

ON A NONLINEAR ELLIPTIC SYSTEM WITH SYMMETRIC COUPLING

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Abstract

Multiplicity results are proved for the nonlinear elliptic system

$$\begin{cases} -\Delta u + g(v) = 0 \\ -\Delta v + g(u) = 0 \\ u = v = 0 \end{cases} \quad \begin{array}{l} \text{in } \Omega, \\ \text{on } \partial\Omega, \end{array} \quad (1)$$

where $\Omega \subset \mathbb{R}^N$ is a bounded domain with smooth boundary and $g : \mathbb{R} \rightarrow \mathbb{R}$ is a nonlinear C^1 -function which satisfies additional conditions. No assumption of symmetry on g is imposed.

Extensive use is made of a global version of the Lyapunov-Schmidt reduction method due to Castro and Lazer (see [C] and [CL]), and of symmetric versions of the Mountain Pass Theorem (see [AR] and [R]).

Key Words and phrases: Elliptic system, Lyapunov-Schmidt reduction method, Mountain Pass Theorem.

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1 Introduction

It is well-known that a symmetry in a differential equation often generates the existence of multiple solutions. Consider e.g. the superlinear and subcritical equation

$$-\Delta u = f(u), \quad \text{in } \Omega, \quad u|_{\partial\Omega} = 0, \quad (2)$$

where $f \in C(\mathbb{R})$ is a superlinear and subcritical nonlinearity. If $f(u)$ is an odd function, then the equation has the symmetry $u \mapsto -u$. Using the concept of index theories (e.g. the Krasnoselskii genus), one shows that this symmetry implies that the equation has infinitely many solutions.

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In this article we consider a semilinear elliptic system in which the symmetry is not given by an odd nonlinearity, but by a *symmetric coupling*. We consider systems of the following form

$$\begin{cases} -\Delta u + g(v) = 0 \\ -\Delta v + g(u) = 0 \\ u = v = 0 \end{cases} \quad \begin{array}{l} \text{in } \Omega, \\ \text{on } \partial\Omega, \end{array} \quad (3)$$

where $\Omega \subset \mathbb{R}^N$, $N \geq 2$, is a bounded domain with smooth boundary and $g : \mathbb{R} \rightarrow \mathbb{R}$ is a C^1 -function satisfying some assumptions to be specified later, but is not required to be odd. Note that this system allows the following symmetry:

$$T_1 : (u, v) \mapsto (v, u).$$

Indeed, looking at the associated functional (supposing it is well-defined)

$$J(u, v) = \int_{\Omega} \nabla u \cdot \nabla v + \int_{\Omega} G(u) + \int_{\Omega} G(v), \quad (4)$$

where $G(s) = \int_0^s g(t)dt$ is the primitive of g , we see that this functional is invariant under the group action $T = \{id, T_1\}$.

Thus, one may try to proceed similarly as for equation (2) by defining a suitable index. However, one encounters two major problems. First, the functional is strongly indefinite due to the first term in the functional. Second, the group T has an infinite-dimensional fixed point space, given by the pairs of functions of the form $\{(u, u)\}$. We overcome these difficulties by performing an infinite dimensional Lyapunov-Schmidt reduction (following Castro-Lazer [CL]). Surprisingly, the resulting reduced functional \tilde{J} has the classical \mathbb{Z}_2 -symmetry $\{id, -id\}$ (although, as we emphasize, no oddness assumption is taken for the nonlinearity), and so classical variational methods for the existence of multiple solutions can be employed.

We will denote by $0 < \lambda_1 < \lambda_2 \leq \dots \leq \lambda_k \leq \dots$ the sequence of eigenvalues of $-\Delta$ with zero Dirichlet boundary condition in Ω . Also, $\{\varphi_j\}_j$ will denote an orthonormal basis, in $H_0^1(\Omega)$, of eigenfunctions of $-\Delta$ in Ω with Dirichlet boundary condition. We will study the existence of multiple solutions for problem (3) under three different sets of conditions. For the first two sets, we assume g satisfies

$$(g_0) \quad g(0) = 0 \text{ and}$$

$$(g_1) \quad \inf_{t \in \mathbb{R}} g'(t) > -\lambda_1.$$

First, we consider the *superlinear setting*, in which we assume

$$(g_2) \quad \text{There exists a positive constant } C \text{ such that}$$

$$|g(t)| \leq C(1 + |t|^p), \text{ where } p \in (1, \frac{N+2}{N-2}) \text{ for all } t \in \mathbb{R}, \text{ and}$$

$$(g_3) \quad \text{There exists } R > 0 \text{ such that } 0 < \mu G(t) \leq tg(t), \text{ for } |t| > R, \text{ where } \mu > 2.$$

Secondly, we also consider the *asymptotically linear setting*, in which g is assumed to satisfy

$$(g_4) \quad g'(\infty) := \lim_{|t| \rightarrow \infty} \frac{g(t)}{t} \in (\lambda_k, \lambda_{k+1}) \text{ for some } k \geq 1.$$

Our main results read as follows.

Theorem A. (*superlinear case*) *If g satisfies $(g_0) - (g_3)$, problem (3) has infinitely many solutions.*

We observe that conditions (g_2) and (g_3) include the “classical” nonlinearity $g(t) = t|t|^{p-1}$. But we emphasize that Theorem A holds true for a more general kind of nonlinearities, e.g. $g(t) = (t^+)^p - (t^-)^q$, for $t \in \mathbb{R}$ and $1 < p, q < (N + 2)/(N - 2)$, without any further restriction on p and q .

In the asymptotically linear framework we have the following analogue of Theorem A.

