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A New Stable Boundary Layer Parameterization for Weather and Forecasting Models: a Heat Flux Budget Approach

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- ² for Weather and Forecasting Models: a Heat Flux
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Abstract The present study introduces a new boundary layer parameteriza-10 tion for weather and forecasting models. It is implemented here as a boundary 11 layer module in Weather Research and Forecasting (WRF) model. The main 12 novelty in the new scheme is that it includes prognostic equations for the heat 13 flux and temperature variance, being the first WRF boundary layer scheme 14 with that feature. This is specially aimed at improving the representation of 15 nocturnal stable boundary layer and of its turbulence regimes, weakly and 16 very stable. The effort is supported by previous studies that found that the 17 two regimes and the transitions between them are better represented by sim-18 plified numerical schemes that represent the interactions between the surface 19 and the air adjacent to it when the heat flux and temperature variance are 20 solved prognostically. The results show that the two regimes are adequately 21 simulated by the new scheme. Such an evaluation is presented in terms of the 22 relationship between the turbulence velocity scale and mean wind speed, of 23 the dependence of the potential temperature gradient near the surface and the 24 mean wind speed, and by the relationship between flux and gradient Richard-25 son numbers. In the new scheme, the relationship between thermal structure 26 and the mean and turbulent flows arises naturally from the heat flux prognostic 27 equation, not being arbitrarily imposed by an empirical stability function. 28

 $_{29}$ Keywords Eddy diffusivity \cdot Stable boundary layer \cdot Turbulence

- $_{30}$ $\,$ parametrizations \cdot Turbulence regime \cdot Weather Research and Forecast-
- 31 ing model
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33 1 Introduction

Through mechanical drag and thermal effects, the Earth's surface directly af-34 fects the flow in the atmospheric boundary layer (ABL), making it turbulent 35 (Stull 1988; Cuxart et al. 2006). As a consequence, forecasting the mean state 36 of the ABL demands an adequate representation of the effects of turbulence, 37 which is usually described in turbulent models through the statistical moments 38 of the fluctuations of the variables that describe the atmospheric flow. Fur-39 thermore, as the majority of human activities take place in the ABL, such flow 40 is often affected by anthropogenic action. It is clear that a good representation 41 of the ABL and its interaction with the surface is essential for all atmospheric 42 applications. 43

The adequate modelling of the ABL and of its importance as a lower bound-44 ary to upper atmospheric flow has been pursued by the micrometeorological 45 community for a long time (Taylor 1915; Blackadar 1962; Taylor and Delage 46 1971; Mellor and Yamada 1974; Wyngaard 1975; Louis 1979, among others). 47 Naturally, the quality of such model representations is limited by the same 48 difficulties that affect the bulk of knowledge of the ABL at any given historic 49 context. Currently, a major challenge for this understanding regards the stable 50 51 boundary layer (SBL), its turbulence regimes and how they relate to the mean flow and to quantities that are external to the SBL (van Hooijdonk et al. 2015; 52 Vignon et al. 2017; van der Linden et al. 2017; Holdsworth and Monahan 2019). 53 It has been studied by numerous authors in the last decades (Mahrt 1998; Sun 54 et al. 2012, 2016; Acevedo et al. 2014; Mahrt 2014, among others), having been 55 classified both observationally and in modelling in two distinct regimes: weakly 56 stable and very stable. According to Mahrt (2014) the "fundamental features 57 of the very stable boundary layer still remain a mystery". In this context, the 58 simulation of the very SBL and the representation of transitions from and 59 to such a regime by planetary boundary layer parameterizations is a major 60 micrometeorological challenge that limits the quality of the representation of 61 the mean state of the atmosphere near the surface in both numerical weather 62 prediction (NWP) and climate models today {(van de Wiel et al. 2017; Bat-63 tisti et al. 2017; Baas et al. 2019; Holdsworth and Monahan 2019; Lapo et al. 64 2019; Maroneze et al. 2019, 2021; Lorenz et al. 2022; Kähnert et al. 2022). At 65 the same time, the weakly SBL is well described by Monin-Obukhov similarity 66 theory and, for this reason, is comparatively well simulated and represented by 67 numerical planetary boundary layer (PBL) parametrization schemes (Mahrt 68 2014). 69 The Weather Research and Forecasting (WRF) model (Skamarock et al. 70

2008) is largely employed to investigate hydrology, renewable energy, regional
climate, weather prediction, and other phenomena (Powers et al. 2017), both
for scientific research and for operational numerical prediction. Maroneze et al.
(2021) have analyzed the quality of the representation of turbulence in very
stable conditions by the different WRF PBL parameterizations that solve the
turbulence kinetic energy, either diagnostically or prognostically. They found
that the variety of existing parameterizations lead to a large diversity in rep-

⁷⁸ resentations between turbulent and mean quantities, with different simulated

thresholds between the two regimes and consequent very different predictions
of mean quantities in specific situations. None of the boundary-layer param-

eterizations available in WRF solves a prognostic equation for the heat flux, although there are indications in the literature that this variable has a decisive

 $_{\tt 83}$ $\,$ control in the the SBL turbulence regime (van de Wiel et al. 2012; Maroneze

et al. 2019). Maroneze et al. (2019) have shown that the adequate simulation of the transition between the two regimes is much better simulated when a

⁸⁶ prognostic for the heat flux is solved by a prognostic equation, rather than

⁸⁷ represented by a parmeterization.

