $\mathcal{C}_{w s C}(U ; Y)$ we denote the linear subspace of $\mathcal{C}(U ; Y)$ consisting of all mappings that are $w-\|\cdot\|$ sequentially Cauchy-continuous on CCB subsets of $U$, i.e. that map weakly Cauchy sequences in CCB subsets of $U$ to convergent sequences in $Y$.
- By $\mathcal{C}_{K}(U ; Y)$ we denote the linear subspace of $\mathcal{C}(U ; Y)$ consisting of all mappings that map CCB subsets of $U$ to relatively compact sets in $Y$.
- By $\mathcal{C}_{w K}(U ; Y)$ we denote the linear subspace of $\mathcal{C}(U ; Y)$ consisting of all mappings that map CCB subsets of $U$ to relatively weakly compact sets in $Y$.


## Remark 1.7.2.

- When the range space is the scalar field, we simply omit it, e.g. $\mathcal{C}_{w s c}(U)=\mathcal{C}_{w s c}(U ; \mathbb{K})$.
- If we substitute CCB sets in the above definitions with bounded sets, $\mathcal{C}_{w s c}(U ; Y)\left(\right.$ resp. $\left.\mathcal{C}_{w s C}(U ; Y)\right)$ are just $w-\|\cdot\|$ sequentially continuous (resp. $w-\|\cdot\|$ sequentially Cauchy-continuous) mappings on $U$.
- If $X^{*}$ is separable, it is well-known that $\left(B_{X}, w\right)$ is metrizable, thus $\mathcal{C}_{w s c}(U ; Y)=\mathcal{C}_{w}(U ; Y)$ and $\mathcal{C}_{w s C}(U ; Y)=\mathcal{C}_{w u}(U ; Y)$.
- $\mathcal{C}_{w}(U ; Y), \mathcal{C}_{w u}(U ; Y), \mathcal{C}_{w s c}(U ; Y), \mathcal{C}_{w s C}(U ; Y)$ and $\mathcal{C}_{K}(U ; Y)$ are closed subspaces of $\mathcal{C}(U ; Y)$.
- If $Y$ is any Banach space and $U$ is any convex subset of a normed linear space $X$, the following inclusions hold true:

$$
\begin{array}{rll} 
& \subset \mathcal{C}_{K}(U ; Y) & \subset \mathfrak{C}_{w K}(U ; Y) \\
\mathcal{C}_{w u}(U ; Y) & \subset \mathcal{C}_{w}(U ; Y) & \subset \mathfrak{C}_{w s c}(U ; Y) \\
& \subset \mathcal{C}_{w s C}(U ; Y) & \subset
\end{array}
$$

Corollary 1.7.3 ([6]). Let $X$ be a normed linear space, $Y$ a Banach space and $n \in \mathbb{N}$. Then

$$
\begin{aligned}
\mathcal{L}_{w}\left({ }^{n} X ; Y\right) & =\mathcal{L}_{w u}\left({ }^{n} X ; Y\right), \\
\mathcal{L}_{w s c}\left({ }^{n} X ; Y\right) & =\mathcal{L}_{w s C}\left({ }^{n} X ; Y\right), \\
\mathcal{P}_{w}\left({ }^{n} X ; Y\right) & =\mathcal{P}_{w u}\left({ }^{n} X ; Y\right), \\
\mathcal{P}_{w s c}\left({ }^{n} X ; Y\right) & =\mathcal{P}_{w s C}\left({ }^{n} X ; Y\right) .
\end{aligned}
$$

From this and the relations shown earlier we obtain the following inclusions:

$$
\begin{gathered}
\subset \mathcal{P}_{K}(X ; Y) \subset \mathcal{P}_{w K}(X ; Y) \\
\mathcal{P}_{w u}(X ; Y)=\mathcal{P}_{w}(X ; Y) \subset \mathcal{P}_{w s c}(X ; Y)=\mathcal{P}_{w s C}(X ; Y) \\
\\
\subset \mathcal{L}_{w K}(X ; Y) \\
\mathcal{L}_{w u}(X ; Y)=\mathcal{L}_{K}(X ; Y)=\mathcal{L}_{w} \subset \mathcal{L}_{w s c}(X ; Y)=\mathcal{L}_{w s C}(X ; Y)
\end{gathered}
$$

Remark 1.7.4. It is not sufficient to check the $w-\|\cdot\|$ continuity of polynomials only at the origin, ${ }^{12}$ as shown by the following example by Aron in [4]..$^{13}$
Let $P \in \mathcal{P}\left({ }^{3} \ell_{2}\right)$ be defined as $P(x)=x_{1} \sum_{n=2}^{\infty} x_{n}^{2}$. Then the restriction of $P$ to any bounded set is weakly continuos at the origin, but $P$ is not weakly sequentially continuous. Indeed, $e_{1}+e_{1} \xrightarrow{w} e_{1}$ but $P\left(e_{1}+e_{n}\right)=1$ and $P\left(e_{1}\right)=0$.

Let $X, Y$ be Banach spaces. Recall the duality relationship treated in the previous section:

$$
\begin{equation*}
\left(\left(\otimes_{\pi, s}^{n} X\right) \otimes_{\pi} Y\right)^{*}=\mathcal{L}\left(\otimes_{\pi, s}^{n} X ; Y^{*}\right)=\mathcal{P}\left({ }^{n} X ; Y^{*}\right) \tag{1.15}
\end{equation*}
$$

As special cases, we of course have $\left(\otimes_{\pi, s}^{n} X\right)^{*}=\mathcal{P}\left({ }^{n} X\right),\left(X \otimes_{\pi} Y\right)^{*}=$ $\mathcal{L}\left(X ; Y^{*}\right)$. Recall a result by Bessaga and Pełczyński ([36] p. 206). Let $X$ be a Banach space, $c_{0} \hookrightarrow X^{*}$. Then $X$ contains a complemented copy of $\ell_{1}$ (and hence $X^{*}$ actually contains a complemented copy of $\ell_{\infty}$ ). Applying this result to the duality relation (1.15) we get the next (probably known) result.

[^9]Theorem 1.7.5. Let $X$ be a Banach space. The following are equivalent for $n \in \mathbb{N}$.

1. $\mathcal{P}_{K}\left({ }^{n} X ; \ell_{1}\right)=\mathcal{P}\left({ }^{n} X ; \ell_{1}\right)$,
2. $c_{0} \leftrightarrow \mathcal{P}\left({ }^{n} X\right)$.

Proof. Suppose 2 fails. Since $\left(\otimes_{\pi, s}^{n} X\right)^{*}=\mathcal{P}\left({ }^{n} X\right), \ell_{1}$ is complemented in $\otimes_{\pi, s}^{n} X$ by the Bessaga- Pełczyński theorem. Hence $\ell_{1}$ is a range of a bounded linear operator from $\otimes_{\pi, s}^{n} X$ and 1 fails by the universality of the projective symmetric tensor product. On the other hand, if 1 fails, then there is a non-compact bounded linear operator $T: \otimes_{\pi, s}^{n} X \rightarrow \ell_{1}$.
Setting $B=T\left(B_{\otimes_{\pi}^{n}, s} X\right)$, we claim that $B$ contains $B_{\ell_{1}}$ (up to isomorphism). Indeed, since $B$ is not relatively compact, $\bar{B}$ is not weakly compact ([36] p. 277). By the Eberlein-Šmulyan theorem, there exists a bounded sequence $\left\{x_{n}\right\} \subseteq B$ with no weakly convergent subsequences, which cannot be weakly Cauchy either (Schur). Thus, by Rosenthal's $\ell_{1}$-theorem, $\left\{x_{n}\right\}$ admits a subsequence equivalent to the usual $\ell_{1}$-basis, which proves the claim.
Finally, using the lifting property of $\ell_{1}$ ([36] p. 238), $\ell_{1}$ is a complemented subspace of $\otimes_{\pi, s}^{n} X$, whence 2 fails by duality.

We will need two principles for passing to suitable sequences in the domain. The first one is based on an improvement of the classical result that $\ell_{2}$ is a linear quotient of any Banach space containing a copy of $\ell_{1}$.

Lemma 1.7.6. Let $X$ be a Banach space, $\ell_{1} \hookrightarrow X, p \geqslant 2$. Then there exists $T \in \mathcal{L}\left(X ; \ell_{p}\right)$ and a basic sequence $\left\{f_{j}\right\}$ in $X$ equivalent to $\ell_{1}$ basis such that $T\left(f_{j}\right)=e_{j}$ is the unit basis in $\ell_{p}$.

Proof. It suffices to prove the result for $p=2$, since then we can compose $T$ with the formal identity $I d: \ell_{2} \rightarrow \ell_{p}$, which is a bounded linear operator. Let $L: \ell_{2} \hookrightarrow L_{1}$ be an isomorphic embedding, $\left\{e_{j}\right\}$ be the basis of $\ell_{2}$. By Pełczyński-Hagler, [46] p. 253, there is an isomorphic embedding $M: L_{1} \hookrightarrow$ $X^{*}$. So $\left\{y_{j}=M \circ L\left(e_{j}\right)\right\}$ is a weakly null sequence in $X^{*}$, which is equivalent to the $\ell_{2}$ basis. There is a normalized sequence $\left\{\tilde{f}_{j}\right\} \in X^{* *}$ biorthogonal to $M \circ L\left(e_{j}\right)$. By Goldstine's theorem we replace $\tilde{f}_{j}$ by $f_{j} \in B_{X}$ so that $\left\langle f_{j}, y_{k}\right\rangle=0, k \leqslant j,\left\langle f_{j}, y_{j}\right\rangle=1$. Since $\left\{y_{j}\right\}$ is weakly null, we can pass to subsequences so that $\left\{f_{j}, y_{j}\right\}$ is a biorthogonal system. Since $M^{*}(X) \subset$
$L_{\infty}$ and $\left\{L\left(e_{j}\right), M^{*}\left(f_{j}\right)\right\}$ is a biorthogonal system in $L_{1}, L_{\infty}$, by the DPP property of $L_{1},\left\{M^{*}\left(f_{j}\right)\right\}$ does not contain a weakly Cauchy subsequence. By Rosenthal's $\ell_{1}$-theorem, we may assume without loss of generality that it is an $\ell_{1}$-basis. By the lifting property of $\ell_{1},\left\{f_{j}\right\}$ is an $\ell_{1}$-basis. Finally, $R=L^{*} \circ M^{*}: X^{* *} \rightarrow \ell_{2}$ is a quotient mapping such that $R\left(f_{j}\right)=e_{j}$. So $T=R \upharpoonright_{X}: X \rightarrow \ell_{2}$ is the desired operator.

In particular, let $X$ be a Banach space, $\ell_{1} \hookrightarrow X$. Then there is a $P \in$ $\mathcal{P}\left({ }^{2} X ; \ell_{1}\right)$ such that it takes a sequence $\left\{f_{j}\right\}$ in $X$, equivalent to an $\ell_{1}$-basis, into $\left\{e_{j}\right\}$ a unit basis in the range $\ell_{1}$.

Proposition 1.7.7. Let $X$ be a Banach space, $\ell_{1} \hookrightarrow X, k \in \mathbb{N}, k \geqslant 2$. Then there exists a polynomial $P \in \mathcal{P}\left({ }^{k} X\right)$ and a basic sequence $\left\{f_{j}\right\}$ in $X$ equivalent to an $\ell_{1}$-basis such that

$$
\begin{equation*}
P\left(\sum_{j=1}^{\infty} a_{j} f_{j}\right)=\sum_{j=1}^{\infty} a_{j}^{k} \tag{1.16}
\end{equation*}
$$

In particular, $P$ is not weakly continuous at the origin and

$$
\mathcal{P}_{w u}\left({ }^{k} X\right) \neq \mathcal{P}\left({ }^{k} X\right)
$$

Proof. Let $T$ and $\left\{f_{j}\right\}$ be as above and let $\left\{g_{j}\right\}$ be the sequence of the coordinate functionals on $\ell_{k}$. Letting $P(x)=\sum_{j=1}^{\infty}\left(g_{j}(T(x))\right)^{k}$ proves (1.16). Assume by contradiction that $P$ is weakly continuous, so given $\varepsilon>0$ there exist $\phi_{1}, \ldots, \phi_{n} \in X^{*}$ and $\delta>0$ such that $\left|\phi_{j}(x)\right|<\delta, j=1, \ldots, n$, implies $|P(x)|<\varepsilon$. We have that $\phi_{j} \upharpoonright_{\left[f_{j}\right]} \in \ell_{\infty}$. By a simple argument there exist pairwise distinct indices $m, l, r$ such that

$$
\left|\phi_{j}\left(f_{m}\right)-\phi_{j}\left(f_{l}\right)\right|,\left|\phi_{j}\left(f_{m}\right)-\phi_{j}\left(f_{r}\right)\right|<\delta, j=1, \ldots, n
$$

So choosing $\varepsilon>0$ small enough and letting $x=f_{m}-\frac{1}{2} f_{l}-\frac{1}{2} f_{r}$ clearly witnesses the contradiction.

