

SAT-Based Proof Search in Intermediate Propositional Logics

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Abstract. We present a decision procedure for intermediate logics relying on a modular extension of the SAT-based prover intuitR for IPL (Intuitionistic Propositional Logic). Given an intermediate logic L and a formula α , the procedure outputs either a Kripke countermodel for α or the instances of the characteristic axioms of L that must be added to IPL in order to prove α . The procedure exploits an incremental SAT-solver; during the computation, new clauses are learned and added to the solver.

1 Introduction

Recently, Claessen and Rosén have introduced intuit [4], an efficient decision procedure for Intuitionistic Propositional Logic (IPL) based on the Satisfiability Modulo Theories (SMT) approach. The prover language consists of (flat) clauses of the form $\bigwedge A_1 \to \bigvee A_2$ (with A_i a set of atoms), which are fed to the SATsolver, and implication clauses of the form $(a \rightarrow b) \rightarrow c$ (a, b, c atoms); thus, we need an auxiliary clausification procedure to preprocess the input formula. The search is performed via a proper variant of the DPLL(\mathcal{T}) procedure [16], by exploiting an incremental SAT-solver; during the computation, whenever a semantic conflict is thrown, a new clause is learned and added to the SAT-solver. As discussed in [9], there is a close connection between the intuit approach and the known proof-theoretic methods. Actually, the decision procedure mimics the standard root-first proof search strategy for a sequent calculus strongly connected with Dyckhoff's calculus LJT [5] (alias G4ip). To improve performances, we have re-designed the prover by adding a restart operation, thus obtaining intuit [8] (intuit with Restart). Differently from intuit, the intuit procedure has a simple structure, consisting of two nested loops. Given a formula α , if α is provable in IPL the call intuit $\mathbf{R}(\alpha)$ yields a derivation of α in the sequent calculus introduced in [8], a plain calculus where derivations have a single branch. If α is not provable in IPL, the outcome of intuit $\mathbf{R}(\alpha)$ is a (typically small) countermodel for α , namely a Kripke model falsifying α . We stress that intuitR is highly performant: on the basis of a standard benchmarks suite, it outperforms intuit and other state-of-the-art provers (in particular, fCube [6] and intHistGC [12]).

In this paper we present intuitRIL, an extension of intuitR to Intermediate Logics, namely propositional logics extending IPL and contained in CPL (Classical Propositional Logic). Specifically, let α be a formula and L an axiomatizable intermediate logic having Kripke semantics; the call intuitRIL(α, L) tries to prove the validity of α in L. To this aim, the prover searches for a set Ψ containing instances of Ax(L), the characteristic axioms of L, such that α can be proved in IPL from Ψ . Note that this is different from other approaches, where the focus is on the synthesis of specific inference rules for the logic at hand (see, e.g., [17]). Basically, intuitRIL(α, L) searches for a countermodel \mathcal{K} for α , exploiting the search engine of intuitR: whenever we get \mathcal{K} , we check whether \mathcal{K} is a model of L. If this is the case, we conclude that α is not valid in L (and K is a witness to this). Otherwise, the prover selects an instance ψ of Ax(L) falsified in \mathcal{K} (there exists at least one); ψ is acknowledged as learned axiom and, after clausification, it is fed to the SAT-solver. We stress that a naive implementation of the procedure, where at each iteration of the main loop the computation restarts from scratch, would be highly inefficient: each time the SAT-solver should be initialized by inserting all the clauses encoding the input problem and all the clauses learned so far. Instead, we exploit an incremental SAT-solver, where clauses can be added but never deleted (hence, all the simplifications and optimisations performed by the solver are preserved); note that this prevents us from exploiting strategies based on standard sequent/tableaux calculi, where backtracking is required.

If the call intuitRIL(α, L) succeeds, by tracking the computation we get a derivation \mathcal{D} of α in the sequent calculus C_L (see Fig. 1); from \mathcal{D} we can extract all the axioms learned during the computation. We stress that the procedure is quite modular: to handle a logic L, one has only to implement a specific learning mechanism for L (namely: if \mathcal{K} is not a model of L, pick an instance of Ax(L)falsified in \mathcal{K}). The main drawback is that there is no general way to bound the learned axioms, thus termination must be investigated on a case-by-case basis. We guarantee termination for some relevant intermediate logics, such as Gödel-Dummett Logic GL, the family GL_n $(n \ge 1)$ of Gödel-Dummett Logics with depth bounded by n (GL₁ coincides with Here and There Logic, well known for its applications in Answer Set Programming [15]) and Jankov Logic (for a presentation of such logics see [2]). As a corollary, for each of the mentioned logic L we get a bounding function [3], namely: given α , we compute a bounded set Ψ_{α} of instances of Ax(L) such that α is valid in L iff α is provable in IPL from assumptions Ψ_{α} ; in general we improve the bounds in [1,3]. The intuitRIL Haskell implementation and other additional material (e.g., the omitted proofs) can be downloaded at https://github.com/cfiorentini/intuitRIL.

2 Basic Definitions

Formulas, denoted by lowercase Greek letters, are built from an enumerable set of propositional variables \mathcal{V} , the constant \perp and the connectives \land, \lor, \rightarrow ; moreover, $\neg \alpha$ stands for $\alpha \rightarrow \bot$ and $\alpha \leftrightarrow \beta$ stands for $(\alpha \rightarrow \beta) \land (\beta \rightarrow \alpha)$. Elements of the set $\mathcal{V} \cup \{\bot\}$ are called *atoms* and are denoted by lowercase Roman letters,

uppercase Greek letters denote sets of formulas. By \mathcal{V}_{α} we denote the set of propositional variables occurring in α . The notation is extended to sets: \mathcal{V}_{Γ} is the union of \mathcal{V}_{α} such that $\alpha \in \Gamma$; $\mathcal{V}_{\Gamma,\Gamma'}$ and $\mathcal{V}_{\Gamma,\alpha}$ stand for $\mathcal{V}_{\Gamma\cup\Gamma'}$ and $\mathcal{V}_{\Gamma\cup\{\alpha\}}$ respectively. A substitution is a map from propositional variables to formulas. By $[p_1 \mapsto \alpha_1, \ldots, p_n \mapsto \alpha_n]$ we denote the substitution χ such that $\chi(p) = \alpha_i$ if $p = p_i$ and $\chi(p) = p$ otherwise; the set $\{p_1, \ldots, p_n\}$ is the domain of χ , denoted by $\text{Dom}(\chi)$; ϵ is the substitution having empty domain. The application of χ to a formula α , denoted by $\chi(\alpha)$, is defined as usual; $\chi(\Gamma)$ is the set of $\chi(\alpha)$ such that $\alpha \in \Gamma$. The composition $\chi_1 \cdot \chi_2$ is the substitution mapping p to $\chi_1(\chi_2(p))$.

A (classical) interpretation M is a subset of \mathcal{V} , identifying the propositional variables assigned to true. By $M \models \alpha$ we mean that α is true in M; $M \models \Gamma$ iff $M \models \alpha$ for every $\alpha \in \Gamma$. Classical Propositional Logic (CPL) is the set of formulas true in every interpretation. We write $\Gamma \vdash_c \alpha$ iff $M \models \Gamma$ implies $M \models \alpha$, for every M. Note that α is CPL-valid (namely, $\alpha \in \text{CPL}$) iff $\emptyset \vdash_c \alpha$.