In NWP models, the influence of flow stability to the ABL flow is usually 88 prescribed as an empirical and arbitrary stability function (Costa et al. 2020). 89 Here, it is hypothesized that the model flow dependence on stratification, and, 90 more generally, the relationship between mean and turbulence quantities (such 91 as the flux and gradient Richardson numbers) arises naturally in the model 92 when the heat flux is prognostically solved, instead of being prescribed by a 93 stability function. Therefore, the main goal of the present study is to intro-94 duce a new stable boundary layer parameterization for weather and forecasting 95 models that includes prognostic equations for the heat flux and temperature 96 variance. Such a scheme is implemented in the WRF model version 3.9, de-97 scribed in section 2. The proposed parametrization is calibrated and validated 98 using GEWEX Atmospheric Boundary Layer Study (GABLS) I (Kosović and 99 Curry 2000) as a control case, in section 3.2. The ability of the new parame-100 terization to represent the two contrasting SBL regimes is evaluated in section 101 4, through the relationships it simulates between the turbulence velocity scale 102 and the mean wind speed, between the potential temperature gradient near the 103 ground surface and the mean wind speed, and between the flux and gradient 104

105 Richardson numbers.

¹⁰⁶ 2 Description of the Planetary-Boundary-Layer Parametrization

¹⁰⁷ Turbulence affects the mean state of the planetary boundary layer through the ¹⁰⁸ divergence of turbulent fluxes. Such a divergence in the vertical direction is ¹⁰⁹ often the dominant process affecting mean quantities near the surface. When ¹¹⁰ its role is sufficiently larger than that of other influences, the prognostic equa-¹¹¹ tions for mean horizontal velocity components and potential temperature may ¹¹² be regarded as

$$\left[\frac{\partial \overline{u}}{\partial t}\right]_{PBL} = -\frac{\partial \overline{u'w'}}{\partial z},\tag{1}$$

$$\left[\frac{\partial \overline{v}}{\partial t}\right]_{PBL} = -\frac{\partial \overline{v'w'}}{\partial z},\tag{2}$$

$$\left[\frac{\partial \overline{\theta}}{\partial t}\right]_{PBL} = -\frac{\partial \overline{w'\theta'}}{\partial z}.$$
(3)

In equations (1-3) $\overline{u}, \overline{v}$ and $\overline{\theta}$ are respectively the mean velocity components in zonal and meridional directions, and the mean potential temperature. The vertical turbulent momentum fluxes are given by $\overline{u'w'}$ and $\overline{v'w'}$, while $\overline{w'\theta'}$ is the turbulent heat flux.

According to K theory, the vertical turbulent momentum fluxes are parametrized

as (Mellor and Yamada 1974, 1982; Therry and Lacarrere 1983; Bougeault and

Lacarrere 1989; Janjić 1994; Nakanishi and Niino 2009; Bretherton and Park

 $_{120}$ 2009, among others)

$$\overline{u'w'} = -K_m \frac{\partial \overline{u}}{\partial z},\tag{4}$$

121 and

$$\overline{v'w'} = -K_m \frac{\partial \overline{v}}{\partial z},\tag{5}$$

where K_m is the vertical turbulent diffusion coefficients for momentum. In turbulence closures that solve the TKE either prognostically or diagnostically, it is common to estimate K_m as a function of TKE, the mixing length l_m , and a stability function f_m (Mellor and Yamada 1974, 1982; Nakanishi and Niino 2009; Bretherton and Park 2009; Costa et al. 2020, among others)

$$K_m = \sqrt{\overline{e}} \ l_m f_m. \tag{6}$$

For a horizontally homogeneous atmosphere, the prognostic equation for TKE (\overline{e}) is

$$\frac{\partial \overline{e}}{\partial t} = -\overline{u'w'}\frac{\partial \overline{u}}{\partial z} - \overline{v'w'}\frac{\partial \overline{v}}{\partial z} + \frac{g}{\Theta}\overline{w'\theta'} - \frac{\partial}{\partial z}\left[\overline{w'e} + \frac{\overline{p'w'}}{\rho_0}\right] - \epsilon_e, \tag{7}$$

¹²⁹ where p is pressure, ρ_0 is a reference density and Θ is a reference temperature. ¹³⁰ In the right hand side (r.h.s) of Eq. 7, the first and second terms represent the ¹³¹ turbulence shear production (SP);the third term is the turbulence buoyant de-¹³² struction (production) under stable (unstable) conditions (BD/P); the fourth ¹³³ term is the vertical transport of TKE both by turbulence and by pressure ¹³⁴ fluctuations (TR); and the fifth term is TKE viscous dissipation (DIS).