Theorem B. (*asymptotically linear case*) *Assume g satisfies $(g_0) - (g_1)$ and (g_4) . If, in addition, $g'(0) < \lambda_j$ for $j \leq k$, then problem (3) has (at least) $2(k - j + 1)$ nontrivial solutions.*

On the other hand, we consider a third setting, in which we only assume

$$(g_5) \quad \sup_{t \in \mathbb{R}} g'(t) < \lambda_1.$$

We observe that under condition (g_5) , system (3) is equivalent to the system

$$\begin{cases} -\Delta u = h(v) \\ -\Delta v = h(u) \\ u = v = 0 \end{cases} \quad \begin{array}{l} \text{in } \Omega, \\ \text{on } \partial\Omega, \end{array} \quad (5)$$

where $h = -g$ satisfies $\inf h' > -\lambda_1$. We point out that (5) is the very analogue in systems of the single-equation problem (2). In this direction we prove the following result which shows that system (3) (or, equivalently, system (5)) has a *strong hidden symmetry*.

Theorem C. *Assume g satisfies (g_5) . Then (u, v) is a solution of (3) if and only if $u \equiv v$ and*

$$-\Delta u + g(u) = 0, \quad \text{in } \Omega, \quad u|_{\partial\Omega} = 0. \quad (6)$$

In other words, under condition (g_5) , solving system (3) is equivalent to solving the single-equation problem (6).

System (3) is Hamiltonian and our approach to it is variational, i.e. we define an energy functional $J : H_0^1(\Omega) \times H_0^1(\Omega) \rightarrow \mathbb{R}$ by

$$J(u, v) = \int_{\Omega} (\nabla u \cdot \nabla v + G(u) + G(v)) \, d\zeta,$$

where $G(t) := \int_0^t g(s) \, ds$. Assuming either (g_2) or (g_4) , this functional is of class C^1 (see [R]) and

$$\partial_u J(u, v)\varphi = \int_{\Omega} (\nabla \varphi \cdot \nabla v + g(u)\varphi) \, d\zeta, \quad \forall u, v, \varphi \in H_0^1(\Omega), \quad (7)$$

and

$$\partial_v J(u, v)\psi = \int_{\Omega} (\nabla u \cdot \nabla \psi + g(v)\psi) \, d\zeta, \quad \forall u, v, \psi \in H_0^1(\Omega). \quad (8)$$

Thus, because of classical regularity theory (see [GT]), critical points of J agree with classical solutions of problem (3). We then prove Theorem A and B showing the existence of critical points of J . Because of the form of the system

$$(u, v) \text{ is a solution of (3) if and only if } (v, u) \text{ is a solution of (3),} \quad (9)$$

as can be easily verified. This fact provides some symmetry on the functional J when it is written in appropriate coordinates.

The paper is organized as follows: in Section 2 we recall the Castro-Lazer version of the Lyapunov-Schmidt reduction method in an abstract setting. We then show that our functional J satisfies the conditions of such setting. In Section 3 we prove Theorem A and in Section 4 we prove Theorem B. In proving them, we recall and use appropriate symmetric versions of the Mountain Pass Theorem of Ambrosetti and Rabinowitz. Finally, in Section 5 we prove Theorem C.

2 Preliminaries

We begin by stating a global version of the Lyapunov-Schmidt method (see [C] and [CL]).

Lemma 2.1. *Let H be a real separable Hilbert space. Let Z and W be closed subspaces of H such that $H = Z \oplus W$. Let $J : H \rightarrow \mathbb{R}$ a function of class C^1 . If there exist $m > 0$ and $\sigma > 1$ such that*

$$\langle \nabla J(\mathbf{z} + \mathbf{w}) - \nabla J(\mathbf{z} + \mathbf{w}_1), \mathbf{w} - \mathbf{w}_1 \rangle \geq m \|\mathbf{w} - \mathbf{w}_1\|_H^\sigma \quad \forall \mathbf{z} \in Z \quad \forall \mathbf{w}, \mathbf{w}_1 \in W \quad (10)$$

then:

(i) *There exists a continuous function $\phi : Z \rightarrow W$ such that*

$$J(\mathbf{z} + \phi(\mathbf{z})) = \min_{\mathbf{w} \in W} J(\mathbf{z} + \mathbf{w}).$$

Moreover, given $\mathbf{z} \in Z$, $\phi(\mathbf{z})$ is the unique element of W such that

$$\langle \nabla J(\mathbf{z} + \phi(\mathbf{z})), \mathbf{w} \rangle = 0 \quad \forall \mathbf{w} \in W. \quad (11)$$

(ii) *The functional $\tilde{J} : Z \rightarrow \mathbb{R}$, defined by $\tilde{J}(\mathbf{z}) := J(\mathbf{z} + \phi(\mathbf{z}))$ for $\mathbf{z} \in Z$, is of class C^1 . Moreover,*

$$D\tilde{J}(\mathbf{z})\mathbf{h} = \langle \nabla \tilde{J}(\mathbf{z}), \mathbf{h} \rangle = \langle \nabla J(\mathbf{z} + \phi(\mathbf{z})), \mathbf{h} \rangle \quad \forall \mathbf{z}, \mathbf{h} \in Z. \quad (12)$$

(iii) *Given $\mathbf{z} \in Z$, \mathbf{z} is a critical point of \tilde{J} if and only if $\mathbf{z} + \phi(\mathbf{z})$ is a critical point of J .*