A (rooted) Kripke model is a quadruple $\langle W, \leq, r, \vartheta \rangle$ where W is a finite and non-empty set (the set of *worlds*), \leq is a reflexive and transitive binary relation over W, the world r (the root of \mathcal{K}) is the minimum of W w.r.t. \leq , and $\vartheta: W \mapsto 2^{\mathcal{V}}$ (the *valuation* function) is a map obeying the persistence condition: for every pair of worlds w_1 and w_2 of \mathcal{K} , $w_1 \leq w_2$ implies $\vartheta(w_1) \subseteq \vartheta(w_2)$; the triple $\langle W, \leq, r \rangle$ is called (*Kripke*) frame. The valuation ϑ is extended to a forcing relation between worlds and formulas as follows:

$$\begin{split} w \Vdash p \text{ iff } p \in \vartheta(w), \forall p \in \mathcal{V} \qquad w \nvDash \bot \qquad w \Vdash \alpha \land \beta \text{ iff } w \Vdash \alpha \text{ and } w \Vdash \beta \\ w \Vdash \alpha \lor \beta \text{ iff } w \Vdash \alpha \text{ or } w \Vdash \beta \qquad w \Vdash \alpha \to \beta \text{ iff } \forall w' \ge w, w' \Vdash \alpha \text{ implies } w' \Vdash \beta. \end{split}$$

By $w \Vdash \Gamma$ we mean that $w \Vdash \alpha$ for every $\alpha \in \Gamma$. A formula α is *valid* in the frame $\langle W, \leq, r \rangle$ iff for every valuation $\vartheta, r \Vdash \alpha$ in the model $\langle W, \leq, r, \vartheta \rangle$. Propositional Intuitionistic Logic (IPL) is the set of formulas valid in all frames. Accordingly, if there is a model \mathcal{K} such that $r \nvDash \alpha$ (here and below r designates the root of \mathcal{K}), then α is not IPL-valid; we call \mathcal{K} a *countermodel* for α . We write $\Gamma \vdash_i \delta$ iff, for every model $\mathcal{K}, r \Vdash \Gamma$ implies $r \Vdash \delta$; thus, α is IPL-valid iff $\emptyset \vdash_i \alpha$.

Let L be one of the logics IPL and CPL; then, L is closed under modus ponens $(\{\alpha, \alpha \to \beta\} \subseteq L \text{ implies } \beta \in L)$ and under substitution (for every χ , $\alpha \in L$ implies $\chi(\alpha) \in L$). An intermediate logic is any set of formulas L such that $IPL \subseteq L \subseteq CPL$, L is closed under modus ponens and under substitution. A model \mathcal{K} is an L-model iff $r \Vdash L$; if $r \nvDash \alpha$, we say that \mathcal{K} is an L-countermodel for α . An intermediate logic L can be characterized by a set of CPL-valid formulas, called the *L*-axioms and denoted by Ax(L). An *L*-axiom ψ of Ax(L) must be understood as a schematic formula, representing all the formulas of the kind $\chi(\psi)$; we call $\chi(\psi)$ an *instance* of ψ . Formally, IPL + Ax(L) is the intermediate logic collecting the formulas α such that $\Psi \vdash_i \alpha$, where Ψ is a finite set of instances of L-axioms from Ax(L). A bounding function for L is a map that, given α , yields a finite set Ψ_{α} of instances of L-axioms such that $\Psi_{\alpha} \vdash_{i} \alpha$. If L admits a computable bounding function, we can reduce L-validity to IPL-validity (see [3] for an in-depth discussion). Let \mathcal{F} be a class of frames and let $Log(\mathcal{F})$ be the set of formulas valid in all frames of \mathcal{F} ; then, $Log(\mathcal{F})$ is an intermediate logic. A logic L has Kripke semantics iff there exists a class of frames \mathcal{F} such that $L = \text{Log}(\mathcal{F})$; we also say that L is characterized by \mathcal{F} . Henceforth, when we mention a logic L, we leave understood that L is an axiomatizable intermediate logic having Kripke semantics.

Example 1 (GL). A well-known intermediate logic is Gödel-Dummett logic GL [2], characterized by the class of linear frames. An axiomatization of GL is obtained by adding the linearity axiom $\mathbf{lin} = (a \rightarrow b) \lor (b \rightarrow a)$ to IPL. Using the terminology of [3], GL is formula-axiomatizable: a bounding function for GL is obtained by mapping α to the set Ψ_{α} of instances of **lin** where a and b are replaced with subformulas of α . In [1] it is proved that it is sufficient to consider the subformulas of α of the kind $p \in \mathcal{V}_{\alpha}, \neg \beta, \beta_1 \rightarrow \beta_2$. In Lemma 4 we further improve this bound tacking as bounding function the following map:

$$\begin{aligned} \operatorname{Ax}_{\operatorname{GL}}(\alpha) &= \{ (a \to b) \lor (b \to a) \mid a, b \in \mathcal{V}_{\alpha} \} \cup \{ (a \to \neg a) \lor (\neg a \to a) \mid a \in \mathcal{V}_{\alpha} \} \\ &\cup \{ (a \to (a \to b)) \lor ((a \to b) \to a)) \mid a, b \in \mathcal{V}_{\alpha} \} \end{aligned}$$

Thus, if $\mathcal{V}_{\alpha} = \{a\}$, the only instance of **lin** to consider is $(a \to \neg a) \lor (\neg a \to a)$, independently of the size of α (the other instances are IPL-valid and can be omitted). As pointed out in [3], GL is not variable-axiomatizable, namely: it is not sufficient to consider instances of **lin** obtained by replacing a and b with variables from \mathcal{V}_{α} . As an example, let $\alpha = \neg a \lor \neg \neg a$; α is GL-valid, the only variable-replacement instance of **lin** is $\psi_{\alpha} = (a \to a) \lor (a \to a)$ and $\psi_{\alpha} \nvDash_i \alpha$. \Diamond We review the main concepts about the clausification procedure described

We review the main concepts about the clausification procedure described in [4]. Clauses φ and implication clauses λ are defined as

$$\varphi \coloneqq \bigwedge A_1 \to \bigvee A_2 \mid \bigvee A_2 \qquad \qquad \emptyset \subset A_k \subseteq \mathcal{V} \cup \{\bot\}, fork \in \{1, 2\} \\ \lambda \coloneqq (a \to b) \to c \qquad \qquad \qquad a \in \mathcal{V}, \ \{b, c\} \subseteq \mathcal{V} \cup \{\bot\}$$

where $\bigwedge A_1$ and $\bigvee A_2$ denote the conjunction and the disjunction of the atoms in A_1 and A_2 respectively ($\bigwedge \{a\} = \bigvee \{a\} = a$). Henceforth, $\bigwedge \emptyset \to \bigvee A_2$ must be read as $\bigvee A_2$; R, R_1, \ldots denote sets of clauses, X, X_1, \ldots sets of implication clauses. Given a set of implication clauses X, the *closure* of X, denoted by $(X)^*$, is the set of clauses $b \to c$ such that $(a \to b) \to c \in X$.

The following lemma states some properties of clauses and closures.

Lemma 1. (i) $R \vdash_i g$ iff $R \vdash_c g$, for every set of clauses R and every atom g. (ii) $X \vdash_i b \to c$, for every $b \to c \in (X)^*$. (iii) $\Gamma \vdash_i \alpha$ iff $\alpha \leftrightarrow g, \Gamma \vdash_i g$, where $g \notin \mathcal{V}_{\Gamma,\alpha}$.

Clausification. We assume a procedure Clausify that, given a formula α , computes sets of clauses R and X equivalent to α w.r.t. IPL. Formally, let α be a formula and let V be a set of propositional variables such that $\mathcal{V}_{\alpha} \subseteq V$. The procedure Clausify (α, V) computes a triple (R, X, χ) satisfying:

- (C1) $\Gamma, \alpha \vdash_{i} \delta$ iff $\Gamma, R, X \vdash_{i} \delta$, for every Γ and δ such that $\mathcal{V}_{\Gamma,\delta} \subseteq V$.
- (C2) $\operatorname{Dom}(\chi) = \mathcal{V}_{R,X} \setminus V$ and $\mathcal{V}_{\chi(p)} \subseteq V$ for every $p \in \operatorname{Dom}(\chi)$.
- (C3) $R, X \vdash_{i} p \leftrightarrow \chi(p)$ for every $p \in \text{Dom}(\chi)$.