The TKE viscous dissipation (ϵ_e) can be parameterized as a function of TKE and a characteristic dissipation length l_{ϵ} :

$$\epsilon_e = c_1 \frac{\overline{e}^{3/2}}{l_\epsilon},\tag{8}$$

where c_1 is a numerical constant. According to Cuxart et al. (2006), values from 0.08 to 0.7 have been used for c_1 .

¹³⁹ Following Duynkerke (1988), the TKE transport term is represented as:

$$-\frac{\partial}{\partial z}\left[\overline{w'e} + \frac{\overline{p'w'}}{\rho_0}\right] = \frac{\partial}{\partial z}\left[K_e\frac{\partial\overline{e}}{\partial z}\right],\tag{9}$$

140 here $K_e = \alpha_e K_M$.

4

The prognostic equation for the heat flux $(\overline{w'\theta'})$ is:

$$\frac{\partial \overline{w'\theta'}}{\partial t} = -\overline{w'^2}\frac{\partial \overline{\theta}}{\partial z} + \frac{g}{\Theta}\overline{\theta'^2} - \frac{\partial \overline{w'w'\theta'}}{\partial z} + \frac{1}{\rho_0}\overline{\theta'\frac{\partial p'}{\partial z}},\tag{10}$$

where the first term on the r.h.s represents the thermal gradient production of 142 heat flux in a SBL (TGP). The second term is heat flux buoyant destruction 143 (production) under stable (unstable) condition, and the third term represents 144 the transport of heat flux by turbulence, while the fourth term either one or 145 the other both the transport by pressure fluctuations and return-to-isotropy. 146 Following Therry and Lacarrere (1983) the last term of Eq. 10 is param-147 eterized according to the idea of a pressure relaxation, as the sum of two 148 contributions. The first is proportional to the heat flux (P1) itself and the 149 second is proportional to the temperature variance (P2)150

$$\frac{1}{\rho_0}\theta'\frac{\partial p'}{\partial z} = P1 + P2,\tag{11}$$

151 where

$$P1 = -c_2 \frac{\overline{e}^{1/2}}{l_{\epsilon}} \overline{w'\theta'} \quad \text{and} \quad P2 = -c_3 \frac{g}{\Theta} \overline{\theta'^2}, \tag{12}$$

and c_2 and c_3 are numerical constants.

¹⁵³ For temperature variance, the prognostic equation is:

$$\frac{\overline{\partial \theta'^2}}{\partial t} = -2\overline{w'\theta'}\frac{\partial\overline{\theta}}{\partial z} - \frac{\partial\overline{w'\theta'^2}}{\partial z} - \epsilon_{\theta}, \qquad (13)$$

¹⁵⁴ where the first term in the r.h.s is the heat flux production of temperature

variance (Pr), the second is its turbulent transport (TR) and the third term
is its molecular dissipation (DIS).

¹⁵⁷ The dissipation term of temperature variance is parametrized as

$$\epsilon_{\theta} = c_4 \frac{\sqrt{e}}{l_{\epsilon}} \overline{\theta'^2},\tag{14}$$

where c_4 is numerical constants.

In analogy with Eq. 9, the transport term in Eqs. 10 and 13 are parametrized as

$$-\frac{\partial \overline{w'w'\theta'}}{\partial z} = \frac{\partial}{\partial z} \left[K_e \frac{\partial \overline{w'\theta'}}{\partial z} \right] \text{ and } -\frac{\partial \overline{w'\theta'^2}}{\partial z} = \frac{\partial}{\partial z} \left[K_e \frac{\partial \overline{\theta'^2}}{\partial z} \right].$$

To close the above set of equations, the numerical constants, the mixing length l_m and the characteristic dissipation length l_{ϵ} must be specified. In the literature, the two mixing lengths are generally taken as equal to each other (Therry and Lacarrere 1983; Weng and Taylor 2003; Costa et al. 2020, among other) and many different formulations and numerical constants have already been proposed.