Assuming (g_1) and either (g_2) or (g_4) , we intend to apply Lemma 2.1 to the functional $J : H_0^1(\Omega) \times H_0^1(\Omega) \rightarrow \mathbb{R}$ defined as

$$J(u, v) = \int_{\Omega} (\nabla u \cdot \nabla v + G(u) + G(v)) d\zeta,$$

where $G(t) := \int_0^t g(s)ds$. First, it is well-known that assuming either (g_2) or (g_4) , this functional is of the class C^1 (see [R]) and

$$\partial_u J(u, v)\varphi = \int_{\Omega} (\nabla\varphi \cdot \nabla v + g(u)\varphi) d\zeta, \quad \forall u, v, \varphi \in H_0^1(\Omega), \quad (13)$$

and

$$\partial_v J(u, v)\psi = \int_{\Omega} (\nabla u \cdot \nabla\psi + g(v)\psi) d\zeta, \quad \forall u, v, \psi \in H_0^1(\Omega). \quad (14)$$

Let us take $H = H_0^1(\Omega) \times H_0^1(\Omega)$ equipped with the inner product $\langle (u_1, v_1), (u_2, v_2) \rangle = \langle u_1, u_2 \rangle_{H_0^1} + \langle v_1, v_2 \rangle_{H_0^1}$. Here, $\langle f_1, f_2 \rangle_{H_0^1} = \int_{\Omega} \nabla f_1 \cdot \nabla f_2$. Let us define $W := \{\mathbf{w} = (w, w) : w \in H_0^1(\Omega)\}$ and $Z := \{\mathbf{z} = (z, -z) : z \in H_0^1(\Omega)\}$. Then $H_0^1(\Omega) \times H_0^1(\Omega) = Z \oplus W$. Let us verify (10). Let $\mathbf{z} \in Z$ and $\mathbf{w}, \mathbf{w}_1 \in W$. Then

$$\begin{aligned} & \langle \nabla J(\mathbf{z} + \mathbf{w}) - \nabla J(\mathbf{z} + \mathbf{w}_1), \mathbf{w} - \mathbf{w}_1 \rangle \\ &= \langle \nabla J(z + w, -z + w) - \nabla J(z + w_1, -z + w_1), (w - w_1, w - w_1) \rangle \\ &= [\partial_u J(z + w, -z + w) - \partial_u J(z + w_1, -z + w_1)](w - w_1) \\ & \quad + [\partial_v J(z + w, -z + w) - \partial_v J(z + w_1, -z + w_1)](w - w_1) \\ &= 2 \int_{\Omega} |\nabla(w - w_1)|^2 + \int_{\Omega} [g(z + w) - g(z + w_1)](w - w_1) \\ & \quad + \int_{\Omega} [g(-z + w) - g(-z + w_1)](w - w_1). \end{aligned}$$

Because of (g_1) , there exists $\epsilon \in (0, \lambda_1)$ such that $g'(t) \geq -\lambda_1 + \epsilon$ for all $t \in \mathbb{R}$. Thus, the Mean Value Theorem, the previous identities, and Poincaré's $\frac{1}{2}$'s Inequality give us

$$\begin{aligned} & \langle \nabla J(\mathbf{z} + \mathbf{w}) - \nabla J(\mathbf{z} + \mathbf{w}_1), \mathbf{w} - \mathbf{w}_1 \rangle \\ & \geq 2 \int_{\Omega} |\nabla(w - w_1)|^2 + 2(-\lambda_1 + \epsilon) \int_{\Omega} (w - w_1)^2 \\ & \geq 2 \int_{\Omega} |\nabla(w - w_1)|^2 + 2 \frac{(-\lambda_1 + \epsilon)}{\lambda_1} \int_{\Omega} |\nabla(w - w_1)|^2 \\ & = 2 \frac{\epsilon}{\lambda_1} \int_{\Omega} |\nabla(w - w_1)|^2 = \frac{\epsilon}{\lambda_1} \|\mathbf{w} - \mathbf{w}_1\|_H^2. \end{aligned}$$

We have then verified the hypotheses of Lemma 2.1. Thus, there exist a continuous function $\mathbf{w} \equiv \phi : Z \rightarrow W$ and a functional $\tilde{J} : Z \rightarrow \mathbb{R}$ which satisfy (i), (ii) and (iii). Because of (iii), our concern becomes the existence of critical points of the functional \tilde{J} .

Observe that, given $\mathbf{z} = (z, -z) \in Z$, $\mathbf{w}(\mathbf{z}) = (w(z), w(z))$ and

$$\begin{aligned} \tilde{J}(\mathbf{z}) &= J(z + w(z), -z + w(z)) \\ &= \int_{\Omega} [|\nabla w(z)|^2 - |\nabla z|^2 + G(z + w(z)) + G(-z + w(z))] d\zeta. \end{aligned} \quad (15)$$

The symmetry of problem (3) expressed by condition (9) is translated into the following lemma.

Lemma 2.2. *If g satisfies (g_1) and either (g_2) or (g_4) , then the function $\mathbf{w} \equiv \phi$ and the functional \tilde{J} are even.*

Proof. Let $\mathbf{z} = (z, -z) \in Z$. First, let us verify that

$$\langle \nabla J(-z + w(z), z + w(z)), (\varphi, \varphi) \rangle = 0, \quad \forall \varphi \in H_0^1(\Omega)$$

which, by uniqueness in (i) of Lemma 2.1, implies that $\mathbf{w}(\mathbf{z}) = \mathbf{w}(-\mathbf{z})$. Indeed, observe that

$$\begin{aligned} & \langle \nabla J(-z + w(z), z + w(z)), (\varphi, \varphi) \rangle \\ &= \partial_u J(-z + w(z), z + w(z))\varphi + \partial_v J(-z + w(z), z + w(z))\varphi \\ &= \int_{\Omega} \nabla \varphi \cdot \nabla(z + w(z)) + g(-z + w(z))\varphi \, d\zeta + \int_{\Omega} \nabla(-z + w(z)) \cdot \nabla \varphi + g(z + w(z))\varphi \, d\zeta \\ &= \int_{\Omega} \nabla \varphi \cdot \nabla(-z + w(z)) + g(z + w(z))\varphi \, d\zeta + \int_{\Omega} \nabla(z + w(z)) \cdot \nabla \varphi + g(-z + w(z))\varphi \, d\zeta \\ &= \partial_u J(z + w(z), -z + w(z))\varphi + \partial_v J(z + w(z), -z + w(z))\varphi \\ &= \langle \nabla J(z + w(z), -z + w(z)), (\varphi, \varphi) \rangle = 0, \quad \forall \varphi \in H_0^1(\Omega). \end{aligned}$$