$$\begin{array}{l} R \vdash_{c} g\\ R, X \Rightarrow g \end{array} \operatorname{cpl}_{0} & \begin{array}{c} R, A \vdash_{c} b & R, \varphi, X \Rightarrow g\\ R, X \Rightarrow g \end{array} \operatorname{cpl}_{1}(\lambda) & \begin{array}{c} \lambda = (a \rightarrow b) \rightarrow c \in X\\ A \subseteq \mathcal{V}_{R,X,g}\\ \varphi = \bigwedge (A \setminus \{a\}) \rightarrow c \end{array}$$

$$\begin{array}{c} \frac{R, (X)^{\star}, X \Rightarrow g}{\Rightarrow \alpha} \operatorname{Claus}_{0}(g, \chi) & \begin{array}{c} g \notin \mathcal{V}_{\alpha}\\ (R, X, \chi) = \operatorname{Clausify}(\alpha \leftrightarrow g, \mathcal{V}_{\alpha,g}) \end{array}$$

$$\begin{array}{c} \frac{R, R', (X')^{\star}, X, X' \Rightarrow g}{R, X \Rightarrow g} \operatorname{Claus}_{1}(\psi, \chi) & \begin{array}{c} \psi \in \operatorname{Ax}(L, \mathcal{V}_{R,X,g})\\ (R', X', \chi) = \operatorname{Clausify}(\psi, \mathcal{V}_{R,X,g}) \end{array}$$

$$\begin{array}{c} R \text{ is a set of clauses}\\ X \text{ is a set of implication clauses} & \pi(\rho) = \begin{cases} \langle \emptyset, [g \mapsto \alpha] \cdot \chi \rangle & \text{if } \rho = \operatorname{Claus}_{0}(g, \chi)\\ \langle \{\psi\}, \chi \rangle & \text{if } \rho = \operatorname{Claus}_{1}(\psi, \chi) \end{cases} \end{cases}$$

Fig. 1. The sequent calculus C_L .

Basically, clausification introduces new propositional variables to represent subformulas of α ; as a result we obtain a substitution χ which tracks the mapping on the new variables. Condition (C1) states that α can be replaced by $R \cup X$ in IPL reasoning. By (C2) the domain of χ consists of the new variables introduced in the clausification process. The following properties easily follow by (C1)-(C3):

(P1)
$$R, X \vdash_{i} \alpha$$
. (P2) $R, X \vdash_{i} \beta \leftrightarrow \chi(\beta)$ for every formula β .

We exploit a Clausify procedure essentially similar to the one described in [4], with slight modifications in order to match (C3). As discussed in [4], in IPL we can use a weaker condition (either $R, X \vdash_i p \to \chi(p)$ or $R, X \vdash_i \chi(p) \to p$ according to the case). It is not obvious whether the weaker condition should be more efficient; in many cases strong equivalences are more performant, maybe because they trigger more simplifications in the SAT-solver.

Example 2. Let $\alpha = (a \to b) \lor (b \to a)$ and $V = \{a, b\}$. The call Clausify (α, V) introduces the new variables \tilde{p}_0 and \tilde{p}_1 associated with the subformulas $a \to b$ and $b \to a$ respectively. Accordingly, the obtained sets R and X must satisfy $R, X \vdash_{i} \tilde{p}_{0} \leftrightarrow (a \rightarrow b) \text{ and } R, X \vdash_{i} \tilde{p}_{1} \leftrightarrow (b \rightarrow a).$ We get:

$$R = \{ \tilde{p}_0 \lor \tilde{p}_1, \ \tilde{p}_0 \land a \to b, \ \tilde{p}_1 \land b \to a \} \qquad \chi = [\tilde{p}_0 \mapsto a \to b, \ \tilde{p}_1 \mapsto b \to a] X = \{ (a \to b) \to \tilde{p}_0, \ (b \to a) \to \tilde{p}_1 \}$$

 \Diamond

otherwise

3 The Calculus C_L

g is an atom

Let L be an intermediate logic; we introduce the sequent calculus C_L to prove L-validity. We assume that L is axiomatized by a set Ax(L) of L-axioms; by ъ

$$\frac{R_{n-1} \vdash_{c} g}{R_{n-1}, X_{n-1} \Rightarrow g} \rho_{n} = \operatorname{cpl}_{0} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\vdots \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{Claus}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \text{ or } \rho_{i} = \operatorname{cpl}_{1} \\
\xrightarrow{R_{n-2}, X_{n-2} \Rightarrow g} \rho_{n-1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad \forall i \in \{1, \dots, n-1\}, \rho_{i} = \operatorname{cpl}_{1} \quad$$

Fig. 2. A C_L -derivation of $\Rightarrow \alpha$.

Ax(L, V) we denote the set of instances ψ of L-axioms such that $\mathcal{V}_{\psi} \subseteq V$. The calculus relies on a clausification procedure Clausify satisfying conditions (C1)–(C3) and acts on sequents $\Gamma \Rightarrow \delta$ such that:

– either $\Gamma = \emptyset$ or $\Gamma = R \cup X$ and $(X)^* \subseteq R$ and δ is an atom.

Rules of C_L are displayed in Fig. 1. Rule cpl_0 (initial rule) can only be applied if the condition $R \vdash_{c} g$ holds; if this is the case, the conclusion $R, X \Rightarrow g$ is an initial sequent, namely a top sequent of a derivation. The other rules depend on parameters that are made explicit in the rule name. A bottom-up application of cpl_1 requires the choice of an implication clause $\lambda = (a \rightarrow b) \rightarrow c$ from X, we call the main formula, and the selection of a set of atoms $A \subseteq \mathcal{V}_{R,X,q}$ such that $R, A \vdash_{c} b$, where b is the middle variable in λ . As discussed in [8,9], cpl₁ is a sort of generalization of the rule $L \rightarrow \rightarrow$ of the sequent calculus LJT/G4ip for IPL [5,18]. Rules Claus₀ and Claus₁ exploit the clausification procedure. Rule Claus₀ requires the clausification of the formula $\alpha \leftrightarrow g$, with g a new atom $(q \notin \mathcal{V}_{\alpha})$; in rule Claus₁, the clausified formula ψ is selected from Ax $(L, \mathcal{V}_{R,X,q})$. In both cases, the clauses returned by Clausify are stored in the premise of the applied rule and the computed substitution χ is displayed in the rule name; moreover, Claus_0 is annotated with the new atom g and Claus_1 with the chosen L-axiom ψ . To recover the relevant information associated with the application of a rule ρ , in Fig. 1 we define the pair $\pi(\rho) = \langle \Psi, \chi \rangle$, where Ψ is a set of instances of L-axioms and χ is a substitution. C_L -trees and C_L -derivations are defined as usual (see e.g. [18]); a sequent σ is provable in C_L iff there exists a C_L -derivation having root sequent σ . Let us consider a C_L -derivation \mathcal{D} of $\Rightarrow \alpha$ (see Fig. 2). Reading the derivation bottom-up, the first applied rule is $Claus_0$. After such an application, the obtained sequents have the form $\sigma_k = R_k, X_k \Rightarrow g$, where $R_k \cup X_k$ is non-empty, thus rule Claus₀ cannot be applied any more; the rule applied at the top is cpl_0 . Note that \mathcal{D} contains a unique branch, consisting of the sequents $\Rightarrow \alpha, \sigma_0, \ldots, \sigma_{n-1}$. In Fig. 2 we also define the pair $\pi(\mathcal{D}) = \langle \Psi, \chi \rangle$: Ψ collects the (instances of) L-axioms selected by rule Claus₁, χ is obtained by composing the substitutions associated with the applied rules. The definition of $\pi(\mathcal{T})$, with \mathcal{T} a C_L -tree, is similar. By $\mathcal{T}(\alpha; R, X \Rightarrow g)$ we denote a C_L -tree having root $\Rightarrow \alpha$ and leaf $R, X \Rightarrow g$. Given a C_L -tree $\mathcal{T}, \mathcal{V}_{\mathcal{T}}$ is the set of variables occurring in \mathcal{T} . We state some properties about C_L -trees:

Lemma 2. Let $\mathcal{T} = \mathcal{T}(\alpha; R, X \Rightarrow g)$ and let $\pi(\mathcal{T}) = \langle \Psi, \chi \rangle$.

(i) $\mathcal{V}_{\chi(p)} \subseteq \mathcal{V}_{\alpha}$, for every $p \in \mathcal{V}_{\mathcal{T}}$. (ii) $R, X \vdash_{i} \beta \leftrightarrow \chi(\beta)$, for every formula β . (iii) If $R, X, \Gamma \vdash_{i} g$ and $\mathcal{V}_{\Gamma} \subseteq \mathcal{V}_{\alpha}$, then $\Gamma, \chi(\Psi) \vdash_{i} \alpha$.