WRF uses an Arakawa C grid, where the center of the grid cell (represented 167 by symbol \times in fig. 1) are referred as "mass points" or full levels, while the face 168 grid points staggered at one-half grid length from the mass points are referred 169 as half levels (represented by symbol \bigcirc in fig. 1). Here, the prognostic equa-170 tions for any turbulent variables are calculated at the full levels, in contrast 171 with other parameterizations present in WRF. Therefore, here the turbulent 172 flux divergences can be estimated directly through centered finite differences, 173 not being necessary the use of spatially averaged values (Fig. 1). 174

Equations (7),(10), and (13) are solved through an implicit time-integration method. They can be generically discretized as

$$\underbrace{\frac{\Psi_k^{n+1} - \Psi_k^n}{\Delta t}}_{\text{tendency}} = \underbrace{\frac{\partial}{\partial z} \left[K_m^n \frac{\partial}{\partial z} \Psi^{n+1} \right]_k}_{\text{Transport}} + \underbrace{\frac{P_k^n}{Production}}_{\text{Destruction}} - \underbrace{\frac{F_k^n \Psi_k^{n+1}}{Pisipation}}_{\text{Dissipation}}, \quad (15)$$

where Ψ is the turbulent variable, n denotes the time index and k denotes the vertical full level index. Equation (15) is integrated in time by the relationship

$$a \, \Psi_{k-1}^{n+1} + b \, \Psi_k^{n+1} + c \, \Psi_{k+1}^{n+1} = d \tag{16}$$

where a, b, and c are the elements of the matrix that solves the implicit system for Ψ_{k-1}^{n+1} .



Fig. 1 The schematic representation of vertical adapted Arakawa C grid for the present PBL parametrization.

6

¹⁸¹ 3 Model Validation

¹⁸² 3.1 Control Case and model discretization

PBL schemes are typically calibrated through a control case. One of the most 183 widely used reference cases for such a purpose is the first Global Energy 184 and Water cycle EXperiment (GEWEX) Atmospheric Boundary Layer Study 185 (GABLS I). GABLS I provides a model intercomparison for SCM (Cuxart 186 et al. 2006) and LES (Beare et al. 2006) for a weakly stable boundary layer, 187 with prescribed temperature at the surface (Kosović and Curry 2000). Over 188 the years, GABLS I has been used to validate schemes designed for different 189 purposes, such as the development of new parametrizations (Bretherton and 190 Park 2009; Cheng et al. 2020), SBL regimes regime transitions studies (Costa 191 et al. 2020). 192

The boundary and initial conditions used in all simulations described in this section are the same as those in GABLS I (Kosović and Curry 2000; Cuxart et al. 2006):

- Constant geostrophic wind components ($u_G = 8 \text{ m s}^{-1}$ and $v_G = 0 \text{ m s}^{-1}$) at the domain top, along the entire simulation;
- Constant surface cooling rate (0.25 K h^{-1}) along the simulation;
- ¹⁹⁹ The initial profiles of wind components, temperature and turbulence kinetic
- energy are: $\overline{u}(z, t = 0) = u_G; \ \overline{v}(z, t = 0) = v_G; \ \overline{\theta}(z < 100 \text{ m}, t = 0) = 263.5$
- K, while a constant lapse rate of 0.1 K m⁻¹ is considered at heights z > 100 m; $\bar{e} = 0.4(1 z/250)^3$.

WRF single column mode (WRF-SCM), with 170 levels between the surface (z = 0) and the domain top (z = 6 km), is used in the PBL scheme validation. The first atmospheric level is fixed at z = 1.5 m, and the grid spacing increases steadily from 1.6 m near the surface, to 198 m near the domain top.

²⁰⁸ 3.2 Model calibration

Typically, PBL schemes implemented in weather and climate models have a 209 large number of tuning parameters. The number of numerical constants is 210 proportional to the number of parametrizations necessary to close the system 211 of equations. According to Audouin et al. (2021), the model calibration consists 212 in adjusting each tuning parameter, by taking into account both the model 213 performance and physical restrictions. It can be a difficult task because of the 214 large number of degrees of freedom which demand a high computational cost 215 (Audouin et al. 2021). 216

217 3.2.1 Stable Boundary Layer Mixing Length Formulation

An adequate mixing length formulation is crucial to properly describe the boundary layer flow (Weng and Taylor 2003), having a very important role in any PBL scheme. In the literature, many different formulations have been
 proposed. Blackadar (1962) suggested

$$\frac{1}{l_{Blackadar}} = \frac{1}{\kappa z} + \frac{1}{\lambda_0},\tag{17}$$

where $l_{Blackadar}$ is a mixing length, κ is von Karman constant, and λ_0 is a reference length scale. Table 1 show different formulations for λ_0 proposed in the literature.

The mixing length tends to be smaller under stable thermal stratification (André et al. 1978), and can be given by the harmonic average between $l_{Blackadar}$ and a buoyant length scale L_B (Sukoriansky et al. 2005; Nakanishi and Niino 2009, among other)

$$\frac{1}{l_m} = \frac{1}{l_{Blackadar}} + \frac{1}{L_B},\tag{18}$$

229 where

$$L_B = C_N \frac{\sqrt{2\ \overline{e}}}{N},\tag{19}$$

where N is the Brunt–Väisälä frequency and C_N is a numerical constant whose used values range from 0.2 to 1 (André et al. 1978; Baas et al. 2008; Nakanishi and Niino 2009).