We will need a modification of a well-known principle for dealing with nonweakly sequentially continuous polynomials of minimal degree, which has been used many times in the literature (see e.g. [20] for its most general formulation). In our case, we replace the non-wsc property by the noncompactness and add the assumption $\ell_{1} \leftrightarrow X$.

Lemma 1.7.8. Let $X, Y$ be Banach spaces, $\ell_{1} \leftrightarrows X, \mathcal{P}\left({ }^{k} X ; Y\right)=\mathcal{P}_{K}\left({ }^{k} X ; Y\right)$ for all $k<n$ and $P \in \mathcal{P}\left({ }^{n} X ; Y\right) \backslash \mathcal{P}_{K}\left({ }^{n} X ; Y\right)$. Then there is a weakly null sequence $\left\{y_{k}\right\}_{k=1}^{\infty}$ such that $\left\{P\left(y_{k}\right)\right\}_{k=1}^{\infty}$ is not relatively compact.

Proof. By Rosenthal's $\ell_{1}$-theorem, there is a $\delta>0$ and a weakly Cauchy sequence $\left\{x_{k}\right\}_{k=1}^{\infty}$ such that

$$
\begin{equation*}
\left\|P\left(x_{k}\right)-P\left(x_{l}\right)\right\|>\delta, \quad k \neq l \in \mathbb{N} \tag{1.17}
\end{equation*}
$$

By a simple application of the multilinearity of $\check{P}$,

$$
P\left(x_{k}-x_{l}\right)=P\left(x_{k}\right)+\sum_{j=1}^{n-1}\binom{n}{j}(-1)^{j} \check{P}\left({ }^{j} x_{l},{ }^{n-j} x_{k}\right)+(-1)^{n} P\left(x_{l}\right)
$$

By assumption, all polynomials of degree less than $n$ are compact, so for any fixed $k$, passing to a subset of indices $N_{k} \subset N_{k-1}, N_{0}=\mathbb{N}$, there exist the limits

$$
y_{k}^{j}=\lim _{l \in N_{k}} \check{P}\left({ }^{j} x_{l},{ }^{n-j} x_{k}\right), \quad j=1, \ldots, n-1 .
$$

Let $M$ be the diagonal set of $N_{k}, k \in \mathbb{N}$. Next, fix for each $k \in M$, an $m_{k}$ such that for all $j \in\{1, \ldots, n-1\}$

$$
\left\|y_{k}^{j}-\check{P}\left({ }^{j} x_{l},{ }^{n-j} x_{k}\right)\right\|<\frac{\delta}{20 n^{n+1}}, \quad l \geqslant m_{k}, l \in M
$$

Then

$$
\left\|P\left(x_{k}-x_{l}\right)-\left(P\left(x_{k}\right)+\sum_{j=1}^{n-1}\binom{n}{j}(-1)^{j} y_{k}^{j}+(-1)^{n} P\left(x_{l}\right)\right)\right\|<\frac{\delta}{20},
$$

whenever $l \geqslant m_{k}, l \in M$.
Whence,

$$
\left.\| P\left(x_{k}-x_{l}\right)-P\left(x_{k}\right)-(-1)^{n} P\left(x_{l}\right)-\left(\sum_{j=1}^{n-1}\binom{n}{j}(-1)^{j} y_{k}^{j}\right)\right) \|<\frac{\delta}{20},
$$

for $l \geqslant m_{k}, l \in M$.
Thus
$\left\|P\left(x_{k}-x_{l}\right)-P\left(x_{p}-x_{r}\right)\right\| \geqslant\left\|P\left(x_{k}\right)-(-1)^{n} P\left(x_{l}\right)-P\left(x_{p}\right)+(-1)^{n} P\left(x_{r}\right)\right\|-\frac{\delta}{10}$,
whenever $k, p \in \mathbb{N}, l, r \in M, l \geqslant m_{k}$ and $r \geqslant m_{p}$.
Suppose that $k, l, p \in \mathbb{N}$ are given and denote

$$
z=(-1)^{n} P\left(x_{k}\right)+P\left(x_{l}\right)-(-1)^{n} P\left(x_{p}\right)
$$

Using (1.17), there is an $r_{k, l, p} \in \mathbb{N}$ such that $\left\|P\left(x_{r}\right)-z\right\| \geqslant \frac{\delta}{2}$ for all $r \geqslant r_{k, l, p}$. Whence

$$
\left\|P\left(x_{k}-x_{l}\right)-P\left(x_{p}-x_{r}\right)\right\| \geqslant \frac{\delta}{2}-\frac{\delta}{10}>\frac{\delta}{4}
$$

whenever $k, p \in \mathbb{N}, l, r \in M, l \geqslant m_{k}$ and $r \geqslant \max \left\{m_{p}, r_{k, l, p}\right\}$.
Now it suffices to find $l_{k} \in M$ such that $l_{k} \geqslant \max \left\{m_{k}, r_{1, l_{1}, k}, \ldots, r_{k-1, l_{k-1}, k}\right\}$ and put $y_{k}=x_{k}-x_{l_{k}}$. Then $\left\{y_{k}\right\}$ is weakly null and $\left\{P\left(y_{k}\right)\right\}$ is a $\frac{\delta}{4}$-separated sequence.

Proposition 1.7.9 ([44]). Let $X$ be a Banach space, $Y=\ell_{p}, 1 \leqslant p<\infty$, or $Y=c_{0}$ and suppose there is a non-compact operator $T \in \mathcal{L}(X ; Y)$. Then there are $S \in \mathcal{L}(X ; Y)$ and a normalized basic sequence $\left\{x_{n}\right\} \subset X$ such that $S\left(x_{n}\right)=e_{n}, n \in \mathbb{N}$, where $\left\{e_{n}\right\}$ is the canonical basis of $Y$. If $X$ does not contain $\ell_{1}$, then $\left\{x_{n}\right\}$ may be chosen to be weakly null. If $X=\ell_{1}$, then $S$ is in fact onto.

Definition 1.7.10. Let $1 \leqslant p, q \leqslant \infty$. We say that a sequence $\left\{x_{j}\right\}_{j=1}^{\infty}$ in a Banach space over $\mathbb{K}$ has an upper $p$-estimate (resp. lower $q$-estimate) if there exists $C>0$ such that for every $n \in \mathbb{N}$ and every $a_{1}, \ldots, a_{n} \in \mathbb{K}$

$$
\begin{equation*}
\left\|\sum_{j=1}^{n} a_{j} x_{j}\right\| \leqslant C\left(\sum_{j=1}^{n}\left|a_{j}\right|^{p}\right)^{\frac{1}{p}} \tag{1.18}
\end{equation*}
$$

respectively

$$
\left\|\sum_{j=1}^{n} a_{j} x_{j}\right\| \geqslant C\left(\sum_{j=1}^{n}\left|a_{j}\right|^{q}\right)^{\frac{1}{q}}
$$

where the right-hand side is replaced by $\max _{j=1, \ldots, n}\left|a_{j}\right|$ if $p=\infty$ or $q=\infty$.
Fact 1.7.11. Let $X$ be a Banach space and $1 \leqslant p, q \leqslant \infty$. A sequence $\left\{x_{j}\right\}_{j=1}^{\infty} \subset X$ has an upper $p$-estimate if and only if the linear operator $T: \ell_{p} \longrightarrow X, T\left(e_{j}\right)=x_{j}$ is bounded. A sequence $\left\{x_{j}\right\}_{j=1}^{\infty} \subset X$ has a lower $q$-estimate if and only if the linear operator $T: \operatorname{span}\left\{x_{j}\right\} \longrightarrow \ell_{q}, T\left(x_{j}\right)=e_{j}$ is bounded. In case $p=\infty$ we replace $\ell_{p}$ by $c_{0}$ and analogously for $q=\infty$.

Corollary 1.7.12 ([38]). Let $X$ be a Banach space such that $X^{*}$ is of type $p>1, \frac{1}{p}+\frac{1}{q}=1$ and let $\left\{x_{k}\right\}_{k=1}^{\infty} \subset X$ be a semi-normalized basic sequence. Then for each $s>q$ there is a subsequence $\left\{x_{n_{k}}\right\}_{k=1}^{\infty}$ such that there exists a bounded linear operator $T: X \longrightarrow \ell_{s}$ satisfying $T\left(x_{n_{k}}\right)=e_{k}$, where $\left\{e_{k}\right\}$ is the canonical basis of $\ell_{s}$. Furthermore, there is a subsequence $\left\{x_{n_{k}}\right\}_{k=1}^{\infty}$ such that for each $n \in \mathbb{N}, n>q$, there is $P \in \mathcal{P}\left({ }^{n} X\right)$ such that $P\left(x_{n_{k}}\right)=1$ for all $k \in \mathbb{N}$.

Definition 1.7.13 ([47]). Let $1 \leqslant p \leqslant \infty$. We say that a Banach space $X$ has the $S_{p}$-property (resp. the $T_{p}$-property) if every normalized weakly null sequence has a subsequence with an upper $p$-estimate (resp. lower $q$ estimate).
The $S_{\infty}$ property is equivalent to saying that every normalized weakly null sequence contains a subsequence equivalent to the basis of $c_{0}$.

Theorem 1.7.14 ([54]). Let $X, Y$ be Banach spaces and $P \in \mathcal{P}\left({ }^{n} X ; Y\right)$. If $n<p<\infty$, then $P$ takes sequences with an upper $p$-estimate into sequences with an upper $\frac{p}{n}$-estimate.

Corollary 1.7.15 ([40]). Let $X$ be a Banach space which enjoys the $S_{p^{-}}$ property, $1<p \leqslant \infty$. If $n<p$, then

$$
\mathcal{P}^{n}(X)=\mathcal{P}_{w S C}^{n}(X) .
$$

The next result holds true, as $\ell_{p}$ and $c_{0}$ have properties $S_{p}$ and $S_{\infty}$ respectively.

Corollary 1.7.16 ([16], [54]). Let $\Gamma$ be any set, $1<p<\infty$ and $n \in \mathbb{N}$, $n<p$. Then

$$
\begin{aligned}
& \mathcal{P}^{n}\left(\ell_{p}\right)=\mathcal{P}_{w u}^{n}\left(\ell_{p}\right), \\
& \mathcal{P}\left(c_{0}\right)=\mathcal{P}_{w u}\left(c_{0}\right) .
\end{aligned}
$$

Conversely, if $n \geqslant p$, then $\sum_{j=1}^{\infty} x_{j}^{n} \in \mathcal{P}\left({ }^{n} \ell_{p}\right) \backslash \mathcal{P}_{\text {wsc }}\left({ }^{n} \ell_{p}\right)$.
Theorem 1.7.17 ([56]). Let $X$ be a normed linear space. The following are equivalent:
(i) $X$ has the Dunford-Pettis property.
(ii) $\mathcal{L}_{w K}(X ; Y) \subset \mathcal{L}_{w s C}(X ; Y)$ for every Banach space $Y$.
(iii) $\mathcal{L}_{w K}\left({ }^{n} X ; Y\right) \subset \mathcal{L}_{w s C}\left({ }^{n} X ; Y\right)$ for every Banach space $Y$ and every $n \in$ $\mathbb{N}$.
(iv) $\mathcal{P}_{w K}(X ; Y) \subset \mathcal{P}_{w s C}(X ; Y)$ for every Banach space $Y$.