Proposition 1. Let \mathcal{D} be a C_L -derivation of $\Rightarrow \alpha$ and let $\pi(\mathcal{D}) = \langle \Psi, \chi \rangle$. Then, $\mathcal{V}_{\chi(\Psi)} \subseteq \mathcal{V}_{\alpha}$ and $\chi(\Psi) \vdash_{i} \alpha$.

Proof. Since \mathcal{D} is a C_L -derivation, \mathcal{D} has the form depicted on the right where $\mathcal{T} = \mathcal{T}(\alpha; R, X \Rightarrow g)$; note that $\pi(\mathcal{T}) = \pi(\mathcal{D}) = \langle \Psi, \chi \rangle$. Since $R \vdash_c g$, by Lemma 1(i) we get $R \vdash_i g$, hence $R, X \vdash_i g$. We can apply Lemma 2 and claim that $\mathcal{V}_{\chi(\Psi)} \subseteq \mathcal{V}_{\alpha}$ and $\chi(\Psi) \vdash_i \alpha$. $\mathcal{D} = \frac{\begin{array}{c} R \vdash_{c} g \\ \hline R, X \Rightarrow g \end{array}}{\begin{array}{c} \vdots \\ \mathcal{T} \\ \Rightarrow \alpha \end{array}} \operatorname{cpl}_{0}$

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Given a C_L -derivation \mathcal{D} of $\Rightarrow \alpha$, Prop. 1 exhibits how to extract a set of instances Ψ_{α} of the *L*-axioms such that $\Psi_{\alpha} \vdash_{i} \alpha$. If \mathcal{D} does not contain applications of rule Claus₁, Ψ_{α} is empty, and this ascertains that α is IPL-valid; actually, \mathcal{D} can be immediately embedded into the calculus for IPL introduced in [8]. As an immediate consequence of Prop. 1, we get the soundness of C_L : if $\Rightarrow \alpha$ is provable in C_L , then α is *L*-valid.

Even though C_L -derivations have a simple structure, the design of a rootfirst proof search strategy for C_L is far from being trivial. After having applied rule Claus₀ to the root sequent $\Rightarrow \alpha$, we enter a loop where at each iteration k we search for a derivation of $\sigma_k = R_k, X_k \Rightarrow g$. It is convenient to firstly check whether $R_k \vdash_c g$ so that, by applying rule cpl_0 , we immediately close the derivation at hand. To check classical provability, we exploit a SAT-solver; each time the solver is invoked, the set R_k has increased, thus it is advantageous to use an incremental SAT-solver. If $R_k \nvDash_c g$, we have to apply either rule cpl_1 or rule Claus₁, but it is not obvious which strategy should be followed. First, we have to select one between the two rules. If rule cpl_1 is chosen, we have to guess proper λ and A; otherwise, we have to apply Claus₁, and this requires the selection of an instance ψ of an L-axiom. In any case, if we followed a blind choice, the procedure would be highly inefficient. To guide proof search, we follow a different approach based on countermodel construction; to this aim, we introduce a representation of Kripke models where worlds are classical interpretations ordered by inclusion.

Countermodels. Let W be a finite set of interpretations with minimum M_0 , namely: $M_0 \subseteq M$ for every $M \in W$. By $\mathcal{K}(W)$ we denote the Kripke model $\langle W, \leq, M_0, \vartheta \rangle$ where \leq coincides with the subset relation \subseteq and ϑ is the identity map, thus $M \Vdash p$ (in $\mathcal{K}(W)$) iff $p \in M$. We introduce the following *realizability relation* \triangleright_W between elements of W and implication clauses:

$$M \triangleright_W (a \to b) \to c \text{ iff } (a \in M) \text{ or } (b \in M) \text{ or } (c \in M) \text{ or}$$
$$(\exists M' \in W \text{ s.t. } M \subset M' \text{ and } a \in M' \text{ and } b \notin M').$$

By $M \triangleright_W X$ we mean that $M \triangleright_W \lambda$ for every $\lambda \in X$. We state the crucial properties of the model $\mathcal{K}(W)$:

Proposition 2. Let $\mathcal{K}(W)$ be the model generated by W and let $w \in W$. Let φ be a clause and $\lambda = (a \rightarrow b) \rightarrow c$ an implication clause.

(i) If $w' \models \varphi$, for every $w' \in W$ such that $w \leq w'$, then $w \Vdash \varphi$. (ii) If $w' \models b \to c$ and $w' \triangleright_W \lambda$, for every $w' \in W$ such that $w \leq w'$, then $w \Vdash \lambda$.

Let $\mathcal{K}(W)$ be a model with root r, and assume that every interpretation w in W is a model of R; our goal is to get $r \Vdash R \cup X$ (where $(X)^* \subseteq R$), possibly by filling W with new worlds. To this aim, we exploit Prop. 2. By our assumption and point (i), we claim that $r \Vdash R$. Suppose that there is $w \in W$ and $\lambda = (a \to b) \to c \in X$ such that $w \not\models_W \lambda$; is it possible to amend $\mathcal{K}(W)$ in order to match (ii) and conclude $r \Vdash X$? By definition of \triangleright_W , none of the atoms a, b, c belongs to w; moreover $\mathcal{K}(W)$ lacks a world w' such that $w \subset w'$ and $a \in w'$ and $b \notin w'$. We can try to fix $\mathcal{K}(W)$ by inserting the missing world w'; to preserve (i), we also need $w' \models R$. Accordingly, such a w' exists if and only if $R, w, a \nvDash_c b$, the solver also computes the required w'. This completion process must be iterated until $\mathcal{K}(W)$ has been saturated with all the missing worlds or we get stuck. It is easy to check that the process eventually terminates. This is one of the key ideas beyond the procedure intuitRIL we present in next section.

4 The Procedure intuitRIL

We present the procedure intuitRIL (intuit with Restart for Intermediate Logics) that, given a formula α and a logic L = IPL + Ax(L), returns either a set of L-axioms Ψ_{α} or a model $\mathcal{K}(W)$ with the following properties:

(Q1) If intuitRIL(α, L) returns Ψ_{α} , then $\Psi_{\alpha} \subseteq \operatorname{Ax}(L, \mathcal{V}_{\alpha})$ and $\Psi_{\alpha} \vdash_{i} \alpha$. (Q2) If intuitRIL(α, L) returns $\mathcal{K}(W)$, then $\mathcal{K}(W)$ is an *L*-countermodel for α .

Thus, α is *L*-valid in the former case, not *L*-valid in the latter. If intuitRIL(α ,*L*) returns Ψ_{α} , by tracing the computation we can build a C_L -derivation \mathcal{D} of $\Rightarrow \alpha$ such that $\Psi_{\alpha} = \chi(\Psi)$, where $\langle \Psi, \chi \rangle = \pi(\mathcal{D})$; this certificates that $\Psi_{\alpha} \vdash_{i} \alpha$.

The procedure is described by the flowchart in Fig. 3 and exploits a single incremental SAT-solver s: clauses can be added to s but not removed; by R(s) we denote the set of clauses stored in s. The SAT-solver is required to support the following operations:

- newSolver(R) creates a new SAT-solver initialized with the clauses in R.
- addClauses (s, R) adds the clauses in R to the SAT-solver s.
- satProve(s, A, g) calls s to decide whether R(s), $A \vdash_c g$ (A is a set of propositional variables). The solver outputs one of the following answers:
 - Yes(A'): thus, $A' \subseteq A$ and $\mathbf{R}(s), A' \vdash_{\mathbf{c}} g$;
 - No(M): thus, $A \subseteq M \subseteq \mathcal{V}_{\mathbf{R}(s)} \cup A$ and $M \models \mathbf{R}(s)$ and $g \notin M$.

In the former case it follows that $\mathbf{R}(s), A \vdash_{\mathbf{c}} g$, in the latter $\mathbf{R}(s), A \nvDash_{\mathbf{c}} g$.