The role of the reference length scale can be evaluated by considering 233 $L_B \to \infty$ in Eq. (18) and varying λ_0 . Fig. 2 shows that the mean vertical pro-234 files of the different atmospheric quantities vary largely with λ_0 . For example, 235 the height and width of the near surface maxima of the wind-velocity profile 236 increases linearly with λ_0 (Fig. 2a,b). The absolute values of momentum flux 237 $\left(\tau/\rho = \sqrt{\overline{u'w'}^2 + \overline{v'w'}^2}\right)$, potential temperature $(\overline{\theta})$, heat flux $(\overline{w'\theta'})$, tem-238 perature variance $(\overline{\theta'}^2)$, vertical wind velocity variance component $(\overline{w'}^2)$, and 239 TKE (\bar{e}) and the momentum eddy viscosity (K_m) generally increase at all 240 heights as λ_0 increases. When compared to the GABLS1 observations, the 241 simulated TKE is underestimated for most of the values of λ_0 considered. In 242 general, the comparison indicates that when $\lambda_0 = 2$ m, the model outputs are 243 closest to the GABLS1 reference case (Fig. 2 c-i). However, the intensity of the 244 wind-speed maximum near the surface (low-level-jet nose, Klein et al. 2016) 245 is underestimated. For larger values of λ_0 , the temperature variance increases 246 with height until it reaches a maximum near the SBL top (Fig. 2f). When λ_0 247 is evaluated by formulations such as those proposed by Mellor and Yamada 248 (1974) (MY, black dashed lines in Fig. 2) and Bretherton and Park (2009) 249 (UWBLS, yellow lines in Fig. 2) the mean vertical profiles of the atmospheric 250 quantities approach their values when large values of λ_0 are considered. 251

Finite values of the buoyant length scale, in Eq. (18), make the wind-speed maximum near the surface sharper and more intense. Moreover, it reduces the turbulence intensity promoting a shallower SBL (not shown). The value chosen for C_N is important because the buoyant length scale plays a similar



Fig. 2 Vertical profiles, mean values taken over last two hours from the simulation of zonal and meridional velocity components \overline{u} (a) and \overline{v} (b), the absolute values of momentum flux τ/ρ (c), potential temperature $\overline{\theta}$ (d), kinematic heat flux $\overline{w'\theta'}$ (e), temperature variance $\overline{\theta'}^2$ (f), vertical wind velocity variance component $\overline{w'}^2$ (g), TKE (h), and the momentum eddy viscosity K_m (i) for different reference length scales. The solid thick gray line is the GABLS I case.

role as a stability function does in the mixing length formulation under stable 256 conditions (Fig. 3). When smaller values of C_N are considered, the profiles 257 of the wind speed components present a sharper and more intense maximum 258 than when C_N is larger (Figs. 3a,b). On the other hand, in those cases the 259 momentum eddy diffusivity is smaller than in the cases with large C_N (Fig. 260 3i). This occurs because the buoyant length scale will decrease, for small C_N , 261 and then, it will reduce the mixing length intensity and the diffusion coeffi-262 cients, consequently. When large values of C_N are assumed the momentum 263 flux, the heat flux, the temperature variance and TKE become more intense 264 (Fig. 3c,e,f,h), determining a more turbulent and deeper SBL. Even though the 265 turbulence intensity increases with C_N , the temperature vertical profile shows 266 that the SBL will become colder near the the boundary layer top because the 267 enhanced turbulent transport allows the cold air reaching higher levels (Fig. 268 3d). In almost all comparisons between the profiles presented in Fig. 3, one 269 can verify that the model profiles are closer to the control case when the pa-270 rameters $\lambda_0 = 6.5$ m and $C_N = 0.2$ are used. Therefore, in order to keep the 271



parametrization as simple and as accurate as possible, such optimized values of λ_0 and C_N are used in the following analysis.

Fig. 3 Same of Fig. 2 considering a finite values of the buoyant length scale and different values of C_N .

 ${\bf Table \ 1} \ {\rm Reference \ length \ scale}$

Reference	λ_0 [m]
Blackadar (1979)	$0.00027 \frac{U_G}{f}$
Bretherton and Park (2009)	0.085 PBLH
Mellor and Yamada (1974)	$0.1 \frac{\int_0^\infty z q dz}{\int_0^\infty q dz}$
Therry and Lacarrere (1983)	50
QNSE	$0.0063 \frac{u_*}{f}$

274 3.2.2 Second order constants dependence

- As mentioned in section 2, the value of c_1 in the parameterization of the viscous
- ²⁷⁶ dissipation (Eq. 8), varies by almost an order of magnitude among existing