The following result is a generalization of a well-known result (due to Aron and co-authors), which holds true for polynomials.

Theorem 1.7.18 ([20]). Let $X, Y$ be Banach spaces, $\ell_{1} \leftrightarrow X$ and $U \subset X$ be a convex subset with non-empty interior. Then $\mathcal{C}_{w}(U ; Y)=\mathcal{C}_{w s c}(U ; Y)$.

Theorem 1.7.19 ([20]). Let $X, Y$ be Banach spaces, $\ell_{1} \leftrightarrow X$ and $U \subset X$ be a convex subset with non-empty interior. Then $\mathcal{C}_{w u}(U ; Y)=\mathcal{C}_{w s C}(U ; Y)$.

## Chapter 2

## A corrigendum in the finite-dimensional setting

### 2.1 Contextualization

The main result of this thesis relies on [41], more precisely on the finitedimensional quantitative Lemma 1.5.4 (Lemma 2 in the paper), which is also the principal tool for obtaining the results in [41] and which was obtained as a by-product of a new theory of algebraic bases for algebras of sub-symmetric polynomials on $\mathbb{R}^{n}$.

Unfortunately, the arguments in [41] contain a serious gap, which was recently spotted by our colleague Michal Johanis. More precisely, the power series on top of page 213 should have been correctly centered at the point $\left(x_{1}^{0}, \ldots, x_{n}^{0}\right)$, rather than at the origin. It is not clear to us at the present moment if this problem can be fixed, so the theory of algebraic bases developed in [41] remains to be only a conjecture.

In this chapter we give a different proof of the above-mentioned lemma. As a result, all the infinite dimensional applications stated in [41], as well as in several papers by various authors which have relied on our previous work (e.g. [28], [29]), remain valid. In fact, the strongest results concerning polynomial algebras are contained in the paper [21], which is also based on the lemma in question.

Let us now proceed with the corrected proof of Lemma 1.5.4.

### 2.2 Sub-symmetric polynomials on $\mathbb{R}^{n}$

Given $k, n \in \mathbb{N}, k \leqslant N$ and $\alpha \in \mathcal{J}^{+}(k, d)$, we define $P_{\alpha}^{N} \in \mathcal{P}\left({ }^{d} \mathbb{R}^{N}\right)$ by

$$
\begin{equation*}
P_{\alpha}^{N}(x)=\sum_{1 \leqslant \rho_{1}<\cdots<\rho_{k} \leqslant N} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{k}}^{\alpha_{k}} \tag{2.1}
\end{equation*}
$$

For $N \geqslant d$, the polynomials $P_{\alpha}^{N}$, for $\alpha \in \mathcal{J}^{+}(d)$, form a linear basis of the space of subsymmetric $d$-homogeneous polynomials on $\mathbb{R}^{N}$. An important special case of these polynomials are the power sum symmetric polynomials $s_{n}^{N}(x)=P_{(n)}^{N}(x)=x_{1}^{n}+\cdots+x_{N}^{n}$.
Our main result concerns the properties of subsymmetric polynomials. However in its proof we need to work also with partial derivatives of the polynomials $P_{\alpha}^{N}$ and for this reason we consider also the polynomials $P_{\alpha}^{N}$ given by the formula (2.1), where $\alpha \in \mathcal{J}(k, d), k \leqslant N$, using the convention that $x^{0}=1$ for every $x \in \mathbb{R}$.
We denote by $H^{n, K}\left(\mathbb{R}^{N}\right)$ the subspace of $\mathcal{P}^{n}\left(\mathbb{R}^{N}\right)$ generated by the polynomials $P_{\alpha}^{N}, \alpha \in \bigcup_{d=0}^{n} \bigcup_{k=1}^{K} \mathcal{J}(k, d)$.
For formal reasons, we also put $P_{\alpha}^{N}=0$ if $k>N$ and $P_{\varnothing}^{N}=1$, both even for $N=0$, further $\mathcal{J}(0,0)=\{\varnothing\}$ and $\mathbb{R}^{0}=\{0\}$. Note that these definitions are consistent with (2.1), using the convention that a sum over an empty set is zero and a product over an empty set is equal to 1 .

The following fact describes an important relation between the restriction of $P_{\alpha}^{M}$ to the first $N$ coordinates and $P_{\alpha}^{N}$. Note that for $M>N$ we consider canonically $\mathbb{R}^{N}$ as a subspace of $\mathbb{R}^{M}$.

Fact 2.2.1. Let $M, N, k, d \in \mathbb{N}_{0}, N<M$ and $\alpha \in \mathcal{J}(k, d)$ be such that $\alpha_{m}>0$ and $\alpha_{m+1}=\cdots=\alpha_{k}=0$ for some $0 \leqslant m \leqslant k$. Then

$$
P_{\alpha}^{M}(x)=\sum_{j=m}^{k}\binom{M-N}{k-j} P_{\left(\alpha_{1}, \ldots, \alpha_{j}\right)}^{N}(x)
$$

for every $x \in \mathbb{R}^{N}$. Conversely

$$
P_{\alpha}^{N}(x)=\sum_{j=m}^{k}(-1)^{k-j}\binom{M-N+k-j-1}{k-j} P_{\left(\alpha_{1}, \ldots, \alpha_{j}\right)}^{M}(x)
$$

for every $x \in \mathbb{R}^{N}$.

Proof. The first relation follows from the following (recall that $x \in \mathbb{R}^{N}$, i.e. $x_{N+1}=\cdots=x_{M}=0$ as per the aforementioned convention):

$$
\begin{aligned}
P_{\alpha}^{M}(x) & =\sum_{1 \leqslant \rho_{1}<\cdots<\rho_{k} \leqslant M} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{m}}^{\alpha_{m}} \\
& =\sum_{1 \leqslant \rho_{1}<\cdots<\rho_{k} \leqslant M}^{\substack{\rho_{m} \leqslant N}} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{m}}^{\alpha_{m}} \\
& =\sum_{j=m}^{k} \sum_{\substack{1 \leqslant \rho_{1}<\cdots<\rho_{k} \leqslant M \\
\rho_{j} \leqslant N \leqslant \rho j+1}} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{m}}^{\alpha_{m}} \\
& =\sum_{j=m}^{k}\binom{M-N}{k-j} P_{\left(\alpha_{1}, \ldots, \alpha_{j}\right)}^{N}(x)
\end{aligned}
$$

The second relation can be proved by induction on $k-m$. For $k-m=0$ it follows immediately from the first one. For the induction step we use the first relation together with the inductive hypothesis to obtain

$$
\begin{aligned}
P_{\alpha}^{N}(x) & =P_{\alpha}^{M}(x)-\sum_{j=m}^{k-1}\binom{M-N}{k-j} P_{\left(\alpha_{1}, \ldots, \alpha_{j}\right)}^{N}(x) \\
& =P_{\alpha}^{M}(x)-\sum_{j=m}^{k-1}\binom{M-N}{k-j} \sum_{l=m}^{j}(-1)^{j-l}\binom{M-N+j-l-1}{j-l} P_{\left(\alpha_{1}, \ldots, \alpha_{l}\right)}^{M}(x) \\
& \left.=P_{\alpha}^{M}(x)-\sum_{l=m}^{k-1}\left(\begin{array}{c}
k-1 \\
j=l \\
k-1)^{j-l} \\
k-j
\end{array}\right)\left(\begin{array}{c}
M-N \\
k-j-l-1 \\
j-l
\end{array}\right)\right) P_{\left(\alpha_{1}, \ldots, \alpha_{l}\right)}^{M}(x)
\end{aligned}
$$

and the result now follows from the identity

$$
\sum_{j=l}^{k}(-1)^{j-l}\binom{M-N}{k-j}\binom{M-N+j-l-1}{j-l}=0
$$

Adding or removing a couple of zero summands, this is equivalent to

$$
\sum_{p=0}^{M-N}(-1)^{k-l-p}\binom{M-N}{p}\binom{M-N+k-l-p-1}{M-N-1}=0
$$

which is the Fréchet formula for the polynomial

$$
t \mapsto\binom{M-N+k-l-t-1}{M-N-1}
$$

of degree $M-N-1$ (see [39] or [45] for a more recent proof).

It is very important to notice that the previous fact covers all the special cases like $N<k \leqslant M, k>M, N=0, m=0$ or $k=0$. Observe also that in particular in the subsymmetric case (i.e. $\alpha \in \mathcal{J}^{+}(d)$ ) we have $P_{\alpha}^{M} \upharpoonright_{\mathbb{R}^{N}}=P_{\alpha}^{N}$. Hence for sub-symmetric polynomials the superscript $N$ can be dropped. We will use this simplification for the polynomials $s_{n}^{N}=s_{n}$.
The next fact deals with the situation when we fix the first $N$ coordinates of $P_{\alpha}^{M}$.

Fact 2.2.2. Let $N, d \in \mathbb{N}_{0}, M, k \in \mathbb{N}, N<M, k \leqslant M, \alpha \in \mathcal{J}(k, d)$ and $y \in$ $\mathbb{R}^{N}$. Then the polynomial $\left(x_{1}, \ldots, x_{M-N}\right) \mapsto P_{\alpha}^{M}\left(y_{1}, \ldots, y_{N}, x_{1}, \ldots, x_{M-N}\right)$ belongs to $H^{d, \min \{k, M-N\}}\left(\mathbb{R}^{M-N}\right)$.

Proof.

$$
\begin{aligned}
& P_{\alpha}^{M}\left(y_{1}, \ldots, y_{N}, x_{1}, \ldots, x_{M-N}\right) \\
= & \sum_{j=0}^{k} \sum_{\substack{1 \leqslant \rho_{1}<\ldots<\rho_{k} \leqslant M \\
\rho_{j} \leqslant N \leqslant \rho_{j+1}}}^{k} y_{\rho_{1}}^{\alpha_{1}} \cdots y_{\rho_{j}}^{\alpha_{j}} x_{\rho_{j+1}-N}^{\alpha_{j+1}} \cdots x_{\rho_{k}-N}^{\alpha_{k}} \\
= & \sum_{\substack{0 \leqslant j \leqslant k \\
-(M-N) \leqslant j \leqslant N}} P_{\left(\alpha_{1}, \ldots, \alpha_{j}\right)}^{N}(y) P_{\left(\alpha_{j+1}, \ldots, \alpha_{k}\right)}^{M-N}\left(x_{1}, \ldots, x_{M-N}\right) .
\end{aligned}
$$

Let $k, d \in \mathbb{N}, \alpha \in \mathcal{J}(k, d), k \leqslant N, x \in \mathbb{R}^{N}$ and $1 \leqslant l \leqslant N$. Then

$$
\begin{aligned}
\frac{\partial P_{\alpha}^{N}}{\partial x_{l}}(x) & =\frac{\partial}{\partial x_{l}}\left(\sum_{j=1}^{k} \sum_{\substack{1 \leqslant \rho_{1}<\ldots<\rho_{k} \leqslant N \\
\rho_{j}=l}} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{k}}^{\alpha_{k}}\right) \\
& =\sum_{\substack{j=1 \\
\alpha_{j}>0}}^{k} \sum_{\substack{1 \leqslant \rho_{1}<\cdots<\rho_{j-1}<l \\
l<\rho_{j+1}<\cdots<\rho_{k} \leqslant N}}^{k} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{j-1}}^{\alpha_{j-1}} x_{l}^{\alpha_{j}-1} x_{\rho_{j+1}}^{\alpha_{j+1}} \cdots x_{\rho_{k}}^{\alpha_{k}} \\
& =\sum_{\substack{j=1 \\
\alpha_{j}>0}}^{k} \alpha_{j} P_{\left(\alpha_{1}, \ldots, \alpha_{j-1}\right)}^{l-1}\left(x_{1}, \ldots, x_{l-1}\right) x_{l}^{\alpha_{j}-1} P_{\left(\alpha_{j+1}, \ldots, \alpha_{k}\right)}^{N-l}\left(x_{l+1}, \ldots, x_{N}\right)
\end{aligned}
$$

These partial derivatives have the following useful property:
Fact 2.2.3. Let $k, d, N \in \mathbb{N}, \alpha \in \mathcal{J}(k, d), k \leqslant N$. Then $\sum_{l=1}^{N} \frac{\partial P_{\alpha}^{N}}{\partial x_{l}}$ belongs to $H^{d-1, k}\left(\mathbb{R}^{N}\right)$.