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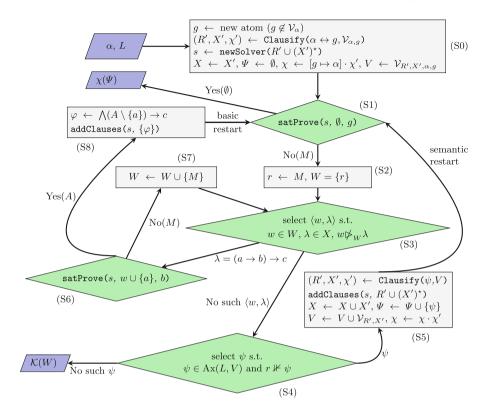


Fig. 3. Computation of intuitRIL(α , L).

The computation of intuitRIL(α ,L) consists of the following steps:

- (S0) The formula $\alpha \leftrightarrow g$, with g new propositional variable, is clausified. The outcome (R', X', χ') is used to create a new SAT-solver s and to properly initialize the global variables X (set of implication clauses), Ψ (set of *L*-axiom instances), V (set of propositional variables) and χ (substitution).
- (S1) A loop starts (main loop). The SAT-solver s is called to check whether $R(s) \vdash_c g$. If the answer is $Yes(\emptyset)$, the computation stops yielding $\chi(\Psi)$. Otherwise, the output is No(M) and the computation continues at Step (S2).
- (S2) We set r = M (the root of $\mathcal{K}(W)$) and $W = \{r\}$.
- (S3) A loop starts (inner loop). We have to select a pair $\langle w, \lambda \rangle$ such that $w \in W$, $\lambda \in X$ and $w \not >_W \lambda$. If such a pair does not exist, the inner loop ends and next step is (S4), otherwise the inner loop continues at Step (S6).
- (S4) As we show in Lemma 3, at this point $\mathcal{K}(W)$ is a countermodel for α . If all the axioms in $\operatorname{Ax}(L, V)$ are forced at the root r of $\mathcal{K}(W)$, then $\mathcal{K}(W)$ is an *L*-countermodel for α and the computation ends returning $\mathcal{K}(W)$. Otherwise, we select ψ from $\operatorname{Ax}(L, V)$ such that $r \nvDash \psi$ and the computation continues at Step (S5); we call ψ the *learned axiom*.

- (S5) We clausify ψ and we update the global variables. The computation restarts from Step (S1) with a new iteration of the main loop (*semantic restart*).
- (S6) Let $\langle w, (a \to b) \to c \rangle$ be the pair selected at Step (S3). The SAT-solver s is called to check whether $\mathbf{R}(s), w, a \vdash_{\mathbf{c}} b$. If the result is $\operatorname{No}(M)$, the inner loop continues at step (S7). Otherwise, the answer is $\operatorname{Yes}(A)$; the inner loop ends and the computation continues at Step (S8).
- (S7) The interpretation M is added to W and the computation continues at Step (S3) with a new iteration of the inner loop.
- (S8) The clause φ (*learned basic clause*) is added to the SAT-solver s and the computation restarts from Step (S1) (*basic restart*).

Intuitively, intuitRIL(α, L) searches for an L-countermodel $\mathcal{K}(W)$ for α . In the construction of $\mathcal{K}(W)$, whenever a conflict arises, a restart operation is triggered. A basic restart happens when it is not possible to fill the set W with a missing world (see the discussion after Prop. 2). A semantic restart is thrown when $\mathcal{K}(W)$ is a countermodel for α but it fails to be an L-model. In either case, the construction of $\mathcal{K}(W)$ restarts from scratch. However, to prevent that the same kind of conflict shows up again, new clauses are learned and fed to the SAT-solver (this complies with $\text{DPLL}(\mathcal{T})$ with learning computation paradigm [16]). If the outcome is $\chi(\Psi)$, by tracing the computation we can build a C_L -derivation \mathcal{D} of $\Rightarrow \alpha$ such that $\pi(\mathcal{D}) = \langle \Psi, \chi \rangle$. The derivation is built bottom-up. The initial Step (S0) corresponds to the application of rule Claus₀ to the root sequent $\Rightarrow \alpha$; basic and semantic restarts bottom-up expand the derivation by applying rule cpl_1 and $Claus_1$ respectively. We stress that the procedure is quite modular; to treat a specific logic L one has only to provide a concrete implementation of Step (S4). For L = IPL, Step (S4) is trivial, since the set Ax(IPL, V) is empty. Actually, intuitRIL applied to IPL has the same behaviour as the procedure intuitR introduced in [8].

Example 3. Let us consider Jankov axiom wem = $\neg a \lor \neg \neg a$ [2,13] (aka weak excluded middle), which holds in all frames having a single maximal world (thus, wem is GL-valid). The trace of the execution of intuitRIL(wem,GL) is shown in Fig. 4. The initial clausification yields (R_0, X_0, \tilde{g}) , where X_0 consists of the implication clauses λ_0, λ_1 in Fig. 4 and R_0 contains the 7 clauses below:

$$\tilde{g} \to \tilde{p}_2, \quad \tilde{p}_0 \to \tilde{p}_2, \quad a \wedge \tilde{p}_0 \to \bot, \quad \tilde{p}_1 \to \tilde{p}_2, \quad \tilde{p}_0 \wedge \tilde{p}_1 \to \bot, \quad \tilde{p}_2 \to \tilde{g}, \quad \tilde{p}_2 \to \tilde{p}_0 \lor \tilde{p}_1.$$

Each row in Fig. 4 displays the validity tests performed by the SAT-solver and the computed answers. If the result is No(M), the last two columns show the worlds w_k in the current set W and, for each w_k , the list of λ such that $w \not\models_W \lambda$; the pair selected for the next step is underlined. For instance, after call (1) we have $W = \{w_0\}, w_0 \not\models_W \lambda_0$ and $w_0 \not\models_W \lambda_1$; the selected pair is $\langle w_0, \lambda_0 \rangle$. After call (2), the set W is updated by adding the world w_1 ; we have $w_1 \triangleright_W \lambda_0$, $w_1 \triangleright_W \lambda_1, w_0 \triangleright_W \lambda_0$ and $w_0 \not\models_W \lambda_1$. Whenever the SAT-solver outputs Yes(A), we display the learned clause ψ_k . The SAT-solver is invoked 18 times and there are 6 restarts (1 semantic, 5 basic). After (3), we get $W = \{w_0, w_1, w_2\}$ and no pair $\langle w, \lambda \rangle$ can be selected, hence the model $\mathcal{K}(W)$ (displayed in the figure) is

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a countermodel for **wem**. However, $\mathcal{K}(W)$ is not a GL-model (indeed, it is not linear), hence we choose an instance of the linearity axiom not forced at w_0 , namely ψ_0 , and we force a semantic restart. The clausification of ψ_0 produces 6 new clauses and the new implication clauses λ_2 , λ_3 , λ_4 . After each restart, the sets R_j are:

$$R_1 = R_0 \cup \{ \tilde{p}_3 \to \tilde{p}_4, a \to \tilde{p}_5, \tilde{p}_3 \land \tilde{p}_5 \to a, a \land \tilde{p}_4 \to \tilde{p}_3, a \land \tilde{p}_3 \to \bot, \tilde{p}_4 \lor \tilde{p}_5 \}$$

$$R_j = R_{j-1} \cup \{ \psi_{j-1} \} \quad \text{for } 2 \le j \le 6 \text{ (the } \psi'_j \text{s are defined in Fig. 4).}$$

The C_{GL} -derivation of $\Rightarrow \neg a \lor \neg \neg a$ extracted from the computation is:

Now, we discuss partial correctness and termination of intuitRIL. Let us denote with $\sim_{\rm c}$ classical equivalence ($\alpha \sim_{\rm c} \beta$ iff $\vdash_{\rm c} \alpha \leftrightarrow \beta$) and with $\sim_{\rm i}$ intuitionistic equivalence ($\alpha \sim_{\rm i} \beta$ iff $\vdash_{\rm i} \alpha \leftrightarrow \beta$). We introduce some notation.

- (†) The following terms refer to the configuration at the beginning of iteration $k \ (k \ge 0)$, just after the execution of Step (S2):
 - $-\Phi_k$ is the set collecting all the learned basic clauses;
 - $-R_k$ is the set of clauses stored in the SAT-solver s;
 - $-X_k, \Psi_k, V_k, \chi_k, r_k$ are the values of the corresponding global variables.