Hence, given $z \in H_0^1(\Omega)$,

$$\begin{aligned} \tilde{J}(-\mathbf{z}) &= J(-z + w(-z), z + w(-z)) \\ &= J(-z + w(z), z + w(z)) \\ &= \int_{\Omega} (|\nabla w(z)|^2 - |\nabla(-z)|^2 + G(-z + w(z)) + G(z + w(z))) \, d\zeta \\ &= J(z + w(z), -z + w(z)) \\ &= \tilde{J}(\mathbf{z}). \end{aligned}$$

□

Remark 1: Observe that from condition (g_1) and Lemma 2.1, we conclude that the set of candidates to be solutions of (3) is contained in the graph $\{\mathbf{z} + \mathbf{w}(\mathbf{z}) : \mathbf{z} \in Z\}$. From condition (g_0) we have $\mathbf{w}(\mathbf{0}) = \mathbf{0}$. Hence, combining these two facts, we observe that under $(g_0) - (g_1)$ the unique solution (u, v) of (3) with $u \equiv v$, i.e living in the set of fixed points of the action group, is the trivial one. Compare this with Theorem C.

3 Proof of Theorem A

Throughout this section we assume g satisfies (g_0) , (g_1) , (g_2) and (g_3) . To prove Theorem A we make use of the following version of the Symmetric Mountain Pass Theorem (see e. g. [R]). We recall that if E is a Banach space and $I \in C^1(E, \mathbb{R})$, a sequence $\{e_n\}$ in E is a (PS)-sequence for the functional I , provided that

$$\forall n \in \mathbb{N}, \quad |I(e_n)| \leq C \quad \text{and} \quad DI(e_n) \longrightarrow 0, \quad n \rightarrow \infty. \quad (16)$$

The functional I is said to satisfy the (PS)-condition on E if every (PS)-sequence in E has a convergent subsequence.

Theorem 3.1. *Let $E = E_1 \oplus E_2$ be an infinite dimensional Banach space, where E_1 is a finite dimensional subspace. Let us assume $I \in C^1(E, \mathbb{R})$ is even, satisfies the Palais-Smale condition and $I(0) = 0$. Assume, in addition, I satisfies:*

(I₁) There exist positive constants α and ρ such that $I|_{\partial B_\rho \cap E_2} \geq \alpha$.

(I₂) For each finite dimensional subspace $X \subset E$ there exists an $R = R(X) > 0$ such that $I|_{X \setminus B_R(0)} \leq 0$.

Then I possesses an unbounded sequence of critical values.

We apply Theorem 3.1 to the functional $-\tilde{J}$. To this end, let $j \in \mathbb{N}$ such that $g'(0) < \lambda_j$. We take $E_1 := \langle (\varphi_1, -\varphi_1), \dots, (\varphi_{j-1}, -\varphi_{j-1}) \rangle \subset Z$ and $E_2 = E_1^\perp \subset Z$.

Claim 1: Under assumptions (g₀)-(g₃) functional $-\tilde{J}$ satisfies (I₁).

Proof. Let us consider the functional $F : H_0^1(\Omega) \rightarrow \mathbb{R}$ defined as

$$\begin{aligned} F(z) &= -J(z, -z) = \int_{\Omega} (|\nabla z|^2 - G(z) - G(-z)) d\zeta \\ &= \int_{\Omega} \left(\frac{1}{2} |\nabla z|^2 - G(z) \right) d\zeta + \int_{\Omega} \left(\frac{1}{2} |\nabla(-z)|^2 - G(-z) \right) d\zeta. \end{aligned}$$

Because of hypothesis (g₀) and the variational characterization of λ_j (see [R] or [CV]), $F|_{\langle \varphi_1, \dots, \varphi_{j-1} \rangle^\perp}$ has a strict local minimum at zero and there exist positive constants α and ρ such that

$$F(z) \geq \alpha \quad \forall z \in \partial B_\rho \cap \langle \varphi_1, \dots, \varphi_{j-1} \rangle^\perp \subset H_0^1(\Omega).$$

Hence, for each $\mathbf{z} = (z, -z) \in \partial B_{\sqrt{2}\rho} \cap E_2 \subset Z$,

$$-\tilde{J}(\mathbf{z}) = - \min_{w \in H_0^1(\Omega)} J(z+w, -z+w) \geq -J(z, -z) = F(z) \geq \alpha. \quad \square$$

Claim 2: Under assumptions (g₀)-(g₃) the functional $-\tilde{J}$ satisfies (I₂).