Proof.

$$
\begin{aligned}
\sum_{l=1}^{N} \frac{\partial P_{\alpha}^{N}}{\partial x_{l}} & =\sum_{\substack{l=1}}^{N} \sum_{\substack{j=1 \\
\alpha_{j}>0}}^{k} \sum_{\substack{1 \leqslant \rho_{l}<\cdots<\rho_{j-1}<l \\
l<\rho_{j+1}<\cdots<\rho_{k} \leqslant N}} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{j-1}}^{\alpha_{j-1}} x_{l}^{\alpha_{j}-1} x_{\rho_{j+1}}^{\alpha_{j+1}} \cdots x_{\rho_{k}}^{\alpha_{k}} \\
& =\sum_{\substack{j=1 \\
\alpha_{j}>0}}^{k} \alpha_{j} \sum_{l=1}^{N} \sum_{\substack{1 \leqslant \rho_{1}<\ldots<\rho_{k} \leqslant N \\
\alpha_{j}=l}} x_{\rho_{1}}^{\alpha_{1}} \cdots x_{\rho_{j-1}}^{\alpha_{j-1}} x_{l}^{\alpha_{j}-1} x_{\rho_{j+1}}^{\alpha_{j+1}} \cdots x_{\rho_{k}}^{\alpha_{k}} \\
& =\sum_{\substack{j=1 \\
\alpha_{j}>0}}^{k} \alpha_{j} P_{\left(\alpha_{1}, \ldots, \alpha_{j-1}, \alpha_{j}-1, \alpha_{j+1}, \ldots, \alpha_{k}\right)}^{N}(x) .
\end{aligned}
$$

We note that this fact does not hold with $\mathcal{J}^{+}(k, d)$ and the space of subsymmetric polynomials in place of $\mathcal{J}(k, d)$ and $H^{d-1, k}\left(\mathbb{R}^{N}\right)$ : this is the sole reason for considering the larger spaces $H^{n, K}\left(\mathbb{R}^{N}\right)$.
For each $x \in \mathbb{R}^{N}$ we naturally identify $D P_{\alpha}^{N}(x)$ with the vector

$$
\left(\frac{\partial P_{\alpha}^{N}}{\partial x_{1}}(x), \ldots, \frac{\partial P_{\alpha}^{N}}{\partial x_{N}}(x)\right) \in \mathbb{R}^{N}
$$

Fact 2.2.4. Let $M, N, k, d \in \mathbb{N}, M>N, \alpha \in \mathcal{J}(k, d), k \leqslant N$ and $x \in \mathbb{R}^{N}$. Then $D P_{\alpha}^{N}(x)$ is a linear combination of vectors

$$
D P_{\beta}^{M}(x) \uparrow_{\mathbb{R}^{N}}=\left(\frac{\partial P_{\beta}^{M}}{\partial x_{1}}(x), \ldots, \frac{\partial P_{\beta}^{M}}{\partial x_{N}}(x)\right) \in \mathbb{R}^{N},
$$

where $\beta \in \cup_{m=1}^{k} \mathcal{I}(m, d)$.
Proof. Let $1 \leqslant m \leqslant k$ be such that $\alpha_{m}>0$ and $\alpha_{m+1}=\cdots=\alpha_{k}=0$. Fix $1 \leqslant l \leqslant N$. If $\alpha_{j}>0$, then $m \geqslant j$ and hence, by Fact 2.2.1:

$$
P_{\left(\alpha_{j+1}, \ldots, \alpha_{k}\right)}^{N-l}\left(x_{l+1}, \ldots, x_{N}\right)=\sum_{s=m}^{k} c_{s} P_{\left(\alpha_{j+1}, \ldots, \alpha_{s}\right)}^{M-l}\left(x_{l+1}, \ldots, x_{N}, 0, \ldots, 0\right),
$$

where $c_{s}=(-1)^{k-s}\binom{M-N+k-s-1}{k-s}$.

Therefore, using Fact 2.2.2 and the fact that $\alpha_{s+1}=\cdots=\alpha_{k}=0$, if $m \leqslant s \leqslant k$ we obtain

$$
\begin{aligned}
\frac{\partial P_{\alpha}^{N}}{\partial x_{l}}= & \sum_{\substack{j=1 \\
\alpha_{j}>0}}^{k} \alpha_{j} P_{\left(\alpha_{1}, \ldots, \alpha_{j-1}\right)}^{l-1}\left(x_{1}, \ldots, x_{l-1}\right) x_{l}^{\alpha_{j}-1} \\
& \cdot \sum_{s=m}^{k} c_{s} P_{\left(\alpha_{j+1}, \ldots, \alpha_{s}\right)}^{M-l}\left(x_{l+1}, \ldots, x_{N}, 0, \ldots, 0\right) \\
= & \sum_{s=m}^{k} c_{s} \frac{\partial P_{\left(\alpha_{1}, \ldots, \alpha_{s}\right)}^{M}}{\partial x_{l}}(x),
\end{aligned}
$$

from which the statement follows.

We will also make use of the following version of the Lagrange multipliers theorem.

Theorem 2.2.5. Let $G \subseteq \mathbb{R}^{n}$ be an open set, $f \in C^{1}(G), F \in C^{1}\left(G ; \mathbb{R}^{M}\right)$ and assume that $F$ has a constant rank. If the function $f$ has a local extremum with respect to $M=\{x \in G: F(x)=0\}$ at $a \in M$, then $\operatorname{Df}(a)$ is a linear combination of $D F_{1}(a), \ldots, D F_{m}(a)$, where $F_{1}, \ldots, F_{m}$ are the components of the mapping $F$.

Proof. Let $k=\operatorname{rank} F(x)$ for $x \in G$. Since $D F$ is continuous, we may without loss of generality assume that $D F_{1}(x), \ldots, D F_{k}(x)$ are linearly independent for each $x \in G$. From the Rank theorem it follows that there are $C^{1}$-smooth functions $g_{j}$ of $k$ variables, $j=k+1, \ldots, m$ and a neighbourhood $U$ of $a$ such that $F_{j}(x)=g_{j}\left(F_{1}(x), \ldots, F_{k}(x)\right)$ for each $x \in$ $U, j=k+1, \ldots, m$ (see e.g. [62], Proposition 8.6.3.1). Notice that $g_{j}(0, \ldots, 0)=g_{j}\left(F_{1}(a), \ldots, F_{k}(a)\right)=F_{j}(a)=0, j=k+1, \ldots, m$. Therefore $M \cap U=\left\{x \in U: F_{1}(x)=0, \ldots, F_{k}(x)=0\right\}$ and we may use the classical version of the Lagrange multipliers theorem.

Now we are ready to prove the key lemma.

Lemma 2.2.6. For every $n, K \in \mathbb{N}$ there are $N \in \mathbb{N}$ and $u, v \in \mathbb{R}^{N}$ such that $P(u)=P(v)$ for every $P \in H^{n, K}\left(\mathbb{R}^{N}\right)$ but $s_{n+1}(u) \neq s_{n+1}(v)$.

Proof. The proof is based on the observation that

$$
\sum_{l=1}^{N} \frac{\partial s_{n+1}}{\partial x_{l}}(x)=(n+1) s_{n}(x)
$$

which, together with Fact 2.2.3, leads to an inductive proof.
For each fixed $k \in \mathbb{N}$ we prove the statement by induction on $n$.
So fix $K \in \mathbb{N}$ and denote

$$
\mathcal{M}(n)=\bigcup_{1 \leqslant d \leqslant n} \bigcup_{1 \leqslant k \leqslant K} \mathcal{J}(k, d)
$$

The space $H^{n, K}\left(\mathbb{R}^{N}\right)$ is generated by a constant function and polynomials $P_{\alpha}^{N}, \alpha \in \mathcal{M}(n)$.
For $n=1$ the functions $P_{\alpha}^{N}, \alpha \in \mathcal{M}(n)$ are linear, so there is $N \in \mathbb{N}$ large enough such that $\bigcap_{\alpha \in \mathcal{N}(n)}$ ker $P_{\alpha}^{N}$ contains a non-zero element $u$. Then it suffices to take $v=2 u$.
The inductive step from $n-1$ to $n$ will be proven by contradiction. So assume that for each $N \geqslant K$ and each $u, v \in \mathbb{R}^{N}$ satisfying $P_{\alpha}^{N}(u)=P_{\alpha}^{N}(v)$ for all $\alpha \in \mathcal{M}(n)$ we have $s_{n+1}(u)=s_{n+1}(v)$.
Now let

$$
F^{N}: \mathbb{R}^{N} \longrightarrow \mathbb{R}^{|\mathcal{M}(n)|}
$$

be the mapping whose components are the polynomials $P_{\alpha}^{N}, \alpha \in \mathcal{M}(n)$, in some fixed order and let $\mathbb{A}_{N}(x)$ be its Jacobi matrix at $x \in \mathbb{R}^{N}$, i.e.

$$
\mathbb{A}_{N}(x)=\left(\frac{\partial P_{\alpha}^{N}}{\partial x_{l}}(x)\right)_{(\substack{\alpha \in \mathcal{M}(n) \\ l=1, \ldots, M}}
$$

Note that the number of rows of the matrix of functions $\mathbb{A}_{N}$ does not depend on $N$. Thus there is $N \geqslant K$ and $y \in \mathbb{R}^{N}$ such that

$$
\operatorname{rank} \mathbb{A}_{N}(y)=r=\max _{\substack{M \geqslant K \\ x \in \mathbb{R}^{M}}} \operatorname{rank} \mathbb{A}_{M}(x)
$$

By the inductive hypothesis, there are $M>N$ and $g, h \in \mathbb{R}^{M-N}$ such that $P(g)=P(h)$ for all $P \in H^{h-1, K}\left(\mathbb{R}^{M-N}\right)$ but $s_{n}(g) \neq s_{n}(h)$. If we denote by $\mathbb{A}_{M}(x) \upharpoonright_{N}$ the matrix consisting of the first $N$ columns of the matrix $\mathbb{A}_{M}(x)$, then

$$
r=\operatorname{rank} \mathbb{A}_{N}(y) \leqslant \operatorname{rank} \mathbb{A}_{M}(y) \upharpoonright_{N} \leqslant \operatorname{rank} \mathbb{A}_{M}(y) \leqslant r
$$

where the first inequality follows from Fact 2.2.4.
Let $w_{1}^{M}, \ldots w_{r}^{M}$ be the rows of $\mathbb{A}_{M}$ such that $w_{1}^{M} \upharpoonright_{N}(y), \ldots w_{r}^{M} \upharpoonright_{N}(y)$ are linearly independent. Using the continuity of the entries of $\mathbb{A}_{M}$ it is easy to see that there is a neighbourhood $U \subseteq \mathbb{R}^{M}$ of $y$ such that, for each $x \in U$, the vectors $w_{1}^{M} \upharpoonright_{N}(x), \ldots w_{r}^{M} \upharpoonright_{N}(x)$ are linearly independent: therefore they form a basis of the space spanned by the rows of $\mathbb{A}_{M} \upharpoonright_{N}$. Clearly the same holds for $w_{1}^{M}(x), \ldots, w_{r}^{M}(x)$ and $\mathbb{A}_{M}(x)$.
Fix an arbitrary $z \in U$ and put

$$
S=\left\{x \in U: P_{\alpha}^{M}(x)=P_{\alpha}^{M}(z), \alpha \in \mathcal{M}(n)\right\}
$$