PBL schemes. Fig. 4 shows how the variation of c_1 impacts the model. All 277 profiles show that the SBL height decreases appreciably as c_1 increases (Fig. 278 4). When larger values of c_1 are considered, the magnitudes of momentum flux, 279 heat flux, temperature variance, TKE, and momentum eddy diffusivity become 280 smaller and a shallower SBL is simulated (Fig. 4c,e,f,h,i). Increasing c_1 leads 281 to larger TKE dissipation, reducing the turbulent quantities and causing the 282 SBL to be more stratified. Moreover, the turbulent flux divergence also varies, 283 affecting the vertical potential temperature profile, which is nearly linear in 284 the SBL (Fig. 4d) for large c_1 values, while it is curved, which a smaller 285 286



Fig. 4 Same of Fig. 2 for different values of c_1 in the parametrization of the viscous dissipation.

While c_1 values impact the SBL depth, the choice of parameters c_2 and c_3 287 (Eq. 12) does not have the same effect. On the other hand, varying c_2 affects 288 the vertical profiles of temperature (Fig. 5a), heat flux (Fig. 5b) and of the 289 mean temperature variance (Fig. 5c). The constants c_2 and c_3 are, respec-290 tively, control parameters in the parameterization of the transport by pressure 291 fluctuations and in the return-to-isotropy terms in the heat flux budget (Eq. 292 10). In particular, c_2 is a coefficient in the parameterization that mimics a heat 293 flux dissipation rate (P_1) . Therefore, larger values of c_2 cause a decrease on 294 the simulated heat flux magnitude (Fig. 5b), consequently reducing variance 295 as well (Fig. 5c). Furthermore, smaller values of c_2 imply larger absolute heat, 296

allowing larger turbulent heat transport at levels near the SBL top, which 297 becomes colder (read line in Fig. 5a), although not affecting the SBL thick-298 ness. In such case, the stability of the entire SBL is reduced, and it becomes a 299 near-neutral layer from the ground until near the top, where a large thermal 300 inversion is present. As the temperature variance production is proportional 301 to both the heat flux and the thermal gradient, in this case the temperature 302 variance is small for most of the SBL, reaching a local maximum near the max-303 imum of the thermal gradient, at the SBL top (red line in Fig. 5c). Fig. 5 also 304 shows that the SBL height is not affected by the choice of free coefficient in 305 the temperature variance dissipation rate (c_4) . A 4-fold variation in c_4 causes 306 the surface heat flux to vary by less than 11 % (Fig. 5e). 307



Fig. 5 Vertical profiles, mean values taken over last two hours from the simulation, for potential temperature $\overline{\theta}$ (a, d), kinematic heat flux $\overline{w'\theta'}$ (b, e), temperature variance $\overline{\theta'^2}$ (c, f) for different values of c_2 , c_3 and c_4 . The solid thick gray line is the GABLS I case.

Based on these results, the free parameters of the model have been chosen to optimize the model performance, when the outputs are compared with the values from GABLS I case (Table 2). Such a comparison is shown in Fig. 6 for PBL height (Fig. 6a), surface sensible heat flux (Fig. 6b) and the surface friction velocity (Fig. 6c). Following Cuxart et al. (2006), in this analysis the boundary-layer height is the level where the sensible heat flux decays to 5% of its surface value.



Fig. 6 PBL height (a), heat flux (b), and friction velocity (c) temporal evolution. The solid thick gray points is the GABLS I case.

e 2 Free Paramet	er
e 2 Free Paramet	e

c_1	0.172
c_2	0.4
c_3	0.4
c_4	0.2
c_N	0.2
α_e	3

315 4 SBL Regimes

The methodology employed to evaluate whether the newly proposed PBL 316 scheme correctly reproduces the physical properties of both SBL turbulence 317 regimes is similar to that employed by Maroneze et al. (2021). The geostrophic 318 zonal velocity component u_G is assumed to be temporally and vertically con-319 stant for each simulation. Values of u_G considered varied from 0.5 m s⁻¹ to 320 24 m s⁻¹, with 0.5 m s⁻¹ steps between 0.5 and 14 m s⁻¹, and with 1 m 321 s^{-1} steps between 14 and 24 m s^{-1} . In this section the skin temperature is 322 estimated through the Unified Noah Land Surface Model (Mukul Tewari et al. 323 2004), while the RRTM Longwave Scheme (Mlawer et al. 1997) and the Dud-324 hia Shortwave Scheme (Dudhia 1989) are adopted for radiative processes. The 325 Purdue Lin scheme (Chen and Sun 2002) has been used to represent the mi-326 crophysical process. For all simulations one dryland cropland and pasture land 327 vegetation with vegetation fraction of 0.5 are considered. The roughness length 328 for this surface type is 0.15 m. 329

The SBL turbulence regime transition can be determined from both local and bulk variables. Initially, both SBL regime classifications and regime transitions have been marked in terms of stability parameters (Mahrt 1998). However, the use of a single stability parameter such as the Obukhov length, or the Richardson number (either in its flux or gradient form), is ineffective at distinguishing the SBL regimes universally (Monahan et al. 2015). On the other hand, since the mean wind speed has a crucial control on the SBL regime, it has become common practice to assess it through the relationship among turbulent quantities, such as the turbulence velocity scale ($V_{TKE} = \sqrt{\overline{e}}$), and the mean wind speed (Sun et al. 2012; van de Wiel et al. 2012; Acevedo et al. 2016, 2019, among others).