In Fig. 5 we inductively define the C_L -tree \mathcal{T}_k , having the form $\mathcal{T}(\alpha; R_k, X_k \Rightarrow g)$. In the application of rule Claus₀, g and χ' are defined as in Step (S0). In rule cpl₁, λ is the implication clause selected at iteration k - 1 (of the main loop) in the last execution of Step (S3); A is the value computed at Step (S6) of iteration k - 1. In the application of rule Claus₁, ψ and χ' are defined as in the execution of Step (S4) and (S5) of iteration k - 1. One can easily check that the applications of the rules are sound. If Step (S1) yields $\operatorname{Yes}(\emptyset)$, we can turn \mathcal{T}_k into a C_L -derivation by applying rule cpl₀.

Next lemma states some relevant properties of the computations of intuitRIL.

Lemma 3. Let us consider the execution of iteration k of the main loop $(k \ge 0)$.

- $(i) \ (X_k)^* \cup \Phi_k \subseteq R_k.$
- (*ii*) $V_k = \mathcal{V}_{\mathcal{T}_k}$ and $\Psi_k \subseteq \operatorname{Ax}(L, V_k)$ and $\pi(\mathcal{T}_k) = \langle \Psi_k, \chi_k \rangle$.
- (iii) $\mathcal{V}_{\chi_k(p)} \subseteq \mathcal{V}_{\alpha}$, for every $p \in V_k$, and $R_k, X_k \vdash_i \beta \leftrightarrow \chi_k(\beta)$, for every β .

$\lambda_0 = (ilde{p}_0 o ot) o ilde{p}_1 \qquad \lambda_1 = (a o ot) o ilde{p}_0$					
$\lambda_2 = (a \to \tilde{p}_3) \to \tilde{p}_4 \qquad \lambda_3 = (a \to \bot) \to \tilde{p}_3 \qquad \lambda_4 = (\tilde{p}_3 \to a) \to \tilde{p}_5$					
$w_0 = \emptyset w_1 = \{\tilde{g}, \tilde{p}_0, \tilde{p}_2\} w_2 = \{a, \tilde{g}, \tilde{p}_1, \tilde{p}_2\} w_3 = \{\tilde{p}_4\} w_4 = \{\tilde{g}, \tilde{p}_0, \tilde{p}_2, \tilde{p}_4\}$					
$w_5 = \{ \tilde{g}, \tilde{p}_0, \tilde{p}_2, \tilde{p}_3, \tilde{p}_4 \} w_6 = \{ a, \tilde{p}_5 \} w_7 = \{ \tilde{p}_3, \tilde{p}_4 \} w_8 = \{ \tilde{g}, \tilde{p}_0, \tilde{p}_2, \tilde{p}_3, \tilde{p}_4 \}$					
$w_9 = \{\tilde{p}_5\} w_{10} = \{\tilde{p}_4\} w_{11} = \{\tilde{g}, \tilde{p}_0, \tilde{p}_2, \tilde{p}_3, \tilde{p}_4\}$					
$\chi_0 = [\tilde{g} \mapsto \neg a \lor \neg \neg a, \ \tilde{p}_0 \mapsto \neg a, \ \tilde{p}_1 \mapsto \neg \neg a, \ \tilde{p}_2 \mapsto \neg a \lor \neg \neg a]$					
$\chi_1 = [\tilde{p}_3 \mapsto \neg a, \ \tilde{p}_4 \mapsto a \to \neg a, \ \tilde{p}_5 \mapsto \neg a \to a]$					

	@SAT	Answer	W	λ s.t. $w {\not\!$
Start	(1) $R_0 \vdash_{\mathbf{c}} \tilde{g}$?	$\operatorname{No}(w_0)$	w_0	$\underline{\lambda_0}, \lambda_1$
	(2) $R_0, w_0, \tilde{p}_0 \vdash_{\rm c} \bot$?	$No(w_1)$	w_1	Ø
			w_0	$\underline{\lambda_1}$
	(3) $R_0, w_0, a \vdash_{c} \bot$?	$No(w_2)$	w_2	Ø
			w_1	Ø
			w_0	Ø
Semantic failure	$\begin{array}{l} \textbf{kiom:} \\ \neg a) \lor (\neg a \to a) \end{array}$			
	$w_0: \emptyset$	T	-	-
SRest 1	$(4) R_1 \vdash_{c} \tilde{g} ?$	$No(w_3)$	$\underline{w_3}$	$\underline{\lambda_0}, \lambda_1, \lambda_3, \lambda_4$
	(5) $R_1, w_3, \tilde{p}_0 \vdash_{\rm c} \bot ?$	$No(w_4)$	w_4	$\lambda_3, \underline{\lambda_4}$
			w_3	$\lambda_1, \lambda_3, \lambda_4$
	(6) $R_1, w_4, \tilde{p}_3 \vdash_{\rm c} a$?	$\operatorname{No}(w_5)$	w_5	Ø
			$\underline{w_4}$	$\frac{\lambda_3}{\lambda}$
	$(7) D \dots + 2$	$\mathbf{V}_{-}((\cdot,\tilde{\tau}))$	w_3	λ_1, λ_3
	(7) $R_1, w_4, a \vdash_{c} \bot$?	$\operatorname{Yes}(\{a, \tilde{p}_0\})$	$\psi_1 = \tilde{p}_0 \to \tilde{p}_3$	
BRest 2	(8) $R_2 \vdash_{\mathrm{c}} \tilde{g}$?	$No(w_6)$	w_6	$\overline{\lambda_0}$
	(9) $R_2, w_6, \tilde{p}_0 \vdash_{\rm c} \bot$?	$\operatorname{Yes}(\left\{a,\widetilde{p}_{0}\right\})$	$\psi_2 = a \to \tilde{p}_1$	
BRest 3	(10) $R_3 \vdash_{\mathrm{c}} \tilde{g}$?	$No(w_7)$	w_7	$\underline{\lambda_0}, \lambda_1$
	(11) $R_3, w_7, \tilde{p}_0 \vdash_{\rm c} \bot$?	$No(w_8)$	w_8	Ø
			w_7	λ_1
	(12) $R_3, w_7, a \vdash_{\rm c} \bot ?$	$\operatorname{Yes}(\left\{a,\tilde{p}_3\right\})$	$\psi_3 = \tilde{p}_3$ -	$ ightarrow ilde{p}_0$
BRest 4	(13) $R_4 \vdash_{\rm c} \tilde{g}$?	$No(w_9)$	w_9	$\underline{\lambda_0}, \lambda_1, \lambda_2, \lambda_3$
	(14) $R_4, w_9, \tilde{p}_0 \vdash_{\rm c} \bot ?$	$\operatorname{Yes}(\left\{\tilde{p}_{0},\tilde{p}_{5}\right\})$	$\psi_4 = ilde{p}_5$ -	$\rightarrow \tilde{p}_1$
BRest 5	(15) $R_5 \vdash_{\rm c} \tilde{g}$?	$\operatorname{No}(w_{10})$	w_{10}	$\underline{\lambda_0}, \lambda_1, \lambda_3, \lambda_4$
	(16) $R_5, w_{10}, \tilde{p}_0 \vdash_{\rm c} \bot$?	$No(w_{11})$	w_{11}	Ø
			w_{10}	$\underline{\lambda_1}, \lambda_3$
	(17) $R_5, w_{10}, a \vdash_{\rm c} \bot ?$	$\operatorname{Yes}(\{a,\tilde{p}_4\})$	$\psi_5 = \tilde{p}_4$ -	$\rightarrow \tilde{p}_0$
BRest 6	(18) $R_6 \vdash_{c} \tilde{g}$?	$\operatorname{Yes}(\emptyset)$	Proved	

Fig. 4. Computation of intuitRIL($\neg a \lor \neg \neg a$, GL).

$$\mathcal{T}_0 = -\frac{R_0, X_0 \Rightarrow g}{\Rightarrow \alpha} \operatorname{Claus}_0(g, \chi')$$

$$\mathcal{T}_{k} = \frac{\begin{array}{c} R_{k-1}, A \vdash_{c} b & R_{k}, X_{k} \Rightarrow g \\ \hline R_{k-1}, X_{k-1} \Rightarrow g \\ \vdots \\ \mathcal{T}_{k-1} \\ \Rightarrow \alpha \end{array}}{\mathcal{T}_{k}} \operatorname{cpl}_{1}(\lambda) \qquad \begin{array}{c} R_{k}, X_{k} \Rightarrow g \\ \hline R_{k-1}, X_{k-1} \Rightarrow g \\ \vdots \\ \mathcal{T}_{k-1} \\ \Rightarrow \alpha \end{array}} \operatorname{Claus}_{1}(\psi, \chi')$$

if k > 0 and iteration k - 1 ends with a basic restart (thus $X_k = X_{k-1}$) if k > 0 and iteration k - 1 ends with a semantic restart

Fig. 5. Definition of \mathcal{T}_k $(k \ge 0)$.