Proof. Let X be a finite dimensional subspace of Z . Then, there exists a constant $\gamma_X > 0$ such that $\|z\|^2 \leq \gamma_X \|z\|_{L^2}^2$ for all $\mathbf{z} = (z, -z) \in X$. Using hypothesis (g₃) and integrating,

$$G(t) \geq a|t|^\mu - b$$

where $a > 0$ and $b > 0$ are constants. Since $\mu > 2$, given any $\alpha > 0$, there exists a constant C_α such that

$$a|t|^\mu - b \geq \frac{\alpha}{2} t^2 + C_\alpha$$

(for this, simply consider $h(t) := a|t|^\mu - \frac{\alpha}{2} t^2 - b$, which is bounded below and continuous). Thus,

$$G(t) \geq \frac{\alpha}{2} t^2 + C_\alpha \quad \forall t \in \mathbb{R}.$$

Therefore, given $\mathbf{z} = (z, -z) \in X$, $\mathbf{w}(\mathbf{z}) = (w(z), w(z))$,

$$G(z + w(z)) + G(-z + w(z)) \geq \frac{\alpha}{2} (z + w(z))^2 + \frac{\alpha}{2} (-z + w(z))^2 + 2C_\alpha.$$

We then have

$$\begin{aligned} -\tilde{J}(\mathbf{z}) &= \int_{\Omega} [|\nabla z|^2 - |\nabla w(z)|^2 - G(z + w(z)) - G(-z + w(z))] d\zeta \\ &\leq \gamma_X \int_{\Omega} z^2 d\zeta - \alpha \int_{\Omega} z^2 d\zeta - \alpha \int_{\Omega} (w(z))^2 d\zeta - 2\widehat{C}_\alpha \\ &\leq (\gamma_X - \alpha) \int_{\Omega} z^2 - 2\widehat{C}_\alpha. \end{aligned}$$

Thus, taking $\alpha > \gamma_X$, we have that

$$-\tilde{J}(\mathbf{z}) \longrightarrow -\infty, \quad \text{as } \|\mathbf{z}\| \rightarrow \infty, \quad \mathbf{z} \in X.$$

Since, X is arbitrary we have verified (I_2) . ■

It remains to show that \tilde{J} satisfies the Palais-Smale condition.

Lemma 3.1. *Under the assumptions (g_0) - (g_3) the functional \tilde{J} satisfies the (PS)-condition.*

Proof. Observe that from (11) and (12), it suffices to verify that J satisfies the Palais-Smale condition. Let $\{(u_n, v_n)\}_n \subset H_0^1(\Omega) \times H_0^1(\Omega)$ be a (PS)-sequence. We want to extract a strongly convergent subsequence. Due to the form of DJ , the compactness on the Sobolev Embeddings and Vainberg's Lemma (see e.g. [MZ]), we just have to prove that $\{u_n\}_n$ and $\{v_n\}_n$ are bounded sequences in $H_0^1(\Omega)$.

Condition (16) implies that there exists a sequence $\{\varepsilon_n\}_n$, $\varepsilon_n > 0$ and $\varepsilon_n \rightarrow 0^+$ so that

$$|DJ(u_n, v_n)[\phi, \psi]| \leq \varepsilon_n(\|\phi\| + \|\psi\|), \quad \forall \phi, \psi \in H_0^1(\Omega). \quad (17)$$

We take as test functions $\phi = \frac{1}{2}u_n$ and $\psi = \frac{1}{2}v_n$ to get

$$\begin{aligned} C &+ \frac{\varepsilon_n}{2}(\|u_n\| + \|v_n\|) \\ &\geq \frac{1}{2}DJ(u_n, v_n)[u_n, v_n] - J(u_n, v_n) \\ &= \int_{\Omega} \{-G(v_n) - G(u_n)\} + \frac{1}{2} \int_{\Omega} \{g(u_n)u_n + g(v_n)v_n\} \\ &\geq \frac{1}{2} \int_{\Omega} \{g(v_n)v_n - \mu G(v_n)\} + \frac{1}{2} \int_{\Omega} \{g(u_n)(u_n) - \mu G(u_n)\} \\ &\quad + \left(\frac{\mu}{2} - 1\right) \int_{\Omega} \{G(v_n) + G(u_n)\}. \end{aligned}$$

So, changing the constant C if necessary, we find by (g_3) that

$$\int_{\Omega} G(u_n) + G(v_n) \leq C[1 + \varepsilon_n(\|u_n\| + \|v_n\|)]. \quad (18)$$

Since $\{J(u_n, v_n)\}_n$ is bounded, we can choose a large positive constant C such that

$$\left| \int_{\Omega} \nabla u_n \cdot \nabla v_n + \int_{\Omega} G(u_n) + G(v_n) \right| \leq C. \quad (19)$$

Because of hypothesis (g_3) , $|G(t)| - G(t) = 0$, for every $|t| \geq R$, so it is a bounded function. Thus, we get from (18) and (19) that

$$\begin{aligned} \left| \int_{\Omega} \nabla u_n \cdot \nabla v_n \right| &\leq \int_{\Omega} |G(u_n)| + |G(v_n)| + C \\ &\leq \int_{\Omega} G(u_n) + G(v_n) + C \\ &\leq C[1 + \varepsilon_n(\|u_n\| + \|v_n\|)]. \end{aligned} \quad (20)$$

From (17), testing against $[\phi, \psi] = [u_n, v_n]$, we obtain

$$\left| 2 \int_{\Omega} \nabla u_n \cdot \nabla v_n + \int_{\Omega} g(u_n)u_n + g(v_n)v_n \right| \leq \varepsilon_n(\|u_n\| + \|v_n\|).$$

So, by (20) we obtain

$$\int_{\Omega} g(u_n)u_n + g(v_n)v_n \leq C[1 + \varepsilon_n(\|u_n\| + \|v_n\|)]. \quad (21)$$

On the other hand, using again (17) and testing against $[\phi, \psi] = [0, u_n]$, we have

$$\left| \int_{\Omega} |\nabla u_n|^2 + g(v_n)u_n \right| \leq \varepsilon_n \|u_n\|. \quad (22)$$