By our assumption, $s_{n+1}$ is constant on $S$ and so Theorem 2.2.5 implies that $D s_{n+1}(z)$ is a linear combination of the rows of $\mathbb{A}_{M}(z)$. It follows that, for each $z \in U$, the vector $D s_{n+1}(z)$ is a linear combination of $w_{1}^{M}(z), \ldots, w_{r}^{M}(z)$. Next, we put

$$
u=y+c \sum_{j=1}^{M-N} g_{j} e_{N+j}, v=\sum_{j=1}^{M-N} h_{j} e_{N+j}
$$

for some suitable $c \neq 0$ so that $u, v \in U$. Notice that, since $H^{n-1, K}\left(\mathbb{R}^{M-N}\right)$ is generated by homogeneous polynomials, we still have $P(c g)=P(c h)$ for all $P \in H^{n-1, K}\left(\mathbb{R}^{M-N}\right)$ but $s_{n}(c g) \neq s_{n}(c h)$. For a fixed $\alpha \in \mathcal{M}(n)$ and $1 \leqslant l \leqslant N$ consider the polynomial

$$
P(x)=\frac{\partial P_{\alpha}^{M}}{\partial x_{l}}\left(y_{1}, \ldots, y_{N}, x_{1}, \ldots, x_{M-N}\right)
$$

Then, by Fact 2.2 .2 , we have $P \in H^{n-1, K}\left(\mathbb{R}^{M-N}\right)$ and so $P(c g)=P(c h)$. Therefore

$$
\begin{equation*}
w_{j}^{M}(u) \upharpoonright_{N}=w_{j}^{M}(v) \upharpoonright_{N}, \quad j=1, \ldots, r . \tag{2.2}
\end{equation*}
$$

We have $D s_{n+1}(u)=\sum_{j=1}^{r} \lambda_{j} w_{j}^{M}(u)$ and $D s_{n+1}(v)=\sum_{j=1}^{r} \mu_{j} w_{j}^{M}(v)$ for some $\lambda_{j}, \mu_{j} \in \mathbb{R}$ and of course the same holds when we restrict to the first $N$ coordinates of all of these vectors.
But since $D s_{n+1}(u) \upharpoonright_{N}=(n+1)\left(y_{1}^{n}, \ldots, y_{N}^{n}\right)=D s_{n+1}(v) \upharpoonright_{N}$, combined with (2.2) and the fact that $w_{1}^{M}(u) \upharpoonright_{N}, \ldots, w_{r}^{M}(u) \upharpoonright_{N}$ are linearly independent, we obtain $\mu_{j}=\lambda_{j}, j=1, \ldots, r$.

Eventually, from Fact 2.2.3 and Fact 2.2.2 it follows that

$$
x \mapsto \sum_{l=1}^{M} w_{j}^{M}\left(y+\sum_{j=1}^{M-N} x_{j} e_{N+j}\right)_{l} \in H^{n-1, K}\left(\mathbb{R}^{M-N}\right), \quad j=1, \ldots, r
$$

Therefore

$$
\begin{aligned}
(n+1) s_{n}(u) & =\sum_{l=1}^{M} \frac{\partial s_{n+1}}{\partial x_{l}}(u)=\sum_{j=1}^{r} \lambda_{j} \sum_{l=1}^{M} w_{j}^{M}(u)_{l} \\
& =\sum_{j=1}^{r} \lambda_{j} \sum_{l=1}^{M} w_{j}^{M}(v)_{l}=\sum_{l=1}^{M} \frac{\partial s_{n+1}}{\partial x_{l}}(v) \\
& =(n+1) s_{n}(v)
\end{aligned}
$$

Since $s_{n}(u)=s_{n}(y)+s_{n}(c g)$ and $s_{n}(v)=s_{n}(y)+s_{n}(c h)$, we get $s_{n}(c g)=$ $s_{n}(c h)$, which is a contradiction.

### 2.3 The corrected proof

Corollary 2.3.1. For every $n \in \mathbb{N}$ there exist $N \in \mathbb{N}$ and $\varepsilon>0$ such that for every $M \geqslant N$

$$
\sup _{x \in B_{\ell_{1}^{M}}^{M}}\left|p(x)-s_{n+1}(x)\right| \geqslant \varepsilon
$$

for every $p$ from the algebra generated by the sub-symmetric polynomials on $\mathbb{R}^{M}$ of degree at most $N$.

Proof. Applying Lemma 2.2 .6 to $K=n$ we obtain $N \in \mathbb{N}$ and $u, v \in B_{\ell_{1}^{N}}$ such that $P(u)=P(v)$ for every $P \in H^{n, n}\left(\mathbb{R}^{N}\right)$ but $s_{n+1}(u) \neq s_{n+1}(v)$. We put $\varepsilon=\frac{1}{2}\left|s_{n+1}(u)-s_{n+1}(v)\right|$. Let $M \geqslant N$. Since all sub-symmetric polynomials from $\mathcal{P}^{n}\left(\mathbb{R}^{N}\right)$ are contained in $H^{n, n}\left(\mathbb{R}^{N}\right)$, from the remark after Fact 2.2.1 it follows that in particular $P(u)=P(v)$ for every subsymmetric $P \in \mathcal{P}^{n}\left(\mathbb{R}^{M}\right)$. We conclude that $p(u)=p(v)$ for every $p$ from the algebra generated by the sub-symmetric polynomials from $\mathcal{P}^{n}\left(\mathbb{R}^{M}\right)$. The statement now easily follows.

## Chapter 3

## The main theorem

### 3.1 Introduction

Generally speaking, with a single exception when $\mathcal{P}(X)=\mathcal{P}_{w u}(X)$, there are no results giving a characterization of the uniform closure $\overline{\mathcal{P}}(X)^{\tau_{b}}$ in any infinite-dimensional space. The refinement of the problem is finding the characterization of $\overline{\mathcal{A}_{n}(X)}$ and this is wide open as well. The results in this section focus on the natural question when $\overline{\mathcal{A}_{n}(X)}=\overline{\mathcal{A}_{n+1}(X)}$ (the inclusion $\subset$ always holds). We are going to use the theory of sub-symmetric polynomials previously developed together with the asymptotic approach to polynomial behaviour to obtain rather general results showing that the inclusion $\supset$ is almost never satisfied.
We begin by formulating a positive result.
Theorem 3.1.1 ([2], [8]). Let $X, Y$ be Banach spaces, Then $\overline{\mathcal{P}}_{f}(X ; Y)^{\tau_{b}}=$ $\mathcal{C}_{w u}\left(B_{X} ; Y\right)$.

Proposition 3.1.2. Let $X$ be a Banach space such that it does not contain $\ell_{1}$ and $\mathcal{P}\left({ }^{n} X\right)=\mathcal{P}_{\text {wsc }}\left({ }^{n} X\right)$. Then

$$
\mathcal{A}_{1}(X)=\mathcal{A}_{2}(X)=\cdots=\mathcal{A}_{n}(X) .
$$

Proof. The following chain of equalities holds true:

$$
\mathcal{P}_{w}\left({ }^{n} X\right) \underset{\text { Cor. 1.7.3 }}{=} \mathcal{P}_{w u}\left({ }^{n} X\right) \underset{\text { Teo. 1.7.18 }}{=} \mathcal{P}_{w s c}\left({ }^{n} X\right) \underset{\text { hyp. }}{=} \mathcal{P}\left({ }^{n} X\right) .
$$

Thus

$$
\mathcal{P}\left({ }^{n} X\right)=\mathcal{P}_{w u}\left({ }^{n} X\right) \subset \mathcal{C}_{w u}\left({ }^{n} X\right) \underset{\text { Teo. 3.1.1 }}{=} \overline{\mathcal{P}_{f}(X ; Y)^{\tau_{b}}} \underset{\text { easy }}{\subset} \overline{\mathcal{A}_{1}(X)} .
$$

Since $\overline{\mathcal{A}_{1}(X)}$ is an algebra, $\mathcal{A}_{n}(X) \subset \overline{\mathcal{A}_{1}(X)}$, from which the result follows.

All our results, which we are now going to present, go in the opposite direction and rely on the useful criterion investigated in Theorem 1.5.5.

### 3.2 The proof

Theorem 3.2.1. Let $X$ be a Banach space, and $m$ be the minimal integer such that there is a non-compact $P \in \mathcal{P}\left({ }^{m} X ; \ell_{1}\right)$. Then $n \geqslant m$ implies $\mathcal{P}\left({ }^{n} X\right) \notin \overline{\mathcal{A}_{n-1}(X)}$.

Proof. If $\ell_{1} \hookrightarrow X$ then it suffices to combine Theorem 1.5.5 and Proposition 1.7.7. For the rest of the proof we assume that $\ell_{1} \nrightarrow X$. Denote $\left\{f_{j}\right\}_{j=1}^{\infty}$ the canonical basis in $\ell_{1}, P=\left(P_{k}\right)_{k=1}^{\infty} \in \mathcal{P}\left({ }^{m} X ; \ell_{1}\right), P_{k} \in \mathcal{P}\left({ }^{m} X\right)$.
We claim that by performing some adjustments to $P$, we may assume in addition that there exists a weakly null normalized basic sequence $\left\{x_{n}\right\}_{n=1}^{\infty} \subseteq$ $X$ such that $P\left(x_{j}\right)=f_{j}$ for each $j$.
To this end, note that by Lemma 1.7.8 there exists a weakly null sequence $\left\{y_{k}\right\}_{k=1}^{\infty}$ in $X$ such that $\left\{P\left(y_{k}\right)\right\}_{k=1}^{\infty}$ is not relatively compact, i.e. it contains a separated subsequence, which we call again $\left\{P\left(y_{k}\right)\right\}_{k=1}^{\infty}$. By [1] p. 22, by passing to a subsequence, we may assume that $\left\{y_{k}\right\}$ is a normalized basic sequence. As $\ell_{1}$ is a Schur space, $\left\{P\left(y_{k}\right)\right\}_{k=1}^{\infty}$ contains no weakly null subsequences. By Rosenthal's $\ell_{1}$ theorem, $\left\{P\left(y_{k}\right)\right\}_{k=1}^{\infty}$ contains a subsequence, again $\left\{P\left(y_{k}\right)\right\}$, equivalent to the $\ell_{1}$-basis. By a well-known result (according to Bill Johnson, who has pointed out to us some very closely related other results), every sequence in $\ell_{1}$, which is equivalent to the $\ell_{1}$-basis, contains a further subsequence which spans a complemented subspace. Since we have been unable to find this result explicitly in the literature, let us indicate the idea of proof. Supposing that $\left\{z_{k}\right\}$ is the $\ell_{1}$-basic sequence in $\ell_{1}$, we may assume, by passing to a subsequence, that $z_{k}$ is pointwise convergent to $u_{0} \in \ell_{1}$ and that there exists a sequence of disjoint block vectors $\left\{u_{k}\right\}$
such that $\sum_{k}\left|z_{k}-u_{0}-u_{k}\right|<\infty$. The case when $u_{0}=0$ is well-known [36] Prop. 4.45, so let us assume the contrary. Moreover, we may assume that the the norms of $u_{0}$ restricted to the supports of $u_{k}$ form a fast decreasing sequence. Then, by the classical results [36] Thm. 4.23, Prop. 4.45, we have that the sequence $\left\{u_{k}\right\}_{k=0}^{\infty}$ is equivalent to the $\ell_{1}$-basis, which is moreover complemented in $\ell_{1}$. Hence, $u_{0}, z_{1}-u_{0}, z_{2}-u_{0} \ldots$ is also equivalent to a complemented $\ell_{1}$ basis in $\ell_{1}$. To finish, it suffices to find a suitable projection in this latter space, which takes $\left(a_{0}, a_{1}, \ldots\right) \rightarrow\left(\sum_{k=1}^{\infty} a_{k}, a_{1}, a_{2}, \ldots\right)$.
Hence there exists a weakly null and normalized basic sequence $\left\{x_{k}\right\}=$ $\left\{y_{n_{k}}\right\} \subseteq\left\{y_{n}\right\}$ such that $P\left(x_{k}\right)=g_{k}$, where $\left\{g_{k}\right\}$ is a equivalent to an $\ell_{1}$ basis which spans a complemented subspace in $\ell_{1}$. Hence, composing $P$ with the appropriate projection in $\ell_{1}$, we substitute $\ell_{1}$ with its complemented subspace $\left[g_{k}\right]_{k=1}^{\infty}$, and the claim follows.
Let $\left\{\phi_{j}\right\}_{j=1}^{\infty}$ be a bounded sequence in $X^{*}$, biorthogonal to $\left\{x_{j}\right\}_{j=1}^{\infty}$. We are mostly going to be interested in the behaviour of $P$ restricted to $Y=$ $\operatorname{span}\left\{x_{j}: j \in \mathbb{N}\right\} \hookrightarrow X$. For the sake of convenience, set $Y_{\{j: j \geqslant k+1\}}:=$ $\operatorname{span}\left\{x_{j}: j \geqslant k+1\right\}$. Note that we have $P\left(\lambda x_{j}\right)=\lambda^{m} f_{j}$. Formula (1.5) for the restriction of $P$ to $Y$ can be rewritten, by collecting the appropriate finitely many terms, into the following formula, which holds for all finitely supported vectors $x=\sum a_{j} x_{j} \in Y$ :