- (iv) At every step after (S2), $w \models R_k$, for every $w \in W$.
- (v) At every step after (S2), r_k is the root of $\mathcal{K}(W)$ and $r_k \Vdash R_k$ and $r_k \nvDash g$.
- (vi) At Step (S4), $r_k \Vdash R_k \cup X_k \cup \Psi_k$ and $r_k \nvDash g$ (in $\mathcal{K}(W)$).
- (vii) Assume that iteration k ends with a basic restart and let φ be the learned basic clause. For every $\varphi' \in \Phi_k$, $\varphi \not\sim_c \varphi'$.
- (viii) Assume that iteration k ends with a semantic restart and let ψ be the learned axiom. For every $\psi' \in \Psi_k$, $\chi_k(\psi) \not\sim_i \chi_k(\psi')$.

Proof. We only sketch the proof of the non-trivial points. (*iii*). By Lemma 2 applied to \mathcal{T}_k .

(v). Every interpretation M generated at Step (S6) is a superset of r_k , thus after Step (S2) r_k is the minimum element of W and the root of $\mathcal{K}(W)$. By (iv) and Prop. 2(i), $r_k \Vdash R_k$. Since $g \notin r_k$, we get $r_k \nvDash g$.

(vi). At Step (S4), $w \vDash_W \lambda$ for every $w \in W$ and $\lambda \in X_k$. Since $(X_k)^* \subseteq R_k$, by Prop. 2(ii) we get $r_k \Vdash X_k$. Let $\psi \in \Psi_k$; then, ψ has been learned at some iteration k' < k. Let (R', X', χ') be the output of Clausify (ψ, V) at Step (S5) of iteration k'. Since $R' \subseteq R_k$ and $X' \subseteq X_k$, it holds that $r_k \Vdash R' \cup X'$. By (P1) $R', X' \vdash_i \psi$, hence $r_k \Vdash \psi$, which proves $r_k \Vdash \Psi_k$.

(vii). Let $\varphi' \in \Phi_k$; we show that $\varphi \not\sim_c \varphi'$. Let $\varphi = \bigwedge (A \setminus \{a\}) \to c$; then, there are $w \in W$ and $\lambda = (a \to b) \to c \in X_k$ such that $\langle w, \lambda \rangle$ has been selected at Step (S3) and the outcome of satProve $(s, w \cup \{a\}, b)$ at Step (S6) is Yes(A). Note that $w \not\approx_W \lambda$, hence $c \notin w$; since $A \subseteq w \cup \{a\}$, we get $w \not\models \varphi$. On the other hand, $w \models \varphi'$, since $\varphi' \in \Phi_k$ and $\Phi_k \subseteq R_k$. We conclude $\varphi \not\sim_c \varphi'$.

(viii). Let $\psi' \in \Psi_k$ and let $\mathcal{K}(W)$ be the model obtained at Step (S4) of iteration k. By (iii) $R_k, X_k \vdash_i \psi \leftrightarrow \chi_k(\psi)$ and $R_k, X_k \vdash_i \psi' \leftrightarrow \chi_k(\psi')$. Since $r_k \nvDash \psi$ and $r_k \Vdash \psi'$ (indeed, $\psi' \in \Psi_k$ and $r_k \Vdash \Psi_k$) and $r_k \Vdash R_k \cup X_k$, we get $r_k \nvDash \chi_k(\psi)$ and $r_k \Vdash \chi_k(\psi')$. We conclude $\chi_k(\psi) \not\sim_i \chi_k(\psi')$.

The following proposition proves the partial correctness of intuitRIL:

Proposition 3. intuitRIL(α ,L) satisfies properties (Q1) and (Q2).

Proof. Let us assume that the computation ends at iteration k with output Ψ_{α} . Then, the call to the SAT-solver at Step (S0) yields $\operatorname{Yes}(\emptyset)$, meaning that $R_k \vdash_c g$. We can build the following C_L -derivation \mathcal{D} of $\Rightarrow \alpha$:

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$$\mathcal{D} = \frac{\begin{array}{c} \frac{R_k \vdash_{c} g}{R_k, X_k \Rightarrow g} \operatorname{cpl}_0 \\ \vdots \\ \mathcal{T}_k \\ \Rightarrow \alpha \end{array}}{\pi(\mathcal{D}) = \pi(\mathcal{T}_k) = \langle \Psi_k, \chi_k \rangle}$$

Note that $\Psi_{\alpha} = \chi_k(\Psi_k)$. Accordingly, by Prop. 1 we get (Q1).

Let us assume that the output is the model $\mathcal{K}(W)$, having root r. Then, $\mathcal{K}(W)$ is an L-model (otherwise, Step (S4) should have forced a semantic restart). By Lemma 3(vi) we get $r \Vdash R_0 \cup X_0$ and $r \nvDash g$. Since at Step (S0) we have clausified the formula $\alpha \leftrightarrow g$, by (P1) we get $R_0, X_0 \vdash_i \alpha \leftrightarrow g$, which implies $r \Vdash \alpha \leftrightarrow g$. We conclude that $r \nvDash \alpha$, hence (Q2) holds.

It seems challenging to provide a general proof of termination, and each logic must be treated apart. We can only state some general properties about the termination of the inner loop and of consecutive basic restarts.

Proposition 4. (i) The inner loop is terminating.

(ii) The number of consecutive basic restarts is finite.

Proof. Let us assume, by absurd, that the inner loop is not terminating. For every $j \geq 0$, by W_j we denote the value of W at Step (S3) of iteration j of the inner loop; note that the value of the variable V does not change during the iterations. We show that $W_j \subset W_{j+1}$, for every $j \geq 0$. At iteration j, the outcome of Step (S6) is No(M). Thus, there are $w \in W_j$ and $\lambda = (a \to b) \to c \in X$ such that the pair $\langle w, \lambda \rangle$ has been selected at Step (S3); accordingly, $w \not\models_{W_j} \lambda$ and $w \cup \{a\} \subseteq M$ and $b \notin M$. We have $M \notin W_j$, otherwise we would get $w \triangleright_{W_j} \lambda$, a contradiction. Since $W_{j+1} = W_j \cup \{M\}$, this proves that $W_j \subset W_{j+1}$. We have shown that $W_0 \subset W_1 \subset W_2 \ldots$. This leads to a contradiction since, for every $j \geq 0$ and every $w \in W_j$, w is a subset of V and V is finite. We conclude that the inner loop is terminating, and this proves (i).

Let us assume, by contradiction, that there is an infinite sequence of consecutive basic restarts. Then, there is $n \geq 0$ such that, for every $k \geq n$, the iteration k of the main loop ends with a basic restart. Let φ_k be the clause learned at iteration k. Note that an iteration ending with a basic restart does not introduce new atoms, thus $\mathcal{V}_{\varphi_k} \subseteq V_n$ for every $k \geq n$ (where V_n is defined as in (†)). We get a contradiction, since V_n is finite and, by Lemma 3(vi), the clauses φ_k are pairwise non \sim_c -equivalent; this proves (ii).

Lemma 3(vii) guarantees that the learned axioms are pairwise distinct, but this is not sufficient to prove termination since in general we cannot set a bound on the size and on the number of learned axioms. In next section we present some relevant logics where the procedure is terminating.

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5 Termination

Let GL = IPL + lin be the Gödel-Dummett logic presented in Ex. 1; we show that every call intuitRIL(α ,GL) is terminating. To this aim, we exploit the bounding function $Ax_{GL}(\alpha)$ presented in the mentioned example.