Now let us estimate the second term in left-hand side of inequality (22). Using Hölder inequality we have

$$\left| \int_{\Omega} g(v_n)u_n \right| \leq \left(\int_{\Omega} |g(v_n)|^{1+\frac{1}{p}} \right)^{\frac{p}{1+p}} \left(\int_{\Omega} |u_n|^{1+p} \right)^{\frac{1}{1+p}} \quad (23)$$

Now note that for suitable positive constants c, d_1, d_2 ,

$$|g(t)|^{1+\frac{1}{p}} \leq c |g(t)||t| + d_1 \leq c g(t) + d_2. \quad (24)$$

Indeed, the first inequality in (24) follows from hypothesis (g_2) , since

$$|g(t)|^{\frac{1}{p}} \leq C |t| + d :$$

- for $|t| \geq 1$

$$\begin{aligned} |g(t)|^{1+\frac{1}{p}} &\leq C |g(t)||t| + d |g(t)| \\ &\leq C |g(t)||t| + d |g(t)||t|. \end{aligned}$$

- for $|t| \leq 1$ we see that $|g(t)|$ is simply bounded. So the first inequality in (24) holds. As for the second inequality in (24), we write

$$|g(t)||t| = g(t) \cdot t + |g(t)||t| - g(t) \cdot t,$$

and observe that, because of (g_3) , $|g(t)||t| - g(t) \cdot t = 0$, for $|t| \geq R$. So this difference remains bounded in \mathbb{R} and the inequality holds.

From (21), (23) and (24), we get that

$$\begin{aligned} \left| \int_{\Omega} g(v_n)u_n \right| &\leq (c \int_{\Omega} g(v_n)v_n + d_2)^{\frac{p}{1+p}} \|u_n\|_{L^{1+p}} \\ &\leq (C[1 + \varepsilon_n(\|u_n\| + \|v_n\|)])^{\frac{p}{1+p}} \|u_n\|. \end{aligned}$$

Then, by (22),

$$\int_{\Omega} |\nabla u_n|^2 \leq \varepsilon_n \|u_n\| + (C[1 + \varepsilon_n(\|u_n\| + \|v_n\|)])^{\frac{p}{1+p}} \|u_n\|.$$

In a similar fashion, taking $[\phi, \psi] = [v_n, 0]$ in (17), we get the analogous estimate

$$\int_{\Omega} |\nabla v_n|^2 \leq \varepsilon_n \|v_n\| + (C[1 + \varepsilon_n(\|u_n\| + \|v_n\|)])^{\frac{p}{1+p}} \|v_n\|.$$

Joining these two estimates we obtain

$$\|u_n\|^2 + \|v_n\|^2 \leq \varepsilon_n(\|u_n\| + \|v_n\|) + C(\|u_n\| + \|v_n\|)^{\frac{2p+1}{1+p}} + K.$$

Since $\frac{2p+1}{1+p} < 2$, the sequence $\{(u_n, v_n)\}_n$ is bounded in H and the proof of the lemma is complete. \square

4 Proof of Theorem B

Throughout this section we assume that g satisfies (g_0) , (g_1) and (g_4) . To prove Theorem B we make use of the following version of the Symmetric Mountain Pass Theorem (see e.g. [AR], [BBF], and [S]).

Theorem 4.1. *Let $E = E_1 \oplus E_2$ be a real Banach space, where E_1 is a finite dimensional subspace. Let $X \subset E$ be a finite dimensional subspace of E such that $\dim E_1 < \dim X$. Suppose that $I \in C^1(E, \mathbb{R})$ is an even functional, satisfying $I(\mathbf{0}) = 0$ and*

(I₁) *There exists a positive constant ρ such that $I|_{\partial B_\rho \cap E_2} \geq 0$.*

(I₂) *There exists $M > 0$ such that $\max_{z \in X} I(z) < M$.*

If I satisfies the Palais-Smale condition at level c , for every $c \in [0, M]$, then I possesses (at least) $\dim X - \dim E_1$ pairs of nontrivial critical points.

As in Section 3, we take $E_1 := \langle (\varphi_1, -\varphi_1) \dots, (\varphi_{j-1}, -\varphi_{j-1}) \rangle$ and $E_2 = E_1^\perp$. As we proved in the previous section, the fact that $-\tilde{J}$ satisfies (I₁) comes from hypothesis (g_0) and the variational characterization of the eigenvalues, i.e. the local structure of the functional around zero in this case is similar to that of the superlinear setting.

Claim: Under hypotheses (g_0) , (g_1) and (g_4) , the functional $-\tilde{J}$ satisfies (I₂).

Proof. Let us take $X = \langle (\varphi_1, -\varphi_1) \dots, (\varphi_k, -\varphi_k) \rangle$. Since $g'(\infty) > \lambda_k$, taking a number $\alpha \in (\lambda_k, g'(\infty))$ it follows that

$$G(t) > \frac{\alpha}{2} t^2 + C_\alpha \quad \forall t \in \mathbb{R}.$$

The remaining of this proof is very similar to the proof of Claim 2 in Section 3 by simply using the inequality

$$\|x\|^2 \leq \lambda_k \int_{\Omega} x^2 \quad \forall x \in \langle \varphi_1, \dots, \varphi_k \rangle.$$

From this, given $\mathbf{z} = (z, -z) \in X$,

$$-\tilde{J}(\mathbf{z}) \leq (\lambda_k - \alpha) \|z\|_{L^2}^2 + \tilde{C}_\alpha \longrightarrow -\infty \text{ as } \|\mathbf{z}\| \rightarrow \infty, \mathbf{z} \in X. \quad \square$$

It remains to show that \tilde{J} satisfies the Palais-Smale condition. In this case, we follow the ideas of the corresponding proof for the problem with one equation and asymptotic (nonresonant) nonlinearities, although our proof requires a bit more of technicalities.