$$
\begin{equation*}
P_{k}\left(\sum_{j=1}^{\infty} a_{j} x_{j}\right)=\sum_{\substack{p+q+r=m \\ \alpha \in \mathcal{J}(k-1, p)}}\left(a_{1}, \ldots, a_{k-1}\right)^{\alpha} a_{k}^{q} S_{k}^{\alpha, q, r}\left(\sum_{j=k+1}^{\infty} a_{j} x_{j}\right), \tag{3.1}
\end{equation*}
$$

where $S_{k}^{\alpha, q, r} \in \mathcal{P}\left({ }^{r} Y_{\{j: j \geqslant k+1\}}\right)$. Note that, by the minimality assumption on $m$, for a fixed $0 \neq \beta=\left(\beta_{1}, \ldots\right) \in \mathcal{J}(\infty, t), t \leqslant p<m$ where $\beta_{i}=0, i>k-1$, we have that

$$
\frac{\partial^{t}}{\partial^{\beta_{1}} x_{1} \ldots \partial^{\beta_{k-1}} x_{k-1}} P=\left(\frac{\partial^{t}}{\partial^{\beta_{1}} x_{1} \ldots \partial^{\beta_{k-1}} x_{k-1}} P_{j}\right): X \rightarrow \ell_{1}
$$

is a compact $(m-t)$-homogeneous polynomial with range in $\ell_{1}$. So, for a fixed $\beta$ of the aforementioned type,

$$
\lim _{j \rightarrow \infty}\left\|\frac{\partial^{t}}{\partial^{\beta_{1}} x_{1} \ldots \partial^{\beta_{k-1}} x_{k-1}} P_{j}\right\|=0 .
$$

For $y=\sum_{i=1}^{k-1} a_{i} x_{i} \in\left[x_{1}, \ldots, x_{k-1}\right]$ and $l>k-1$,

$$
\begin{aligned}
& \frac{\partial^{t}}{\partial^{\beta_{1}} x_{1} \ldots \partial^{\beta_{k-1}} x_{k-1}} P_{l}\left(y+\sum_{j=l}^{\infty} a_{j} x_{j}\right) \\
= & \sum_{\substack{p+q+r=m \\
\alpha \geqslant \beta \\
\alpha \in \mathcal{J}(k-1, p)}} \frac{\alpha!}{(\alpha-\beta)!}\left(a_{i}\right)^{\alpha-\beta} a_{l}^{q} S_{l}^{\alpha, q, r}\left(\sum_{j=l+1}^{\infty} a_{j} x_{j}\right) .
\end{aligned}
$$

We claim that for a fixed $0 \neq \beta=\left(\beta_{1}, \ldots\right) \in \mathcal{I}(\infty, t), t \leqslant m$ where $\beta_{i}=0$, $i>k-1, q, r$ such that $t+q+r=m$, we have that

$$
\begin{equation*}
\lim _{l \rightarrow \infty}\left\|S_{l}^{\beta, q, r}\right\|_{Y_{\{j: j \geq l+1\}}}=0 . \tag{3.2}
\end{equation*}
$$

For the proof of the claim by contradiction, choose a maximal $\beta \in \mathcal{J}(k-1, t)$ which fails (3.2). Hence, for any (if it exists) $\alpha \in \mathcal{J}(k-1, p), p>t, q, r$ such that $p+q+r=m$,

$$
\begin{equation*}
\lim _{l \rightarrow \infty}\left\|S_{l}^{\alpha, q, r}\right\|_{Y_{\{: j: j l+1\}}}=0 \tag{3.3}
\end{equation*}
$$

Passing to a suitable subsequence of $l \rightarrow \infty$ (for simplicity assuming it is still indexed by $\mathbb{N}$ ) we conclude that there exists a normalized sequence of $v_{l} \in Y_{\{j: j \geqslant l+1\}}$ such that $b^{\alpha, q, r}=\lim _{l \rightarrow \infty} S_{l}^{\alpha, q, r}\left(v_{l}\right)$ exist for all $\alpha, q, r$, and there is at least one non-zero term (with $\alpha=\beta$ ) among them. Moreover, if $\alpha \in \mathcal{J}(k-1, p)$, where $p>t$, then $b^{\alpha, q, r}=0$. That means that, for a suitably chosen $y=\sum_{i=1}^{k-1} a_{i} x_{i} \in\left[x_{1}, \ldots, x_{k-1}\right]$ and $a_{l} \in \mathbb{R}$, we have

$$
\lim _{l \rightarrow \infty} \frac{\partial^{t}}{\partial^{\beta_{1}} x_{1} \ldots \partial^{\beta_{k-1}} x_{k-1}} P_{l}\left(y+a_{l} x_{l}+v_{l}\right)=\sum_{q+r=m-t} \beta!a_{l}^{q} b^{\beta, q, r} \neq 0,
$$

which contradicts the minimality of $m$.
Fix an arbitrary sequence $\delta_{k} \searrow 0$. By passing to a fast enough growing subsequence of $\left\{x_{j}\right\}$ we can disregard in (3.1) all terms with $p \geqslant 1$, so that (using the short notation $S_{k}^{q, r}=S_{k}^{0, q, r}$ )

$$
\begin{equation*}
\sup _{\left\|\sum_{j=1}^{\infty} a_{j} x_{j}\right\| \leqslant 1}\left\|P_{k}\left(\sum_{j=1}^{\infty} a_{j} x_{j}\right)-\sum_{q+r=m} a_{k}^{q} S_{k}^{q, r}\left(\sum_{j=k+1}^{\infty} a_{j} x_{j}\right)\right\| \leqslant \delta_{k} . \tag{3.4}
\end{equation*}
$$

Let $\left\{\varepsilon_{n}^{k}\right\}_{n=1}^{\infty}, \varepsilon_{n}^{k} \searrow 0$, be decreasing sequences of real numbers and $\left\{N_{k}(j)\right\}_{j=1}^{\infty}$ be an increasing sequence of natural numbers. To start with, by applying Theorem 1.4.11, we may assume that $\left\{x_{n}\right\}_{n=1}^{\infty}$ is a characteristic sequence of its spreading model $E$ with a sub-symmetric basis $\left\{e_{n}\right\}_{n=1}^{\infty}$.
By a repeated application of Theorem 1.4.11, there are nested subsequences $\mathbb{N} \supset M_{1} \supset M_{2} \supset \cdots$ of index sets so that the following holds: for a subsequence $\left\{x_{n}\right\}_{n \in M_{k}}$ of $\left\{x_{n}\right\}_{n=1}^{\infty}$, there is a sub-symmetric polynomial $R_{k}^{q, r} \in \mathcal{P}\left({ }^{r} E\right), r$ and $q$ such that, for all scalars $a_{j}, j=1, \ldots, N_{k}(K)$,

$$
\begin{equation*}
R_{k}^{q, r}\left(\sum_{j=1}^{N_{k}(K)} a_{j} e_{j}\right)-\varepsilon_{K}^{k} \leqslant S_{k}^{q, r}\left(\sum_{j=1}^{N_{k}(K)} a_{j} x_{n_{j}}\right) \leqslant R_{k}^{q, r}\left(\sum_{j=1}^{N_{k}(K)} a_{j} e_{j}\right)+\varepsilon_{K}^{k} \tag{3.5}
\end{equation*}
$$

provided $K \leqslant n_{1}<\cdots<n_{N_{k}(K)}, n_{j} \in M_{k}$ and $\left\|\sum_{j=1}^{N_{k}(K)} a_{j} x_{n_{j}}\right\| \leqslant 1$.
By (1.7),

$$
\begin{equation*}
R_{k}^{q, r}\left(\sum_{j=1}^{\infty} a_{j} e_{j}\right)=\sum_{\alpha \in \mathcal{J}(r)} a_{\alpha}^{q, r, k} P_{\alpha}\left(\sum_{j=1}^{\infty} a_{j} e_{j}\right) \tag{3.6}
\end{equation*}
$$

for all finitely supported vectors.
By passing to a suitable diagonal sequence $M=\left\{m_{i}\right\}_{i=1}^{\infty}$ of the system $\left\{M_{k}\right\}_{k=1}^{\infty}$ and keeping in mind that the set $\left\{R_{k}^{q, r}\right\}_{k, q, r}$ in $\mathcal{P}(E)$ is uniformly bounded, we may also assume that there exist finite limits

$$
\begin{equation*}
b_{\alpha}^{q, r}=\lim _{k \rightarrow \infty} a_{\alpha}^{q, r, k}, \quad k \in M \tag{3.7}
\end{equation*}
$$

We consider the sub-symmetric polynomial $W^{q, r} \in \mathcal{P}\left({ }^{r} E\right)$ defined by

$$
\begin{equation*}
W^{q, r}\left(\sum_{j=1}^{\infty} a_{j} e_{j}\right)=\sum_{\alpha \in \mathcal{J}(r)} b_{\alpha}^{q, r} P_{\alpha}\left(\sum_{j=1}^{\infty} a_{j} e_{j}\right) \tag{3.8}
\end{equation*}
$$

We claim that $W^{q, r}=0$, unless $r=0$. Assuming the contrary, there is a finitely supported vector $v=\sum_{i=1}^{T} v_{i} e_{i}$ such that

$$
\sum_{q+r=m, r \geqslant 1} W^{q, r}(v)=\delta \neq 0
$$

We may assume without loss of generality that $\delta>0$. Hence, for a sliding finitely supported block vector $w_{j}=\sum_{i=1}^{T} v_{i+j} x_{m_{i+j}}$, by (3.5), (3.6), and
(3.7), we get that

$$
\begin{equation*}
\underset{j}{\liminf } \sum_{q+r=m, r \geqslant 1} S_{l}^{q, r}\left(w_{j}\right)>\frac{\delta}{2} \tag{3.9}
\end{equation*}
$$

holds for all $l \in M$ large enough. But this contradicts again the minimality assumption on $m$. Indeed, we denote by $U$ a $w^{*}$-cluster point of $\left\{P\left(x+w_{k}\right)\right.$ : $k \in \mathbb{N}\}$ in the dual Banach space $\mathcal{P}^{m}\left(X ; \ell_{1}\right)$. In particular, for every $x$ there is a subsequence $L \subset \mathbb{N}$ such that

$$
U(x)=\lim _{j \rightarrow \infty, k \in L} P\left(x+w_{j}\right) .
$$

Let $U=U^{0}+U^{1}+\cdots+U^{m}=\left(U_{k}^{0}+U_{k}^{1}+\cdots+U_{k}^{m}\right)_{k=1}^{\infty}$ be the unique splitting of $U$ into a sum of $j$-homogeneous summands $U^{j}$. Then by (3.9)

$$
\sum_{i=0}^{m-1} U_{k}^{i}\left(a_{k} x_{k}\right) \geqslant \sum_{q+r=m, r \geqslant 1} a_{k}^{q} W^{q, r}(v) \geqslant \frac{\delta}{2},
$$

a contradiction with the minimality of $m$.
This verifies the claim that $W^{q, r}=0$, unless $r=0$.
Combining all the previous results, we conclude that there is an infinite increasing sequence $M \subset \mathbb{N}$ and $c \neq 0$, such that the following holds: for any $\rho>0$ and $N \in \mathbb{N}$, there is a finite set $\left\{t_{1}, \ldots, t_{N}\right\} \subset M$ such that

$$
\left\|P_{k}\left(\sum_{i=1}^{N} a_{j} x_{t_{i}}\right)-c a_{k}^{m}\right\|<\rho, \quad k \in\left\{t_{1}, \ldots, t_{N}\right\} .
$$

It is now clear that the polynomial $Q \in \mathcal{P}\left({ }^{m+l} X\right), l \geqslant 0$, defined as

$$
Q(x)=\sum_{j=1}^{\infty} \phi_{j}^{l}(x) P_{j}(x),
$$

satisfies the condition laid out in Theorem 1.5.5, whence

$$
Q \in \mathcal{P}\left({ }^{m+l} X\right) \backslash \overline{\mathcal{A}_{m+l-1}(X)} .
$$

### 3.3 Corollaries

In this section we present several previously known results in this area, all implied by Theorem 3.2.1 together with the positive results of [2], [8] and [6] below.