The study of Sun et al. (2012) established the relationship between V_{TKE} 341 and \overline{U} as a criterion to determine the local SBL regime (Acevedo et al. 2016, 342 incluir varios). In general, V_{TKE} increases linearly with \overline{U} in both regimes, 343 but the rate of increase is notably larger in the weakly stable than in the 344 very stable regime. Therefore, the regime transition occurs at the value of U345 for which the slope of such a relationship changes abruptly (Sun et al. 2012). 346 The scheme presently proposed simulates a very stable regime, characterized 347 by a subtle V_{TKE} increase as \overline{U} increases, in general agreement with the ob-348 servations. It is important to notice that for very weak winds speeds, V_{TKE} 349 sometimes assumes a constant value that is equal to minimum value imposed 350 to the scheme. Contrastingly, when the wind speed is larger, a weakly stable 351 regime is simulated, with V_{TKE} increasing rapid as \overline{U} increases (Fig. 7). The 352 change between the two slopes is abrupt, craracterizing the value of \overline{U} for which 353 the SBL regime transition occurs (Fig. 7). Maroneze et al. (2021) compared 354 the relationship between V_{TKE} and \overline{U} for six different boundary layer schemes 355 that explicitly or implicitly solve TKE in WRF: Mellor-Yamada Nakanishi Ni-356 ino 2.5 (MYNN2.5), Mellor-Yamada Nakanishi Niino 3.0 (MYNN3.0), Mellor 357 Yamada-Janjic (MYJ) Quasi-Normal Scale Elimination (QNSE), University of 358 Washington (UWBLS) and Bougeault-Lacarrére (BouLac). Among these, only 359 MYNN2.5 was able to reproduce both SBL regimes and the transition between 360 them as according to the observations as does the scheme presently proposed. 361 The others typically simulate poorly the very-stable regime, as V_{TKE} varies 362 little of nothing as \overline{U} increases. 363

The SBL regime transition is also clear when the temperature difference 364 near the ground is considered (Fig. 8). As shown by Vignon et al. (2017), the 365 near surface potential temperature difference reaches its larger values for weak 366 wind speeds, when turbulence is not strong enough to mix the whole layer, 367 so that the lower levels become decoupled from higher levels. As the mean 368 wind speed increases, the potential temperature difference starts to decreases 369 sharply characterizing the regime transition (Fig. 8). Moreover, for large wind 370 speeds the temperature difference tends to very small values, because the tur-371 bulence is sufficient to keep the bottom and top of the layer coupled. Maroneze 372 et al. (2021) have shown that the relationship between the vertical tempera-373 ture difference and the mean wind speed is not well solved by the many turbu-374 lence schemes used in WRF. Besides, the solutions of the different schemes are 375 largely variable in terms of the thermal gradient they simulate in the limits of 376 small and large wind speed, or in terms of how abrupt is the variation of such 377 a gradient with wind speed at the regime transition. In the present scheme, a 378 temperature difference of 3.5 K between 1 and 30 m is simulated under low 379



Fig. 7 Average turbulence velocity scale V_{TKE} as a function of the mean wind speed U.The panel shows bin-averaged values taken from the all night of simulation, considering all runs.

winds, dropping below 1 K as the 30-m wind speed exceeds 5 m s⁻¹. In gen-380 eral, the new formulation leads to smaller thermal gradients than MYNN2.5, 381 and a more abrupt transition. In Fig. 8, these results are compared to those 382 obtained with MYNN2.5, that was found to best reproduce the regime transi-383 tion among those schemes compared by Maroneze et al. (2021). Particularly, 384 the reduced thermal gradients in the weakly stable regime are confirmed by 385 CASES-99 observations (Sun et al. 2012; Acevedo et al. 2021). The difference 386 is partially a consequence that the present scheme lacks a stability function, 387 so that the dependence on stratification arises naturally from the heat flux 388 prognostic equation. 389

The turbulent Prandtl number is defined as the ratio between the momen-390 tum eddy diffusivity and the heat diffusivity $(Pr_T = K_M/K_H)$. Generally, 391 PBL schemes use a constant value for Pr_T , thus estimating the turbulent 392 heat diffusivity (K_H) . Such a use of a constant Pr_T implies that the ratio 393 between the flux (Ri_f) and gradient (Ri_g) Richardson numbers is also con-394 stant, since $Pr_T = Ri_q/Ri_f$. However, both atmospheric data and laboratory 395 experiments show that only in the weakly stable regime Ri_f increases lin-396 early with Ri_q , implying a constant Pr_T (Zilitinkevich et al. 2013), whose 397 value may be from 0.7 to 0.9 (Basu and Holtslag 2021). On the other hand, 398