Lemma 4.1. *Under assumptions (g_0) , (g_1) and (g_4) the functional \tilde{J} satisfies the (PS)-condition.*

Proof. As before, from (11) and (12), it suffices to verify that J satisfies the Palais-Smale condition. We take a (PS)-sequence $\{(u_n, v_n)\}_n$ in $H_0^1(\Omega) \times H_0^1(\Omega)$ and again it is sufficient to prove that this sequence is bounded. In this case, we argue by contradiction. Let us assume that $\{\|(u_n, v_n)\|\}_n$ is not bounded. Passing to a subsequence, denoted the same for simplicity of notation, we can say that either $\|u_n\| \rightarrow \infty$ or $\|v_n\| \rightarrow \infty$. We claim that

- (I) if $\|u_n\| \rightarrow \infty$, then there exists a subsequence $\|v_{n_k}\| \rightarrow \infty$, and
- (II) if $\|v_n\| \rightarrow \infty$, then there exists a subsequence $\|u_{n_k}\| \rightarrow \infty$.

Indeed, let us prove (I) arguing by contradiction. If $\|u_n\| \rightarrow \infty$ and $\|v_n\| \leq C$, then, passing to a subsequence we have that

$$\begin{aligned} v_n \rightharpoonup v, \quad \text{in } H_0^1(\Omega) & \quad \frac{u_n}{\|u_n\|} \rightharpoonup \bar{u}, \quad \text{in } H_0^1(\Omega) \\ v_n \rightarrow v, \quad \text{in } L^r(\Omega) & \quad \frac{u_n}{\|u_n\|} \rightarrow \bar{u}, \quad \text{in } L^r(\Omega), \quad \text{for } r \in [1, \frac{2N}{N-2}). \end{aligned}$$

There exists a sequence $\{\varepsilon_n\}_n$, $\varepsilon_n > 0$ and $\varepsilon_n \rightarrow 0^+$ so that

$$|DJ(u_n, v_n)[\phi, \psi]| \leq \varepsilon_n(\|\phi\| + \|\psi\|), \quad \forall \phi, \psi \in H_0^1(\Omega). \quad (25)$$

Testing $\partial_v J(u_n, v_n)$ against $\frac{u_n}{\|u_n\|}$ and using (25) we get that

$$\left| \|u_n\| + \int_{\Omega} g(v_n) \frac{u_n}{\|u_n\|} \right| \leq \varepsilon_n.$$

From (g_4) , $|g(t)| \leq C(1 + |t|)$ for all $t \in \mathbb{R}$. Using Vainberg's Lemma (see [MZ]) we have that

$$\int_{\Omega} g(v_n) \frac{u_n}{\|u_n\|} \longrightarrow \int_{\Omega} g(v) \bar{u}$$

and so we get

$$\|u_n\| \longrightarrow - \int_{\Omega} g(v) \bar{u}, \quad \text{as } n \rightarrow \infty.$$

This contradicts our initial assumption. We proceed in an analogue way to prove (II) and therefore the claim is proved.

Now, using the claim, and passing to a subsequence, we can assume without loss of generality that:

$$\|u_n\| \rightarrow \infty \quad \text{and} \quad \|v_n\| \rightarrow \infty.$$

Hence, there exist $u, v \in H_0^1(\Omega)$ such that

$$\begin{aligned} \frac{u_n}{\|u_n\|} \rightharpoonup \bar{u}, \quad \text{in } H_0^1(\Omega) & \quad \frac{v_n}{\|v_n\|} \rightharpoonup \bar{v}, \quad \text{in } H_0^1(\Omega) \\ \frac{u_n}{\|u_n\|} \rightarrow \bar{u}, \quad \text{in } L^r(\Omega) & \quad \frac{v_n}{\|v_n\|} \rightarrow \bar{v}, \quad \text{in } L^r(\Omega), \quad \text{for } r \in [1, \frac{2N}{N-2}). \end{aligned}$$

We claim that $\{\|u_n\|\}_n$ and $\{\|v_n\|\}_n$ go to infinity at the same rate. More precisely, we claim that

$$\lim_{n \rightarrow \infty} \frac{\|u_n\|}{\|v_n\|} = 1. \quad (26)$$

To prove this claim, we first test $\partial_u J(u_n, v_n)$ against $\frac{v_n}{\|v_n\|}$ and then divide by $\|u_n\|$ to get

$$\left| \frac{\|v_n\|}{\|u_n\|} + \int_{\Omega} \frac{g(u_n)}{\|u_n\|} \cdot \frac{v_n}{\|v_n\|} \right| \leq \frac{\varepsilon_n}{\|u_n\|}. \quad (27)$$

Assumption (g_4) implies that $g(t) = g'(\infty)t + \gamma(t)$, where $\gamma(t) = o(t)$, as $|t| \rightarrow \infty$. Then,

$$\int_{\Omega} \frac{g(u_n)}{\|u_n\|} \frac{v_n}{\|v_n\|} = g'(\infty) \int_{\Omega} \frac{v_n}{\|v_n\|} \frac{u_n}{\|u_n\|} + \int_{\Omega} \gamma(u_n) \frac{v_n}{\|v_n\| \|u_n\|}. \quad (28)$$

Now we show that

$$\int_{\Omega} \gamma(u_n) \frac{v_n}{\|v_n\| \|u_n\|} \rightarrow 0.$$

Indeed, just observe that given $\varepsilon > 0$ arbitrary, there exists $T \geq 0$ such that

$$\left| \frac{\gamma(t)}{t} \right| < \varepsilon, \quad \text{for } |t| \geq T.$$