Corollary 3.3.1 ([6], see Theorem 3.1.1). Let $X$, $Y$ be Banach spaces and suppose that $X$ does not contain a subspace isomorphic to $\ell_{1}$. Then $\mathcal{P}_{w u}\left({ }^{n} X ; Y\right)=\mathcal{P}_{w s c}\left({ }^{n} X ; Y\right)$.

The next result was first formulated in [41].

Theorem 3.3.2. Let $X$ be a Banach space, $\ell_{1} \hookrightarrow X$. Then

$$
\overline{\mathcal{A}_{1}(X)} \varsubsetneqq \overline{\mathcal{A}_{2}(X)} \varsubsetneqq \cdots
$$

Proof. Combine Proposition 1.7.7 and Theorem 1.5.5.

Corollary 3.3.3 ([41]). Let $X$ be a Banach space admitting a non-compact linear operator $T \in \mathcal{L}\left(X ; \ell_{p}\right), p \in[1, \infty)$. Then, letting $n=\lceil p\rceil$, we obtain

$$
\begin{equation*}
\overline{\mathcal{A}_{n}(X)} \varsubsetneqq \overline{\mathcal{A}_{n+1}(X)} \varsubsetneqq \cdots \tag{3.10}
\end{equation*}
$$

Proof. By Proposition 1.7.9, we may assume that $T\left(B_{X}\right)$ contains the unit vectors in $\ell_{p}$. It then suffices to compose $T$ with the polynomial $P \in$ $\mathcal{P}\left({ }^{n} \ell_{p} ; \ell_{1}\right)$, given by formula $\left(x_{j}\right) \rightarrow\left(x_{j}^{n}\right)$, to obtain a non-compact $n$ homogeneous polynomial from $X$ into $\ell_{1}$. It remains to apply Theorem 3.2.1.

Corollary 3.3.4. Let $X=L_{p}([0,1]), 1 \leqslant p \leqslant \infty$, or $X=\ell_{\infty}$ or $X=C(K)$, where $K$ is a non-scattered compact. Then

$$
\overline{\mathcal{A}_{1}(X)} \varsubsetneqq \overline{\mathcal{A}_{2}(X)} \varsubsetneqq \ldots
$$

Proof. If $1<p<\infty, \ell_{2}$ is isomorphic to a complemented subspace of $L_{p}([0,1])([36]$ p. 210), therefore we may use Corollary 3.3.3. The spaces $L_{1}([0,1]), \ell_{\infty}, L_{\infty}([0,1])$ and $\mathcal{C}(K), K$ non-scattered, contain $\ell_{1}([36])$, therefore Theorem 3.3.2 applies.

Corollary 3.3.5. Given $1 \leqslant p<\infty$, we have the following:

$$
\overline{\mathcal{A}_{1}\left(\ell_{p}\right)}=\cdots=\overline{\mathcal{A}_{n-1}\left(\ell_{p}\right)} \varsubsetneqq \overline{\mathcal{A}_{n}\left(\ell_{p}\right)} \varsubsetneqq \overline{\mathcal{A}_{n+1}\left(\ell_{p}\right)} \varsubsetneqq \cdots
$$

where $n-1<p \leqslant n$.

Proof. By [6] we know that $\mathcal{P}^{n}\left(\ell_{p}\right)=\mathcal{P}_{w u}^{n}\left(\ell_{p}\right)$ whenever $n<p$. So, using Theorem 3.1.1, we obtain that $\overline{\mathcal{A}_{n-1}\left(\ell_{p}\right)}=\overline{\mathcal{A}_{1}\left(\ell_{p}\right)}$. The rest follows readily from Corollary 3.3.3.

Corollary 3.3.6. Let $X$ be a Banach space, $q>1, \frac{1}{p}+\frac{1}{q}=1$. Assume that $X^{*}$ has type $q$. Then for $n>p$ we have

$$
\overline{\mathcal{A}_{1}(X)} \varsubsetneqq \overline{\mathcal{A}_{n}(X)} \varsubsetneqq \overline{\mathcal{A}_{n+1}(X)} \varsubsetneqq \cdots .
$$

Proof. By Corollary 1.7.12, there is a normalized basic sequence $\left\{y_{k}\right\}_{k=1}^{\infty}$ in $X^{*}$ which has the upper $q$-estimate. Thus, $T: \ell_{q} \rightarrow X^{*}, T\left(e_{k}\right)=y_{k}$, is a non-compact bounded linear operator. Since $T$ is weakly compact, $T^{*}: X \rightarrow \ell_{p}$ is a non-compact operator. An appeal to Lemma 3.3.3 finishes the argument.

Corollary 3.3.7 ([29]). Let $X$ be a Banach space with an unconditional $F D D, \ell_{1} \leftrightarrow X$, and suppose that $n$ is the least integer such that there exists a $P \in \mathcal{P}\left({ }^{n} X\right)$ which is not weakly sequentially continuous. Then

$$
\overline{\mathcal{A}_{1}(X)}=\cdots=\overline{\mathcal{A}_{n-1}(X)} \varsubsetneqq \overline{\mathcal{A}_{n}(X)} \varsubsetneqq \overline{\mathcal{A}_{n+1}(X)} \varsubsetneqq \cdots
$$

Proof. It was shown in [29], by using the averaging technique from [9] as in [28], that under these assumptions $c_{0} \hookrightarrow \mathcal{P}\left({ }^{n} X\right)$.

### 3.4 Some open problems

In this section we list the main remaining open problems, which we have so far failed to solve, in spite of trying several approaches.

Problem 3.4.1. Give a description of $\overline{\mathcal{P}(X)}$ for a general separable Banach space $X$.

This problem is open even for $X=\ell_{2}$ !
Problem 3.4.2. Suppose that $X$ does not contain $\ell_{1}$ and $\mathcal{P}(X) \neq \mathcal{P}_{\text {wsc }}(X)$.
Is there a non-compact bounded linear operator from $X$ into $\ell_{p}$ for some $1 \leqslant p<\infty$ ?

An important remaining problem is the following.

Problem 3.4.3. Let $X$ be a separable Banach space not containing $\ell_{1}$ and let $n \in \mathbb{N}$ be the smallest integer such that $\mathcal{P}\left({ }^{n} X\right) \neq \mathcal{P}_{\text {wsc }}\left({ }^{n} X\right)$. Is then

$$
\overline{\mathcal{A}_{1}(X)}=\cdots=\overline{\mathcal{A}_{n-1}(X)} \subsetneq \overline{\mathcal{A}_{n}(X)} \subsetneq \overline{\mathcal{A}_{n+1}(X)} \subsetneq \cdots ?
$$

The answer to this problem is positive provided the following problem has a positive answer (see [44]).

Problem 3.4.4. Let $X$ be a separable Banach space not containing $\ell_{1}$ and let $n \geqslant 2$ be an integer such that $\mathcal{P}\left({ }^{n} X\right) \neq \mathcal{P}_{\text {wsc }}\left({ }^{n} X\right)$. Does then the space $\mathcal{P}\left({ }^{n} X\right)$ contain $c_{0}$ ?

Note that the opposite implication follows from Theorem 1.7.5.

Observe that if the dual $X^{*}$ contains a subspace isomorphic to $c_{0}$ or a superreflexive space, then we can conclude that (3.10) holds for some $n$. Indeed, in this case either $\ell_{1} \hookrightarrow X$ or, by using the James-Gurarii theorem ([36] p. 450), $X$ admits a non-compact linear operator into some $\ell_{p}$. This leaves us with two possibilities. If $X$ fails (3.10) for every $n \in \mathbb{N}$, then either $X^{*}$ is $\ell_{1}$-saturated or it contains a Tsirelson-like subspace $Y$, in the sense that $Y$ contains no copy of $\ell_{1}, c_{0}$ or a superreflexive space.

Problem 3.4.5. Let $X$ be a Banach space such that $X^{*}$ is $\ell_{1}$-saturated. Is then $\mathcal{P}(X)=\mathcal{P}_{w s c}(X)$ ?

## Chapter 4

## Some results on smooth functions

In this chapter we solve several open problems from the literature regarding the behavior of smooth functions on Banach spaces.

### 4.1 Non-complete $C^{k}$-smooth renormings

We begin with a problem posed in various papers, e.g. in [12] or [10], concerning the existence of a non-complete $C^{k}$-smooth renorming of a Banach space which admits a $C^{k}$-smooth equivalent norm, where $k \geqslant 2$. The noncomplete $C^{k}$-smooth renorming plays an important role in some applications regarding the so-called smooth negligibility and the existence of $C^{k}$-smooth diffeomorphisms between certain subsets of the given Banach space $X$, see e.g. [31]. Our result can be used to simplify some parts of the theory of these mappings, in particular the techniques which bypass the use of the non-complete norm, used in [10], are no longer needed. We begin with an auxiliary result.

Theorem 4.1.1. Let $X$ be a Banach space with $w^{*}$-sequentially compact dual ball. If $c_{0} \cong Y \hookrightarrow X$ then $Y$ contains a further subspace $c_{0} \cong Z \hookrightarrow Y$ such that $Z$ is complemented in $X$.

Proof. If $c_{0} \hookrightarrow X$ then $X^{*}$ has a quotient $\ell_{1}$. By the lifting property, we also have $\ell_{1} \hookrightarrow X^{*}$ is a complemented subspace, and moreover, the basis
$\left\{e_{j}\right\}$ of $c_{0}$ and $\left\{f_{j}\right\}$ of $\ell_{1}$ in $X^{*}$ form a biorthogonal system. Since $B_{X^{*}}$ is $w^{*}$-sequentially compact, by passing to a subsequence we get that $f_{j} \rightarrow f$ in $w^{*}$-topology. So $\left\{g_{2 j}\right\}=\left\{f_{2 j}-f_{2 j+1}\right\}$ is $w^{*}$-null, and also equivalent to an $\ell_{1}$-basis, which is still biorthogonal to $\left\{e_{2 j}\right\}$, again a $c_{0}$ basis sequence. Thus $T: X \rightarrow X, T(x)=\sum g_{2 j}(x) e_{2 j}$ is a projection, and $c_{0}$ is a complemented subspace of $X$.

In fact, a more general version of the above result was shown by Schlumprecht in his PhD thesis [58]. The condition on $X$ is quite common, e.g. all weak Asplund spaces or WLD spaces have it ([26], [35], [36]).

Theorem 4.1.2. Let $X$ be an infinite dimensional Banach space admitting a $C^{k}$-smooth norm, $k \geqslant 2$. Then $X$ admits a decomposition $X=Y \oplus Z$ where $Y$ is infinite dimensional and separable. In particular, $X$ admits a non-complete $C^{k}$-smooth renorming.

Proof. By Corollary 3.3 in [24] we have that either $c_{0} \hookrightarrow X$ or $X$ is superreflexive. Either way, using the previous Theorem 4.1.1 (or the existence of PRI on superreflexive spaces), $X=Y \oplus Z$ where $Y$ is infinite dimensional and separable. But since every separable Banach space injects into $c_{0}$, it admits a non-complete $C^{\infty}$-smooth norm. It follows that $X$ admits a $C^{k}$-smooth noncomplete norm.