Lemma 4. Let us consider the computation of intuitRIL(α ,GL) and assume that at iteration k of the main loop Step (S4) is executed and that the obtained model $\mathcal{K}(W)$ is not linear. Then, there exists $\psi \in \operatorname{Ax}_{GL}(\alpha)$ such that $r_k \nvDash \psi$.

Proof. Let us assume that $\mathcal{K}(W)$ has two distinct maximal worlds w_1 and w_2 ; note that $w_1 \subseteq V_k$ and $w_2 \subseteq V_k$ (with V_k defined as in (\dagger)). We show that:

(a) $w_1 \cap \mathcal{V}_{\alpha} \neq w_2 \cap \mathcal{V}_{\alpha}$.

Suppose by contradiction $w_1 \cap \mathcal{V}_{\alpha} = w_2 \cap \mathcal{V}_{\alpha}$; let $p \in V_k$ and $\beta = \chi_k(p)$ (with χ_k defined as in (†)). By Lemma 3(iii), $R_k, X_k \vdash_i p \leftrightarrow \beta$; by Lemma 3(vi) we get $w_1 \Vdash p \leftrightarrow \beta$ and $w_2 \Vdash p \leftrightarrow \beta$. Since $\mathcal{V}_{\beta} \subseteq \mathcal{V}_{\alpha}$ (see Lemma 3(iii)) and we are assuming $w_1 \cap \mathcal{V}_{\alpha} = w_2 \cap \mathcal{V}_{\alpha}$, it holds that $w_1 \Vdash \beta$ iff $w_2 \Vdash \beta$, thus $w_1 \Vdash p$ iff $w_2 \Vdash p$, namely $p \in w_1$ iff $p \in w_2$. Since p is any element of V_k , we get $w_1 = w_2$, a contradiction; this proves (a). By (a) there is $a \in \mathcal{V}_{\alpha}$ such that either $a \in w_1 \setminus w_2$ or $a \in w_2 \setminus w_1$. We consider the former case (the latter one is symmetric), corresponding to Case 1 in Fig. 6. We have $w_1 \Vdash a$ and $w_2 \Vdash \neg a$; setting $\psi = (a \to \neg a) \lor (\neg a \to a)$, we conclude $r_k \nvDash \psi$.

Assume that $\mathcal{K}(W)$ has only one maximal world; since it is not linear, there are three distinct worlds w_1 , w_2 , w_3 as in Case 2 in Fig. 6, namely: w_1 is an immediate successor of w_2 and w_3 (i.e., for $j \in \{2,3\}$, $w_j < w_1$ and, if $w_j < w$, then $w_1 \leq w$), $w_2 \not\leq w_3$, $w_3 \not\leq w_2$. Reasoning as in (a), we get:

(b) $w_2 \cap \mathcal{V}_{\alpha} \neq w_3 \cap \mathcal{V}_{\alpha}$. (c) $w_2 \cap \mathcal{V}_{\alpha} \subset w_1 \cap \mathcal{V}_{\alpha}$ and $w_3 \cap \mathcal{V}_{\alpha} \subset w_1 \cap \mathcal{V}_{\alpha}$.

By (b) there is $a \in \mathcal{V}_{\alpha}$ such that either $a \in w_2 \setminus w_3$ or $a \in w_3 \setminus w_2$. Let us consider the former case (the latter one is symmetric). By (c), there is $b \in \mathcal{V}_{\alpha}$ such that $b \in w_1 \setminus w_2$. If $b \in w_3$ (Case 2.1 in Fig. 6), we get $a \in w_2$, $b \notin w_2$, $a \notin w_3$, $b \in w_3$. Setting $\psi = (a \to b) \lor (b \to a)$, we conclude $r_k \nvDash \psi$. Finally, let us assume $b \notin w_3$ (Case 2.2). We have $\{a, b\} \subseteq w_1$, $a \in w_2$, $b \notin w_2$, $a \notin w_3$ and $b \notin w_3$. It is easy to check that $w_3 \Vdash a \to b$ (recall that $w_3 < w$ implies $w_1 \leq w$), thus $w_3 \nvDash (a \to b) \to a$. On the other hand $w_2 \nvDash a \to (a \to b)$. Setting $\psi = (a \to (a \to b)) \lor ((a \to b) \to a)$, we get $r_k \nvDash \psi$.

We exploit Lemma 4 to implement Step (S4). If $\mathcal{K}(W)$ is linear, then $\mathcal{K}(W)$ is a GL-model and we are done. Otherwise, the proof of Lemma 4 hints an effective method to select an instance ψ of **lin** from Ax_{GL}(α).

Proposition 5. The computation of intuitRIL(α ,GL) is terminating.

Proof. Assume that intuitRIL(α ,GL) is not terminating. Since the number of iterations of the inner loop and of the consecutive basic restarts is finite (see Prop. 4), Step (S4) must be executed infinitely many times. This leads to a contradiction, since the axioms selected at Step (S4) are pairwise distinct (see Lemma 3(vii)) and such axioms are chosen from the finite set $Ax_{GL}(\alpha)$.

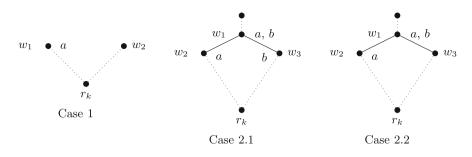


Fig. 6. Proof of Lemma 4, case analysis.

As a corollary, we get that $Ax_{GL}(\alpha)$ is a bounding function for GL:

Proposition 6. If α is GL-valid, there is $\Psi_{\alpha} \subseteq Ax_{GL}(\alpha)$ such that $\Psi_{\alpha} \vdash_{i} \alpha$.

Other proof-search strategies for GL are discussed in [10,14]. This technique can be extended to other notable intermediate logics. Among these, we recall the logics GL_n (Gödel Logic of depth n), obtained by adding to GL the axioms \mathbf{bd}_n (bounded depth) where: $\mathbf{bd}_0 = a_0 \vee \neg a_0$, $\mathbf{bd}_{n+1} = a_{n+1} \vee (a_{n+1} \rightarrow \mathbf{bd}_n)$. Semantically, GL_n is the logic characterized by linear frames having depth at most n. We are not able to prove termination for the logics $\operatorname{IPL} + \mathbf{bd}_n$, but we can implement the following terminating strategy for GL_n . Let $\mathcal{K}(W)$ be the model obtained at Step (S4) of the computation of $\operatorname{intuitRIL}(\alpha, \operatorname{GL}_n)$:

- If $\mathcal{K}(W)$ is not linear, we select the axiom ψ from $\operatorname{Ax}_{\operatorname{GL}}(\alpha)$.
- Otherwise, assume that $\mathcal{K}(W)$ is linear but not a GL_n-model. Then, $\mathcal{K}(W)$ contains a chain of worlds $w_0 \subset w_1 \subset \cdots \subset w_{n+1}$. The crucial point is that $w_{j+1} \setminus w_j$ contains at least a propositional variable from \mathcal{V}_{α} , for every $0 \leq j \leq n$. Thus, we can choose a proper renaming of \mathbf{bd}_n as ψ .

Another terminating logic is the Jankov Logic (see Ex. 3); actually, also in this case the learned axiom can be chosen by renaming the **wem** axiom. In general, all the logics BTW_n (Bounded Top Width, at most n maximal worlds, see [2]) are terminating. An intriguing case is Scott Logic ST [2]: even though the class of ST-frames is not first-order definable, we can implement a learning procedure for ST-axioms arguing as in [7] (see Sec. 2.5.2). Some of the mentioned logics have been implemented in intuitRIL¹.

One may wonder whether this method can be applied to other non-classical logics or to fragments of predicate logics (these issues have been already raised in the seminal paper [4]). A significant work in this direction is [11], where the procedure has been applied to some modal logics. However, the main difference with the original approach is that it is not possible to use a single SAT-solver, but one needs a supply of SAT-solvers. This is primarily due to the fact that forcing relation of modal Kripke models is not persistent; thus worlds are loosely related and must be handled by independent solvers.

¹ Available at https://github.com/cfiorentini/intuitRIL.

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