On the other hand, $\gamma(t) = g(t) - g'(\infty)t$ is continuous in $[-T, T]$ and so it is bounded in $[-T, T]$. Thus, it follows that

$$\begin{aligned} \int_{\Omega} \left| \gamma(u_n) \frac{v_n}{\|v_n\| \|u_n\|} \right| &\leq \int_{\{|u_n| > T\}} + \int_{\{|u_n| \leq T\}} \\ &\leq \varepsilon \int_{\Omega} \left| \frac{u_n}{\|u_n\|} \frac{v_n}{\|v_n\|} \right| + \frac{C_T}{\|u_n\|} \int_{\Omega} \left| \frac{v_n}{\|v_n\|} \right| \\ &\leq C\varepsilon + \frac{C_T}{\|u_n\|} C \\ &\leq 2C\varepsilon, \quad \text{for } n \text{ large enough.} \end{aligned}$$

Hence, we can take the limit in (28) to get

$$\int_{\Omega} \frac{g(u_n)}{\|u_n\|} \frac{v_n}{\|v_n\|} \rightarrow \int_{\Omega} g'(\infty) \bar{u} \bar{v}.$$

This and (27) give

$$\frac{\|v_n\|}{\|u_n\|} \rightarrow - \int_{\Omega} g'(\infty) \bar{u} \bar{v}. \quad (29)$$

Arguing in a similar fashion, but now testing $\partial_v J(u_n, v_n)$ against $\frac{u_n}{\|u_n\|}$, we also obtain

$$\frac{\|u_n\|}{\|v_n\|} \rightarrow - \int_{\Omega} g'(\infty) \bar{u} \bar{v}, \quad (30)$$

which together with (29) implies that actually $\int_{\Omega} g'(\infty) \bar{u} \bar{v} = -1$ and therefore the claim is proved.

Let us now take $\phi \in H_0^1(\Omega)$. Using (25) we have that

$$\left| \int_{\Omega} \nabla \phi \cdot \nabla \left(\frac{v_n}{\|v_n\|} \right) + \frac{g(u_n)}{\|v_n\|} \phi \right| \rightarrow 0. \quad (31)$$

Due to the weak convergence of $\frac{v_n}{\|v_n\|}$ to \bar{v} , we know that

$$\int_{\Omega} \nabla \phi \cdot \nabla \left(\frac{v_n}{\|v_n\|} \right) \longrightarrow \int_{\Omega} \nabla \phi \cdot \nabla \bar{v}. \quad (32)$$

On the other hand, (26) implies that

$$\int_{\Omega} \frac{g(u_n)}{\|v_n\|} \phi \longrightarrow \int_{\Omega} g'(\infty) \bar{u} \phi. \quad (33)$$

To see why this is true, it is enough to notice that

$$\int_{\Omega} \frac{g(u_n)}{\|v_n\|} \phi = \int_{\Omega} \frac{g(u_n)}{\|u_n\|} \cdot \frac{\|u_n\|}{\|v_n\|} \phi = \frac{\|u_n\|}{\|v_n\|} \int_{\Omega} \frac{g'(\infty)u_n + \gamma(u_n)}{\|u_n\|} \phi$$

and arguing as above, it can be proved that $\int_{\Omega} \frac{\gamma(u_n)}{\|u_n\|} \phi \longrightarrow 0$.

From (31), (32) and (33), we have proven that

$$\forall \phi \in H_0^1(\Omega) : \int_{\Omega} \nabla \bar{v} \cdot \nabla \phi + g'(\infty) \bar{u} \phi = 0. \quad (34)$$

Using (29) and reasoning analogously, we also get that

$$\forall \phi \in H_0^1(\Omega) : \int_{\Omega} \nabla \bar{u} \cdot \nabla \phi + g'(\infty) \bar{v} \phi = 0. \quad (35)$$

From relations (34) and (35), testing both integrals against $\phi = \bar{v} + \bar{u}$ we obtain

$$\int_{\Omega} |\nabla(\bar{u} + \bar{v})|^2 = -g'(\infty) \int_{\Omega} (\bar{v} + \bar{u})^2.$$

Since $g'(\infty) > 0$, $\bar{v} = -\bar{u}$. Replacing this in any of the relations (34) or (35) we get that $\bar{u} = -\bar{v} \in H_0^1(\Omega)$ is a weak solution, and actually a classical one, to the problem

$$\begin{cases} -\Delta u = g'(\infty) u & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

This, as well as (29) and (30), imply that $g'(\infty) = \lambda_j$ for some $j \in \mathbb{N}$. This contradicts hypothesis (g_4) . Hence, a contradiction is reached assuming that $\{\|(u_n, v_n)\|\}_n$ is unbounded, and the conclusion of the lemma follows. \square

5 Proof of Theorem C

Assume condition (g_5) . Let us assume (u, v) is a solution of (3). Multiply the first equation in (3) by $u - v$, and then multiply the second equation by $u - v$. Taking the difference of both results, we get

$$\int_{\Omega} |\nabla(u - v)|^2 + (g(v) - g(u))(u - v) = 0$$

or, equivalently,

$$\int_{\Omega} |\nabla(u - v)|^2 = \int_{\Omega} (g(u) - g(v))(u - v).$$

Because of Mean Value Theorem and (g_5) , we have that

$$\int_{\Omega} |\nabla(u - v)|^2 \leq (\lambda_1 - \epsilon) \int_{\Omega} (u - v)^2,$$

for some small $\epsilon > 0$. From Poincarè's Inequality we conclude that $u \equiv v$.

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