We point out that for $k=1$ the existence of a (nonequivalent) $C^{1}$-smooth norm on a given $C^{1}$-smooth Banach space (or even any Asplund space) $X$ remains open.

### 4.2 Separating polynomials

In this section we present a theorem which solves a problem posed in [11], concerning an assumption used by these authors in the proof of their main result. Before we pass to the description of our result, let us recall that for every real Banach space $X$ one may construct its complexified version $X^{\mathbb{C}}$, which is (as a real Banach space) isomorphic to $X \oplus X$. The complex norm on $X^{\mathbb{C}}$ is not uniquely determined, but this fact plays no role in our argument. We refer to the paper [52] for details.

Theorem 4.2.1. Let $X$ be a real Banach space which admits a real analytic separating function whose complex extension exists and is Lipschitz on some strip around $X$, i.e. on $X+2 r B_{X_{\mathbb{C}}} \subset X^{\mathbb{C}}$, for some $r>0$. Then $X$ is superreflexive and admits a separating polynomial.

Proof. By contradiction. Let $f: B_{X} \rightarrow \mathbb{R}$ be a separating real analytic and Lipschitz function with $f(0)=0, d f(0)=0$ and $\inf _{S_{X}} f>1$, and such that the complex extension $\tilde{f}: B_{X}+r B_{X^{\mathbb{C}}} \rightarrow \mathbb{C}$ exists and is $K$-Lipschitz, $r>0$. Denote $S=B_{X}+r B_{X^{\mathbb{C}}} \subset X^{\mathbb{C}}$. This implies that $\tilde{f}$ is bounded by $K+r$ on $S$.
By the Cauchy formula [55] Thm. 10.28 (for the second derivative of $\tilde{f}$ )

$$
\begin{equation*}
d^{2} \tilde{f}(a)[h]=\frac{2}{2 \pi i} \int_{\gamma} \frac{\tilde{f}(a+\zeta h)}{\zeta^{3}} d \zeta \tag{4.1}
\end{equation*}
$$

holds for every $a, h \in B_{X}$, and the path $\gamma(t)=r e^{i t}, t \in[0,2 \pi]$. Noting that the denominator in the Cauchy formula is in absolute value $r^{3}$, we obtain that $d^{2} f(a)$ is uniformly bounded on $B_{X}$. Hence $d f$ is Lipschitz on $B_{X}$.

By a result of Fabian, Whitfield and Zizler in [37], Theorem 3.2 in [24] $X$ is superreflexive. By a result of Deville, Thm 4.1 in [24] $X$ has a separating polynomial.

### 4.3 Extension of uniformly differentiable functions

In the last part of this section we give a solution to an extension problem, posed in the monograph of Benyamini and Lindenstrauss [14] p. 278, concerning uniformly differentiable functions on the unit ball of a Banach space $X$. Suppose that $f: B_{X} \rightarrow \mathbb{R}$ is a uniformly differentiable function in the interior of the unit ball $B_{X}$. Is there a uniformly smooth extension of $f$ whose domain is the whole $X$, or at least some neighbourhood of $B_{X}$ ? A weaker version of this problem (if we expect a positive solution, i.e. the existence of some extension) would be to require that the extension coincides with $f$ at least in some open neighbourhood of the origin. We will show that even the weaker version of the problem has a negative solution. Our solution is based on the application of the theory of $\mathcal{W}$-class of Banach spaces, which was developed in a series of papers [42], [43], [25] and [20] (this class was
denoted by C -class in the first three papers), which provides a link between uniform smoothness and weak continuity.

Definition 4.3.1. Let $X, Y$ be normed linear spaces, $U \subset X$ open, $f \subset$ $\mathrm{C}^{k}(U ; Y)$ and $k \in \mathbb{N}$. We say that $f$ is $\mathrm{C}^{k,+}$-smooth on $U$ if $d^{k} f$ is uniformly continuous on $U$.

Definition 4.3.2. Let $\lambda \in(0,1]$. We say that a Banach space $X$ is a $\mathcal{W}_{\lambda}$-space (or that it belongs to the class $\mathcal{W}_{\lambda}$ ) if

$$
\mathcal{C}^{1,+}\left(B_{X}\right) \subset \mathfrak{C}_{w s C}\left(\lambda B_{X}\right)
$$

(in the sense of restriction). ${ }^{1}$ We say that a Banach space is a $\mathcal{W}$-space (or that it belongs to the class $\mathcal{W}$ ) if it is a $\mathcal{W}$-space for some $\lambda \in(0,1]$.

## Remark 4.3.3.

- Clearly, if $X$ is a $\mathcal{W}_{\lambda}$-space, then it is a $\mathcal{W}_{\xi}$-space for every $0<\xi<\lambda$. Conversely, if $X$ is a $\mathcal{W}_{\xi}$-space for every $0<\xi<\lambda$, then $X$ is a $\mathcal{W}_{\lambda}$-space.
- Every Schur space is trivially a $\mathcal{W}_{1}$-space.
- If $X$ is a $\mathcal{W}$-space, then $\mathcal{C}^{1,+}(X) \subset \mathfrak{C}_{w s C}(X)$.
- It was shown in [20] that every $C(K)$ ( $K$ scattered) space is a $\mathcal{W}_{1-}$ space. In particular, $c_{0}$ in the supremum norm is also a $\mathcal{W}_{1}$-space (this was shown in [42]).
- Being a $\mathcal{W}$-space is invariant under isomorphism, but the precise value of $\lambda$ may change.

Proposition 4.3.4. For every $m \in \mathbb{N}, m \geqslant 2$, there is an equivalent renorming of $c_{0}$ such that $\left(c_{0},\|\cdot\|_{m}\right)$ belongs to $\mathcal{W}_{\frac{1}{m}}$-class, but it does not belong to $\mathcal{W}_{\frac{1}{m-1}}$-class.

[^10]Proof. The renorming $\|\cdot\|_{m}$ of $c_{0}$ is determined by its closed unit ball $B_{m} \subset$ $c_{0}$,

$$
B_{m}=\overline{\operatorname{conv}}\left\{\left\{ \pm m e_{j}\right\}_{j=1}^{\infty} \cup B_{c_{0}}\right\} .
$$

Clearly,

$$
\begin{equation*}
B_{c_{0}} \subset B_{m} \subset m B_{c_{0}} \tag{4.2}
\end{equation*}
$$

Note that if $x=\left(x_{j}\right) \in B_{m}$ then $\operatorname{card}\left\{j:\left|x_{j}\right| \geqslant 1+\frac{1}{m}\right\} \leqslant m^{2}$. Indeed, suppose

$$
x=\sum_{k=1}^{n} a_{k} m e_{k}+a_{0}\left(\sum_{j=1}^{\infty} b_{j} e_{j}\right)=\sum_{j=1}^{\infty} x_{j} e_{j}, \text { where } \sum_{k=0}^{n} a_{k}=1 \text { and } a_{k} \geqslant 0 .
$$

Letting $A=\left\{k: a_{k} \geqslant \frac{1}{m^{2}}\right\}$, clearly $\operatorname{card}(A) \leqslant m^{2}$. Now $\left|x_{j}\right|=\mid a_{0} b_{j}+$ $a_{j} m \left\lvert\, \leqslant a_{0}+m a_{j}<1+\frac{1}{m}\right.$, unless $j \in A$. Choose $\phi_{m}: \mathbb{R} \rightarrow \mathbb{R}_{0}^{+}$a $C^{\infty}$ smooth even convex function, $\phi_{m}\left[-1-\frac{1}{m}, 1+\frac{1}{m}\right]=0, \phi_{m}(t)>0, t>$ $1+\frac{1}{m}$, and such that both $\phi_{m}, \phi_{m}^{\prime}$ are $\frac{1}{m^{2} 2^{m+1}}$-Lipschitz. Let now $\Phi_{m}(x)=$ $\sum_{j=1}^{\infty} \phi_{m}\left(x_{j}\right)$. It is clear from the previous discussion that $\Phi_{m}$ depends on at most $m^{2}$-coordinates in a neighbourhood of any interior point in $B_{m}$. Hence it is a uniformly differentiable symmetric function such that both $\Phi_{m}, d \Phi_{m}$ are $\frac{1}{2^{m+1}}$-Lipschitz. But $\Phi_{m}\left(t e_{j}\right)>0$ for every $t>1+\frac{1}{m}, j \in \mathbb{N}$, hence $\Phi_{m}$ restricted to $\frac{1}{m-1} B_{m}$ does not take weakly null sequences into null sequences.

Example 4.3.5. There is a Banach space $X$ and a uniformly differentiable function $f: B_{X} \rightarrow \mathbb{R}$ which cannot be extended to a uniformly differentiable function on any $\lambda B_{X}, \lambda>1$, preserving its original values in some neighbourhood of 0 .

Proof. Let $X=\oplus_{\ell_{2}} \sum_{m=2}^{\infty}\left(c_{0},\|\cdot\|_{m}\right), P_{m}: X \rightarrow\left(c_{0},\|\cdot\|_{m}\right)$ be the canonical projections onto the direct summands. Let $f(x)=\sum_{m=2}^{\infty} \Phi_{m} \circ P_{m}(x)$. The functions $f$ and $d f$ are 1-Lipschitz, so $f$ is uniformly differentiable (even with a Lipschitz derivative). It is also clear that (4.2) implies that $\Phi_{m}$ cannot be extended to $\left(1+\frac{1}{m-1}\right) B_{m}$, preserving its values on $\frac{1}{m-1} B_{m}$. Since $m$ can be chosen arbitrary large, the result follows.

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[^0]:    ${ }^{1}$ Some among the following definitions hold for vector spaces. For the sake of conciseness, let us consider Banach spaces in this introduction, as the main results we hint at concern Banach spaces.

[^1]:    ${ }^{2}$ Boundedness and continuity are equivalent.

[^2]:    ${ }^{1}$ It is straightforward that $\|\cdot\|$ defines a norm on the subspace of $L\left(X_{1}, \ldots, X_{n} ; Y\right)$ consisting of bounded multilinear mappings.

[^3]:    ${ }^{2}$ It represents the number of distributions of $d$ identical balls into $n$ distinct boxes.

[^4]:    ${ }^{3}$ Note that $\operatorname{deg} P$ is well-defined, as the homogeneous summands of a polynomial are uniquely determined.

[^5]:    ${ }^{4}$ For the sake of completeness, we also set $\mathcal{J}(0)=\{\varnothing\}$.

[^6]:    ${ }^{5}$ This terminology applies also to the case when $X=\mathbb{R}^{n}$.
    ${ }^{6}$ The coefficients $y_{\alpha}$ are given by $y_{\alpha}=\binom{d}{\alpha} \check{P}\left({ }^{\alpha_{1}} e_{1}, \ldots,{ }^{\alpha_{n}} e_{n}\right)$, where $\alpha \in \mathcal{J}(d)$.

[^7]:    ${ }^{7}$ This definition is motivated by the will to linearize multilinear mappings.
    ${ }^{8}$ This denotes the algebraic dual of $X_{j}$.

[^8]:    ${ }^{9} \mathrm{~A}$ CCB set is a closed, convex and bounded subset of a normed linear space $X$.
    ${ }^{10}$ Note that if $U$ is closed (for instance $U=X$ ), then the topology on $\mathcal{C}(U ; Y)$ is the topology of uniform convergence on bounded subsets of $U$.
    ${ }^{11} f \in \mathcal{C}_{w u}(U ; Y)$ if and only if for any CCB set $V$ and any $\varepsilon>0$ there are $\delta>0$ and $\phi_{1}, \ldots, \phi_{k} \in B_{X} *$ such that $\|f(x)-f(y)\|<\varepsilon$ whenever $x, y \in V$ are such that $\left|\phi_{j}(x-y)\right|<\delta$ for $j=1, \ldots, k$.

[^9]:    ${ }^{12}$ Unlike the $\|\cdot\|-\|\cdot\|$ continuity.
    ${ }^{13}$ See also [5].

[^10]:    ${ }^{1} X$ is a $\mathcal{W}_{\lambda}$-space if every uniformly differentiable function $f: B_{X} \rightarrow \mathbb{R}$ takes weakly Cauchy sequences in $\lambda B_{X}$ to convergent sequences.