Fig. 8 Average potential temperature difference between 30.8 and 1.3 m as a function of the 30.8-m wind speed for each PBL parametrization, according to the legend. The panel shows bin-averaged values taken from the all night of simulation, considering all runs.

observations show that when Ri_g exceeds a critical value ($Ri_g \approx 0.2$), Ri_f 399 tends to a finite asymptotic value, characterizing the very stable regime (Zil-400 itinkevich et al. 2013; Bou-Zeid et al. 2018; Basu and Holtslag 2021, among 401 other). Furthermore, under very stable stratification it is possible that wave 402 phenomena increase the momentum diffusivity but not the heat diffusivity 403 (Grachev et al. 2007). In such situation, generally $Pr_T > 1$. In a model that 404 uses stability functions, the flux and gradient Richardson numbers are related 405 as $Ri_f = f_h/f_m Ri_g$, where f_h is the stability function for heat. Therefore, 406 the maximum flux Richardson number is limited by the imposed ratio f_h/f_m . 407 As Pr_T is an important model tuning parameter (Sukoriansky et al. 2005) its 408 values can affect the model performance. 409

In the presently proposed scheme, where a prognostic equation for heat flux is solved, the turbulent Prandtl number is not imposed and its value arises naturally from the solved ratio between Ri_f and Ri_g (Fig. 9). Fig. 9 shows that it is able to reproduce the relationship between Ri_f and Ri_g for both SBL regimes. In the weakly stable regime, Pr_T is approximately constant for $Ri_g < 0.2$, while the turbulent Prandtl number increases linearly with Ri_g if $Ri_g > 0.2$. A very similar pattern is presented by both observational



Fig. 9 Average flux Richardson number as a function of the gradient Richardson number, showing bin-averaged values taken from the all night of simulation, considering all runs

⁴¹⁷ and model studies (Kim and Mahrt 1992; Zilitinkevich et al. 2013; Basu and ⁴¹⁸ Holtslag 2021) (Fig. 9). In very stable conditions, $Ri_g > 0.5$, the model results ⁴¹⁹ are limited by the imposed minimum TKE value assumed equal 0.00001 m² ⁴²⁰ s⁻² (yellow circles Fig 9).

421 5 Conclusion

A new boundary layer parameterization, in which the turbulent heat flux and
the temperature variance are solved through a prognostic equation, has been
introduced. The new scheme has been validated through simulations using
the single-column Weather Research and Forecasting (WRF) model with the
GABLS I experiment as a case-control.

A more realistic simulation of the nocturnal turbulence regimes of very stable and weakly stable boundary layers was the main motivation behind the idea of introducing a scheme that prognostically solves the heat flux and temperature variance. This goal has been achieved to a large degree, as shown by the comparison between mean and turbulent quantities presented in Section 4.

The present parameterization does not assume any prescribed stability 433 function, differently from others SBL schemes. Here, the stratification depen-434 dence on other characteristics of the mean and turbulent flows arises natu-435 rally from the use of a prognostic equation for the heat flux. This way, the 436 present scheme is able to realistically simulate the large temperature gradient 437 that often occurs when mean wind speeds are very small. On the other hand, 438 for large wind speeds, the temperature gradient is nearly destroyed, so that 439 the model simulates a near-neutral SBL. Besides, the new formulation leads 440 to smaller thermal gradients and a more abrupt transition between the SBL 441 regimes than occurs in the Mellor-Yamada Nakanishi Niino 2.5 scheme, which 442 was found by Maroneze et al. (2021) to best simulate the differences between 443 the two regimes among the WRF schemes that solve TKE prognostically. This 444 is also in better agreement with CASES-99 observations. Along the same line, 445 SBL schemes typically use a fixed and prescribed turbulent Prandtl number, 446 which may cause a excessive turbulent heat diffusion under very stable condi-447 tions (Grachev et al. 2007; Zilitinkevich et al. 2013; Maroneze et al. 2021). In 448 the present parametrization, the turbulent Prandtl number is not prescribed, 449 being directly calculated from the ratio between Ri_f and Ri_q . 450

The future steps of this research include the specific development and validation of a parametrization for the convective boundary layer, the inclusion of a more sophisticated parametrization for $\overline{w'^2}$ and the inclusion of humidity effects in the parameterization. Furthermore, three-dimensional model simulation of real cases, where advection and other external processes affect the PBL are necessary to validate the parameterization in a more realistic scenario, so

457 that it can ultimately be implemented in operational models.

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